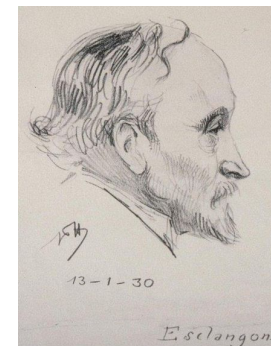




# From transport collapse to kinetic formulations

## rough fluxes and stochastic averaging lemma

Benoît Perthame



## Introduction

Yann invented the Transport Collapse method for computing entropy solutions of

$$\begin{cases} \frac{\partial u}{\partial t} + \sum_{i=1}^N \frac{\partial}{\partial x_i} A_i(u) = 0 & x \in \mathbb{R}^N, t \geq 0 \\ u(, t = 0) = u^0(x) \geq 0 \end{cases}$$

Define

$$\chi(x, \xi, t) = \chi(u(x, t), \xi) = \begin{cases} +1 & \text{if } 0 \leq \xi \leq u(x, t), \\ 0 & \text{otherwise.} \end{cases}$$

Solve on time steps  $[t_k, t_{k+1}]$

$$\begin{cases} \frac{\partial f(t,x,\xi)}{\partial t} + \sum_{i=1}^N a_i(\xi) \frac{\partial f}{\partial x_i} = 0, \\ f(t_k^+, x, \xi) = \chi(u_k(x), \xi), \end{cases}$$

Then project or 'collapse'

$$u_{k+1}(x) = \int_0^\infty f(t_{k+1}, x, \xi) d\xi$$

As  $|t_{k+1} - t_k| \rightarrow 0$ , this converges to the entropy solution.

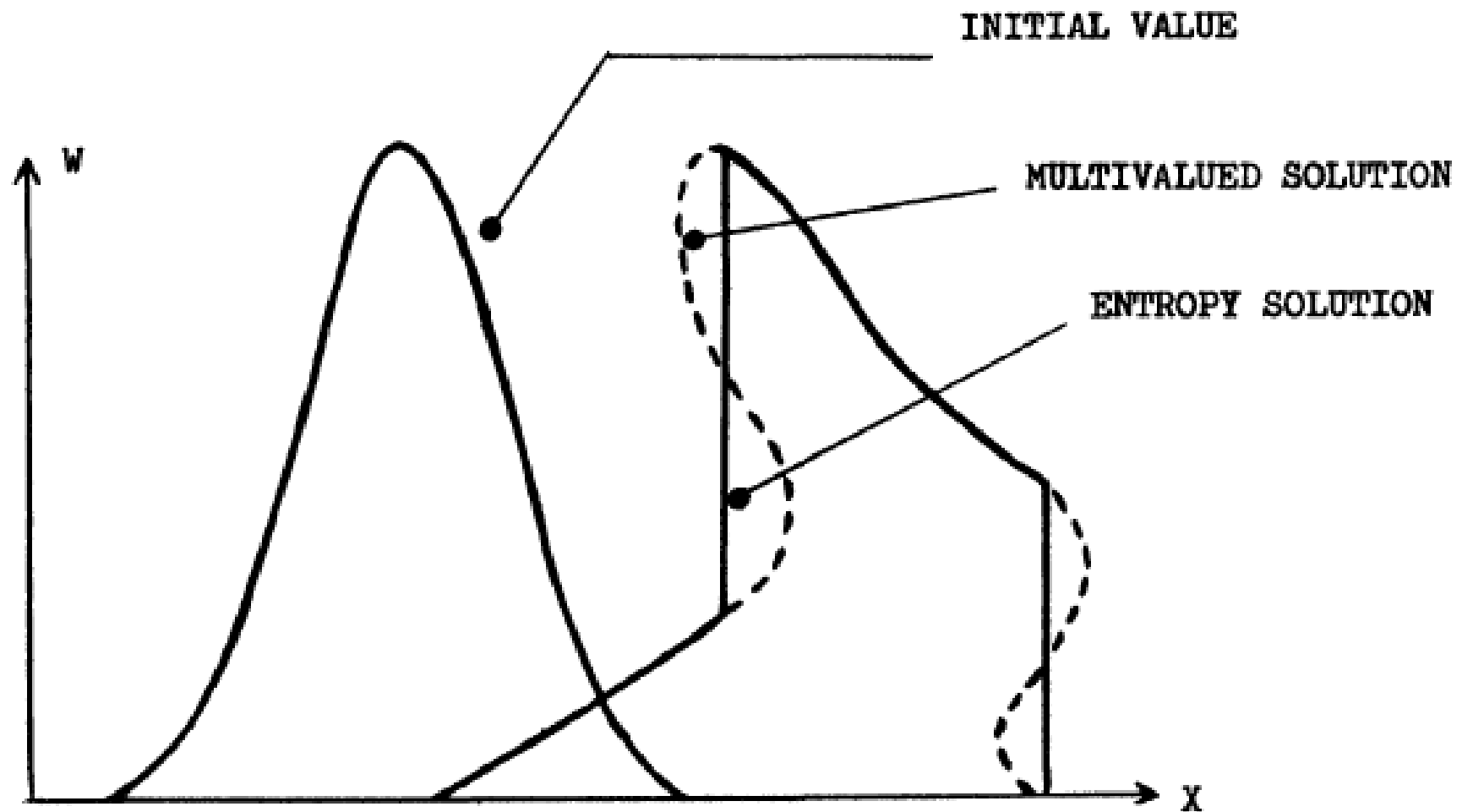


FIG. 2. Geometrical construction of the entropy solution.

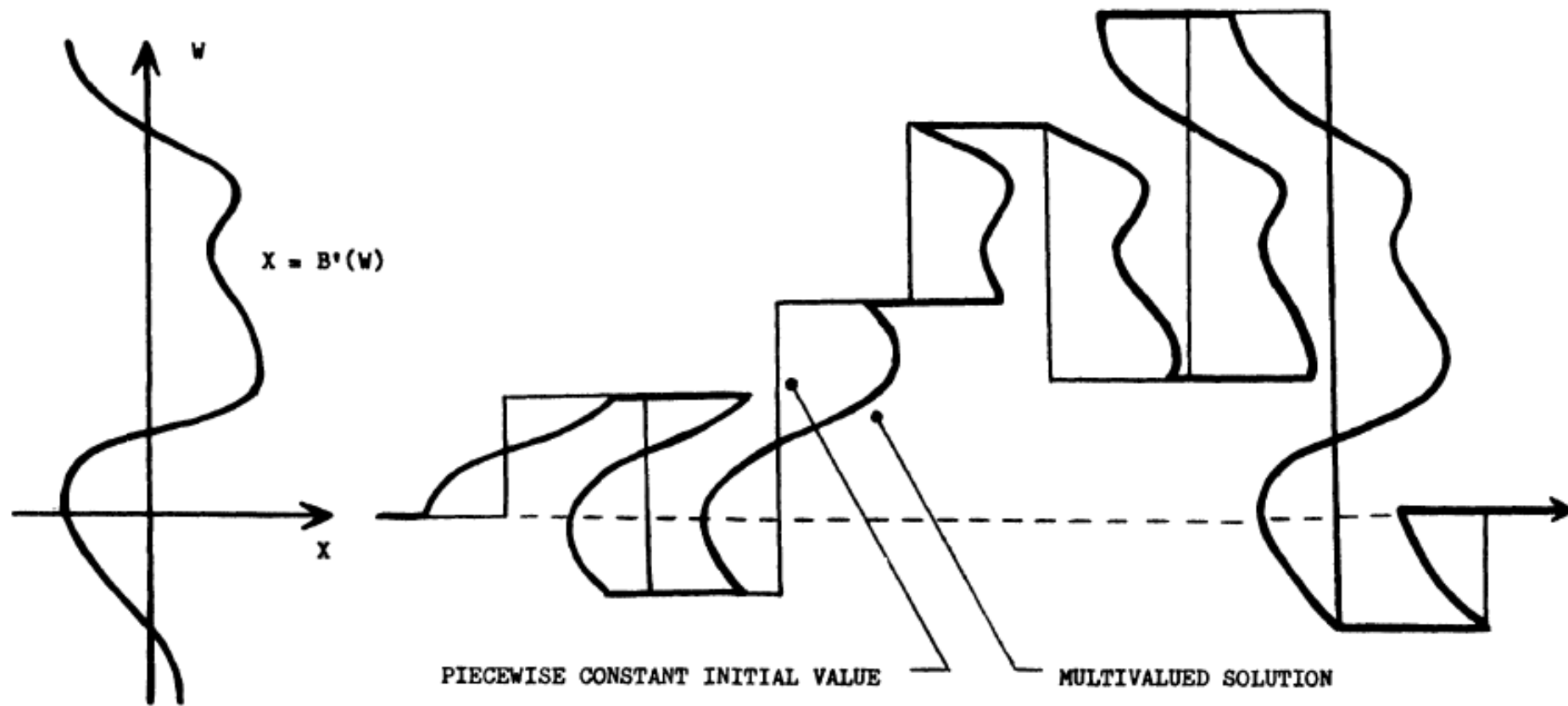


FIG. 4. Interpretation of the Engquist-Osher scheme.

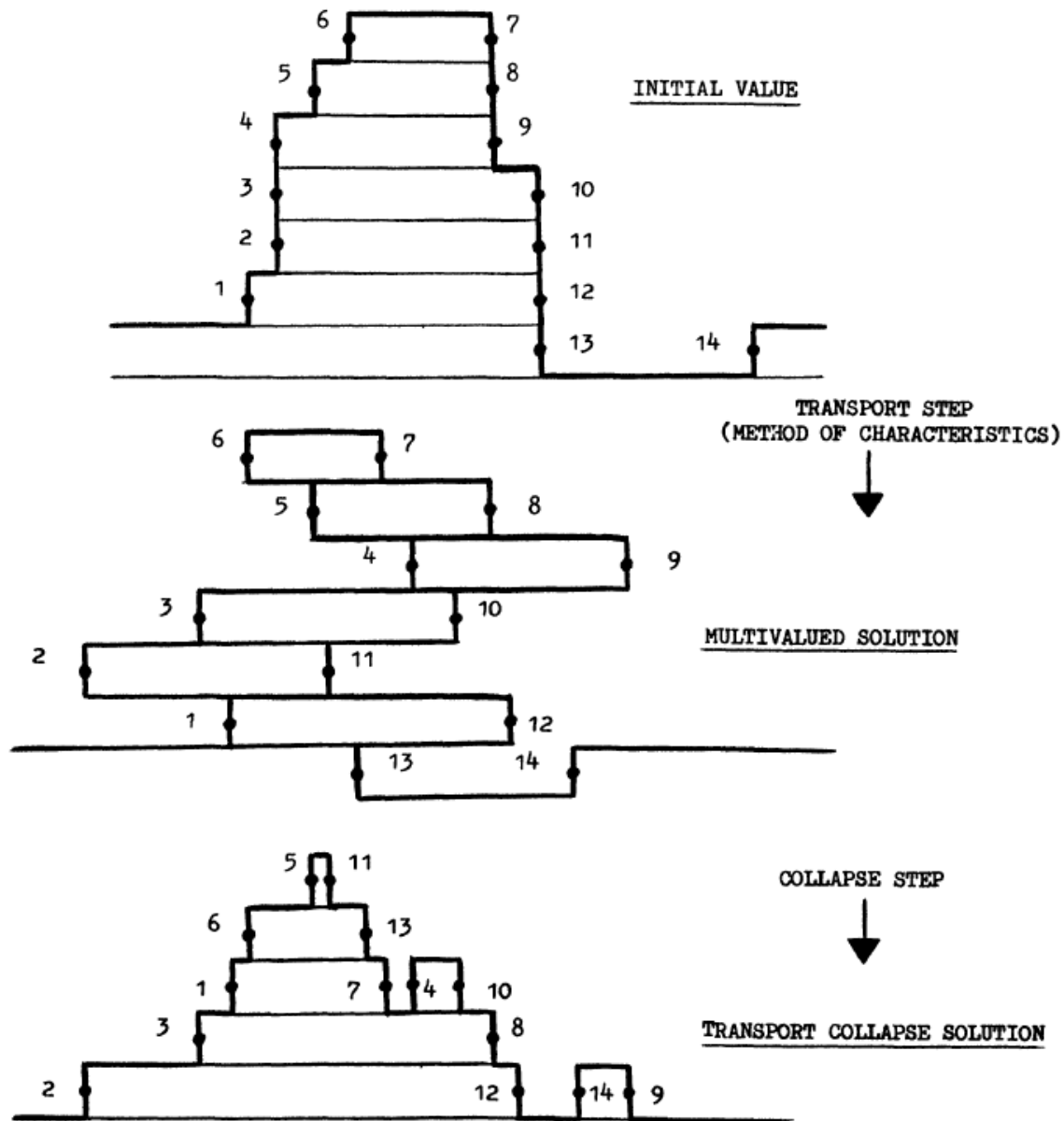


FIG. 5. Description of the x-grid free scheme.

## Kinetic formulation

$$\left\{ \begin{array}{l} \frac{\partial \chi}{\partial t} + \sum_{i=1}^N a_i(\xi) \frac{\partial \chi}{\partial x_i} = \frac{\partial}{\partial \xi} m \quad \text{in } (x, \xi, t) \in \mathbb{R}^N \times \mathbb{R} \times (0, \infty), \\ m(x, \xi, t) \geq 0 \end{array} \right.$$

$$\chi(x, \xi, t) = \chi(u(x, t), \xi) = \begin{cases} +1 & \text{if } 0 \leq \xi \leq u(x, t), \\ 0 & \text{otherwise.} \end{cases}$$

## Kinetic formulation

The reason is that one has

$$\frac{\partial}{\partial t} S(u) + \sum_{i=1}^N \frac{\partial}{\partial x_i} \eta_i(u) \leq 0, \quad \forall S(\cdot) \text{ convex.}$$

$$\frac{\partial}{\partial t} \int_{\mathbb{R}} S'(\xi) \chi(x, \xi, t) d\xi + \sum_{i=1}^N \frac{\partial}{\partial x_i} \int_{\mathbb{R}} S'(\xi) a_i(\xi) \chi(x, \xi, t) d\xi \leq 0$$

$$\left\{ \begin{array}{l} \frac{\partial \chi}{\partial t} + \sum_{i=1}^N a_i(\xi) \frac{\partial \chi}{\partial x_i} = \frac{\partial}{\partial \xi} m \quad \text{in} \quad (x, \xi, t) \in \mathbb{R}^N \times \mathbb{R} \times (0, \infty), \\ m(x, \xi, t) \geq 0 \end{array} \right.$$



## Brenier/Corrias

Can be extended to some systems related to geometrical optics. For isentropic gas dynamics

$$\begin{cases} \frac{\partial \rho}{\partial t} + \frac{\partial \rho u}{\partial x} = 0, \\ \frac{\partial \rho u}{\partial t} + \frac{\partial \rho u^2 + \rho^3}{\partial x} = 0, \end{cases}$$

Just choose

$$\chi(x, \xi, t) = \chi(u(x, t), \xi) = \begin{cases} +1 & \text{if } w_- \leq \xi \leq w_+(x, t), \\ 0 & \text{otherwise.} \end{cases}$$

For smooth solutions, one has

$$\frac{\partial \chi}{\partial t} + \xi \frac{\partial \chi}{\partial x} = 0$$

**Open question.** In Lagrangian variables, this property is lost?

## Diffusive/dispersive case

$$\begin{cases} \frac{\partial u_\varepsilon}{\partial t} + \frac{\partial A(u)}{\partial x} = \varepsilon \frac{\partial^2 u}{\partial x^2} + \varepsilon^2 \frac{\partial^3 u}{\partial x^3} & x \in \mathbb{R}^N, t \geq 0 \\ u(\cdot, t=0) = u^0(x) \geq 0 \end{cases}$$

**Open question.** Is there a kinetic formulation ?  $\chi$  ?  $m$  ?

## Relax

With P.-L. Lions and P. E. Souganidis we used that formalism in a new context.

Shock waves are rare in biology



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## SHAMPOOING

Respectueux de la fibre, les shampooings Elseve hydratent et subliment instantanément la chevelure emportée par leurs textures fondantes et leurs parfums. Découvrez également les shampooings sans silicone sans colorant Botanicals.



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## Rough SCL

We want to find  $u(x, t)$  solution of

$$\begin{cases} du + \sum_{i=1}^N \frac{\partial}{\partial x_i} A_i(u) \circ dW^i(t) = 0 & x \in \mathbb{R}^N, t \geq 0 \\ u(x, t = 0) = u^0(x) \end{cases}$$

$$\mathbf{A} = (A_1, \dots, A_N) \in C^2(\mathbb{R}; \mathbb{R}^N), \quad (\text{Flux})$$

$$\mathbf{W} = (W^1, \dots, W^N) \in C([0, \infty); \mathbb{R}^N),$$

two special cases being

$$\mathbf{W} = (B^1, \dots, B^N) \quad (N\text{-dimensional Brownian motion})$$

$$\mathbf{W}(t) = (t, \dots, t) \quad (\text{Standard SCL, Kruzkov})$$

## Rough SCL

We want to find  $u(x, t)$  solution of

$$\begin{cases} du + \sum_{i=1}^N \frac{\partial}{\partial x_i} A_i(u) \circ dW^i(t) = 0 & x \in \mathbb{R}^N, t \geq 0 \\ u(\cdot, t=0) = u^0(x) \end{cases}$$

**Difficulty.** Even if  $u \in BV_t$ , for  $\mathbf{W} = (W^1, \dots, W^N) \in C([0, \infty); \mathbb{R}^N)$ , one cannot define the product

$$A_i(u) \circ \frac{dW^i(t)}{dt}$$

What is a solution ?

## Rough SCL

**Theorem (Pathwise entropy solutions)** There is a unique 'kinetic pathwise solution'

- for a given  $\mathbf{W}$

$$\|u_2(\cdot, t) - u_1(\cdot, t)\|_{L^1(\mathbb{R}^N)} \leq \|u_2^0 - u_1^0\|_{L^1(\mathbb{R}^N)}.$$



## Rough SCL

**Theorem (Pathwise entropy solutions)** There is a unique 'kinetic pathwise solution'

- for a given  $\mathbf{W}$

$$\|u_2(\cdot, t) - u_1(\cdot, t)\|_{L^1(\mathbb{R}^N)} \leq \|u_2^0 - u_1^0\|_{L^1(\mathbb{R}^N)}.$$

- for two paths  $\mathbf{W}_1 \in C(\mathbb{R}^N)$ ,  $\mathbf{W}_2 \in C(\mathbb{R}^N)$  and  $u_i^0 \in BV(\mathbb{R}^N)$ , then

$$\begin{aligned} \|u_2(\cdot, t) - u_1(\cdot, t)\|_{L^1(\mathbb{R}^N)} \leq & \|u_2^0 - u_1^0\|_{L^1(\mathbb{R}^N)} \\ & + C |(\mathbf{W}_1 - \mathbf{W}_2)(t)| + C \sup_{s \in (0, t)} |(\mathbf{W}_1 - \mathbf{W}_2)(s)|^{1/2} \end{aligned}$$

## Rough SCL

### Related works :

- Flandoli Stochastic perturbations

$$du + \operatorname{div}(bu) + dB(t) \circ \nabla u = 0 \quad (\text{Stratonovich})$$

$$\iff$$

$$du + \operatorname{div}(bu) + dB(t) \cdot \nabla u = \Delta u \quad (\text{It\^o})$$

Extensions to perturbations of Vlasov/Navier-Stokes style equations

- Feng & Nualart, Holden-Risebro, Debussche, Vovelle, Hofmanova, Berthelin, G.-Q Chen, Q. Ding and K. Karlsen

$$du + \operatorname{div}A(u) = F(u) \cdot dW(t)$$

## Rough SCL

We use methods from :

- Lions & Souganidis : **Topological point of view**

$$du = F(D^2u; Du)dt + \sum_{i=1}^m H_i(Du) \circ dW_i$$

$$du = F(D^2u; Du)dt + \sum_{i=1}^m \Phi_i(u) \circ dW_i$$

Principles :

- Pathwise
- Use characteristics for short times (iterate-Trotter)
- Lyons, Fritz, Gubinelli, Hairer...
  - Rough paths..  $\frac{d}{dt}X(t) = \sigma(X(t)).\dot{W}(t)$

## Outlines

1. Difficulties related to  $dW(t)$
2. How do we define a solution ?
3. Can one prove existence, uniqueness ?
4. The  $x$ -dependant case
5. Stochastic averaging lemmas

## Hyperbolic equations and shocks

$$\begin{cases} du + \sum_{i=1}^N \frac{\partial}{\partial x_i} A_i(u) \circ dW^i(t) = 0 & x \in \mathbb{R}^N, t \geq 0 \\ u(, t = 0) = u^0(x) \end{cases}$$

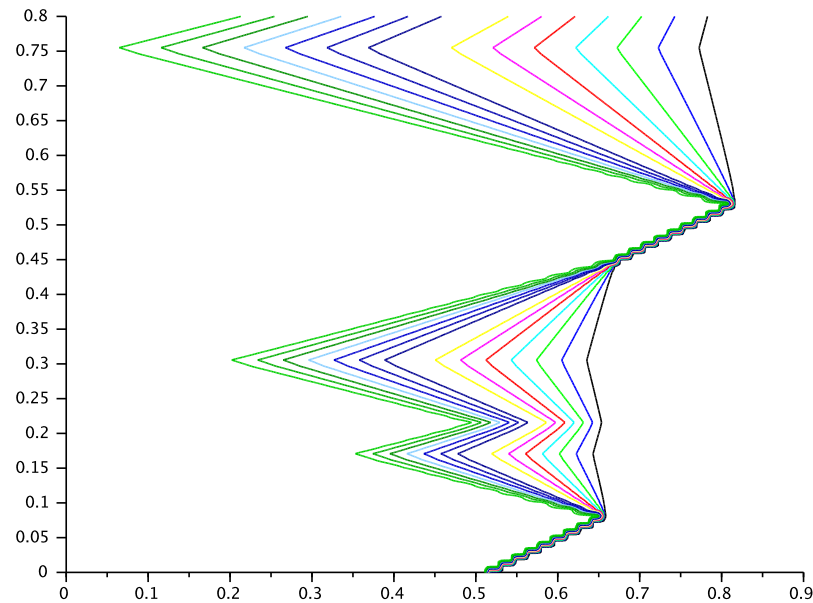
$$\frac{\partial}{\partial t} S(u) + \sum_{i=1}^N \frac{\partial}{\partial x_i} \eta_i(u) \circ dW^i(t) \leq 0, \quad \forall S(\cdot) \text{ convex.}$$

- Motivates the notation ‘ $\circ$ ’ as in Stratonowich form
- Irreversible in time. We **cannot** write in 1 dimension,

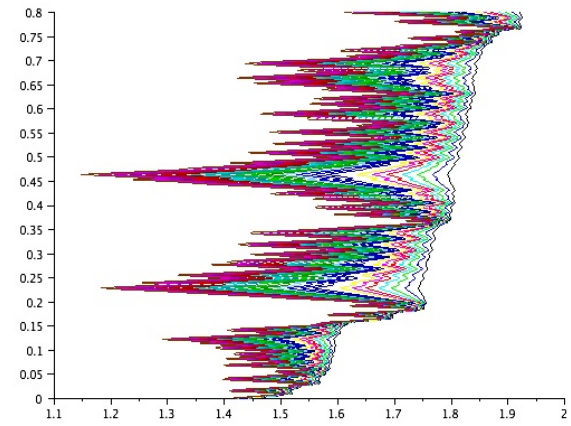
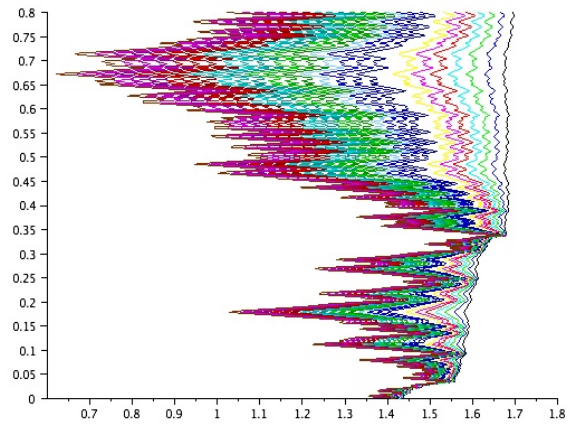
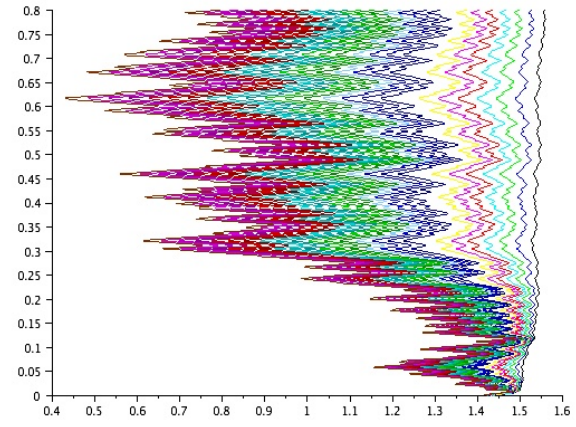
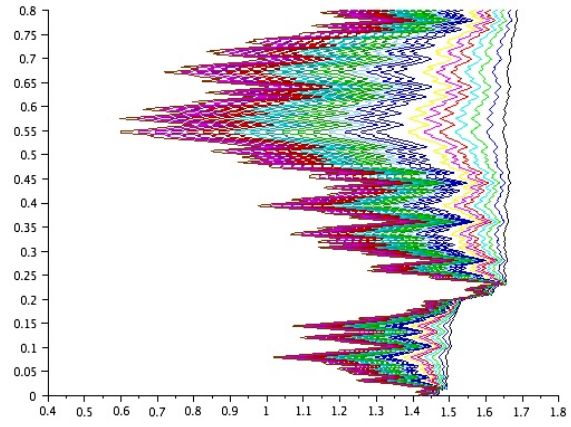
$$u(x, t) = \bar{u}(x, W(t))$$

$$d\bar{u}(x, W(t)) = -\frac{\partial}{\partial x} A(\bar{u}(x, W(t))) \circ dW(t)$$

## Hyperbolic equations and shocks



- Usual method : BV estimates (might be correct in  $x$ , not in  $t$ )
- Compensated compactness (Murat-Tartar)
- Kinetic formulation (Lions, BP, Tadmor)



## What do we want ?

$$\begin{cases} du + \sum_{i=1}^N \frac{\partial}{\partial x_i} A_i(u) \circ dW^i(t) = 0 & \text{in } \mathbb{R}^N \times (0, \infty), \\ u = u^0 & \text{on } \mathbb{R}^N \times \{0\}. \end{cases}$$

$$\mathbf{W} = (W^1, \dots, W^N) \in C([0, \infty); \mathbb{R}^N), \quad \mathbf{A} = (A_1, \dots, A_N) \in C^2(\mathbb{R}; \mathbb{R}^N),$$

$$\mathbf{a}(\mathbf{u}) = \mathbf{A}' = (A'_1(u), \dots, A'_N(u)), \quad (\text{Velocity})$$

- **Entropy dissipation** : For  $S$  convex

$$\begin{cases} dS(u) + \sum_{i=1}^N \frac{\partial}{\partial x_i} \eta_i(u) \circ dW^i \leq 0, \\ \eta_i(u)' = a_i(u) S'(u) \quad a_i = A'_i \end{cases}$$

(Stratonovich, no additional entropy dissipation)



## What do we want ?

- If we use Itô formula we lose the entropy ! We take expectations

$$\frac{d}{dt} \mathbb{E}(u^2) = \mathbb{E}(ua(u)^2(u_x)^2)$$

No possible control of the RHS (shocks)

- For  $W$  continuous and  $u(t) \in BV_x$ , we cannot obtain  $BV$  in time

$$\frac{du}{dt} = \dot{W}(t) \frac{\partial}{\partial x} u(x, t)$$

No control.

- What does it mean to be a solution ?

## How do we define a solution ?

As in **Debussche & Vovelle**, we use the kinetic formulation

$$\chi(x, \xi, t) = \chi(u(x, t), \xi) = \begin{cases} +1 & \text{if } 0 \leq \xi \leq u(x, t), \\ -1 & \text{if } u(x, t) \leq \xi \leq 0, \\ 0 & \text{otherwise.} \end{cases}$$

$$\begin{cases} d\chi + \sum_{i=1}^N a_i(\xi) \frac{\partial}{\partial x_i} \chi \circ dW^i = \frac{\partial}{\partial \xi} m dt & \text{in } (x, \xi, t) \in \mathbb{R}^N \times \mathbb{R} \times (0, \infty), \\ m(x, \xi, t) \geq 0 \end{cases}$$

Equivalent to the **Entropy dissipation**

$$\frac{\partial}{\partial t} S(u) + \sum_{i=1}^N \frac{\partial}{\partial x_i} \eta_i(u) \circ dW^i(t) \leq 0, \quad \forall S(\cdot) \text{ convex.}$$

## How do we define a solution ?

Because

$$S(u(x, t)) = \int_{\mathbb{R}} S'(\xi) \chi(x, \xi, t) d\xi$$

$$\frac{\partial}{\partial t} S(u) + \sum_{i=1}^N \frac{\partial}{\partial x_i} \eta_i(u) \circ dW^i(t) \leq 0, \quad \forall S(\cdot) \text{ convex.}$$

$$\frac{\partial}{\partial t} \int_{\mathbb{R}} S'(\xi) \chi(x, \xi, t) d\xi + \sum_{i=1}^N \frac{\partial}{\partial x_i} \int_{\mathbb{R}} S'(\xi) a_i(\xi) \chi(x, \xi, t) d\xi \leq 0$$

$$\begin{cases} d\chi + \sum_{i=1}^N a_i(\xi) \frac{\partial}{\partial x_i} \chi \circ dW^i = \frac{\partial}{\partial \xi} m dt & \text{in } (x, \xi, t) \in \mathbb{R}^N \times \mathbb{R} \times (0, \infty), \\ m(x, \xi, t) \geq 0 \end{cases}$$

## How do we define a solution ?

We can define solutions **along the characteristics**

$$\dot{X}(t) = a(\xi)\dot{W}, \quad \dot{\xi} = 0,$$

$$\frac{d}{dt}\chi(x - a(\xi)W(t), \xi, t) = \frac{\partial}{\partial \xi}m(x - a(\xi)W(t), \xi, t)$$

These are globally defined (at variance with the case of H.-J. eq.)

- We show continuity with respect to  $W$  in  $C^0$
- Uniqueness proof based on kinetic formulation  
(uses regularization in  $(x, t)$  rather than variable doubling)

## How do we define a solution ?

**Definition.** We 'regularize along the characteristics. Consider

$$\begin{cases} \rho^0 \in \mathcal{D}(\mathbb{R}^N) \quad \text{such that} \quad \rho^0 \geq 0 \quad \text{and} \quad \int_{\mathbb{R}^N} \rho^0(x) dx = 1, \\ \rho(y, x, \xi, t) = \rho^0(y - x + \mathbf{a}(\xi)\mathbf{W}(t)), \end{cases}$$

solves formally the linear transport equation

$$d\rho + \sum_{i=1}^N a_i(\xi) \frac{\partial}{\partial x_i} \rho \circ dW^i = 0 \quad \text{in} \quad \mathbb{R}^N \times \mathbb{R} \times (0, \infty),$$

and, hence,

$$d(\rho(y, x, \xi, t)\chi(x, \xi, t)) + \sum_{i=1}^N a_i(\xi) \frac{\partial}{\partial x_i} \rho \chi \circ dW^i = \rho(y, x, \xi, t) \frac{\partial}{\partial \xi} m(x, \xi, t) dt.$$

$$\frac{d}{dt} \int_{\mathbb{R}^N} \chi(x, \xi, t) \rho(y, x, \xi, t) dx = - \int_{\mathbb{R}^N} \frac{\partial}{\partial \xi} \rho(y, x, \xi, t) m(x, \xi, t) dx.$$

## Can one prove existence, uniqueness ?

**Theorem (Pathwise entropy solutions)** There is a unique 'kinetic pathwise solution'

- for a given  $\mathbf{W}$

$$\|u_2(\cdot, t) - u_1(\cdot, t)\|_{L^1(\mathbb{R}^N)} \leq \|u_2^0 - u_1^0\|_{L^1(\mathbb{R}^N)}.$$

- for two paths  $\mathbf{W}_i$  and  $u_i^0 \in BV(\mathbb{R}^N)$ , then  $u_1$  and  $u_2$  satisfy

$$\begin{aligned} \|u_2(\cdot, t) - u_1(\cdot, t)\|_{L^1(\mathbb{R}^N)} \leq & \|u_2^0 - u_1^0\|_{L^1(\mathbb{R}^N)} \\ & + |(\mathbf{W}_1 - \mathbf{W}_2)(t)| \|\mathbf{a}\| (|u_1^0|_{BV(\mathbb{R}^N)} + |u_2^0|_{BV(\mathbb{R}^N)}) \\ & + \left( \sup_{s \in (0, t)} |(\mathbf{W}_1 - \mathbf{W}_2)(s)| \|\mathbf{a}'\| [\|u_1^0\|_{L^2(\mathbb{R}^N)}^2 + \|u_2^0\|_{L^2(\mathbb{R}^N)}^2] \right)^{1/2}. \end{aligned}$$

Conclude...

## Space dependent case

$$\begin{cases} du + \sum_{i=1}^N \frac{\partial}{\partial x_i} A_i(x, u) \circ dW(t) = 0 & \text{in } \mathbb{R}^N \times (0, \infty), \\ u = u^0 & \text{on } \mathbb{R}^N \times \{0\}. \end{cases}$$

Only one  $W(t)$  !

Kinetic formulation **A.-L. Dalibard**

$$d\chi + \sum_{i=1}^N a_i(x, \xi) \frac{\partial}{\partial x_i} \chi \circ dW(t) - b(x, \xi) \frac{\partial}{\partial \xi} \chi \circ dW(t) = \frac{\partial}{\partial \xi} m dt$$

$$a_i(x, \xi) = \frac{\partial}{\partial x_i} A_i(x, \xi), \quad b(x, \xi) = \sum_i \frac{\partial}{\partial \xi} A_i(x, \xi).$$

## Space dependent case

We test against smooth convolution kernels ‘along characteristics’

$$d\rho + \sum_{i=1}^N a_i(x, \xi) \frac{\partial}{\partial x_i} \rho \circ dW(t) - b(x, \xi) \frac{\partial}{\partial \xi} \rho \circ dW(t) = 0.$$

And these are given by

$$\rho(x, \xi, t) = \hat{\rho}(x, \xi, W(t)),$$

with

$$\frac{\partial}{\partial t} \hat{\rho} + \sum_{i=1}^N a_i(x, \xi) \frac{\partial}{\partial x_i} \hat{\rho} - b(x, \xi) \frac{\partial}{\partial \xi} \hat{\rho} = 0.$$

**Definition** A stochastic kinetic solution is defined by

$$\frac{d}{dt} \int \rho(x, \xi, t) \chi(x, \xi, t) dx d\xi = - \int m(x, \xi, t) \frac{\partial}{\partial \xi} \rho(x, \xi, t).$$



## Space dependent case

**Theorem** There is a unique stochastic kinetic solution and for a given  $W$

$$\|u_2(\cdot, t) - u_1(\cdot, t)\|_{L^1(\mathbb{R}^N)} \leq \|u_2^0 - u_1^0\|_{L^1(\mathbb{R}^N)}.$$

- Existence is through weak limits
- Uniqueness of ‘kinetic solutions’
- Continuous dependency on  $W(t)$  is NOT proved
- Iterate small time steps à la Lions-Souganidis

## Space dependent case

Extension to multiple  $W^i(t)$

$$\begin{cases} du + \sum_{i=1}^N \frac{\partial}{\partial x_i} A_i(x, u) \cdot dZ^i(t) = 0 & \text{in } \mathbb{R}^N \times (0, \infty), \\ u = u^0 & \text{on } \mathbb{R}^N \times \{0\}. \end{cases}$$

B. Guess and Souganidis, Deya, Gubinelli, Hofmanova and Tindel.

We need a notion characteristics

$$dX_i = a_i(X, \Xi) dZ^i(t), \quad d\Xi(t) = -b(X, \Xi) \cdot d\mathbf{Z}(t)$$

and the theory of rough paths is the tool to do that.

## Stochastic averaging lemmas

It is difficult to resist the idea to consider simply

$$\begin{cases} \frac{\partial}{\partial t} f(x, \xi, t) + \dot{B}(t) \circ \xi \cdot \nabla_x f = g(x, \xi, t) & \text{in } \mathbb{R}^{2d} \times (0, \infty), \\ f(0) = f^0 & \text{on } \mathbb{R}^{2N}. \end{cases}$$

The notation for the flux means

$$\dot{B}(t) \circ \xi \cdot \nabla_x f = \dot{B}(t) \sum_{i=1}^N \xi_i \frac{\partial f}{\partial x_i}.$$

And the Stratonovich solution

$$\frac{d}{dt} f(x - B(t)\xi, \xi, t) = g(x - B(t)\xi, \xi, t).$$

## Stochastic averaging lemmas

$$\begin{cases} \frac{\partial}{\partial t} f(x, \xi, t) + \dot{B}(t) \circ \xi \cdot \nabla_x f = g(x, \xi, t) & \text{in } \mathbb{R}^{2N} \times (0, \infty), \\ f(0) = f^0 & \text{on } \mathbb{R}^{2N}. \end{cases}$$

Kinetic averaging lemma aim to prove regularity for

$$\rho_\psi(x, t) = \int_{\mathbb{R}^N} \psi(\xi) f(x, \xi, t) d\xi$$

with  $\psi$  a smooth function with compact support.

## Stochastic averaging lemmas

$$\begin{cases} \frac{\partial}{\partial t} f(x, \xi, t) + \xi \cdot \nabla_x f = g(x, \xi, t) & \text{in } \mathbb{R}^{2N} \times (0, \infty), \\ f(0) = f^0 & \text{on } \mathbb{R}^{2N}. \end{cases}$$

**Theorems (Deterministic averaging).** Take  $B(t) = t$ .

For  $g = 0$  and  $\lambda \geq 0$

$$\|e^{-\lambda t} \rho_\psi\|_{L^2(\mathbb{R}^+; \dot{H}^{1/2}(\mathbb{R}^N))}^2 \leq C(\psi) \|f^0\|_{L^2(\mathbb{R}^N \times \mathbb{R}^N)}^2$$

For  $f^0 = 0$

$$\|\rho_\psi\|_{L^2(\mathbb{R}^+; \dot{H}^{1/2}(\mathbb{R}^N))}^2 \leq C \|g\|_{L^2(\mathbb{R}^+ \times \mathbb{R}^N \times \mathbb{R}^N)} \|f\|_{L^2(\mathbb{R}^+ \times \mathbb{R}^N \times \mathbb{R}^N)}$$

For  $f^0 = 0$  and  $g = \operatorname{div}_\xi h$ , we have

$$\|\rho_\psi\|_{L^2(\mathbb{R}^+; \dot{H}^{1/4}(\mathbb{R}^N))}^2 \leq C \|h\|_{L^2(\mathbb{R}^+ \times \mathbb{R}^N \times \mathbb{R}^N)}^{1/2} \|f\|_{L^2(\mathbb{R}^+ \times \mathbb{R}^N \times \mathbb{R}^N)}^{3/2}$$

## Stochastic averaging lemmas

Long story behind that : F. Golse, BP, R. Sentis (CRAS 1985),  
P.-L. Lions, Meyer, Gérard, Souganidis... Tadmor and Tao

The proof is inspired by the version in F. Bouchut and  
L. Desvillettes (no Fourier in time)

## Stochastic averaging lemmas

**Theorem** (Comparison deterministic/stochastic).

1. For  $g = 0$  and  $\lambda \geq 0$  we have

$$\|e^{-\lambda t} \rho_\psi\|_{L^2(R^+; \dot{H}^{1/2}(\mathbb{R}^N))}^2 \leq C(\psi) \|f^0\|_{L^2(\mathbb{R}^N \times \mathbb{R}^N)}^2.$$

$$\mathbb{E} \|e^{-\lambda t} \rho_\psi\|_{L^2(R^+; \dot{H}^{1/2}(\mathbb{R}^N))}^2 \leq \frac{C(\text{supp } \psi)}{\lambda^{1/2}} \|f^0\|_{L^2(\mathbb{R}^N \times \mathbb{R}^N)}^2.$$

## Stochastic averaging lemmas

**Theorem** (Comparison deterministic/stochastic).

2. For  $f^0 = 0$  we have

$$\|\rho_\psi\|_{L^2(\mathbb{R}^+; \dot{H}^{1/2}(\mathbb{R}^N))}^2 \leq C \|g\|_{L^2(\mathbb{R}^+ \times \mathbb{R}^N \times \mathbb{R}^N)} \|f\|_{L^2(\mathbb{R}^+ \times \mathbb{R}^N \times \mathbb{R}^N)}.$$

$$\mathbb{E} \|\rho_\psi\|_{L^2(\mathbb{R}^+; \dot{H}^{1/2}(\mathbb{R}^N))}^2 \leq C \|g\|_{L^2(\mathbb{R}^+ \times \mathbb{R}^N \times \mathbb{R}^N)}^{1/2} \|f\|_{L^2(\mathbb{R}^+ \times \mathbb{R}^N \times \mathbb{R}^N)}^{3/2}.$$



## Stochastic averaging lemmas

**Theorem** (Comparison deterministic/stochastic).

3. For  $f^0 = 0$  and  $g = \operatorname{div}_\xi h$ , we have

$$\|\rho_\psi\|_{L^2(\mathbb{R}^+; \dot{H}^{1/4}(\mathbb{R}^N))}^2 \leq C \|h\|_{L^2(\mathbb{R}^+ \times \mathbb{R}^N \times \mathbb{R}^N)}^{1/2} \|f\|_{L^2(\mathbb{R}^+ \times \mathbb{R}^N \times \mathbb{R}^N)}^{3/2}.$$

$$\mathbb{E} \|\rho_\psi\|_{L^2(\mathbb{R}^+; \dot{H}^{1/3}(\mathbb{R}^N))}^2 \leq C \|h\|_{L^2(\mathbb{R}^+ \times \mathbb{R}^N \times \mathbb{R}^N)}^{2/3} \|f\|_{L^2(\mathbb{R}^+ \times \mathbb{R}^N \times \mathbb{R}^N)}^{4/3}.$$

## Stochastic averaging lemmas

Idea of the proof.

$$\frac{\partial}{\partial t} \hat{f}(k, \xi, t) + i\dot{B}(t) \circ k \cdot \xi \hat{f} = \hat{g}.$$

$$\frac{\partial}{\partial t} \hat{f}(k, \xi, t) + i\dot{B}(t) \circ k \cdot \xi \hat{f} + \lambda \hat{f} = \hat{g} + \lambda \hat{f}.$$

$$\begin{aligned} \hat{f}(k, \xi, t) &= \hat{f}^0(k, \xi) e^{-\lambda t - iB(t)k \cdot \xi} \\ &\quad + \int_0^t e^{-\lambda s} [\hat{g} + \lambda \hat{f}](k, \xi, t - s) e^{ik \cdot \xi (B(t-s) - B(t))} ds \end{aligned}$$

## Stochastic averaging lemmas

$$|\widehat{\rho}_\psi(k, t)|^2 \leq 2 \left| \int \psi \widehat{f}^0(k, \xi) e^{-\lambda t - iB(t)k \cdot \xi} d\xi \right|^2 \\ + 2 \left| \int_0^t \int e^{-\lambda s} [\psi \widehat{g} + \lambda \psi \widehat{f}](k, \xi, t - s) e^{ik \cdot \xi (B(t-s) - B(t))} ds d\xi \right|^2.$$

For  $g = 0$

$$\leq \mathbb{E} \int_{t=0}^{\infty} \int \psi \widehat{f}^0(k, \xi_1) \overline{\psi \widehat{f}^0(k, \xi_2)} e^{-2\lambda t - iB(t)k \cdot (\xi_1 - \xi_2)} d\xi_2 d\xi_1 dt$$

## Further reading

Conservation laws with  $x$ -dependency by [Guess and Souganidis](#)

Rough PDEs by [Deya, Gubinelli, Hofmanová, Tindel](#)

## Further reading

Thanks to my collaborators



## Question to Yann

The futur belongs to the past ?

**THANK YOU**