

Computational Methods for Blood flow

Associated Team “Cardio”

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Project-team REO

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INSTITUT NATIONAL
DE RECHERCHE
EN INFORMATIQUE
ET EN AUTOMATIQUE

centre de recherche PARIS - ROCQUENCOURT



Associated Team “Cardio”

Website: <https://idal-siege.inria.fr/cardio/>

Coordinator

- Irène Vignon-Clementel



Members

- Stanford (CVBRL, Dept Bioengineering & Mech Engng)
C. Taylor, A. Figueroa, N. Xiao, G. Troianowski,
J Feinstein, A Marsden, S Shadden, J Kim, R. Raghu
- INRIA:
 - Project-team REO: J-F. Gerbeau, M. Fernández, I. Vignon-Clementel, M. Astorino, C. Bertoglio, G. Troianowski
 - Project-team MACS: D. Chapelle, P. Moireau

Associated Team “Cardio”

Similar goals and complementary approaches

- Modeling the blood flow in large arteries
- Interaction simulation / medical data

Collaboration themes

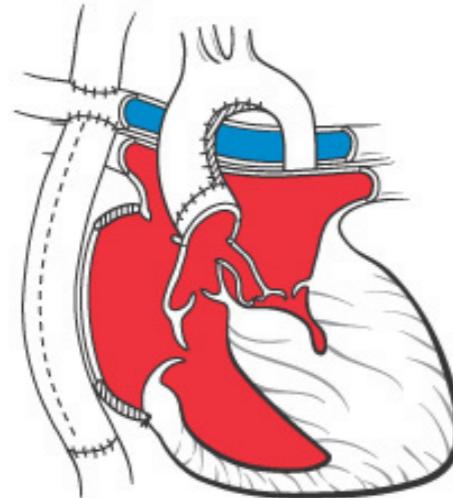
- Boundary conditions (fluid & fluid-structure)
- Advance post-processing techniques
- Image-based fluid-structure interaction

Outline

- Surgical planning
- Fluid-Structure Interaction in blood flows
- Medical Data assimilation / Inverse problems
- *Viscoelasticity (Rashmi Raghu, Stanford)*

Surgical planning

Total Extracardiac Conduit Fontan Palliation
of Hypoplastic Left Heart

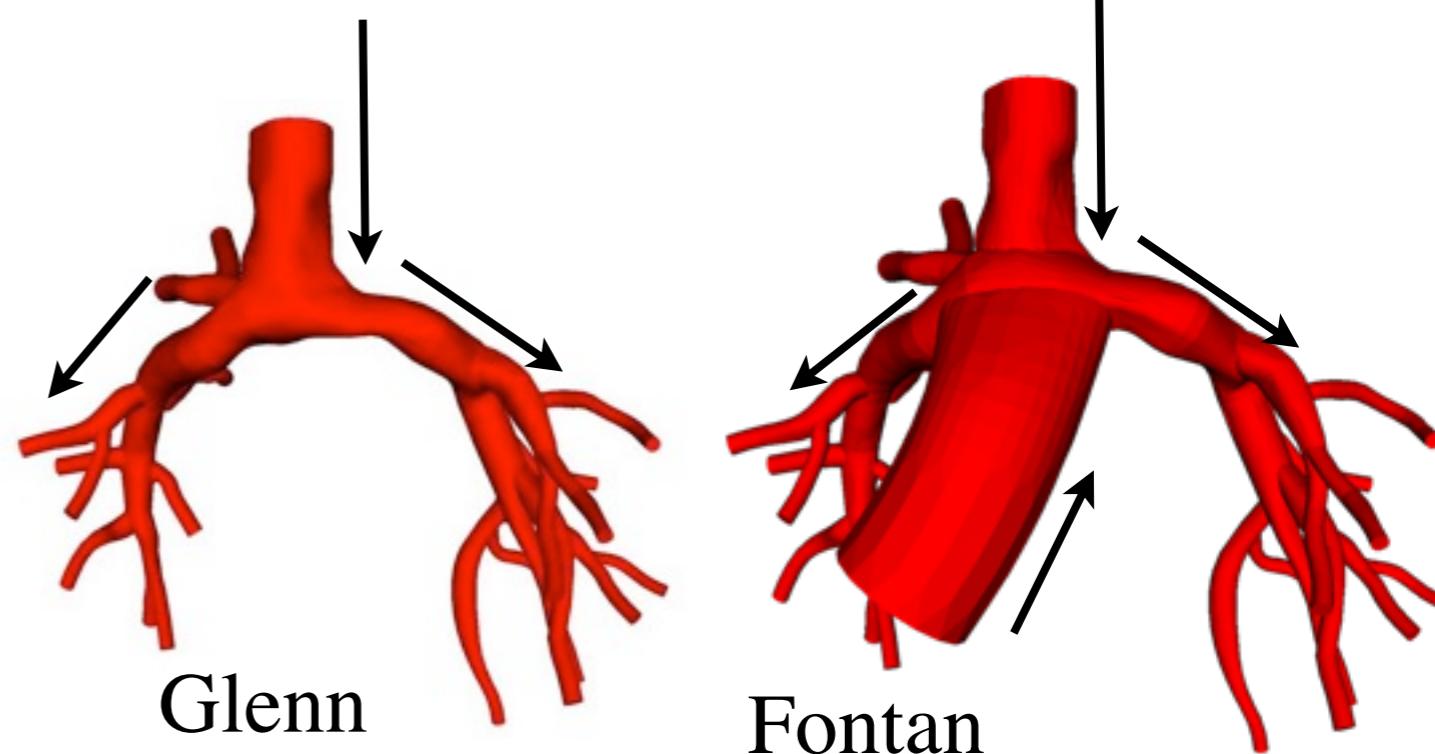


<http://www.americanheart.org>



Glenn-Fontan surgery

- congenital heart disease
- multi-step complex procedure

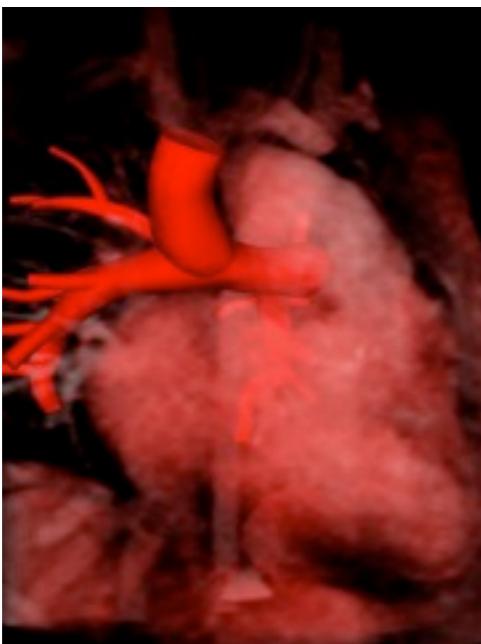
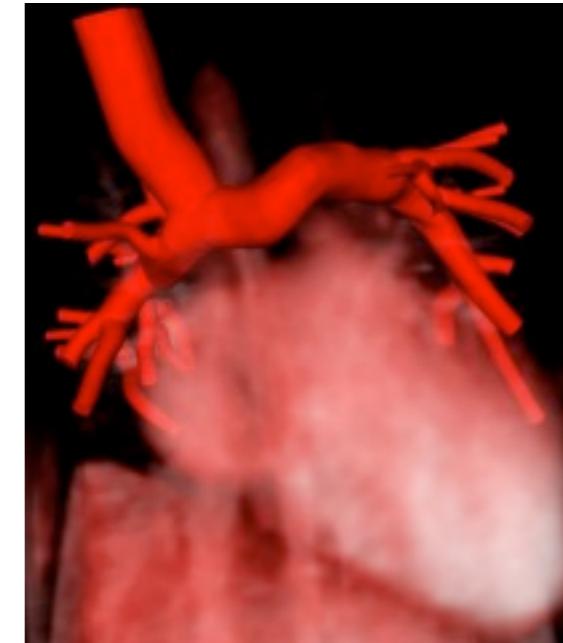


Numerical simulations

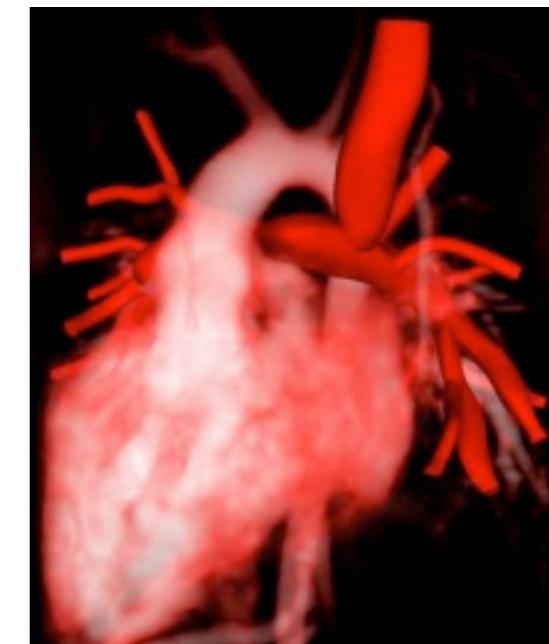
- Patient-specific geometries
- Forecast pressure drop, flow split, wall-shear stress

Troianowski, Taylor, Feinstein, Vignon-Clementel
Stanford/INRIA

Geometry from 5 patients MRI data

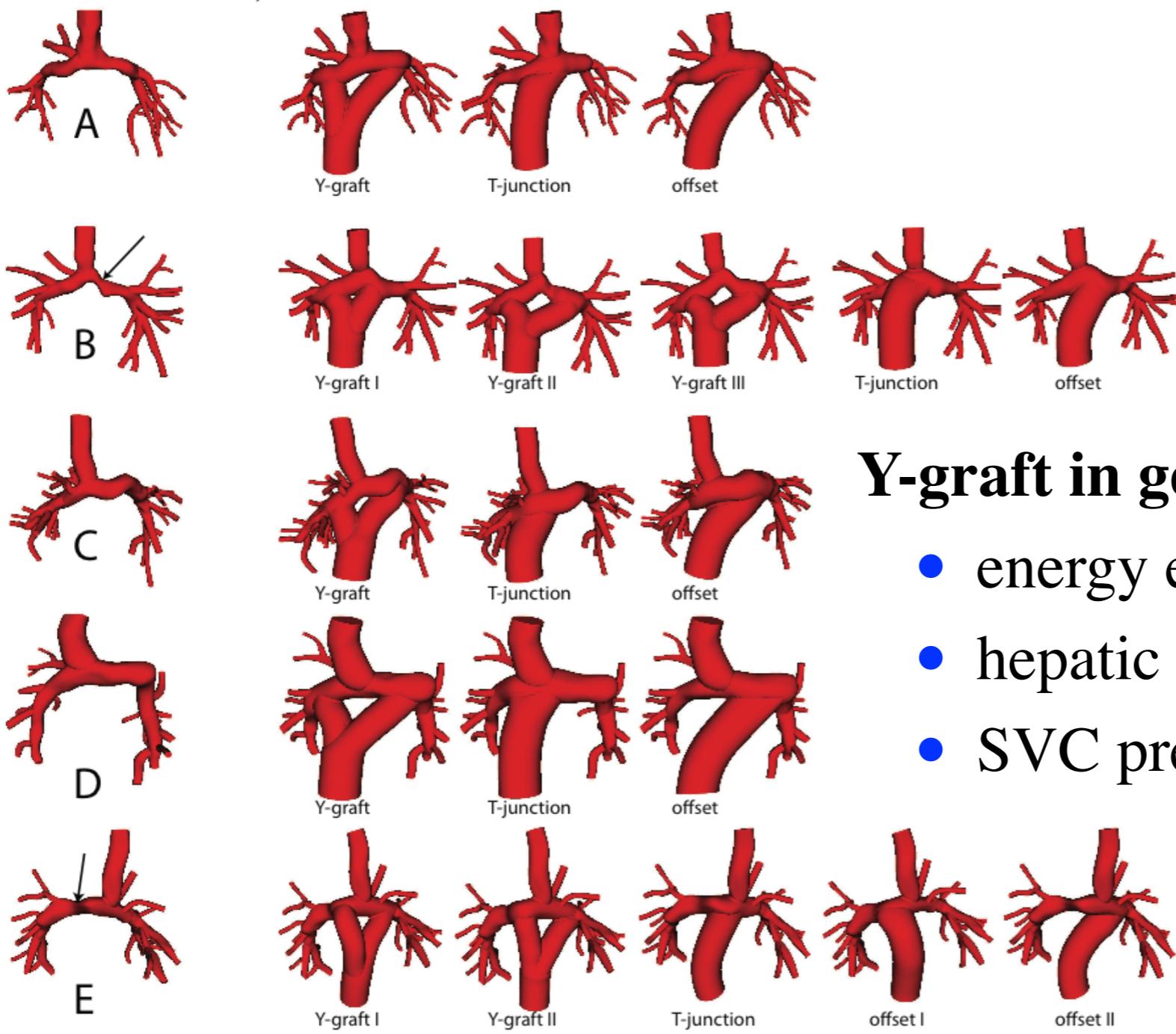


*Internships of A. Birolleau,
G. Troianowski*



Surgical planning

Glenn → Fontan

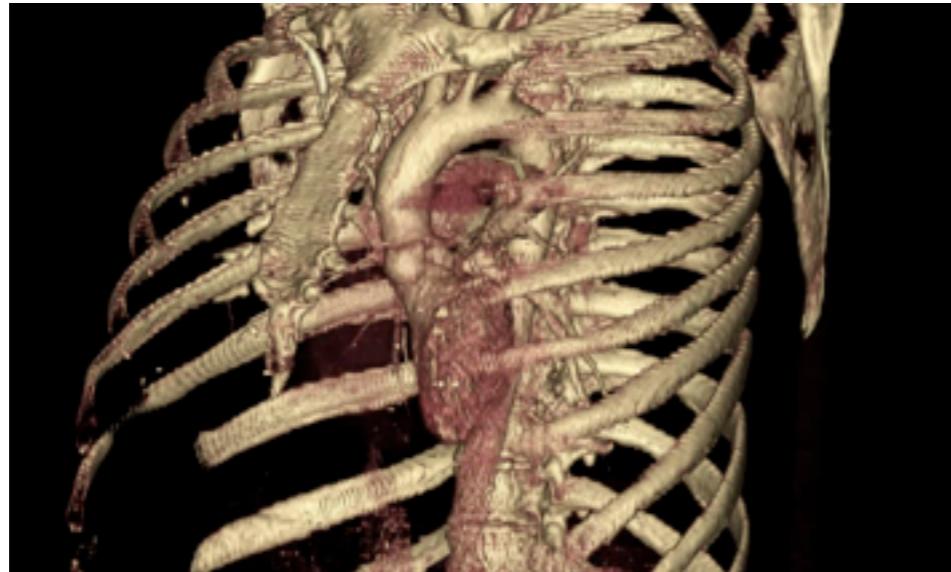


Y-graft in general improves:

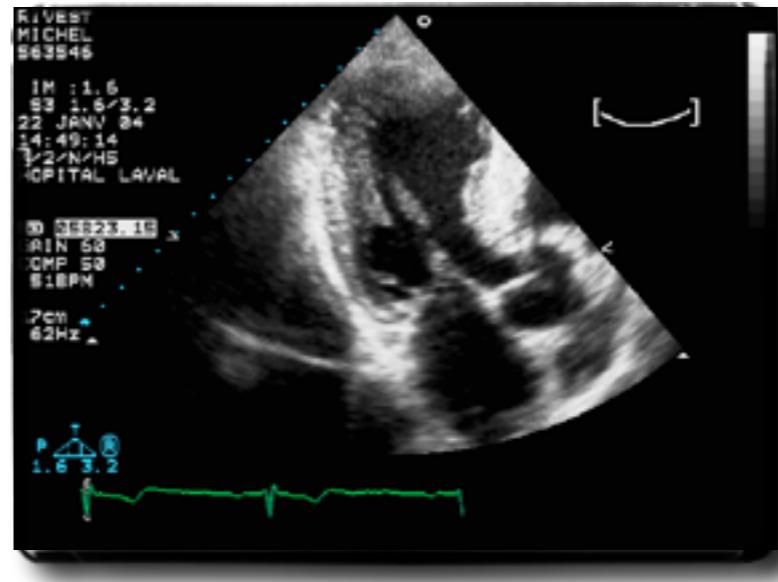
- energy efficiency
- hepatic flow distribution
- SVC pressure under rest & exercise

Troianowski, Taylor, Feinstein, Vignon-Clementel

Fluid-Structure Interaction

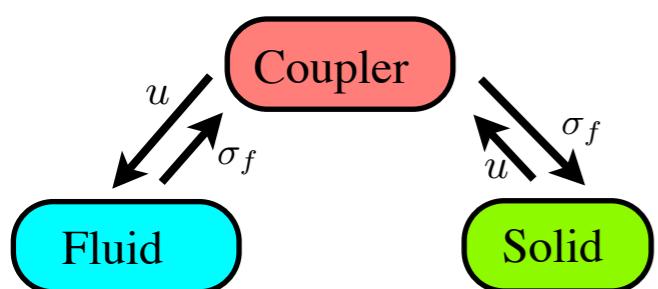


Aorta
(CVBRL, Stanford)



Cardiac valves
(Hôpital Laval)

$$\rho^f \left(\frac{\partial \mathbf{u}}{\partial t} \Big|_{\hat{x}} + (\mathbf{u} - \mathbf{w}) \cdot \nabla \mathbf{u} \right) - 2\mu \operatorname{div} \boldsymbol{\epsilon}(\mathbf{u}) + \nabla p = \mathbf{0}, \quad \text{in } \Omega^f(t)$$



$$\operatorname{div} \mathbf{u} = 0, \quad \text{in } \Omega^f(t)$$

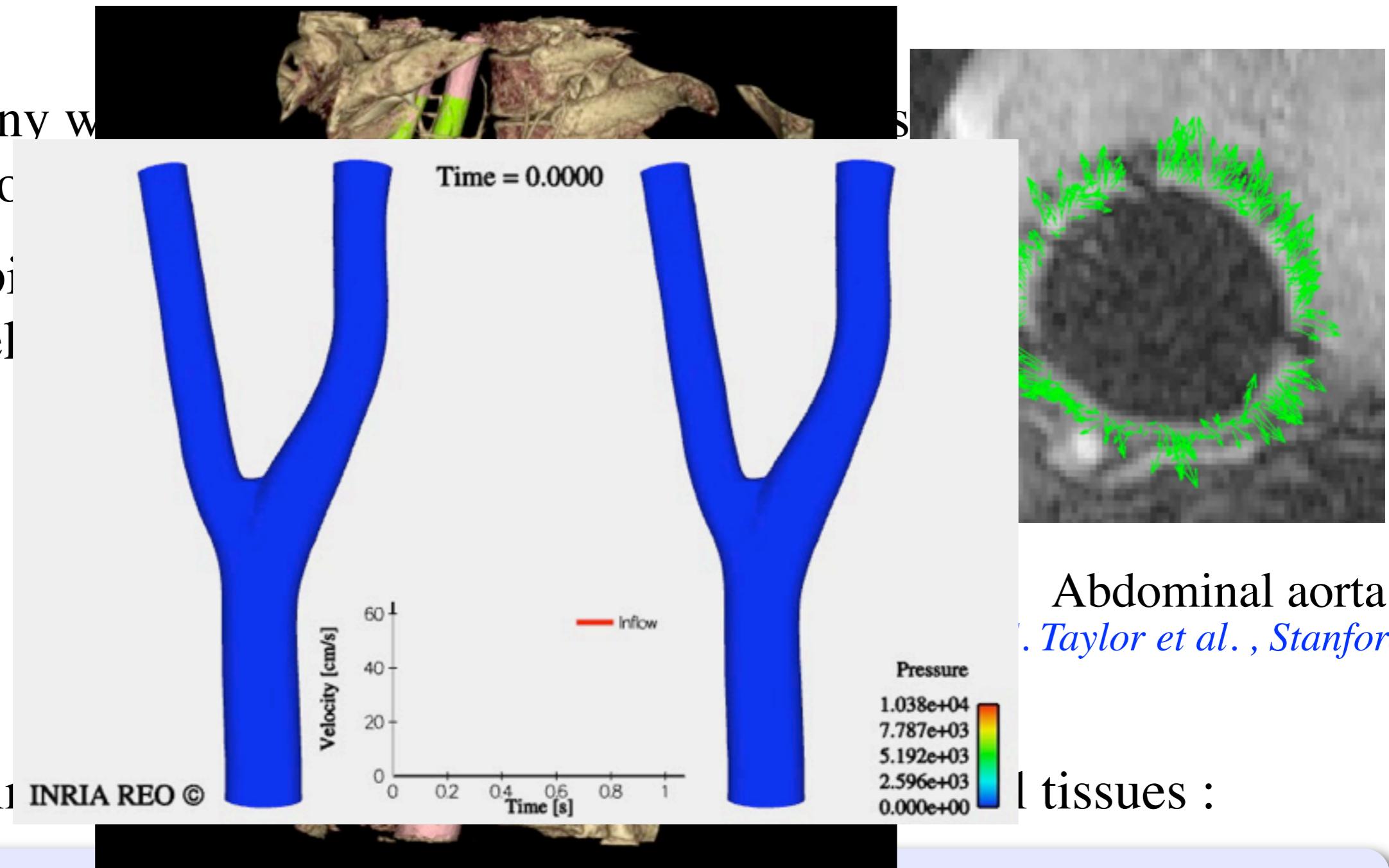
$$\rho^s \frac{\partial^2 \mathbf{d}}{\partial t^2} - \operatorname{div} (\mathbf{F}(\mathbf{d}) \mathbf{S}(\mathbf{d})) = \mathbf{0}, \quad \text{in } \widehat{\Omega}^s$$

Blood flow in aorta

- Many w

but no

- Typi
vessel

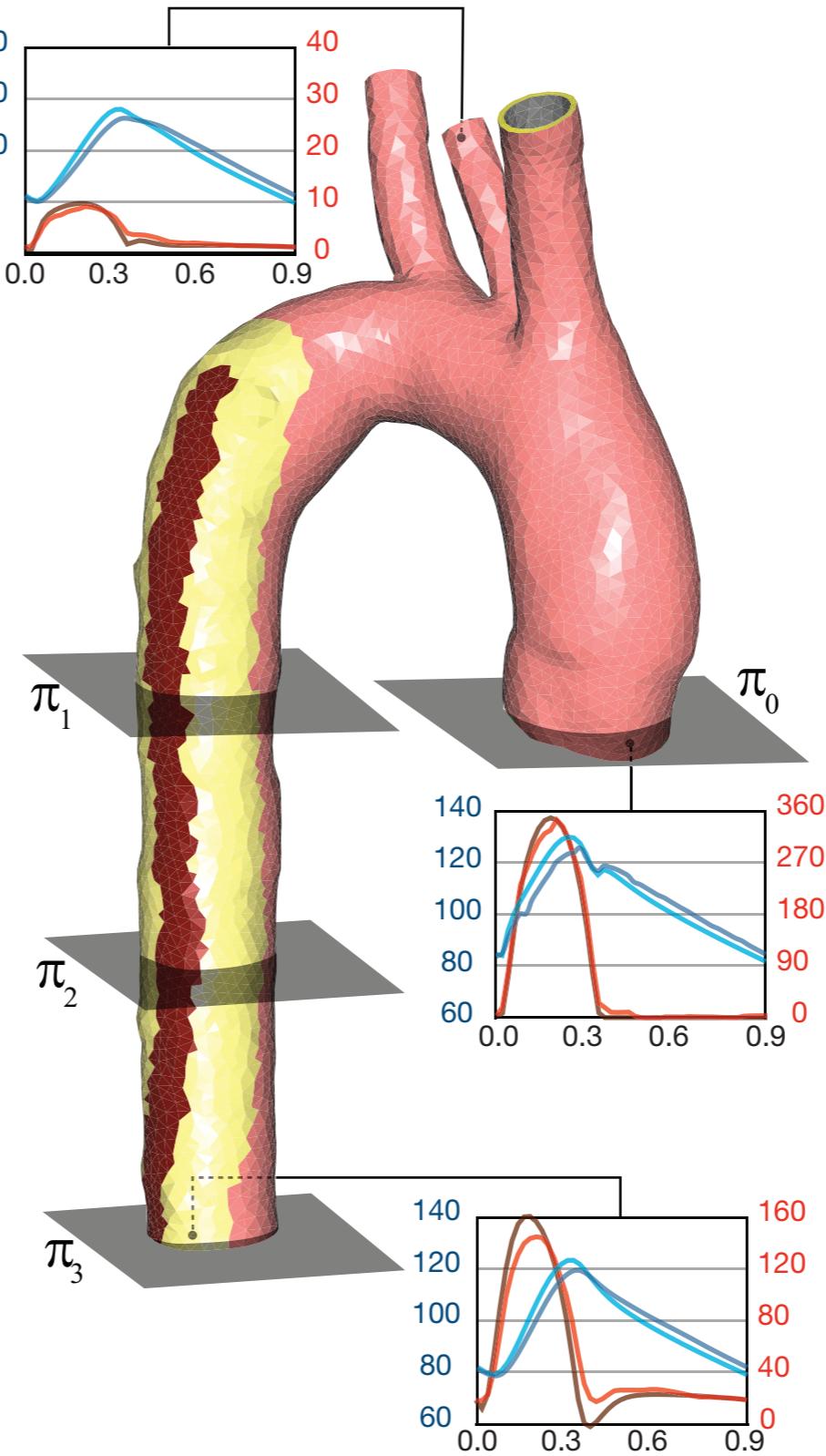
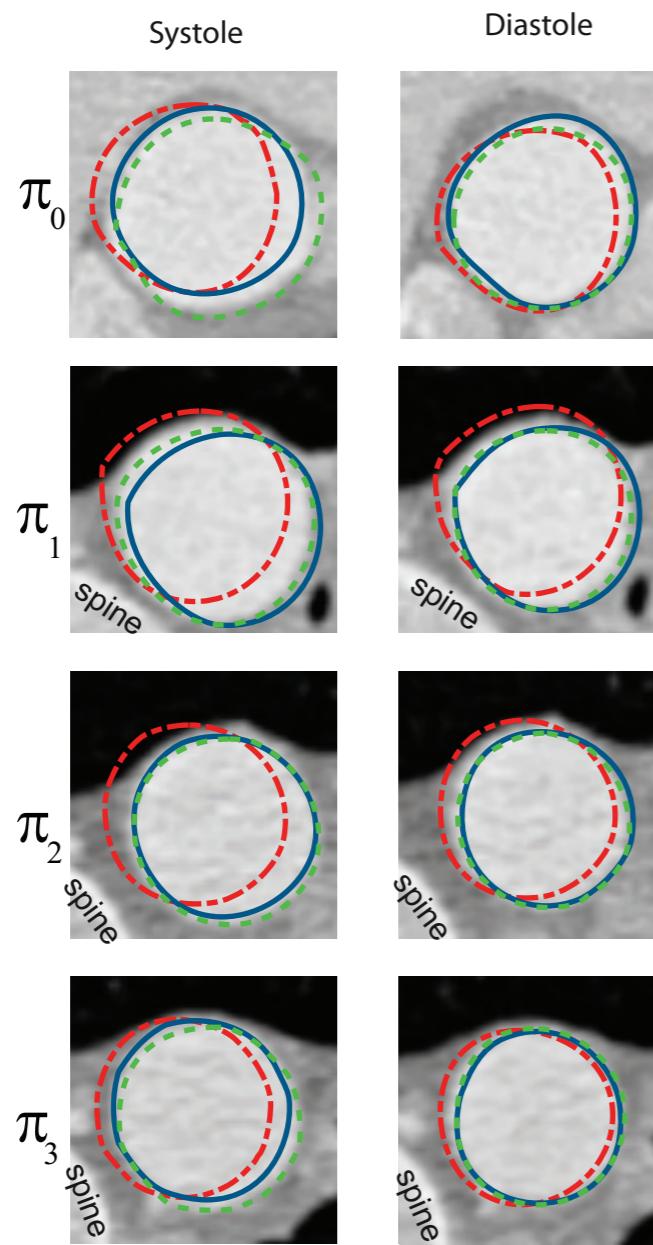
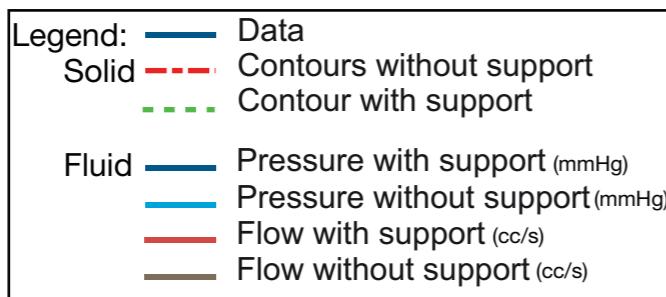


- A si INRIA REO ©

$$\sigma_s n = -k_s d - c_s \frac{\partial d}{\partial t}$$

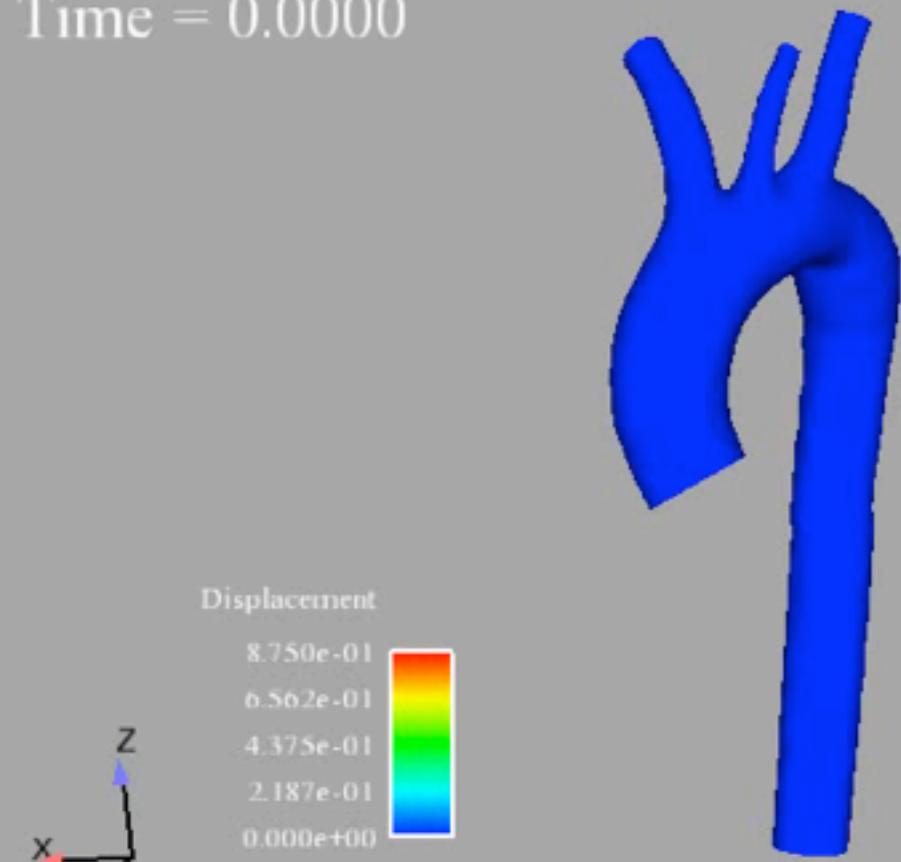
Blood flow in aorta

Comparison simulation / images

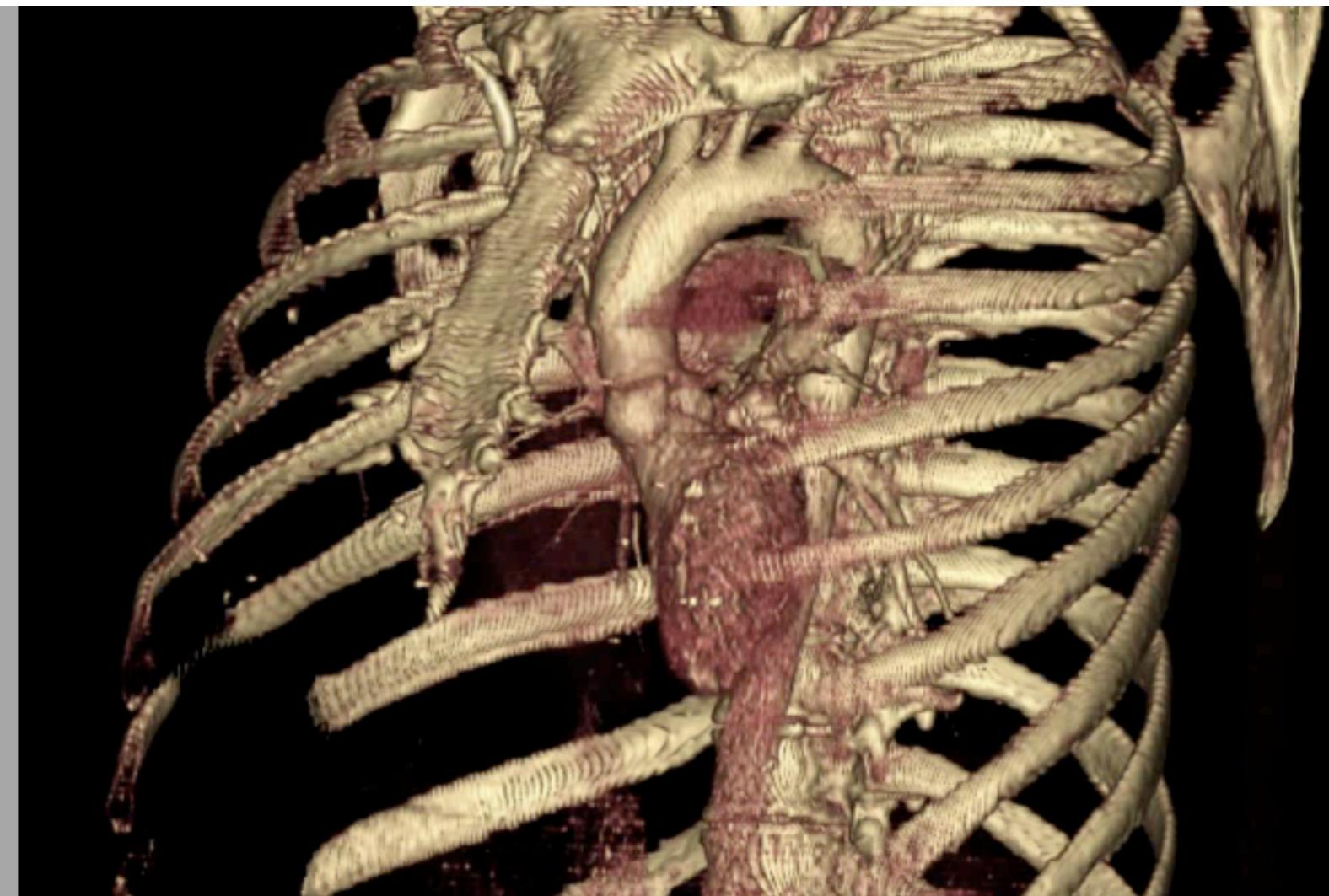


Medical Data Assimilation

Time = 0.0000



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CVBRL, Stanford

Data assimilation

- Reduce model uncertainties using observations
- Access to “hidden” quantities
- Smooth the data

Data assimilation in FSI

- FSI dynamical system:
$$\begin{cases} B\dot{X} &= A(X, \theta) + R \\ X(0) &= X_0 \end{cases}$$
- Time discretization: $X^{n+1} = F^{n+1}(X^n, \theta)$
- State variable: $X = [u, p, d^f, d, v]$
- Parameters: $\theta = [\text{Young modulus, viscosity, boundary conditions, ...}]$
- Uncertainties on the initial condition X_0 and the parameters θ
- Partial observations of X : $Z = H(X)$

Data assimilation

- **State estimation** through “simple” feedback terms.

For example, for velocity measurements:

$$M\ddot{X} + KX = f - \gamma H^T(H\dot{X} - Y_{obs})$$

Moireau, Chapelle, Le Tallec, 2008

- **Parameter estimation** : reduced Unscented Kalman filter (SEIK)

Dinh Tuan Pham, 2001

Moireau, Chapelle, 2009

- With respect to a variational approach: **no tangent, no adjoint**
- Counterpart : as many resolutions as parameters (“particles”)...
- ... but easy to run them in parallel

Data assimilation

Luenberger filter
for the state

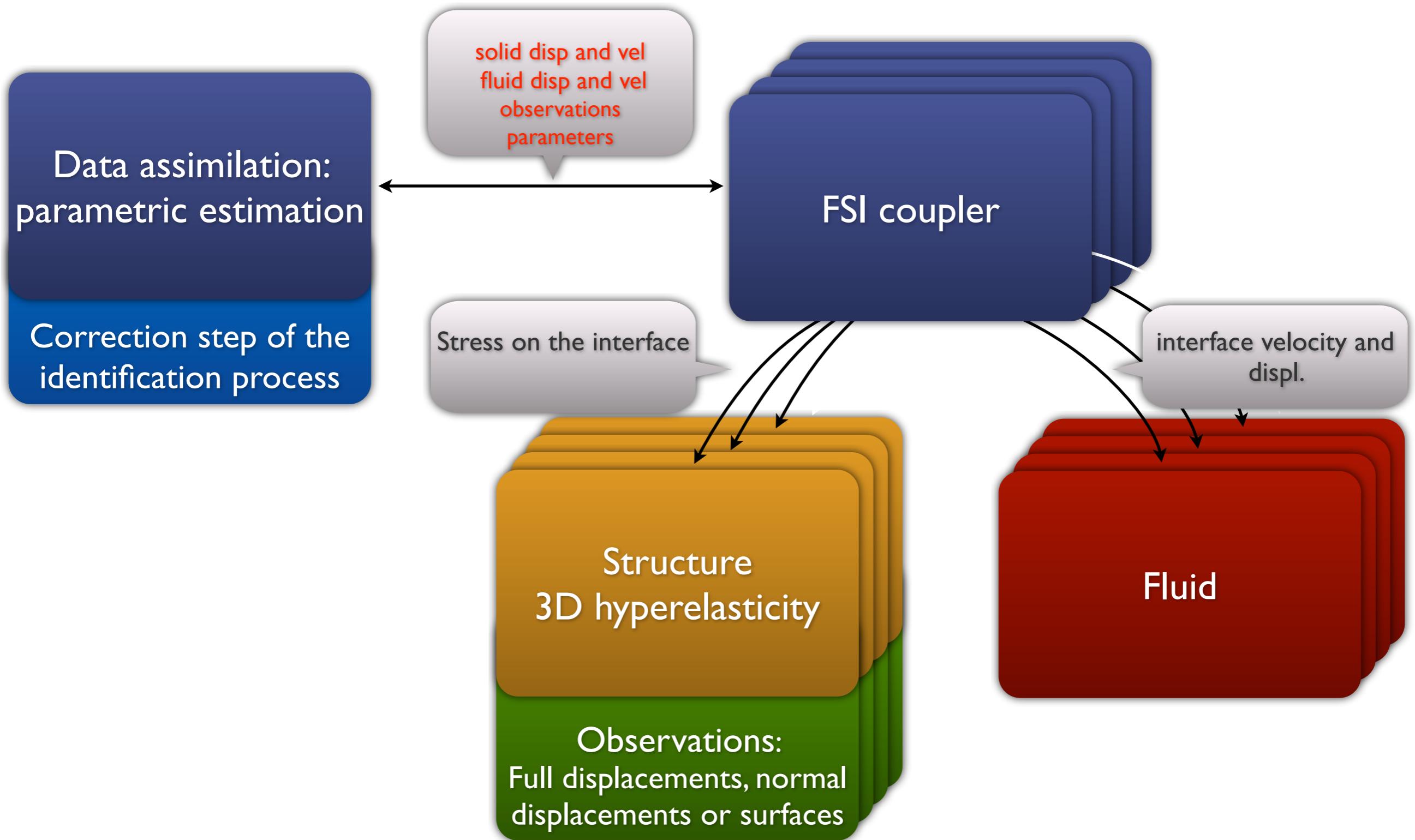
Summary

- Prediction:
$$\begin{cases} \hat{X}_-^{n+1} &= \hat{F}^{n+1}(\hat{X}_+^n, \theta_+^n, Z^{n+1}, K) \\ \hat{\theta}_-^{n+1} &= \hat{\theta}_+^n \end{cases}$$

- Correction:
$$\begin{cases} \hat{X}_+^{n+1} &= \hat{X}_-^{n+1} + \hat{K}_X^{n+1}(Z^{n+1} - H(\hat{X}_-^{n+1})) \\ \hat{\theta}_+^{n+1} &= \hat{\theta}_-^{n+1} + \hat{K}_\theta^{n+1}(Z^{n+1} - H(\hat{X}_-^{n+1})) \end{cases}$$

Kalman-like filter
for the parameters

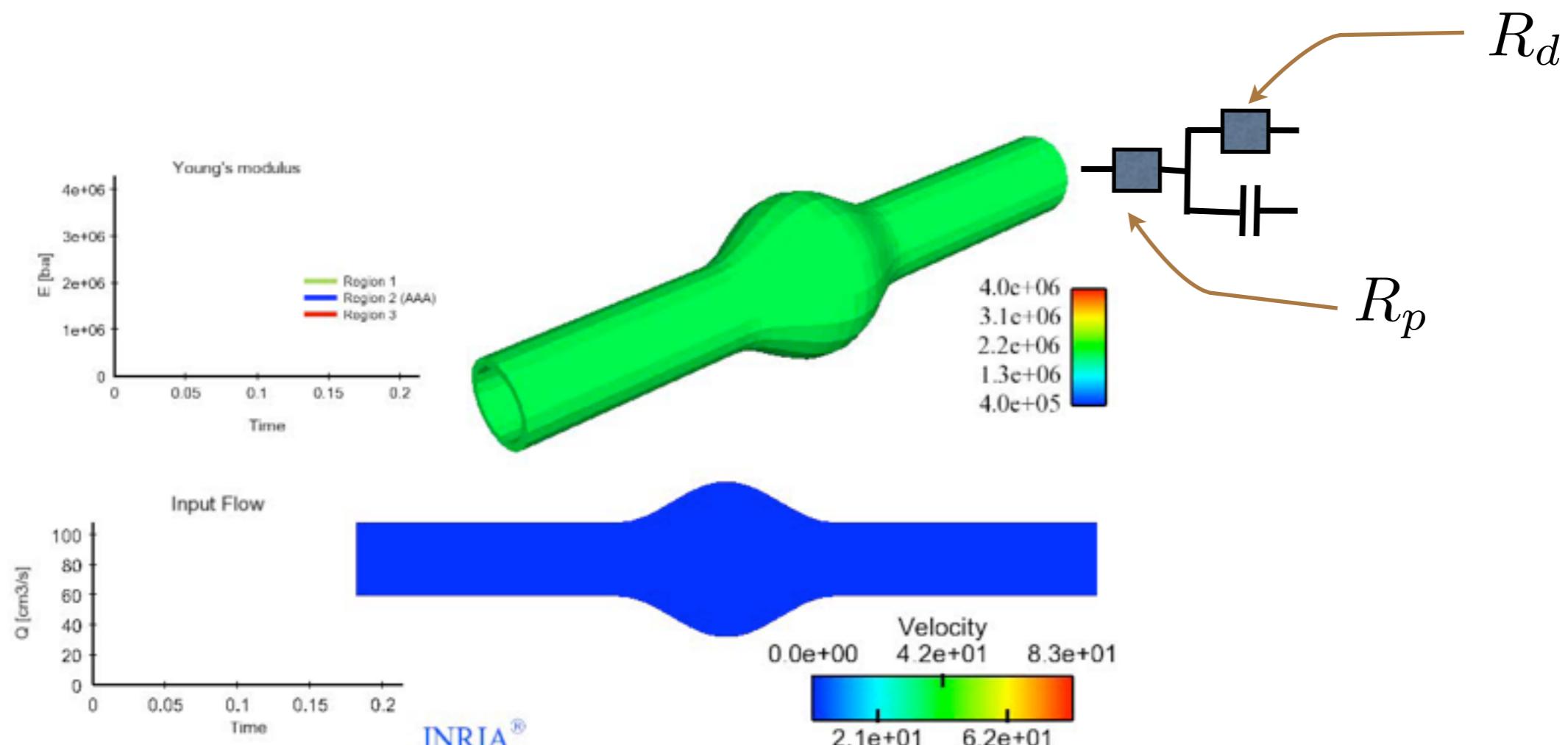
Implementation



Stiffness estimation

Parameter estimation

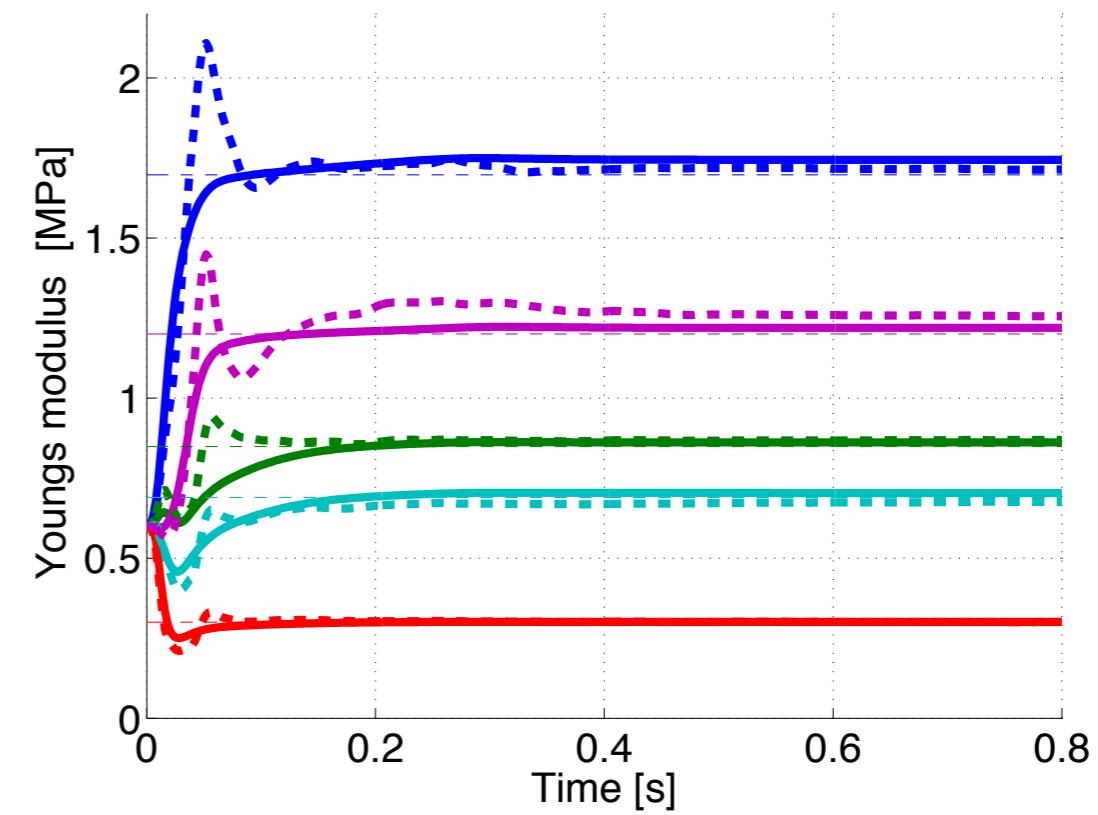
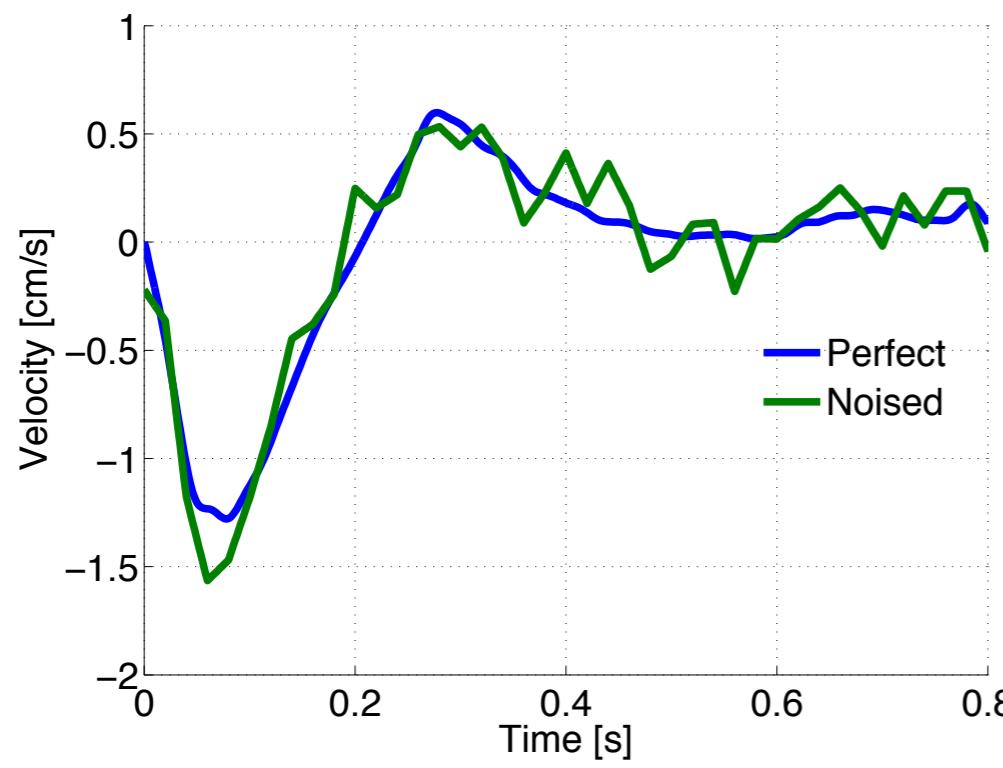
- Parameter estimation: Young modulus E in 3 regions
- Synthetic data with $E_1 = 0.5, E_2 = 2, E_3 = 4 MPa$
- Initial guess: $E = 2 MPa$ in the three regions
- Observations: wall velocity



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Simulation : C.Bertoglio (INRIA)

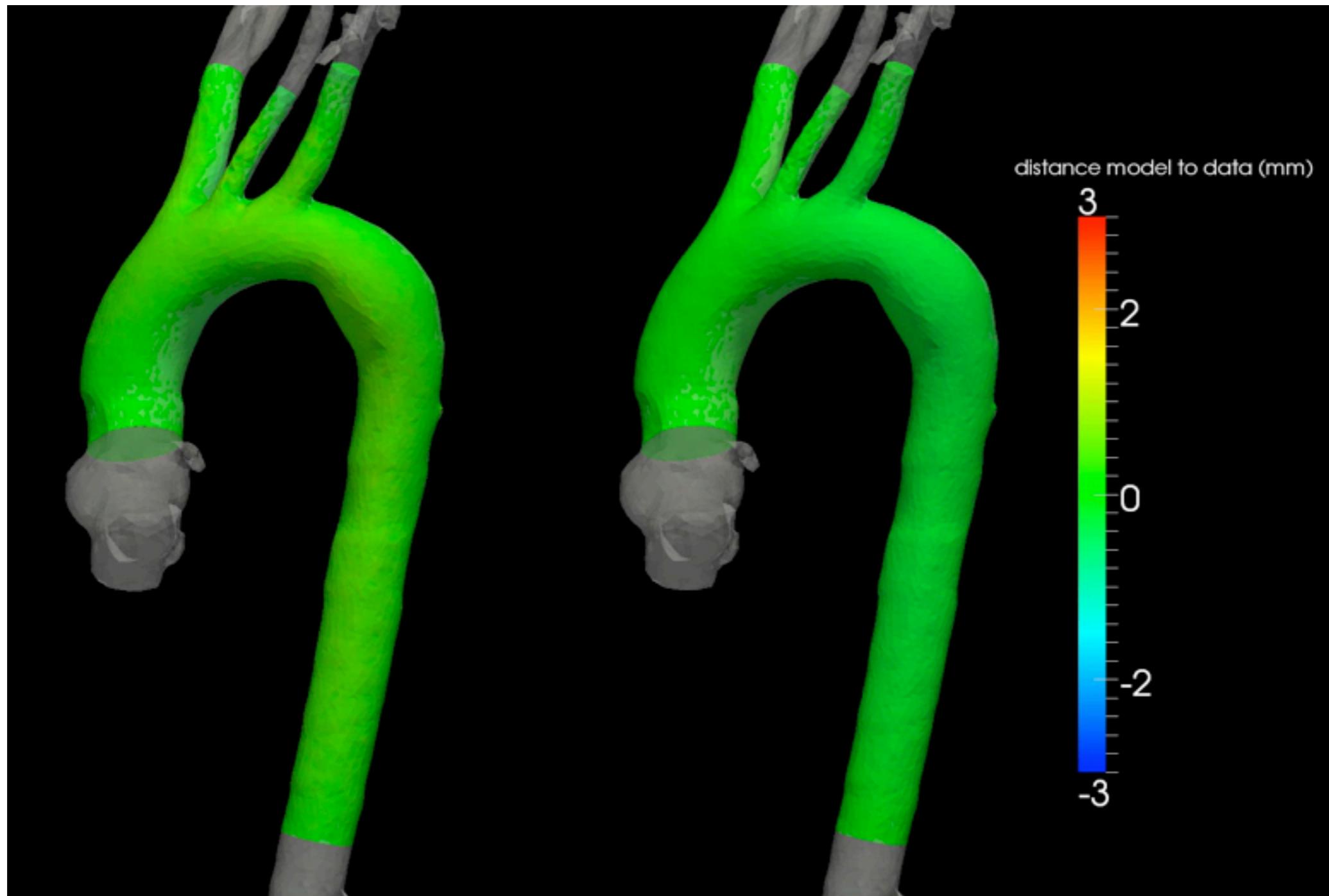
- Similar experiment with 5 regions
- With noise (10%) and resampling:



Simulation : C.Bertoglio (INRIA)

Example 2

State estimation



Data assimilation
(state only)

Direct simulation

Simulation: N. Xiao (Stanford)

Future

- Charley Taylor & col. are about to leave Stanford
- ...but not the end of the collaboration !
 - ★ With A. Figueroa & N. Xiao :
 - inverse problems in full-body-scale 3D vasculature
 - ★ With A. Marsden (UC San Diego) :
 - Pulmonary arteries in the *Transatlantic Network* (Leducq foundation)
 - Respiration modeling