

Uncertainty-Aware Concept Bottleneck Models with Enhanced Interpretability

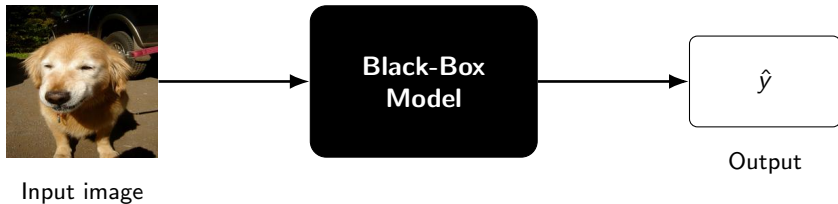
Haifei Zhang, Patrick Barry, Eduardo Brandao

Jean Monnet University
Hubert Curien Laboratory, France

September 15, 2025
Porto, Portugal



Image classification using black-box models

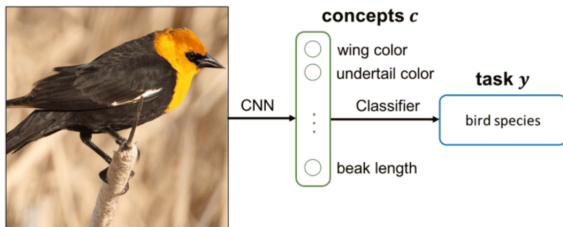


We get the prediction, but we don't understand why!

Concept Bottleneck Models (CBMs)

Core idea: predict labels of images through human-understandable concepts as intermediate reasoning.

- 1 **Concept encoder:** Image x \rightarrow CNN backbone \rightarrow Concept activation probabilities \hat{c} .
- 2 **Task predictor:** $\hat{c} \rightarrow$ Interpretable classifier $\rightarrow \hat{y}$.



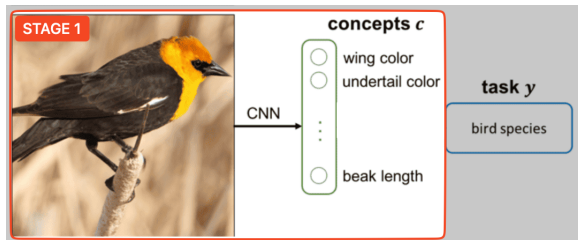
- **Conventional approach for stage 2:** Logistic regression.
 - ✓ Good balance between performance and interpretability.
 - ✗ Coefficient values are abstract and unintuitive to understand.
 - ✗ Difficult to capture uncertainty propagation from the concept prediction to the label prediction.
- **Our Contribution:** A novel interpretable classifier for stage 2 that can capture uncertainty.

Concept Bottleneck Models (CBMs)

Core idea: predict labels of images through human-understandable concepts as intermediate reasoning.

① **Concept encoder:** Image x \rightarrow CNN backbone \rightarrow Concept activation probabilities \hat{c} .

② **Task predictor:** $\hat{c} \rightarrow$ Interpretable classifier $\rightarrow \hat{y}$.



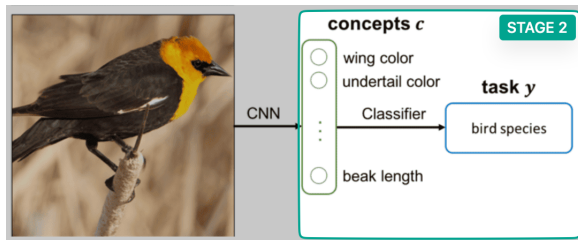
- **Conventional approach for stage 2:** Logistic regression.
 - ✓ Good balance between performance and interpretability.
 - ✗ Coefficient values are abstract and unintuitive to understand.
 - ✗ Difficult to capture uncertainty propagation from the concept prediction to the label prediction.
- **Our Contribution:** A novel interpretable classifier for stage 2 that can capture uncertainty.

Concept Bottleneck Models (CBMs)

Core idea: predict labels of images through human-understandable concepts as intermediate reasoning.

① **Concept encoder:** Image x \rightarrow CNN backbone \rightarrow Concept activation probabilities \hat{c} .

② **Task predictor:** $\hat{c} \rightarrow$ Interpretable classifier $\rightarrow \hat{y}$.

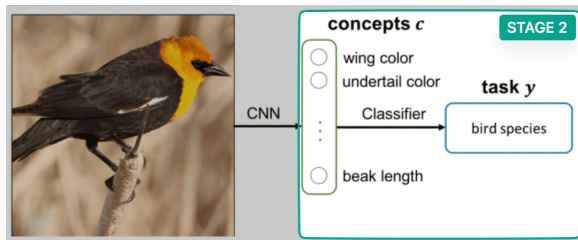


- **Conventional approach for stage 2:** Logistic regression.
 - ✓ Good balance between performance and interpretability.
 - ✗ Coefficient values are abstract and unintuitive to understand.
 - ✗ Difficult to capture uncertainty propagation from the concept prediction to the label prediction.
- **Our Contribution:** A novel interpretable classifier for stage 2 that can capture uncertainty.

Concept Bottleneck Models (CBMs)

Core idea: predict labels of images through human-understandable concepts as intermediate reasoning.

- 1 **Concept encoder:** Image $x \rightarrow$ CNN backbone \rightarrow Concept activation probabilities \hat{c} .
- 2 **Task predictor:** $\hat{c} \rightarrow$ Interpretable classifier $\rightarrow \hat{y}$.



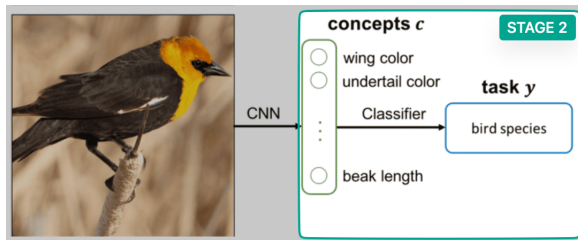
- **Conventional approach for stage 2:** Logistic regression.
 - ✓ Good balance between performance and interpretability.
 - ✗ Coefficient values are abstract and unintuitive to understand.
 - ✗ Difficult to capture uncertainty propagation from the concept prediction to the label prediction.
- **Our Contribution:** A novel interpretable classifier for stage 2 that can capture uncertainty.

Concept Bottleneck Models (CBMs)

Core idea: predict labels of images through human-understandable concepts as intermediate reasoning.

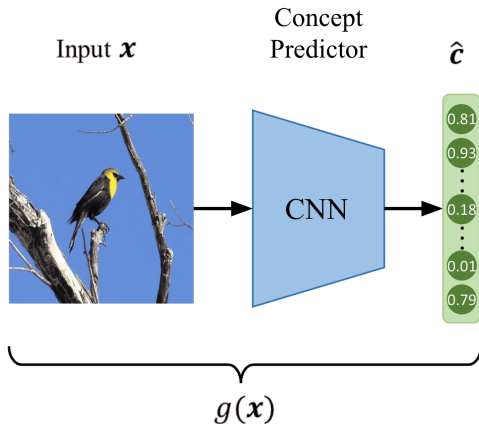
① **Concept encoder:** Image x \rightarrow CNN backbone \rightarrow Concept activation probabilities \hat{c} .

② **Task predictor:** $\hat{c} \rightarrow$ Interpretable classifier $\rightarrow \hat{y}$.



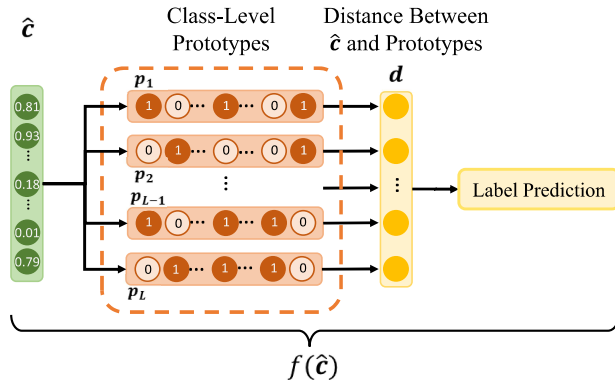
- **Conventional approach for stage 2:** Logistic regression.
 - ✓ Good balance between performance and interpretability.
 - ✗ Coefficient values are abstract and unintuitive to understand.
 - ✗ Difficult to capture uncertainty propagation from the concept prediction to the label prediction.
- **Our Contribution:** A novel interpretable classifier for stage 2 that can capture uncertainty.

Architecture of proposed Class-Level Prototype Classifier (CLPC)



Training of stage 1 to Learn $g(\mathbf{x})$: Fine-tune pre-trained CNN to predict concepts $\hat{\mathbf{c}}$.

Architecture of proposed Class-Level Prototype Classifier (CLPC)



Training of stage 2 to learn $f(\hat{\mathbf{c}})$:

- Assign each class a single **binary-valued prototype** in the concept space.
- Predict label by measuring the distance between **concept activations** $\hat{\mathbf{c}}$ and the **prototypes**.

What are prototypes in our setting?

Learnable binary-valued vectors representing **ideal concepts** for a class.



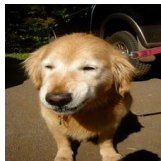
Plane



Car



Frog



Dog

	Plane	Car	Frog	Dog
Ears	0	0	0	1
Hairy	0	0	0	1
Wings	1	0	0	0
⋮	⋮	⋮	⋮	⋮
Wet	0	0	1	0
Wheels	1	1	0	0
Metallic	1	1	0	0

Example of inference

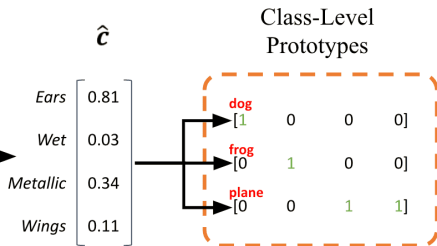
For illustration objective, we consider only 4 concepts: *Ears*, *Wet*, *Metallic*, *Wings*

Class-Level
Prototypes

dog	[1	0	0	0]
frog	[0	1	0	0]
plane	[0	0	1	1]

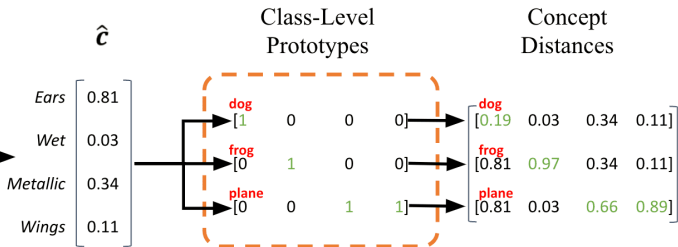
Example of inference

For illustration objective, we consider only 4 concepts: *Ears*, *Wet*, *Metallic*, *Wings*



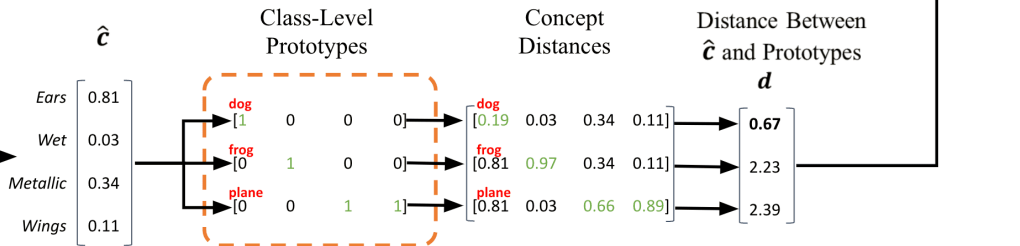
Example of inference

For illustration objective, we consider only 4 concepts: *Ears*, *Wet*, *Metallic*, *Wings*



Example of inference

For illustration objective, we consider only 4 concepts: *Ears*, *Wet*, *Metallic*, *Wings*



Learning prototypes

The loss function learns prototypes that are accurate, sparse, and determinate.

Learning prototypes

The loss function learns prototypes that are accurate, sparse, and determinate.

Total loss:

$$\mathcal{L} = \mathcal{L}_p + \lambda_s \mathcal{L}_s + \lambda_b \mathcal{L}_b \quad (\text{Total Loss})$$

Learning prototypes

The loss function learns prototypes that are **accurate**, sparse, and determinate.

Total loss:

$$\mathcal{L} = \mathcal{L}_p + \lambda_s \mathcal{L}_s + \lambda_b \mathcal{L}_b \quad (\text{Total Loss})$$

Loss components: for training set $\{\hat{\mathbf{c}}^{(i)}, y^{(i)}\}_{i=1}^N$, class label set $\{1, \dots, L\}$ and concept set $\{1, \dots, K\}$

$$\mathcal{L}_p = \frac{1}{N} \sum_{i=1}^N \left(d(\hat{\mathbf{c}}^{(i)}, \mathbf{p}_{y^{(i)}}) - \frac{1}{L-1} \sum_{j \neq y^{(i)}} d(\hat{\mathbf{c}}^{(i)}, \mathbf{p}_j) \right) \quad (\text{Prototype Loss})$$

Learning prototypes

The loss function learns prototypes that are **accurate**, **sparse**, and determinate.

Total loss:

$$\mathcal{L} = \mathcal{L}_p + \lambda_s \mathcal{L}_s + \lambda_b \mathcal{L}_b \quad (\text{Total Loss})$$

Loss components: for training set $\{\hat{\mathbf{c}}^{(i)}, y^{(i)}\}_{i=1}^N$, class label set $\{1, \dots, L\}$ and concept set $\{1, \dots, K\}$

$$\mathcal{L}_p = \frac{1}{N} \sum_{i=1}^N \left(d(\hat{\mathbf{c}}^{(i)}, \mathbf{p}_{y^{(i)}}) - \frac{1}{L-1} \sum_{j \neq y^{(i)}} d(\hat{\mathbf{c}}^{(i)}, \mathbf{p}_j) \right) \quad (\text{Prototype Loss})$$

$$\mathcal{L}_s = \sum_{j=1}^L \|\mathbf{p}_j\|_1 \quad (\text{Sparsity Loss})$$

Learning prototypes

The loss function learns prototypes that are **accurate**, **sparse**, and **determinate**.

Total loss:

$$\mathcal{L} = \mathcal{L}_p + \lambda_s \mathcal{L}_s + \lambda_b \mathcal{L}_b \quad (\text{Total Loss})$$

Loss components: for training set $\{\hat{\mathbf{c}}^{(i)}, y^{(i)}\}_{i=1}^N$, class label set $\{1, \dots, L\}$ and concept set $\{1, \dots, K\}$

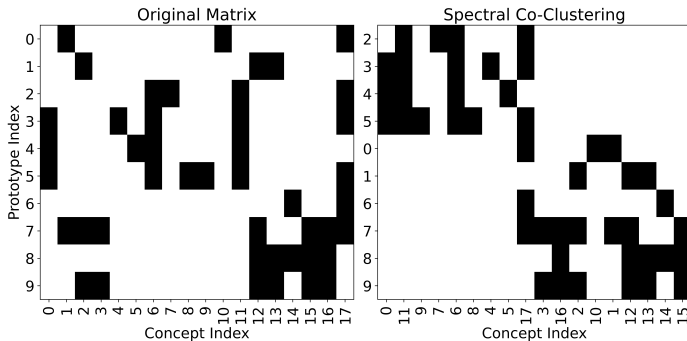
$$\mathcal{L}_p = \frac{1}{N} \sum_{i=1}^N \left(d(\hat{\mathbf{c}}^{(i)}, \mathbf{p}_{y^{(i)}}) - \frac{1}{L-1} \sum_{j \neq y^{(i)}} d(\hat{\mathbf{c}}^{(i)}, \mathbf{p}_j) \right) \quad (\text{Prototype Loss})$$

$$\mathcal{L}_s = \sum_{j=1}^L \|\mathbf{p}_j\|_1 \quad (\text{Sparsity Loss})$$

$$\mathcal{L}_b = \sum_{j=1}^L \sum_{k=1}^K (1 - p_{jk}) \cdot p_{jk} \quad (\text{Binary Loss})$$

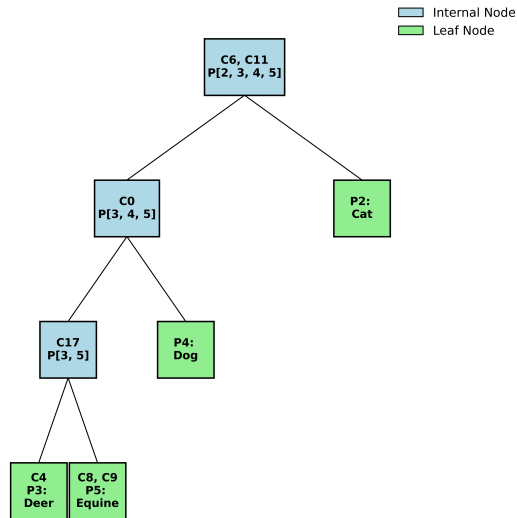
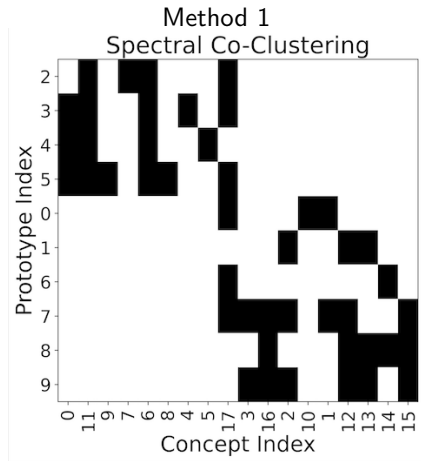
Global explanation: what have we learned?

Clustering prototypes and concepts.



Global explanation: what have we learned?

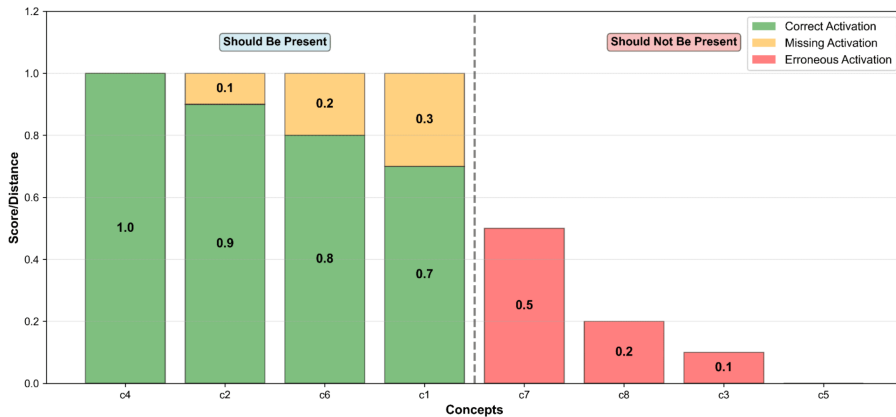
Prototype tree



Local explanation: why do we get this prediction?

Example

	c ₁	c ₂	c ₃	c ₄	c ₅	c ₆	c ₇	c ₈
Prototype	1	1	0	1	0	1	0	0
\hat{c}	0.7	0.9	0.1	1.0	0.0	0.8	0.5	0.2
Uncertainty	0.3	0.1	0.1	0.0	0.0	0.2	0.5	0.2



Concept intervention: how can we get correct prediction?

Intervene 1-by-1 on the most “impactful” concepts to correct wrong label predictions.

- Conventional concept ordering strategy: Feature-importance-based.
However, **the error in concept prediction is not considered.**
- Our proposed concept ordering strategy: Gain-based.
Consider both the importance of concepts and the error in concept prediction.
 - For Logistic Regression:

$$\text{LR-Gain}_k = w_{j^*k} \cdot (\mathbb{1}(w_{j^*k} > 0) - \hat{c}_k).$$

- For CLPC:

$$\text{CLPC-Gain}_k = |p_{j^*k} - \hat{c}_k|.$$

Where j^* and k are indices for true class and concepts, respectively.

If $w_{j^*k} < 0$ or $p_{j^*k} = 0$, set \hat{c}_k to 0. In contrast, if $w_{j^*k} > 0$ or $p_{j^*k} = 1$, set \hat{c}_k to 1.

Image Datasets

- **CUB (Birds)**: 200 classes, 112 concepts
- **Derm7pt (Skin Lesions)**: 5 classes, 19 concepts
- **RIVAL10 (Objects)**: 10 classes, 18 concepts

Evaluations

- Baseline: Logistic regression
- Experiments:
 1. Classification accuracy
 2. Conformal prediction
 3. Robustness to concept noise
 4. Concept intervention efficiency

Classification accuracy

Table: Classification accuracy results

Dataset	Concept Acc (%)	Ave. $\ \mathbf{p}_j\ $	Accuracy (%)		Δ (%)
			LR	CLPC	
CUB	94.86	21.95/112	76.46	76.01	-0.45
Derm7pt	88.38	6.59/19	66.33	64.81	-1.52
RIVAL10	99.71	4.50/18	99.17	98.96	-0.21

Key takeaway

CLPC has competitive classification accuracy compared to logistic regression.

Conformal Prediction (CP)

What is CP?

A framework that yields reliable **set-valued or empty predictions** with guaranteed error rates.

Table: Conformal prediction performance (*error rate = 5%*)

Dataset	Set Acc (%)		Set Size		Reject Ratio (%)	
	LR	CLPC	LR	CLPC	LR	CLPC
CUB	92.12	94.97	1	1	29.5	53.30
Derm7pt	87.34	94.43	2.15	3.38	0	0
RIVAL10	99.96	99.92	1	1	5.07	5.37

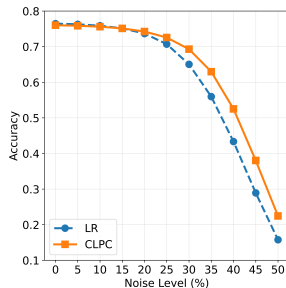
Key takeaway

CLPC is more sensitive and cautious in the face of uncertainty.

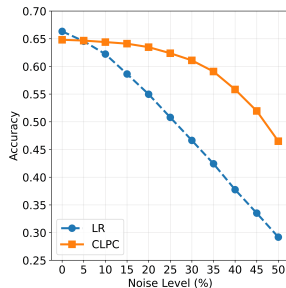
Robustness to concept noise

Inject noise by randomly flipping $\alpha\%$ concepts:

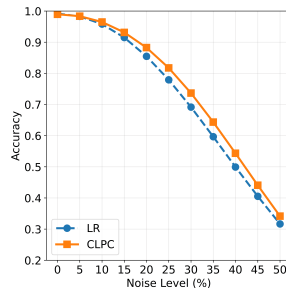
- concept activation score $\leq 0.5 \rightarrow$ random value in $(0.5, 1]$;
- concept activation score $> 0.5 \rightarrow$ random value in $[0, 0.5]$.



(a) CUB



(b) Derm7pt

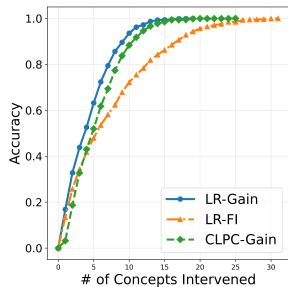


(c) RIVAL10

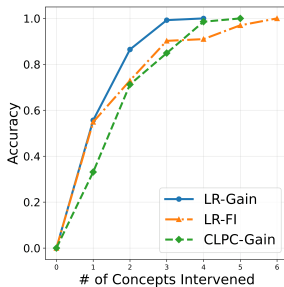
Key takeaway

CLPC is more robust to noise in concept prediction and thus more reliable for low-quality input images.

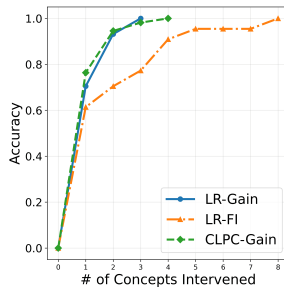
Concept intervention efficiency



(a) CUB



(b) Derm7pt



(c) RIVAL10

Key takeaway

Gain-based strategies are more efficient than the feature-importance-based strategy.

Conclusion

Our proposed CLPC model has:

- Competitive performance as conventional interpretable models;
- Enhanced global and local interpretability;
- Natural capability to capture uncertainty propagation from concepts to labels;
- Strong robustness to noise in concept predictions.

Future work:

- Learn multiple prototypes per class.
- Investigate concept leakage present in the model.
- Conduct user-centred evaluations to validate model interpretability.

Our team



Haifei Zhang  
Associate Professor



Patrick Barry
Master Student



Eduardo Brandao
Associate Professor

Lab page: <https://laboratoirehubertcurien.univ-st-etienne.fr/en/index.html>

