## A discretize-then-map approach for the treatment of parameterized geometries in model order reduction

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Objective

## Model reduction in parametric domains

The goal of parameterized Model Order Reduction ( pMOR ) is to reduce the marginal cost associated with the solution to parameterized problems. pMOR is motivated by real-time and many-query problems design and optimization, UQ, control.

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The aim of this talk is to discuss the treatment of parameterized geometries in projection-based pMOR.
We denote by
$\mu=\left[\mu_{1}, \ldots, \mu_{P}\right] \in \mathcal{P} \subset \mathbb{R}^{P}$ a vector of parameters;
$\left\{\Omega_{\mu}: \mu \in \mathcal{P}\right\}$ a family of parametric domains;
$U_{\mu}: \Omega_{\mu} \rightarrow \mathbb{R}^{D}$ the solution field.

## Mapped formulation

We recast the problem in a parameter-independent domain
$\Omega$ through a mapping $\Phi$ such that
$\Phi_{\mu}$ is invertible and $\Omega_{\mu}=\Phi_{\mu}(\Omega)$, for all $\mu \in \mathcal{P}$.

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Task 1: construction of $\Phi$;
RBF, FFD, ...
Task 2: solution to the mapped problem for $U_{\mu} \circ \Phi_{\mu}$.

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Agenda.

1. two paradigms to deal with geometry variations;
2. projection-based pMOR;
3. application to 2D RANS.

Treatment of parametric geometries in pMOR

## Preliminary definitions

Define the mesh $\mathcal{T}_{\mathrm{hf}}=\left(\left\{x_{j}^{\mathrm{hf}}\right\}_{j}, \mathrm{~T}\right)$, with nodes $\left\{x_{j}^{\mathrm{hf}}\right\}_{j}$ and connectivity matrix T , and the associated FE space $\mathcal{X}_{\mathrm{hf}}$.
Given $w \in \mathcal{X}_{\mathrm{hf}}$, denote by $w \in \mathbb{R}^{N}$ the associated vector representation.

Given $\Phi: \Omega \rightarrow \Omega^{\prime}$, define the mapped mesh $\Phi\left(\mathcal{T}_{\mathrm{hf}}\right)=$ $\left(\left\{\Phi\left(x_{j}^{\mathrm{hf}}\right)\right\}_{j}, \mathrm{~T}\right)$.
Definition. $\Phi$ is $\mathcal{T}_{\mathrm{hf}}$-bijective if the element mappings

$$
\Psi_{k, \Phi}^{\mathrm{hf}}(x)=\sum_{i=1}^{n_{\mathrm{lp}}} \Phi\left(x_{i, k}^{\mathrm{hf}}\right) \hat{\phi}_{i}(x), \quad x_{i, k}^{\mathrm{hf}}=x_{\mathrm{T}_{i, k}}^{\mathrm{hf}},
$$

are invertible.

## Map-then-discretize (MtD) approach

Consider $-\Delta U_{\mu}+b_{\mu} \cdot \nabla U_{\mu}=f_{\mu}$ in $\Omega_{\mu},\left.\quad U_{\mu}\right|_{\partial \Omega_{\mu}}=0$.
If $\Phi_{\mu}: \Omega \rightarrow \Omega_{\mu}$ is Lipschitz, $\widetilde{U}_{\mu}=U_{\mu} \circ \Phi_{\mu}$ solves

$$
\int_{\Omega}\left(K_{\mu} \nabla \widetilde{U}_{\mu} \cdot \nabla v+\widetilde{b}_{\mu} \cdot \nabla \widetilde{U}_{\mu} v-\widetilde{f}_{\mu} v\right) d x=0
$$

for all $v \in H_{0}^{1}(\Omega)$, with $K_{\mu}=g_{\mu} \nabla \Phi_{\mu}^{-1} \nabla \Phi_{\mu}^{-\top}$,
$\widetilde{b}_{\mu}=g_{\mu} \nabla \Phi_{\mu}^{-T} b_{\mu}, \widetilde{f}_{\mu}=g_{\mu} f_{\mu}, g_{\mu}=\operatorname{det}\left(\nabla \Phi_{\mu}\right)$.

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Map-then-discretize.

1. Derive the mapped problem.
map
2. Devise FE and MOR methods for the mapped problem. discretize.
Rozza, Huynh, Patera, 2007; Lassila, Rozza, 2010, ...

## Discretize-then-map (MtD) approach

Consider $-\Delta U_{\mu}+b_{\mu} \cdot \nabla U_{\mu}=f_{\mu}$ in $\Omega_{\mu},\left.\quad U_{\mu}\right|_{\partial \Omega_{\mu}}=0$. Introduce the mesh $\mathcal{T}_{\mathrm{hf}}$ of $\Omega$ and the associated space $\mathcal{X}_{\mathrm{hf}}$. discretize

Define the mapped mesh $\Phi_{\mu}\left(\mathcal{T}_{\mathrm{hf}}\right)$ and approximate the problem as follows:
map

$$
\text { with } r_{\mu}^{k}(u, v)=\int_{\mathrm{D}_{k, \phi_{\mu}}}^{\hat{-}^{-1}} \nabla u \cdot \nabla v+\left(b_{\mu} \cdot \nabla u-f_{\mu}\right) v d x \text {. }
$$

Washabaugh et al., 2016; Dal Santo, Manzoni, 2019.

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$$
R_{\mu}^{\mathrm{hf}}\left(U_{\mu}^{\mathrm{hf}}, v\right)=\sum_{k=1} r_{\mu}^{k}\left(U_{\mu}^{\mathrm{hf}}, v\right)=0, \text { for all } v \in \mathcal{X}_{\mathrm{hf}, \Phi_{\mu}},
$$

$$
\text { with } r_{\mu}^{k}(u, v)=\int_{D_{k, \phi_{\mu}}}^{-1} \nabla u \cdot \nabla v+\left(b_{\mu} \cdot \nabla u-f_{\mu}\right) v d x \text {. }
$$

- The PDE model is left unchanged.
- MOR should be applied at algebraic level. Washabaugh et al., 2016; Dal Santo, Manzoni, 2019.


## Comments (I): equivalence; discrete bijectivity

DtM involves evaluation of $\Phi$ at mesh nodes;

$$
\Psi_{k, \Phi}^{\mathrm{hf}}(x)=\sum_{i=1}^{\mathrm{i}} \Phi\left(x_{i, k}^{\mathrm{hf}}\right) \hat{\phi}_{i}(x)
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MtD requires evaluation of $\Phi$ and its derivatives at quadrature points.
Lemma: if $\Phi \circ \Psi_{k}^{\mathrm{hf}} \in \mathbb{P}_{p}$, DtM and MtD are equivalent.

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MtD requires evaluation of $\Phi$ and its derivatives at quadrature points.
Lemma: if $\Phi \circ \psi_{k}^{\mathrm{hf}} \in \mathbb{P}_{p}$, DtM and MtD are equivalent.
DtM might fail for large non-smooth deformations.

Enforcement of discrete bijectivity might be needed.
Taddei, Zhang, JSC, 2021


## Comments (II): optimal convergence of hf solver

Consider $-\partial_{x x} u=\sin (\pi x) \quad x \in \Omega=(0,1),\left.\quad u\right|_{x=0,1}=0$.
Let $\Phi: \Omega \rightarrow \Omega$ be piecewise-linear, and let $\mathcal{T}_{\text {hf }}$ be a uniform grid with $N_{\mathrm{e}}$ elements of degree 3.

Apply MtD, iso-parametric DtM and sub-parametric DtM.



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Apply MtD, iso-parametric DtM and sub-parametric DtM.
MtD fails to recover optimal rate.

DtM might have inverted elements.

DtM recovers optimal rate.


## Comments (III): simplicity of implementation

Consider SUPG stabilization of the advection term:

$$
\int_{D_{k, \phi}}(-\Delta u+b \cdot \nabla u-f) \frac{b}{\|b\|_{2}} \cdot \nabla v d x=0 .
$$

Note that $\int_{D_{k, \phi}} \Delta u\left(\frac{b}{\|b\|_{2}} \cdot \nabla v\right) d x=$
$\int_{D_{k}}\left(\left(\nabla \Phi^{-T} \nabla\right) \cdot\left(\nabla \Phi^{-T} \nabla u\right)\right)\left(\frac{\nabla \Phi^{-1} b}{\|b\|_{2}} \cdot \nabla v\right) g d x$.

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Implementation of MtD requires new assembly routines

- high implementation costs;
- second-order derivatives of $\Phi$ might not be available.


## Comments (IV): hyper-reduction

$\mathcal{G}_{\mu}\left(U_{\mu}, v\right)=\sum_{k=1}^{N_{0}} \int_{D_{k}} \eta_{\mu}\left(x ; U_{\mu}\right) \cdot[v(x), \nabla v(x)] d x=0$.
Two strategies for hyper-reduction:

1. Affine approximation of integrand $\eta_{\mu}$ : EIM,...

$$
\begin{aligned}
& \eta_{\mu}\left(x ; U_{\mu}\right) \approx \sum_{q=1}^{Q} \eta_{\mu}\left(x_{q}^{\star} ; U_{\mu}\right) \xi_{q}(x) \text { for }\left\{x_{q}^{\star}\right\}_{q} \subset \Omega, \\
& \widehat{\mathcal{G}}_{\mu}\left(U_{\mu}, v\right)=\sum_{k=1}^{N_{e}} \int_{D_{k}} \widehat{\eta}_{\mu, Q}\left(x ; U_{\mu}\right) \cdot[v(x), \nabla v(x)] d x=0 .
\end{aligned}
$$

2. Reduced integration domain:

ECSW, EQP,...
$\widehat{\mathcal{G}}_{\mu}\left(U_{\mu}, v\right)=\sum_{k \in \mathrm{I}_{\mathrm{eq}}} \rho_{k}^{\mathrm{eq}} \int_{\mathrm{D}_{k}} \eta_{\mu}\left(x ; U_{\mu}\right) \cdot[v(x), \nabla v(x)] d x=0$.

## Comments (IV): hyper-reduction

MtD copes with both hyper-reduction paradigms.
DtM requires the introduction of a reduced integration domain to avoid integration over $\Omega_{\mu}$.
${ }^{2}$ For DG discretizations, evaluation of $\Phi_{\mu}$ at nodes of neighboring elements is also required.

## Comments (IV): hyper-reduction

MtD copes with both hyper-reduction paradigms.
DtM requires the introduction of a reduced integration domain to avoid integration over $\Omega_{\mu}$.

- We rely on elementwise empirical quadrature for hyper-reduction. Farhat et al., 2015; Yano 2019.
- Application of EQ within the DtM framework is straightforward: given $\mu \in \mathcal{P}$, $\operatorname{DtM}$ requires evaluation of $\Phi_{\mu}$ in all nodes of the sampled elements ${ }^{2}$.
${ }^{2}$ For DG discretizations, evaluation of $\Phi_{\mu}$ at nodes of neighboring elements is also required.


## Projection-based pMOR

## Projection scheme: LSPG+EQ

Introduce reduced-order bases $\mathbb{Z} \in \mathbb{R}^{N, n}, Y \in \mathbb{R}^{N, j e s}$.
Define the weighted residual $R_{\mu}^{\mathrm{eq}}(u, v)=\sum_{k=1} \rho_{k}^{\mathrm{eq}} r_{\mu}^{k}(u, v)$.
EQ LSPG ROM: find $\widehat{\mathrm{U}}_{\mu} \in \arg \min _{\zeta \in \operatorname{col}(\mathbf{Z})} \sup _{\eta \in \operatorname{col}(\boldsymbol{Y})} \frac{R_{\mu}^{\mathrm{eq}}(\zeta, \eta)}{\|\eta\|_{\mathcal{Y}}}$.

## Projection scheme: LSPG+EQ

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Implementation requires to address several points.

- Choice of trial ROB Z.
- Choice of test ROB Y and the norm $\|\cdot\|_{y}$.
- Choice of the EQ weights $\rho^{\mathrm{eq}}$.

Taddei, Zhang, A discretize-then-map approach for the treatment of parameterized geometries in model order reduction, CMAME, 2021.

## Residual assembly: FE routine

Notation: $\phi_{i, k}^{\mathrm{fe}} i=1, \ldots, n_{\mathrm{lp}}$ FE basis in the $k$-th element; $e_{1}, \ldots, e_{D}$ canonical basis ( $D$ number of equations).

For $k=1, \ldots, N_{e}$
Compute $R_{i, k, d}^{\mathrm{un}}=r^{k}\left(\left.U\right|_{\mathrm{D}_{k, \Phi},}, \phi_{i, k}^{\mathrm{fe}} e_{d}\right)$,

$$
i=1 \ldots, n_{\mathrm{lp}}, d=1, \ldots, D .
$$

EndFor
$\left.\mathbf{R}^{\mathrm{hf}} \leftarrow\left\{R_{i, k, d}^{\mathrm{un}}\right\}\right\}_{i, k, d}, \quad \mathrm{R}^{\mathrm{hf}} \in \mathbb{R}^{N}$ FE vector assembly.

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$\left.\mathbf{R}^{\mathrm{hf}} \leftarrow\left\{R_{i, k, d}^{\mathrm{un}}\right\}\right\}_{i, k, d}, \quad \mathrm{R}^{\mathrm{hf}} \in \mathbb{R}^{N}$ FE vector assembly.

- Computation of $\left\{R_{i, k, d}^{u n}\right\}_{i, d}$ relies on element-wise assembly routines that take as input $\left\{\Phi\left(x_{i, k}\right)\right\}_{i}$.
- Assembly of the FE vector is independent of the PDE.


## Residual assembly: MOR routine

Notation: $\mathrm{Y}=\left[\psi_{1}, \ldots, \psi_{j_{\text {es }}}\right] \in \mathbb{R}^{N \cdot j_{\text {jes }}}$ test space; $\mathrm{T}_{i, k}$ index of the $i$-th node of the $k$-th element.
$Y_{i, k, d, j}^{u n}=Y_{\mathrm{T}_{i, k}+(d-1) N, j}$ unassembled test space, $\widehat{\mathbf{R}} \in \mathbb{R}^{j^{j e s}}$ reduced residual, $(\widehat{R})_{j}=R_{\mu}^{\text {eq }}\left(U, \psi_{j}\right)$.
For $k \in I_{\text {eq }}$
Compute $R_{i, k, d}^{\mathrm{un}}=r^{k}\left(\left.U\right|_{\mathrm{D}_{k, \phi},}, \phi_{i, k}^{\mathrm{fe}} e_{d}\right)$,

$$
i=1 \ldots, n_{\mathrm{lp}}, d=1, \ldots, D .
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EndFor
$(\widehat{\mathbb{R}})_{j}=\sum_{k \in \mathrm{I}_{\mathrm{eq}}} \rho_{k}^{\mathrm{eq}}\left(\sum_{i=1}^{n_{\mathrm{lp}}} \sum_{d=1}^{D} \mathbf{Y}_{i, k, d, j}^{\mathrm{un}} R_{i, k, d}^{\mathrm{un}}\right), j=1, \ldots, j_{\mathrm{es}}$.

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EndFor
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- MOR assembly exploits available FE routines.
- Geometry variations don't influence MOR assembly.


## Application to 2D RANS

## Ahmed's body problem

Closure model: SA. Discretization: stab P2-P2 FEM. $R e=\frac{u_{\text {in }} H_{c}}{\nu}=3 \cdot 10^{3}, \mu \in\left[5^{\circ}, 50^{\circ}\right]$.




## Geometry parametrization

We consider a piecewise-bilinear mapping (Gordon-Hall).
FE mesh is not conforming with the coarse-grained partition.



## Numerical results

Relative error averaged over 10 out-of-sample configurations.

Error analysis


Hyper-reduction


Legend: projection $\boldsymbol{-}$, ROM with HF quadrature $\square$, tol $_{\mathrm{eq}}=10^{-6} \longrightarrow$, tol $_{\mathrm{eq}}=10^{-10} \longrightarrow$, tol ${ }_{\mathrm{eq}}=10^{-14} \longrightarrow$.

## Conclusions and perspectives

## Summary

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- We discuss the treatment of parameterized geometries in projection-based pMOR.
- We consider two approaches: 1. Discretize-then-Map;

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2. Map-then-Discretize.

## Take-aways

- DtM is simpler to implement, and can be used in combination with non-smooth mappings.
- MtD copes with a broader class of hyper-reduction methods ( $\rightarrow$ possibly larger speedups), and does not require discrete bijectivity wrt the mesh.


## Thank you for your attention!

For more information, visit the website:
math.u-bordeaux.fr/~ttaddei/ .

1. Taddei, Zhang; A discretize-then-map approach for the treatment of parameterized geometries in model order reduction, CMAME, 2021.
2. Ferrero, Taddei, Zhang; Registration-based model reduction of parameterized two-dimensional conservation laws, Arxiv preprint 2021.
