A discretize-then-map approach for the treatment of parameterized geometries in model order reduction

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Institut de Mathématiques de Bordeaux Joint work with L Zhang (Inria)

Collaborators:¹

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Objective

Model reduction in parametric domains

The goal of parameterized Model Order Reduction (pMOR) is to reduce the **marginal** cost associated with the solution to parameterized problems.

pMOR is motivated by *real-time* and *many-query* problems design and optimization, UQ, control.

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The aim of this talk is to discuss the **treatment of parameterized geometries** in projection-based pMOR. We denote by

 $\mu = [\mu_1, \dots, \mu_P] \in \mathcal{P} \subset \mathbb{R}^P \text{ a vector of parameters;}$ $\{\Omega_\mu : \mu \in \mathcal{P}\} \text{ a family of parametric domains;}$ $U_\mu : \Omega_\mu \to \mathbb{R}^D \text{ the solution field.}$ We recast the problem in a parameter-independent domain Ω through a mapping Φ such that

 Φ_{μ} is invertible and $\Omega_{\mu} = \Phi_{\mu}(\Omega)$, for all $\mu \in \mathcal{P}$.

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- 1. two paradigms to deal with geometry variations;
- 2. projection-based pMOR;
- 3. application to 2D RANS.

Treatment of parametric geometries in pMOR

Define the mesh $\mathcal{T}_{hf} = (\{x_j^{hf}\}_j, T)$, with nodes $\{x_j^{hf}\}_j$ and connectivity matrix T, and the associated FE space \mathcal{X}_{hf} .

Given $w \in \mathcal{X}_{hf}$, denote by $w \in \mathbb{R}^N$ the associated vector representation.

Given $\Phi: \Omega \to \Omega'$, define the mapped mesh $\Phi(\mathcal{T}_{hf}) = (\{\Phi(x_j^{hf})\}_j, T).$

Definition. Φ is \mathcal{T}_{hf} -bijective if the element mappings

$$\Psi^{\mathrm{hf}}_{k,\Phi}(x) = \sum_{i=1}^{m_{\mathrm{p}}} \Phi(x^{\mathrm{hf}}_{i,k}) \hat{\phi}_i(x), \quad x^{\mathrm{hf}}_{i,k} = x^{\mathrm{hf}}_{\mathrm{T}_{i,k}},$$

are invertible.

Map-then-discretize (MtD) approach

Consider
$$-\Delta U_{\mu} + b_{\mu} \cdot \nabla U_{\mu} = f_{\mu} \text{ in } \Omega_{\mu}, \quad U_{\mu}\big|_{\partial\Omega_{\mu}} = 0$$

If $\Phi_{\mu} : \Omega \to \Omega_{\mu}$ is Lipschitz, $\widetilde{U}_{\mu} = U_{\mu} \circ \Phi_{\mu}$ solves
 $\int_{\Omega} \left(K_{\mu} \nabla \widetilde{U}_{\mu} \cdot \nabla v + \widetilde{b}_{\mu} \cdot \nabla \widetilde{U}_{\mu} v - \widetilde{f}_{\mu} v \right) dx = 0,$
for all $v \in H_{0}^{1}(\Omega)$, with $K_{\mu} = g_{\mu} \nabla \Phi_{\mu}^{-1} \nabla \Phi_{\mu}^{-T},$
 $\widetilde{b}_{\mu} = g_{\mu} \nabla \Phi_{\mu}^{-T} b_{\mu}, \quad \widetilde{f}_{\mu} = g_{\mu} f_{\mu}, \quad g_{\mu} = \det(\nabla \Phi_{\mu}).$

Rozza, Huynh, Patera, 2007; Lassila, Rozza, 2010, ...

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Map-then-discretize.

1. Derive the mapped problem.

 \mathtt{map}

2. Devise FE and MOR methods for the mapped problem. discretize.

Rozza, Huynh, Patera, 2007; Lassila, Rozza, 2010, ...

Discretize-then-map (MtD) approach

Consider $-\Delta U_{\mu} + b_{\mu} \cdot \nabla U_{\mu} = f_{\mu} \text{ in } \Omega_{\mu}, \quad U_{\mu}|_{\partial \Omega_{\mu}} = 0.$ Introduce the mesh \mathcal{T}_{hf} of Ω and the associated space \mathcal{X}_{hf} . discretize

Define the mapped mesh $\Phi_{\mu}(\mathcal{T}_{hf})$ and approximate the problem as follows: map

$$egin{aligned} &\mathcal{R}^{\mathrm{hf}}_{\mu}(\mathcal{U}^{\mathrm{hf}}_{\mu}, oldsymbol{v}) = \sum_{k=1}^{N_{\mathrm{e}}} r^k_{\mu}(\mathcal{U}^{\mathrm{hf}}_{\mu}, oldsymbol{v}) = 0, ext{ for all } oldsymbol{v} \in \mathcal{X}_{\mathrm{hf}, \Phi_{\mu}}, \end{aligned}$$
 with $r^k_{\mu}(u, oldsymbol{v}) = \int_{\mathbb{D}_{k, \Phi_{\mu}}}
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abla v + (b_{\mu} \cdot
abla u - f_{\mu}) oldsymbol{v} \, dx. \end{aligned}$

Washabaugh et al., 2016; Dal Santo, Manzoni, 2019.

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- The PDE model is left unchanged.
- MOR should be applied at algebraic level.
 Washabaugh et al., 2016; Dal Santo, Manzoni, 2019.

Comments (I): equivalence; discrete bijectivity

DtM involves evaluation of Φ at mesh nodes; $\Psi_{k,\Phi}^{\mathrm{hf}}(x) = \sum_{i=1}^{m_{\mathrm{lp}}} \Phi(x_{i,k}^{\mathrm{hf}}) \hat{\phi}_i(x)$

MtD requires evaluation of Φ and its derivatives at quadrature points.

Lemma: if $\Phi \circ \Psi_k^{\text{hf}} \in \mathbb{P}_p$, DtM and MtD are equivalent.

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Lemma: if $\Phi \circ \Psi_k^{\text{hf}} \in \mathbb{P}_p$, DtM and MtD are equivalent.

DtM might fail for large non-smooth deformations.

Enforcement of discrete bijectivity might be needed.

Taddei, Zhang, JSC, 2021



Comments (II): optimal convergence of hf solver

Consider $-\partial_{xx}u = \sin(\pi x)$ $x \in \Omega = (0, 1), u|_{x=0,1} = 0.$

Let $\Phi : \Omega \to \Omega$ be piecewise-linear, and let $\mathcal{T}_{\rm hf}$ be a uniform grid with $N_{\rm e}$ elements of degree 3.

Apply MtD, iso-parametric DtM and sub-parametric DtM.



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Apply MtD, iso-parametric DtM and sub-parametric DtM.

MtD fails to recover optimal rate.

DtM might have inverted elements.

DtM recovers optimal rate.



Comments (III): simplicity of implementation

Consider SUPG stabilization of the advection term: $\int_{\mathbb{D}^{r+1}} \left(-\Delta u + b \cdot \nabla u - f\right) \frac{b}{\|b\|_2} \cdot \nabla v \, dx = 0.$ Note that $\int_{\Sigma} \Delta u \left(\frac{b}{\|b\|_2} \cdot \nabla v \right) dx =$ $\int_{\mathbb{D}^{n}} \left(\left(\nabla \Phi^{-T} \nabla \right) \cdot \left(\nabla \Phi^{-T} \nabla u \right) \right) \left(\frac{\nabla \Phi^{-1} b}{\|b\|_{2}} \cdot \nabla v \right) g \, dx.$

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Implementation of MtD requires new assembly routines

- high implementation costs;
- second-order derivatives of Φ might not be available.

Comments (IV): hyper-reduction

$$\mathcal{G}_{\mu}(U_{\mu}, \mathbf{v}) = \sum_{k=1}^{N_{\mathrm{e}}} \int_{\mathbb{D}_{k}} \eta_{\mu}(x; U_{\mu}) \cdot [\mathbf{v}(x), \nabla \mathbf{v}(x)] dx = 0.$$

Two strategies for hyper-reduction:

1. Affine approximation of integrand η_{μ} : EIM,... $\eta_{\mu}(x; U_{\mu}) \approx \sum_{i=1}^{Q} \eta_{\mu}\left(x_{q}^{\star}; U_{\mu}\right) \xi_{q}(x) \text{ for } \{x_{q}^{\star}\}_{q} \subset \Omega,$ $\widehat{\mathcal{G}}_{\mu}(U_{\mu}, \mathbf{v}) = \sum_{k=1}^{N_{e}} \int_{D_{k}} \widehat{\eta}_{\mu,Q}(x; U_{\mu}) \cdot [\mathbf{v}(x), \nabla \mathbf{v}(x)] \, dx = 0.$ **2. Reduced integration domain:** ECSW, EQP,... $\widehat{\mathcal{G}}_{\mu}(U_{\mu}, \mathbf{v}) = \sum_{k \in \mathbb{I}_{eq}} \rho_{k}^{eq} \int_{D_{k}} \eta_{\mu}(x; U_{\mu}) \cdot [\mathbf{v}(x), \nabla \mathbf{v}(x)] \, dx = 0.$ MtD copes with both hyper-reduction paradigms.

DtM requires the introduction of a reduced integration domain to avoid integration over Ω_{μ} .

 $^{^2 {\}rm For}$ DG discretizations, evaluation of Φ_{μ} at nodes of neighboring elements is also required.

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• We rely on **elementwise empirical quadrature** for hyper-reduction. Farhat et al., 2015; Yano 2019.

• Application of EQ within the DtM framework is straightforward: given $\mu \in \mathcal{P}$, DtM requires evaluation of Φ_{μ} in all nodes of the sampled elements².

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Projection-based pMOR

Projection scheme: LSPG+EQ

Introduce reduced-order bases $Z \in \mathbb{R}^{N,n}$, $Y \in \mathbb{R}^{N,j_{es}}$. Define the weighted residual $R^{eq}_{\mu}(u,v) = \sum_{k=1}^{N_e} \rho^{eq}_k r^k_{\mu}(u,v)$. EQ LSPG ROM: find $\widehat{\mathbf{U}}_{\mu} \in \operatorname*{arg\ min}_{\boldsymbol{\zeta}\in \operatorname{col}(\mathbf{Z})} \sup_{\boldsymbol{\eta}\in \operatorname{col}(\mathbf{Y})} \frac{R^{eq}_{\mu}(\boldsymbol{\zeta},\boldsymbol{\eta})}{\|\boldsymbol{\eta}\|_{\mathcal{Y}}}$.

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Implementation requires to address several points.

- Choice of trial ROB Z.
- Choice of test ROB \mathbf{Y} and the norm $\|\cdot\|_{\mathcal{Y}}$.
- Choice of the EQ weights $ho^{
 m eq}$.

Taddei, Zhang, A discretize-then-map approach for the treatment of parameterized geometries in model order reduction, CMAME, 2021.

Residual assembly: FE routine

Notation: $\phi_{i,k}^{\text{fe}} \ i = 1, \dots, n_{\text{lp}}$ FE basis in the *k*-th element; e_1, \dots, e_D canonical basis (*D* number of equations).

For
$$k = 1, \dots, N_{e}$$

Compute $R_{i,k,d}^{un} = r^{k} \left(U|_{\mathbb{D}_{k,\Phi}}, \phi_{i,k}^{fe} e_{d} \right)$,
 $i = 1 \dots, n_{lp}, d = 1, \dots, D$.

EndFor

 $\mathsf{R}^{\mathrm{hf}} \leftarrow \{\mathsf{R}^{\mathrm{un}}_{i,k,d}\}_{i,k,d}, \ \ \mathsf{R}^{\mathrm{hf}} \in \mathbb{R}^{\mathsf{N}} \ \mathsf{FE} \ \mathsf{vector} \ \mathsf{assembly}.$

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- $\mathsf{R}^{\mathrm{hf}} \leftarrow \{\mathsf{R}^{\mathrm{un}}_{i,k,d}\}_{i,k,d}, \ \ \mathsf{R}^{\mathrm{hf}} \in \mathbb{R}^{\mathsf{N}} \ \mathsf{FE} \ \mathsf{vector} \ \mathsf{assembly}.$
- Computation of $\{R_{i,k,d}^{un}\}_{i,d}$ relies on element-wise assembly routines that take as input $\{\Phi(x_{i,k})\}_i$.
- Assembly of the FE vector is independent of the PDE.

Residual assembly: MOR routine

Notation: $\mathbf{Y} = [\boldsymbol{\psi}_1, \dots, \boldsymbol{\psi}_{j_{es}}] \in \mathbb{R}^{N, j_{es}}$ test space; $\mathbf{T}_{i,k}$ index of the *i*-th node of the *k*-th element. $\mathbf{Y}_{i,k,d,j}^{\text{un}} = \mathbf{Y}_{\mathbf{T}_{i,k}+(d-1)N,j}$ unassembled test space, $\widehat{\mathbf{R}} \in \mathbb{R}^{j_{es}}$ reduced residual, $(\widehat{\mathbf{R}})_j = R^{\text{eq}}_{\mu}(U, \psi_j)$. For $k \in \mathbf{I}_{eq}$ Compute $R^{\text{un}}_{i,k,d} = r^k (U|_{\mathbf{D}_{k,\Phi}}, \phi^{\text{fe}}_{i,k}e_d),$ $i = 1, \dots, n_{\text{lp}}, d = 1, \dots, D$.

EndFor

$$\left(\widehat{\mathsf{R}}\right)_{j} = \sum_{k \in \mathtt{I}_{\mathrm{eq}}} \rho_{k}^{\mathrm{eq}} \left(\sum_{i=1}^{n_{\mathrm{lp}}} \sum_{d=1}^{D} \mathsf{Y}_{i,k,d,j}^{\mathrm{un}} \mathsf{R}_{i,k,d}^{\mathrm{un}}\right), j = 1, \dots, j_{\mathrm{es}}.$$

Residual assembly: MOR routine

Notation: $\mathbf{Y} = [\boldsymbol{\psi}_1, \dots, \boldsymbol{\psi}_{i_{\text{res}}}] \in \mathbb{R}^{N, j_{\text{res}}}$ test space; $T_{i,k}$ index of the *i*-th node of the k-th element. $\mathbf{Y}_{i,k,d,j}^{\mathrm{un}} = \mathbf{Y}_{\mathtt{T}_{i,k}+(d-1)N,j}$ unassembled test space, $\widehat{\mathsf{R}} \in \mathbb{R}^{j_{\mathrm{es}}}$ reduced residual, $(\widehat{\mathsf{R}})_i = R^{\text{eq}}_{\mu}(U, \psi_j).$ For $k \in I_{eq}$ Compute $R_{i,k,d}^{\text{un}} = r^k \left(U|_{\mathsf{D}_{k,\Phi}}, \phi_{i,k}^{\text{fe}} e_d \right)$, $i = 1..., n_{lp}, d = 1, ..., D$

EndFor

$$\left(\widehat{\mathsf{R}}\right)_{j} = \sum_{k \in \mathbb{I}_{eq}} \rho_{k}^{eq} \left(\sum_{i=1}^{n_{lp}} \sum_{d=1}^{D} \mathsf{Y}_{i,k,d,j}^{un} \mathsf{R}_{i,k,d}^{un}\right), j = 1, \dots, j_{es}.$$

• MOR assembly exploits available FE routines.

• Geometry variations don't influence MOR assembly.

Application to 2D RANS

Ahmed's body problem

Closure model: SA. Discretization: stab P2-P2 FEM. Re = $\frac{u_{in}H_c}{\nu} = 3 \cdot 10^3$, $\mu \in [5^\circ, 50^\circ]$.







We consider a piecewise-bilinear mapping (Gordon-Hall). FE mesh is not conforming with the coarse-grained partition.





Numerical results

Relative error averaged over 10 out-of-sample configurations.



Legend: projection $-\bullet$, ROM with HF quadrature $-\blacksquare$, $tol_{eq} = 10^{-6}$, $tol_{eq} = 10^{-10}$, $tol_{eq} = 10^{-14}$.

Conclusions and perspectives

Summary

• We discuss the treatment of parameterized geometries in projection-based pMOR.

- We consider two approaches:
- 1. Discretize-then-Map;
- 2. Map-then-Discretize.

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• We discuss the treatment of parameterized geometries in projection-based pMOR.

• We consider two approaches:

1. Discretize-then-Map;

2. Map-then-Discretize.

Take-aways

• DtM is simpler to implement, and can be used in combination with non-smooth mappings.

• MtD copes with a broader class of hyper-reduction methods (\rightarrow possibly larger speedups), and does not require discrete bijectivity wrt the mesh.

Thank you for your attention!

For more information, visit the website:

math.u-bordeaux.fr/~ttaddei/ .

1. Taddei, Zhang; A discretize-then-map approach for the treatment of parameterized geometries in model order reduction, CMAME, 2021.

2. Ferrero, Taddei, Zhang; *Registration-based model reduction of parameterized two-dimensional conservation laws*, Arxiv preprint 2021.