

# Computational Brain Connectivity Mapping

Winter School Workshop 2017 – November 20-24 2017, Juan-les-Pins, France

## Quality assessment and correction methods for diffusion MRI data

Alexander Leemans

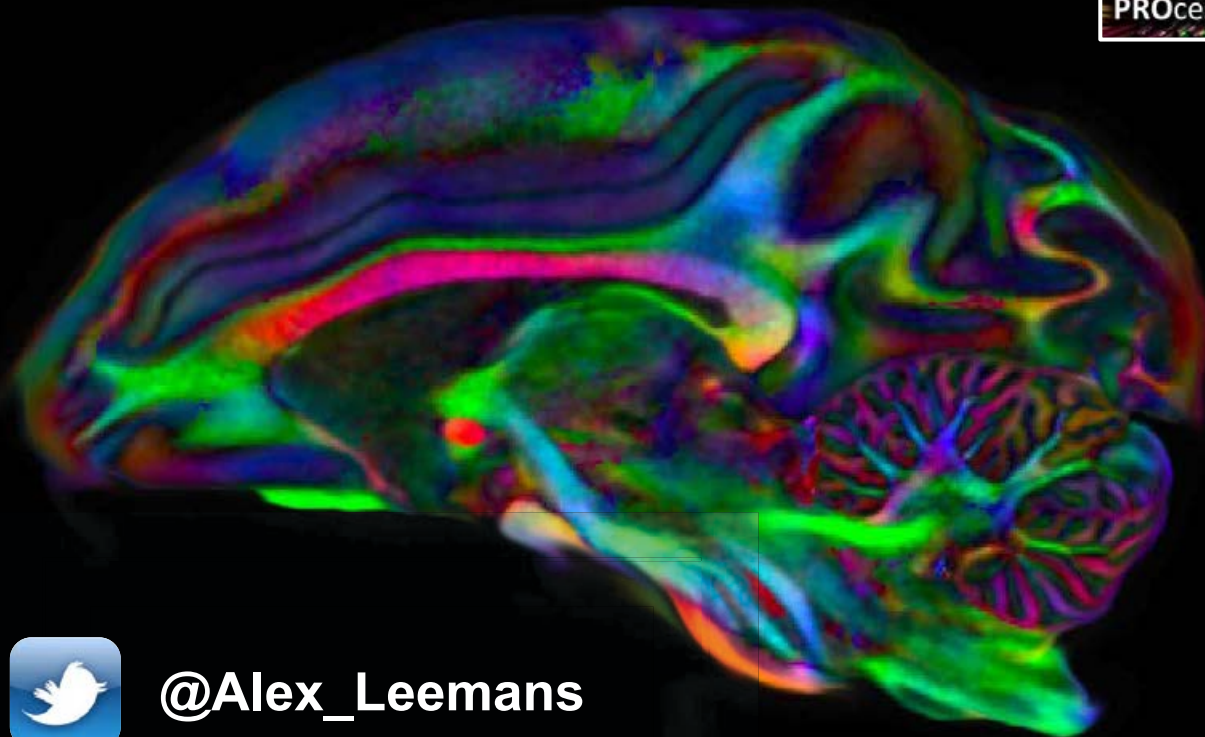


Image Sciences Institute



University Medical Center  
Utrecht, the Netherlands



@Alex\_Leemans

# A typical day at the office...



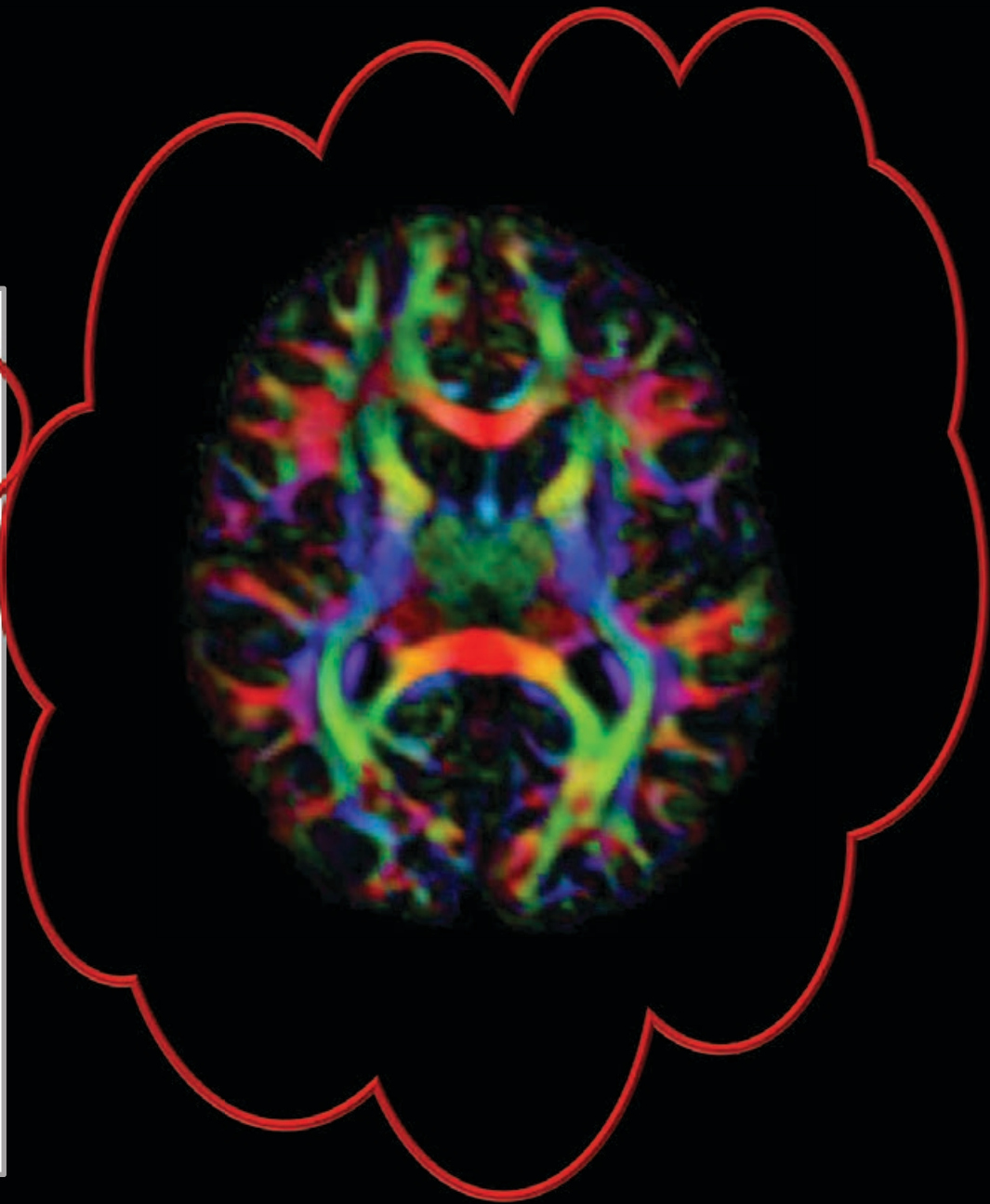
Hi Alex, I have been collecting “advanced DTI data”.  
Can you help me with the analysis?\*



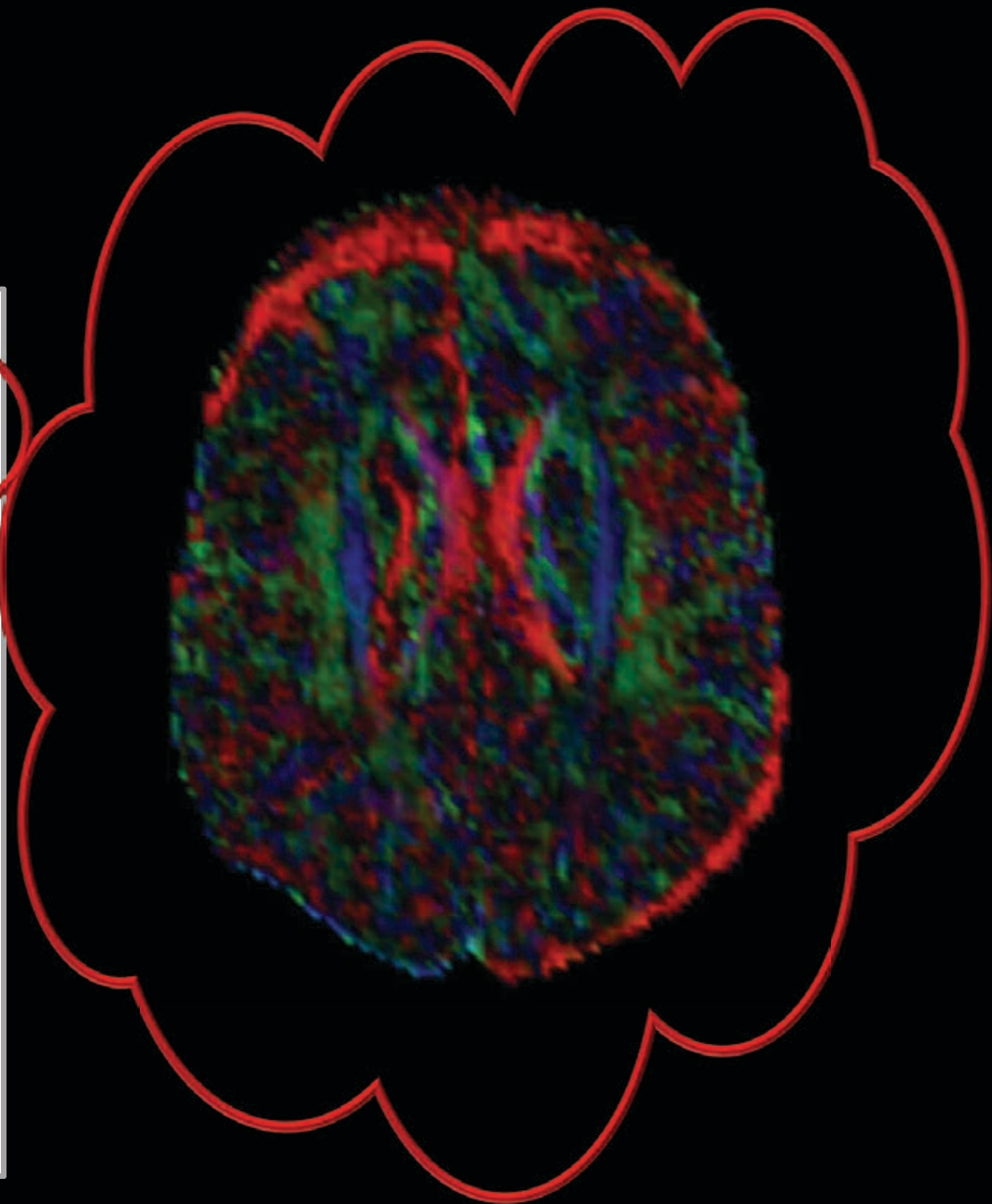
\* Read: “Can you do the analysis for me?”



@Alex\_Leemans

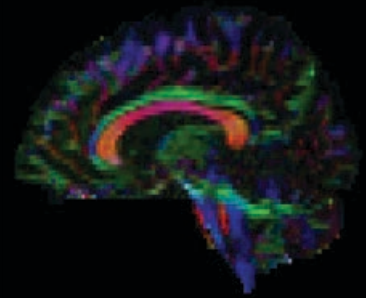
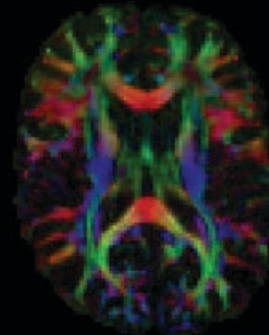
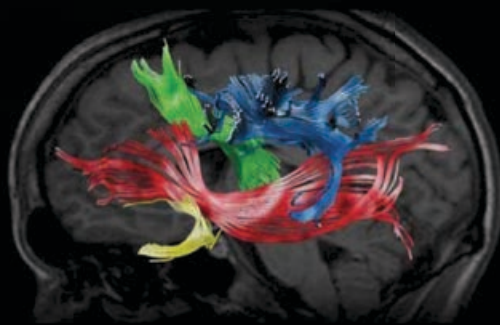
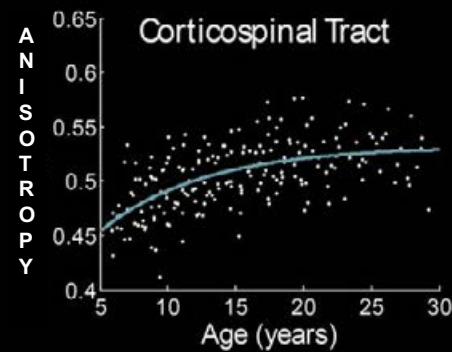
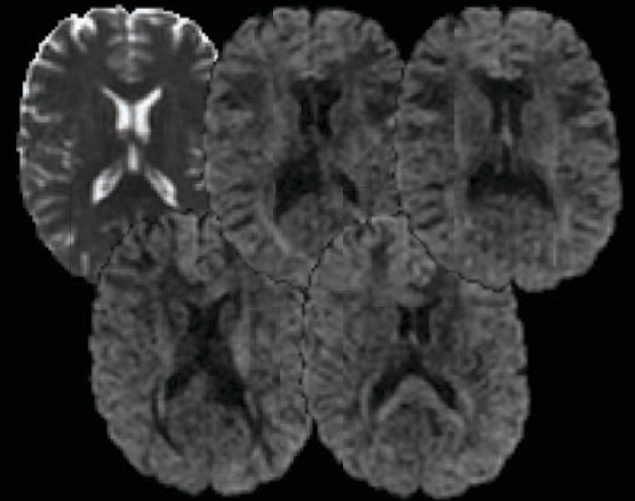
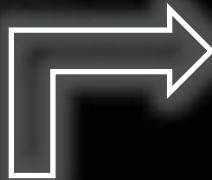


@Alex\_Leemans

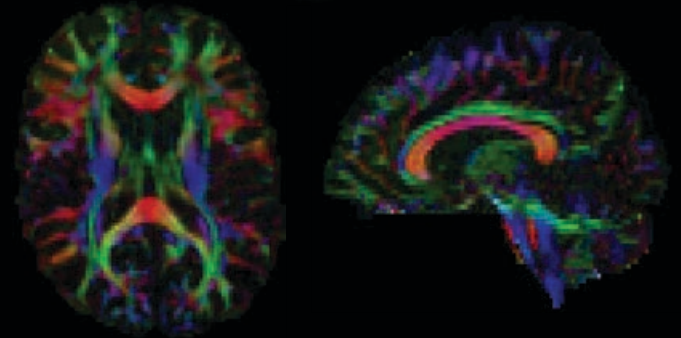
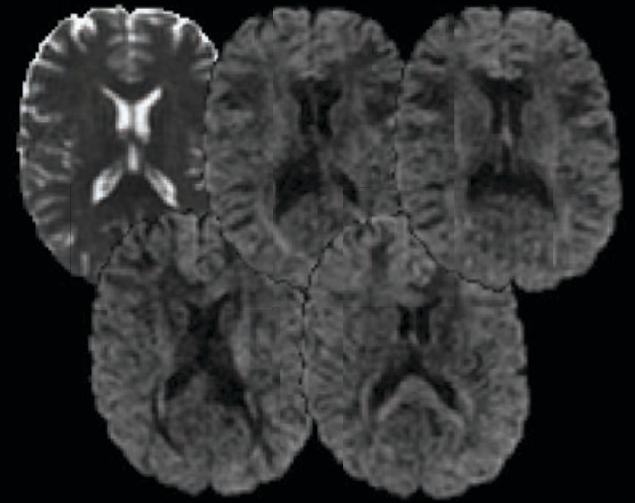


@Alex\_Leemans

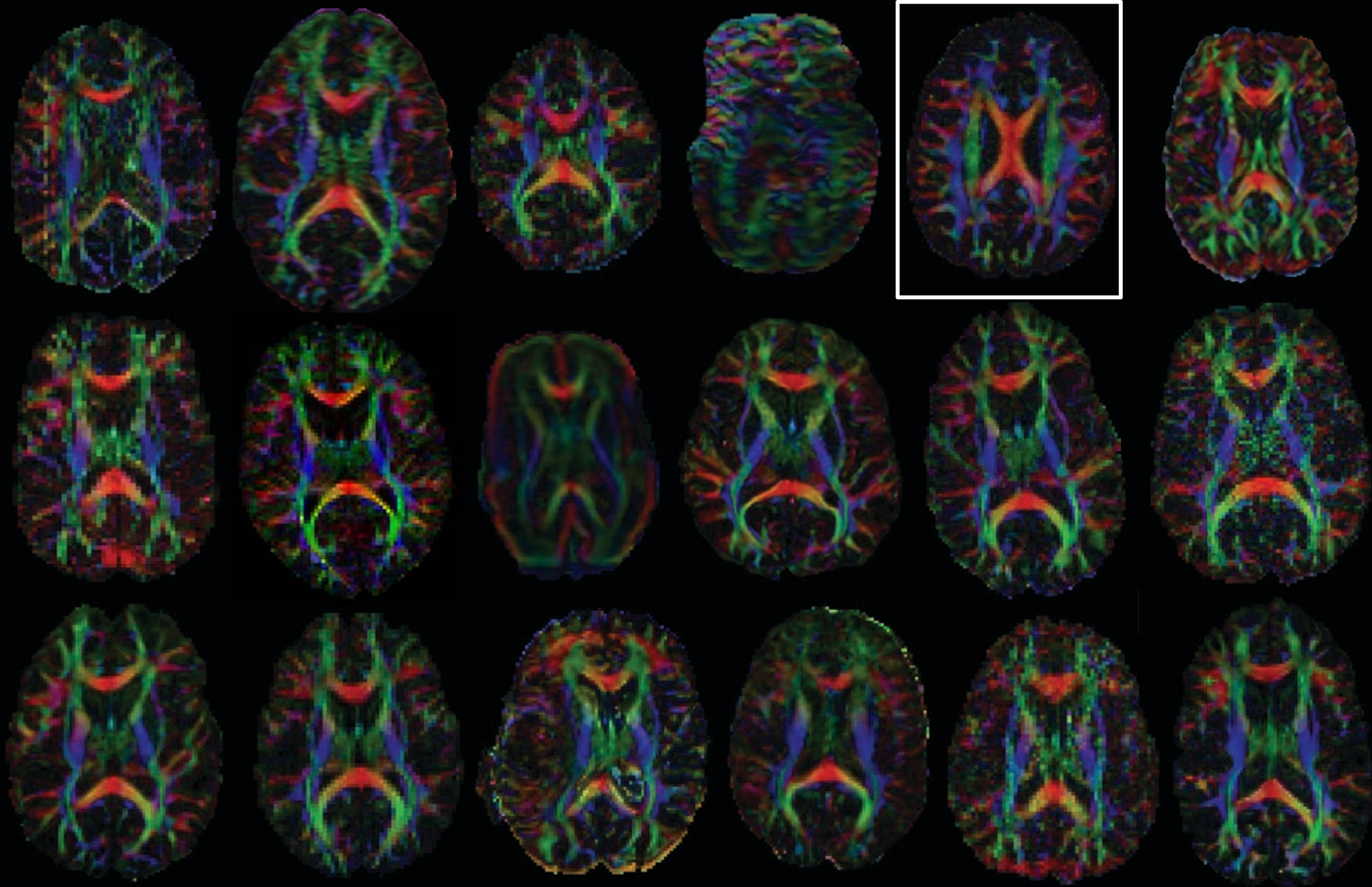
# The pipeline ...



# Data quality assessment ...

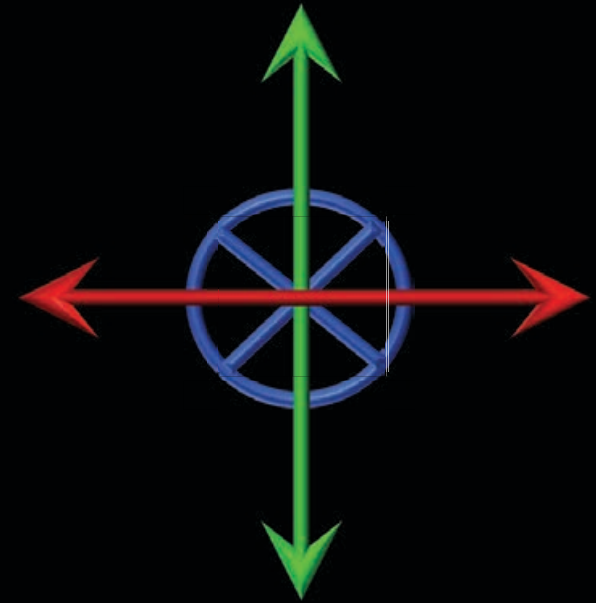
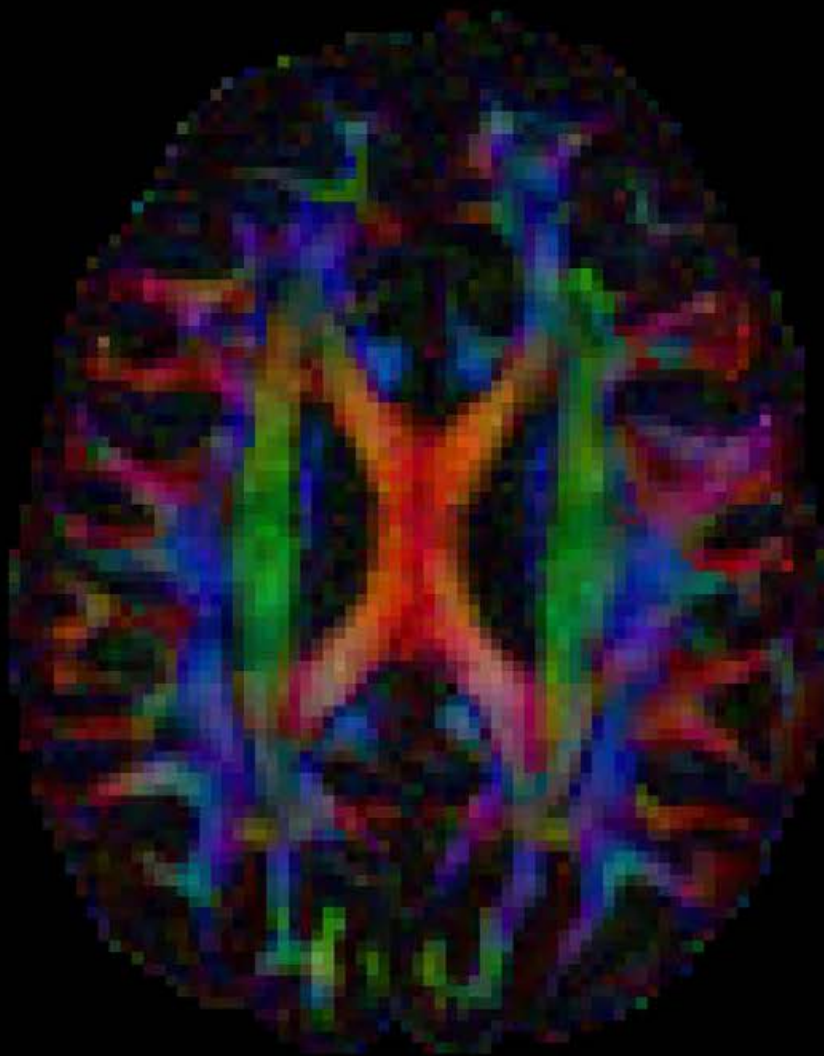


# Data quality assessment ...



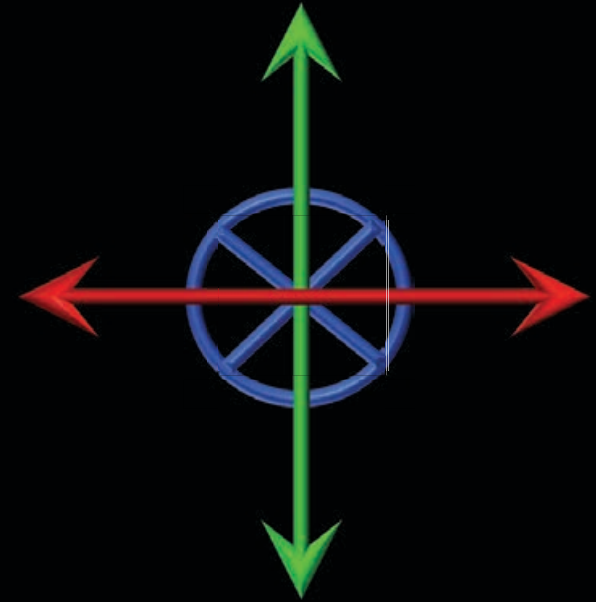
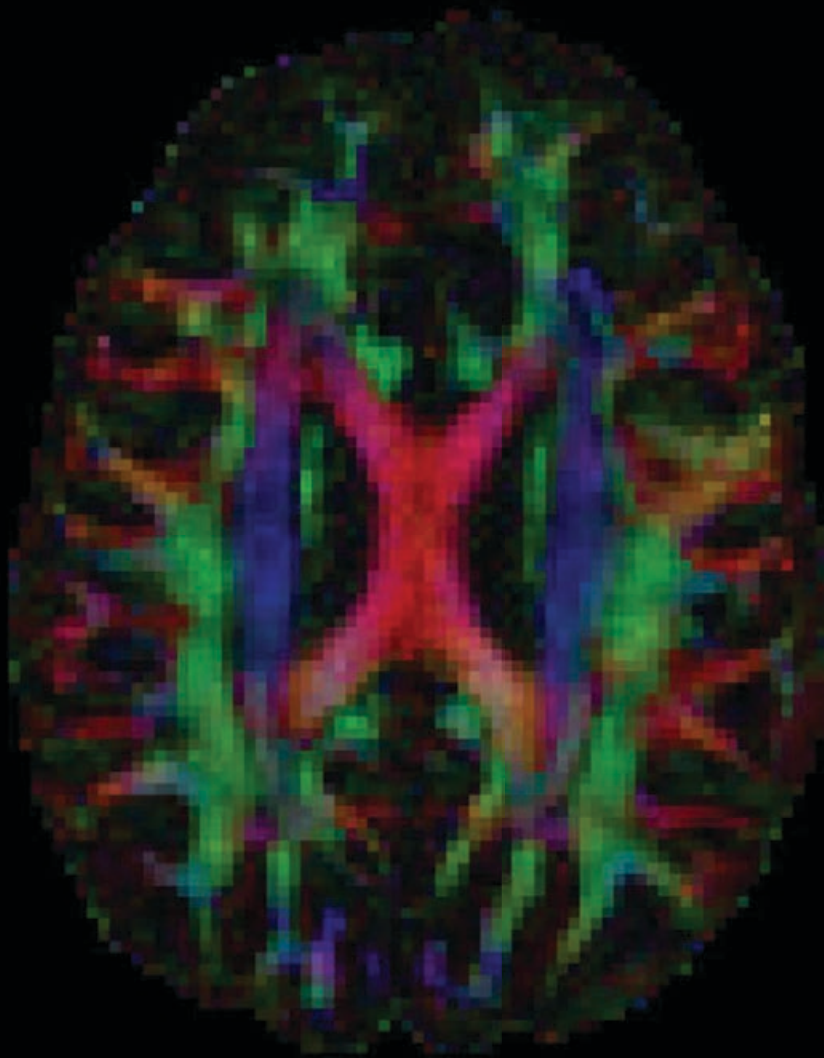


# Data quality assessment ...



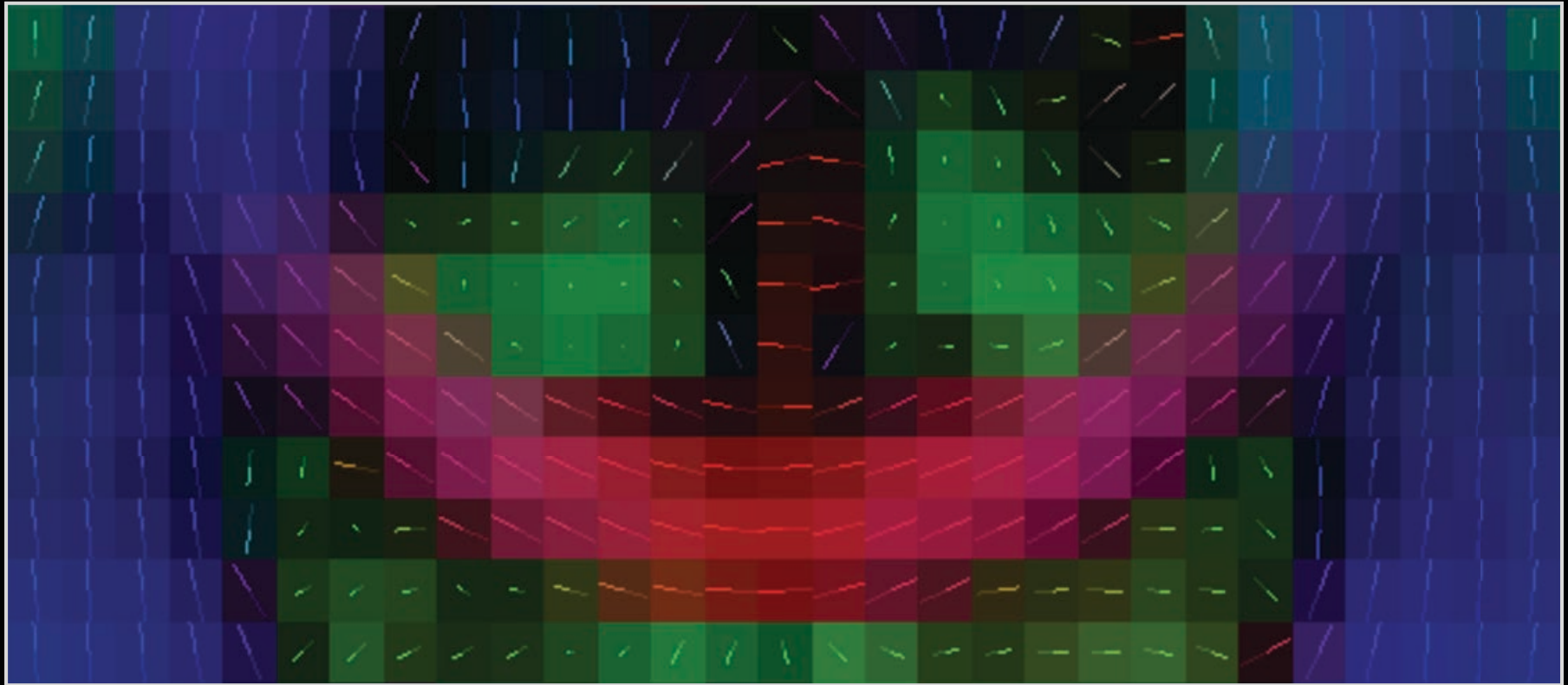
Color-encoding is  
not conventional

# Data quality assessment ...



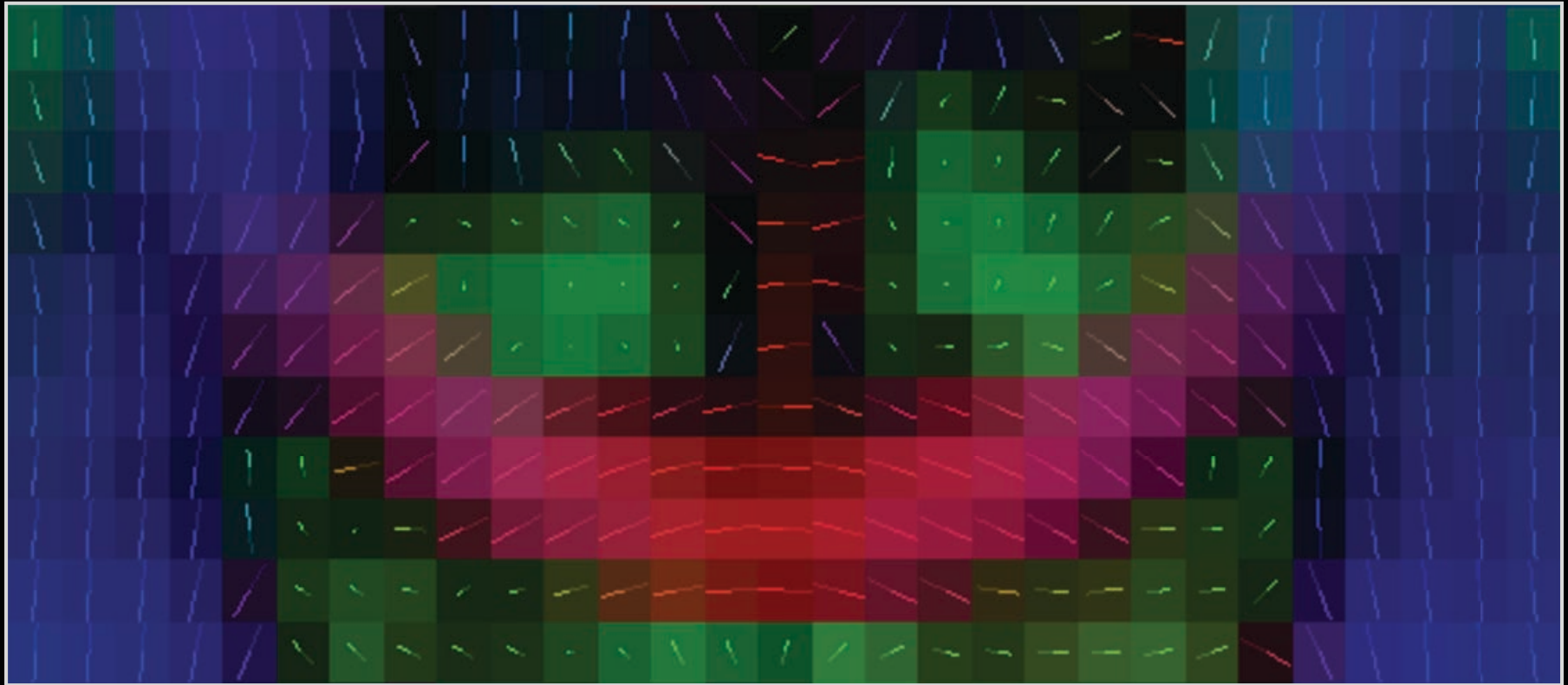
Conventional Color-  
encoding

# Data quality assessment ...



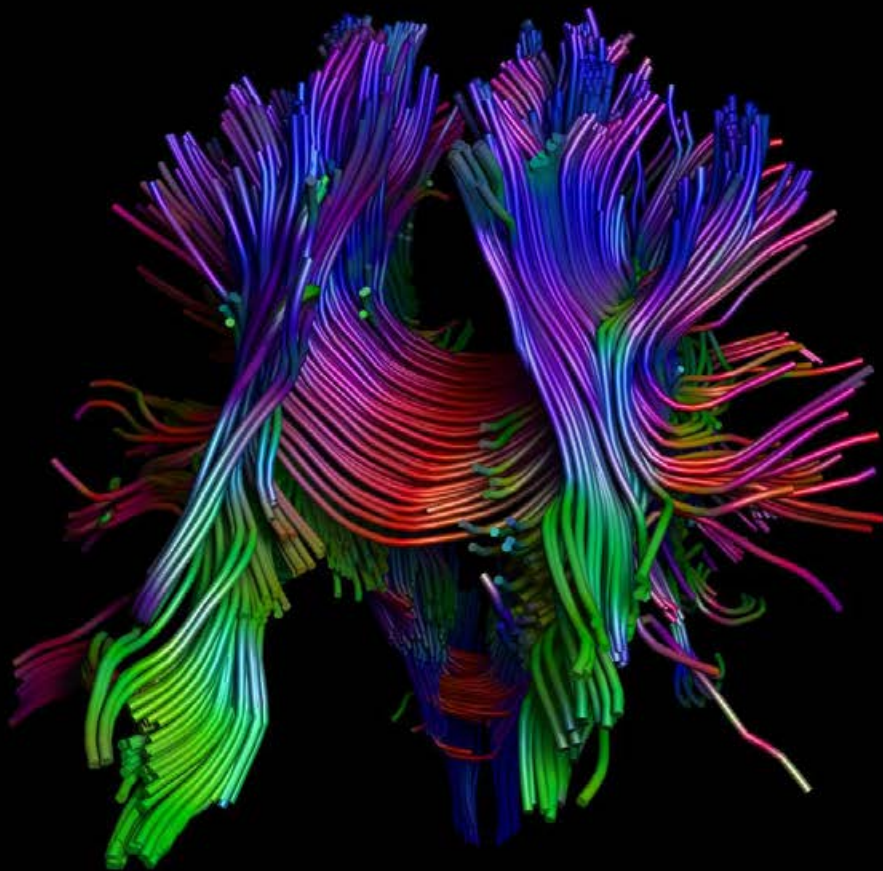
No axis mismatch

# Data quality assessment ...



Axis “sign flip”

# Data quality assessment ...



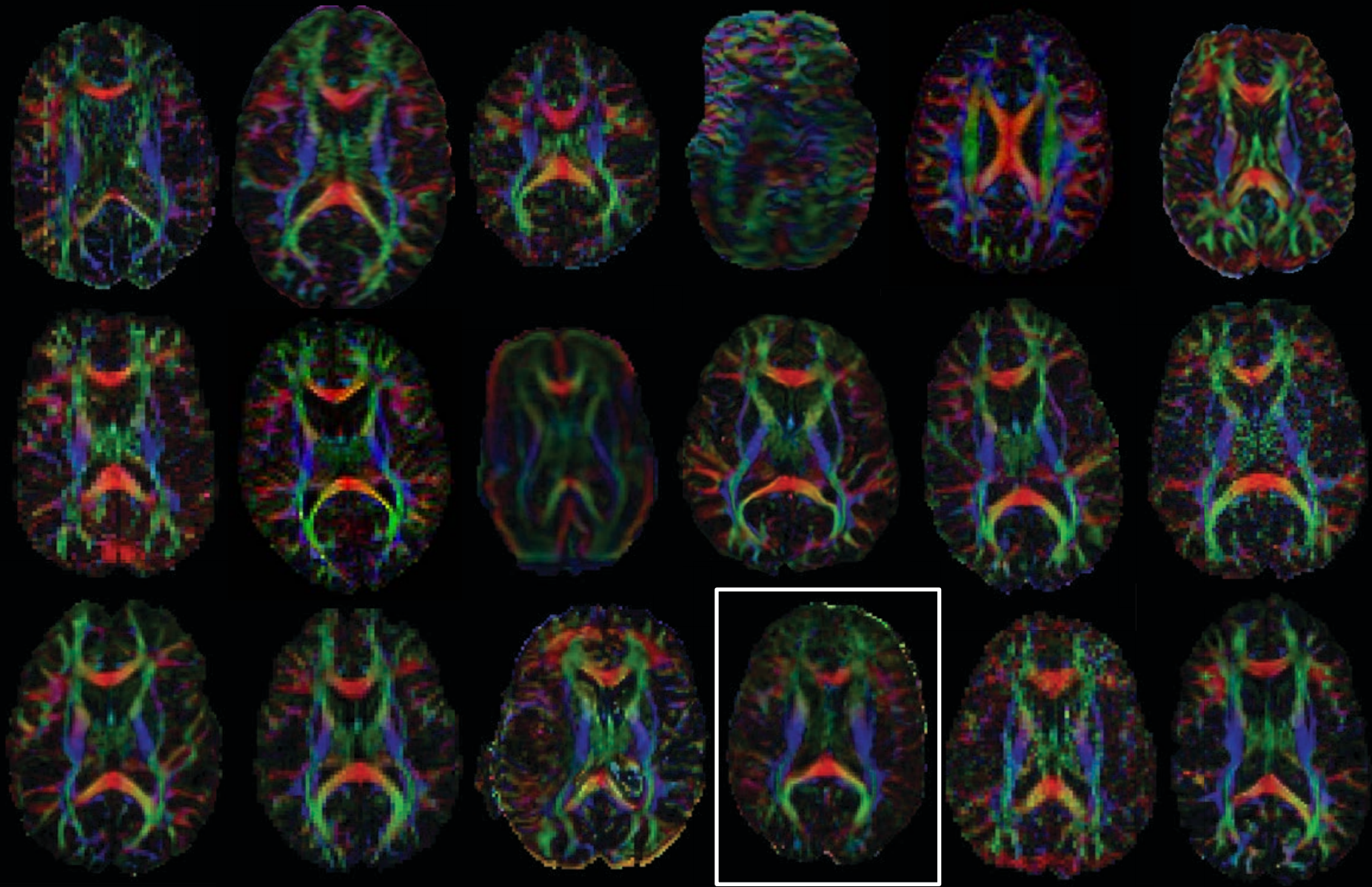
Axis “sign flip”



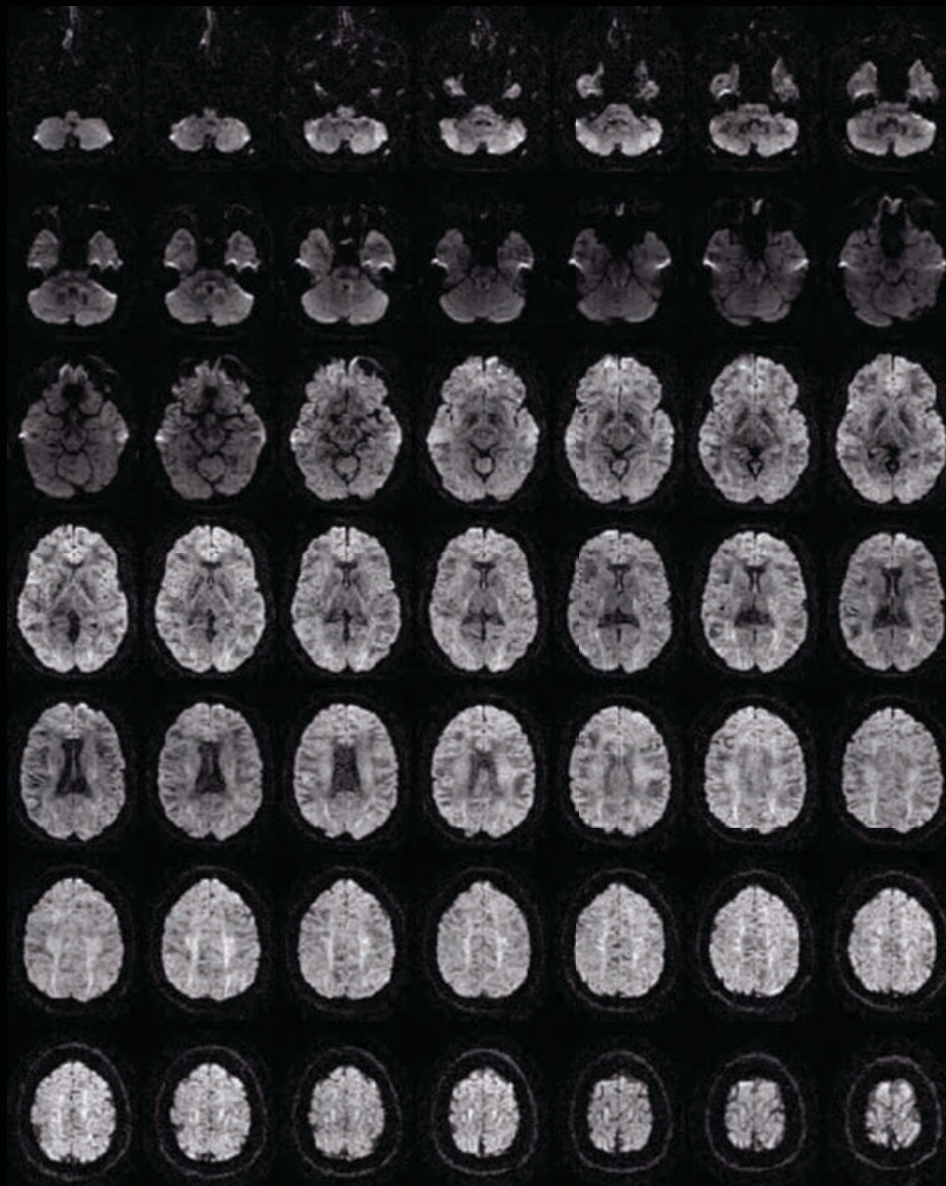
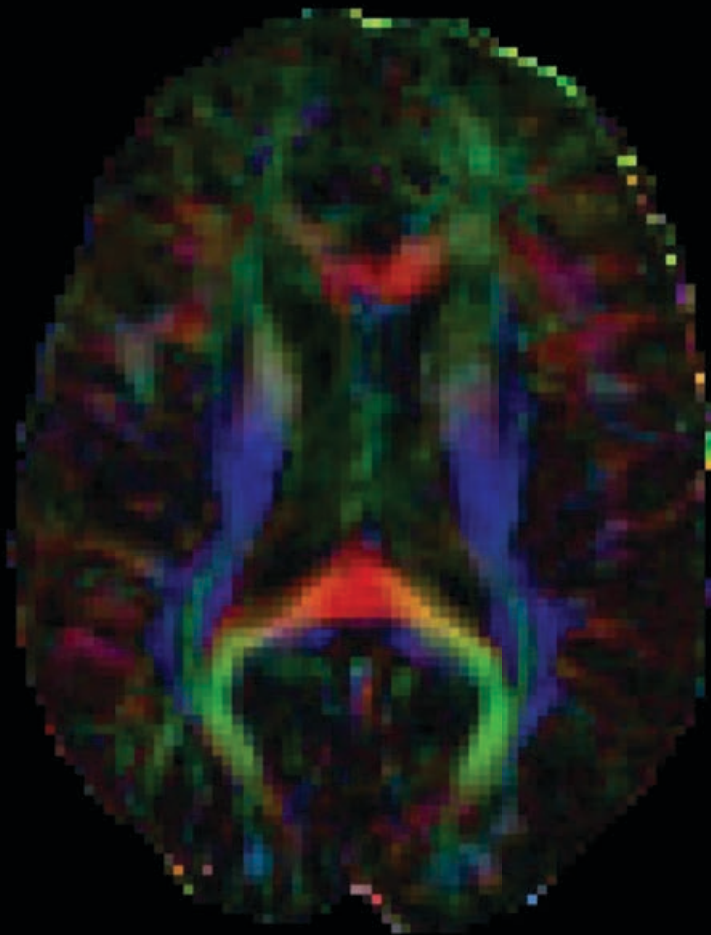
Correct



# Data quality assessment ...



# Data quality assessment ...



Look at your raw data!  
Make a movie loop...



# Data quality assessment ...

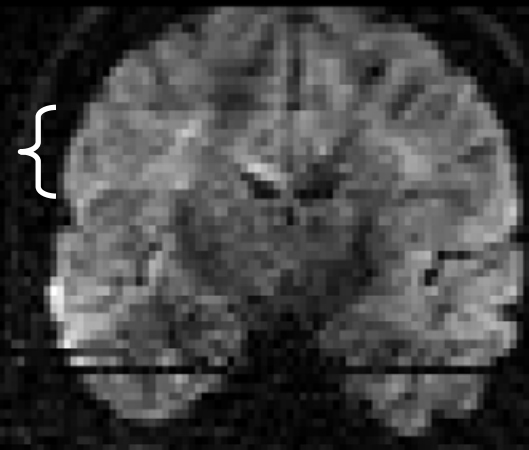
Different views!



Axial



Sagittal

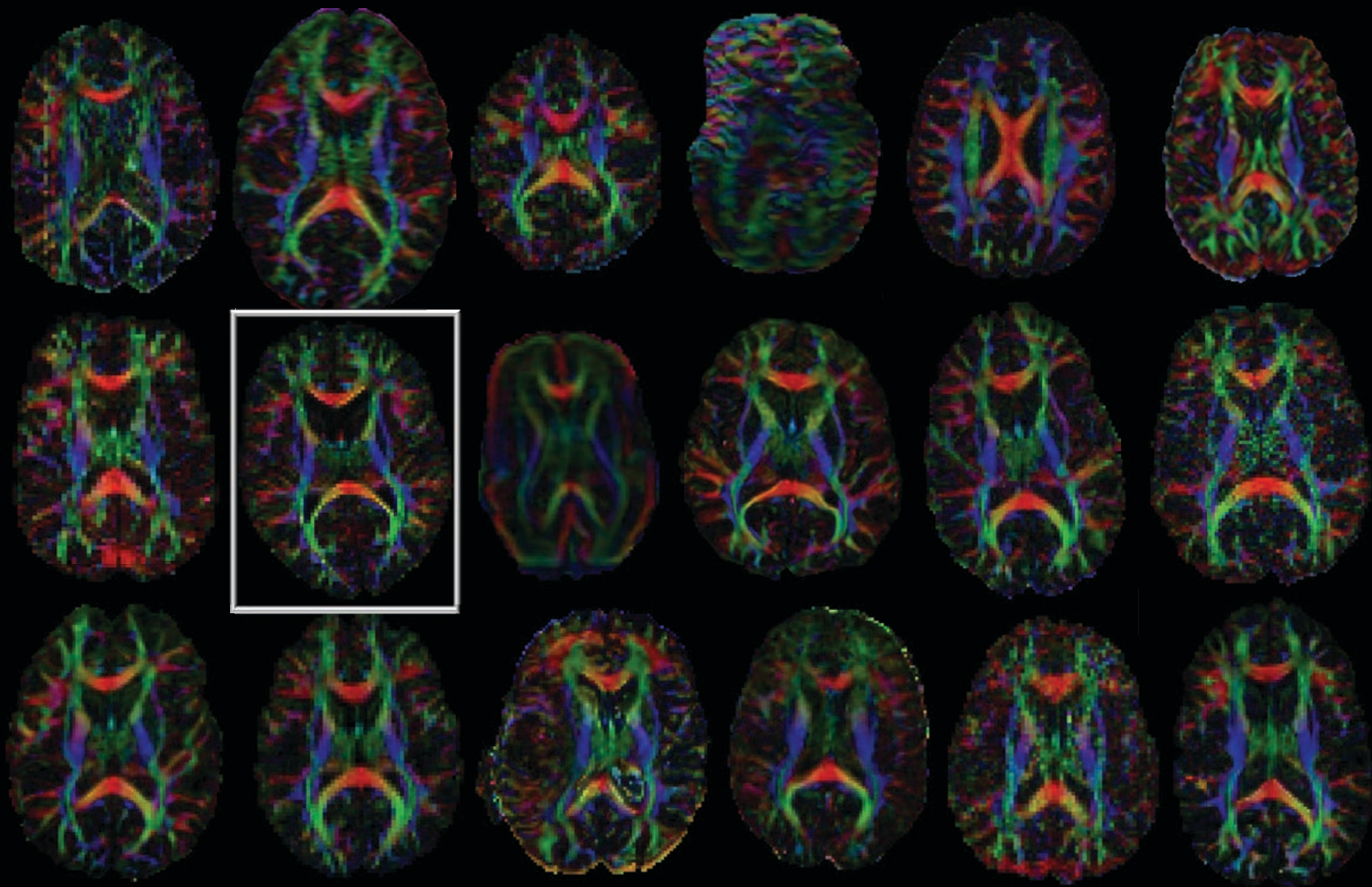


Coronal

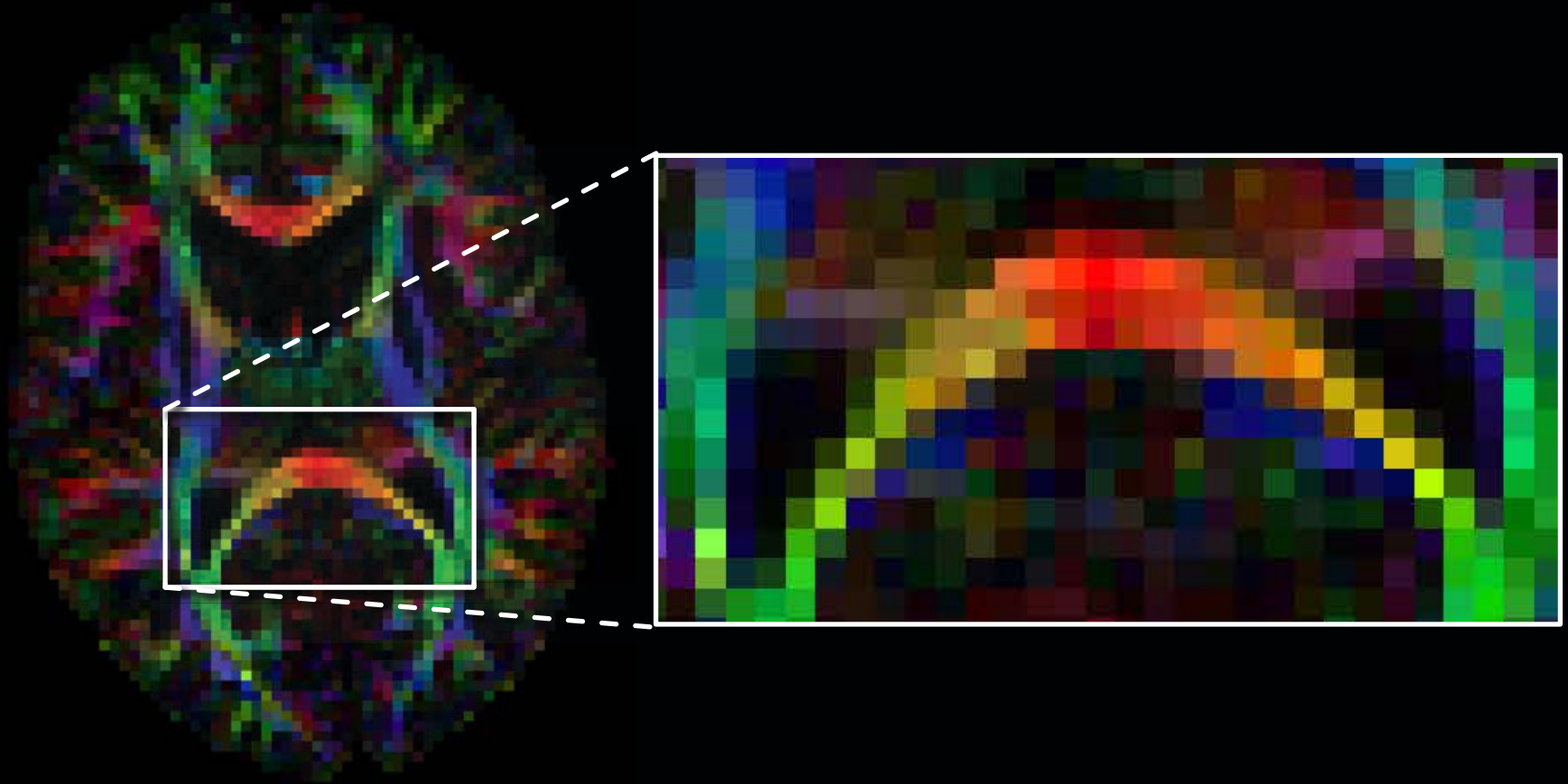




# Data quality assessment ...



# Data quality assessment ...



# Data quality assessment ...

“Physically Implausible Signals” (PIS)

$$S = S_0 e^{-b \cdot D}$$

$S$  = diffusion weighted signal

$S_0$  = non-diffusion weighted signal

$b$  = diffusion weighting

$D$  = diffusion coefficient



# Data quality assessment ...

“Physically Implausible Signals” (PIS)

$$S = S_0 \underbrace{e^{-b \cdot D}}_{< 1}$$
$$\rightarrow S < S_0$$

$S$  = diffusion weighted signal

$S_0$  = non-diffusion weighted signal

$b$  = diffusion weighting

$D$  = diffusion coefficient



# Data quality assessment ...

“Physically Implausible Signals” (PIS)

The painful reality ...

$$S > S_0$$

$S$  = diffusion weighted signal

$S_0$  = non-diffusion weighted signal

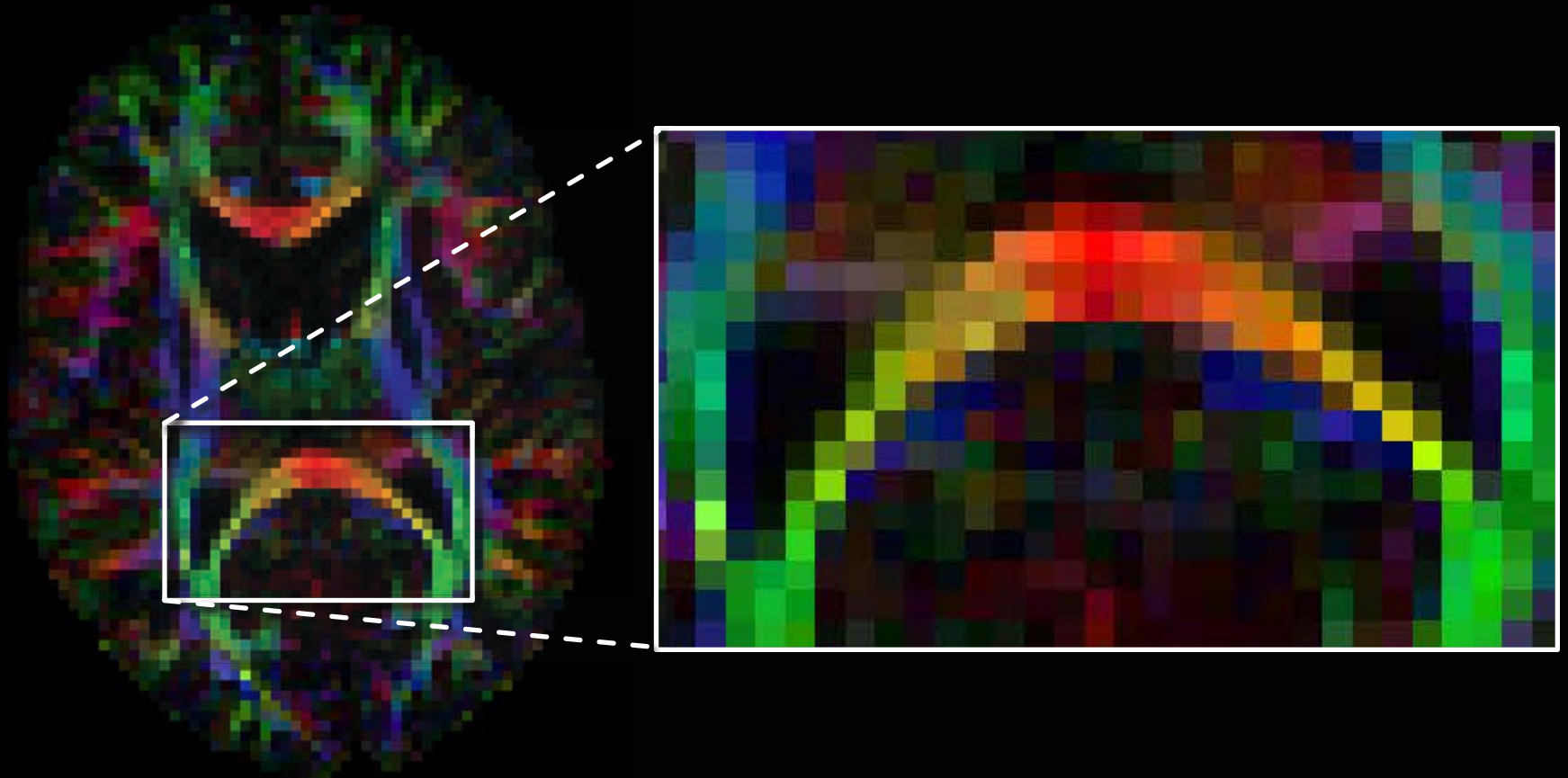
$b$  = diffusion weighting

$D$  = diffusion coefficient



# Data quality assessment ...

“Physically Implausible Signals” (PIS)

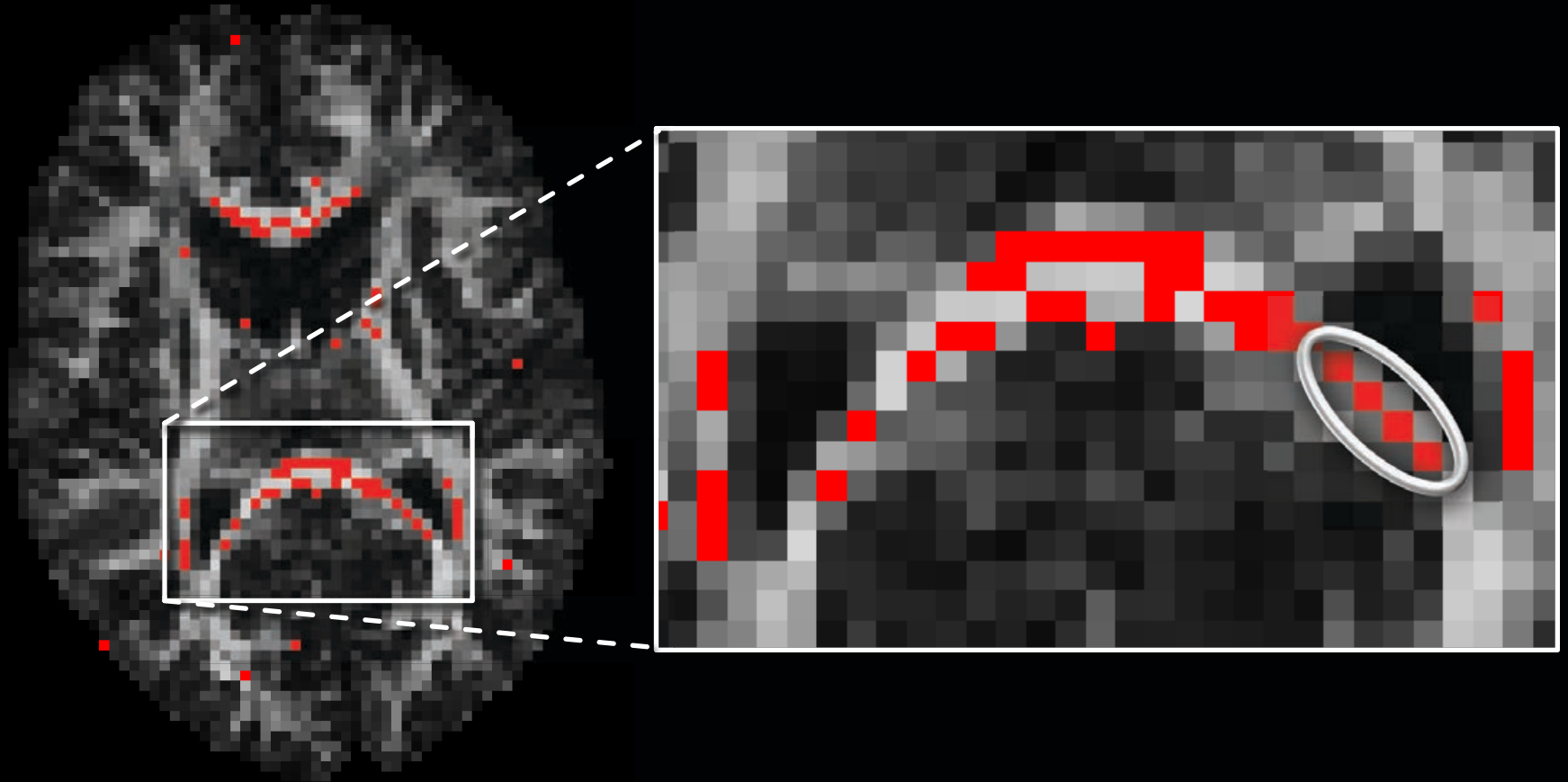


Color-coded fractional anisotropy (FA)



# Data quality assessment ...

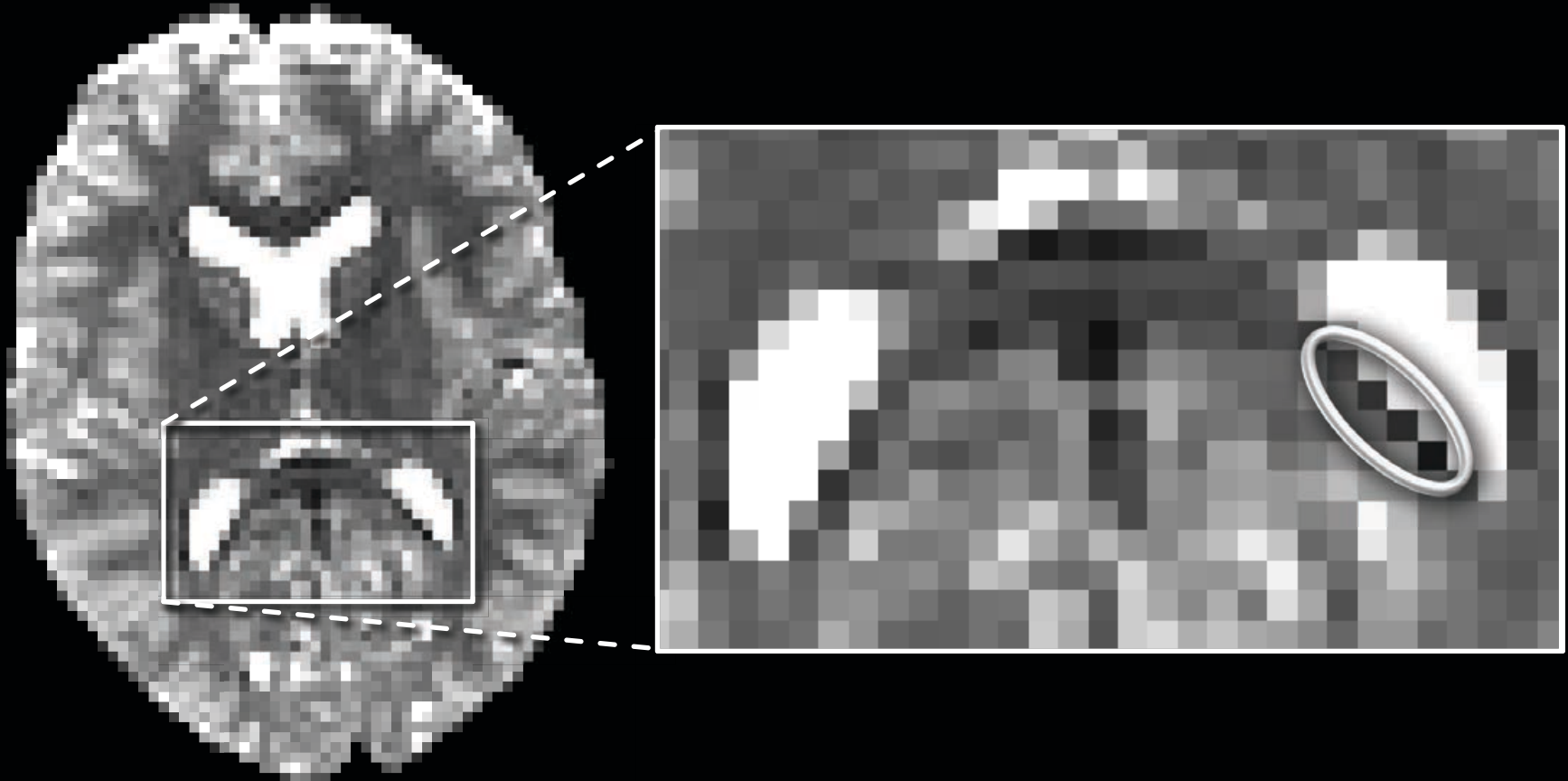
“Physically Implausible Signals” (PIS)



Regions with “PIS” ( $S > S_0$ ) overlaid on FA!!!

# Data quality assessment ...

“Physically Implausible Signals” (PIS)

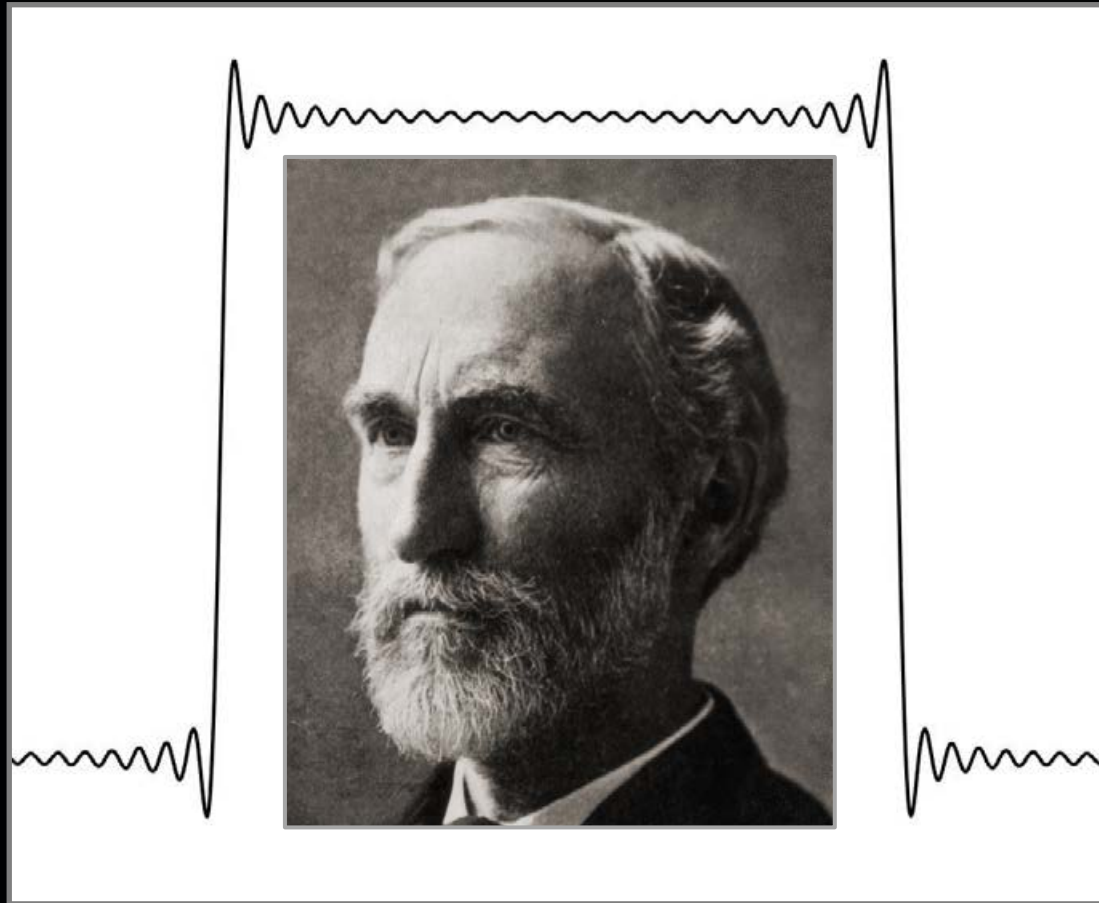


“PIS” → in regions with low  $S_0$  values



# Data quality assessment ...

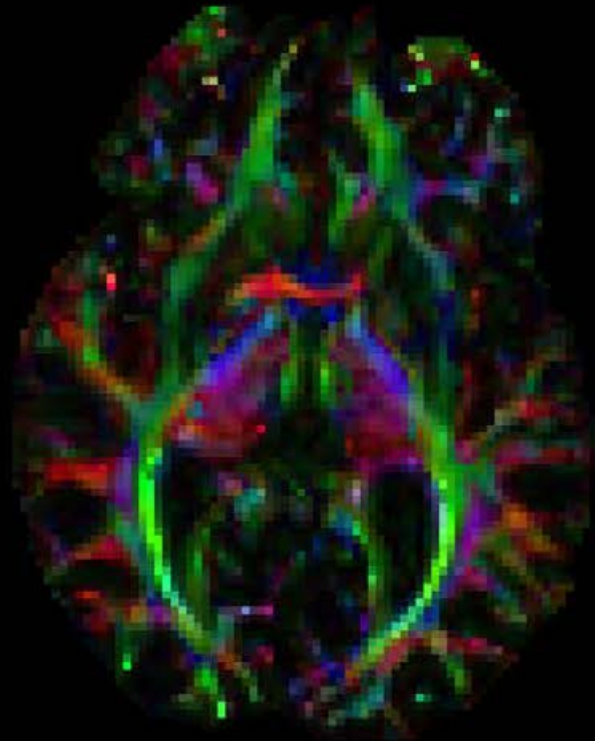
“Physically Implausible Signals” (PIS)



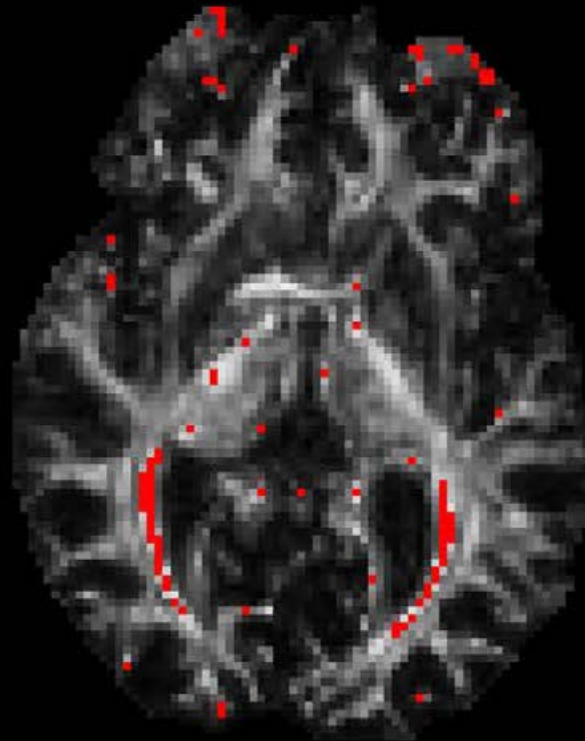
Josiah W. Gibbs

# Data quality assessment ...

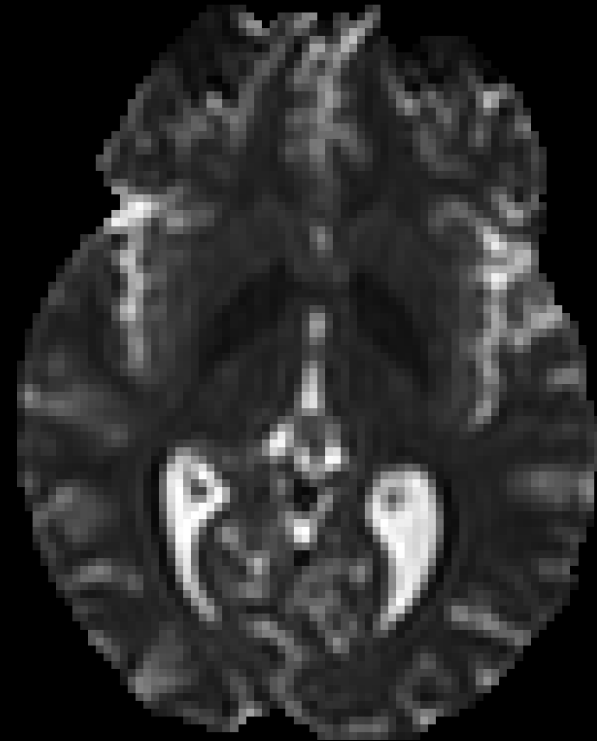
“Physically Implausible Signals” (PIS)



Color-coded FA



“PIS” on FA

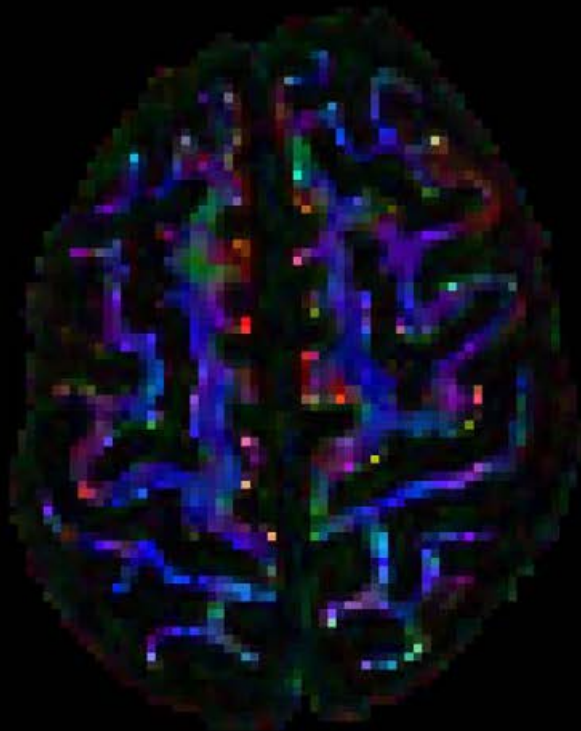


$S_0$

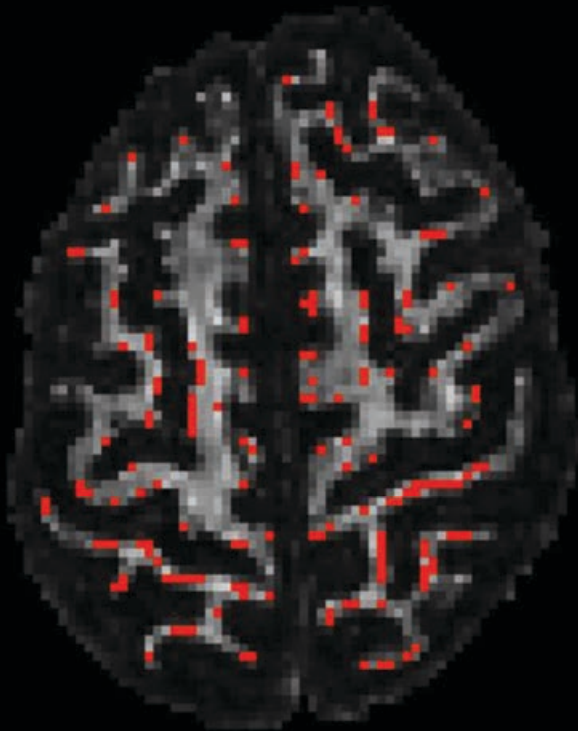


# Data quality assessment ...

“Physically Implausible Signals” (PIS)



Color-coded FA



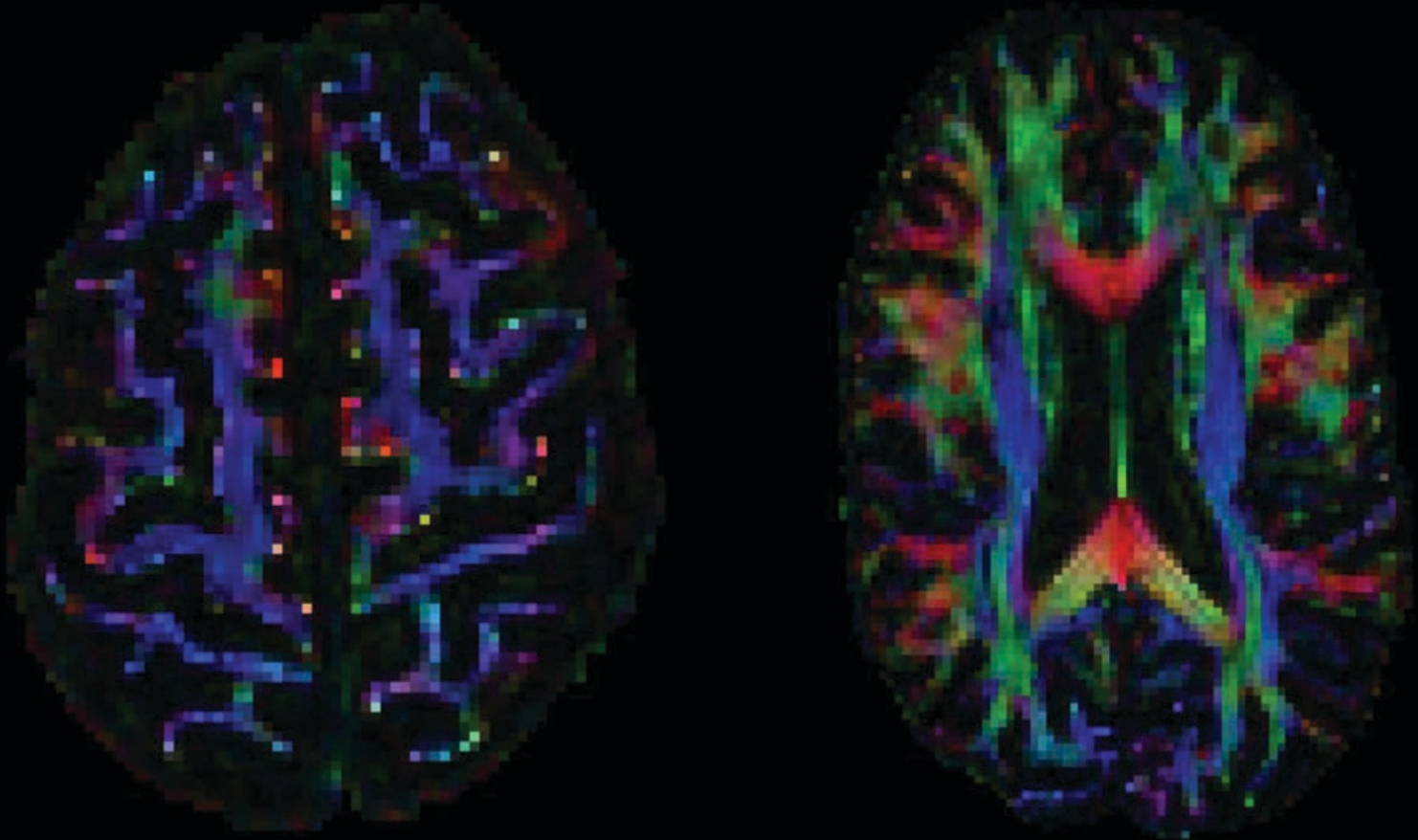
“PIS” on FA



$S_0$

# Data quality assessment ...

“Physically Implausible Signals” (PIS)

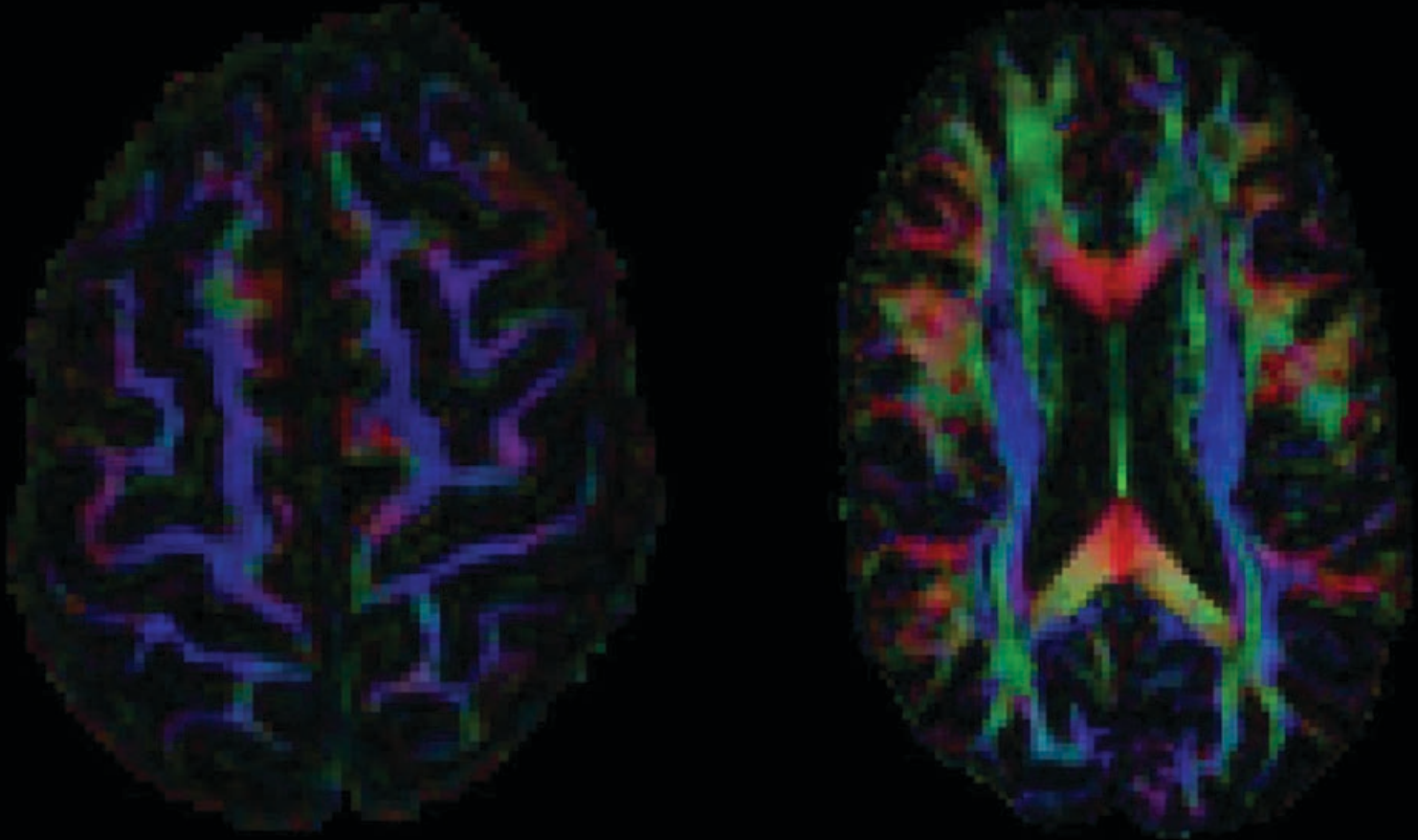


**Before** correcting for Gibbs ringing artifacts



# Data quality assessment ...

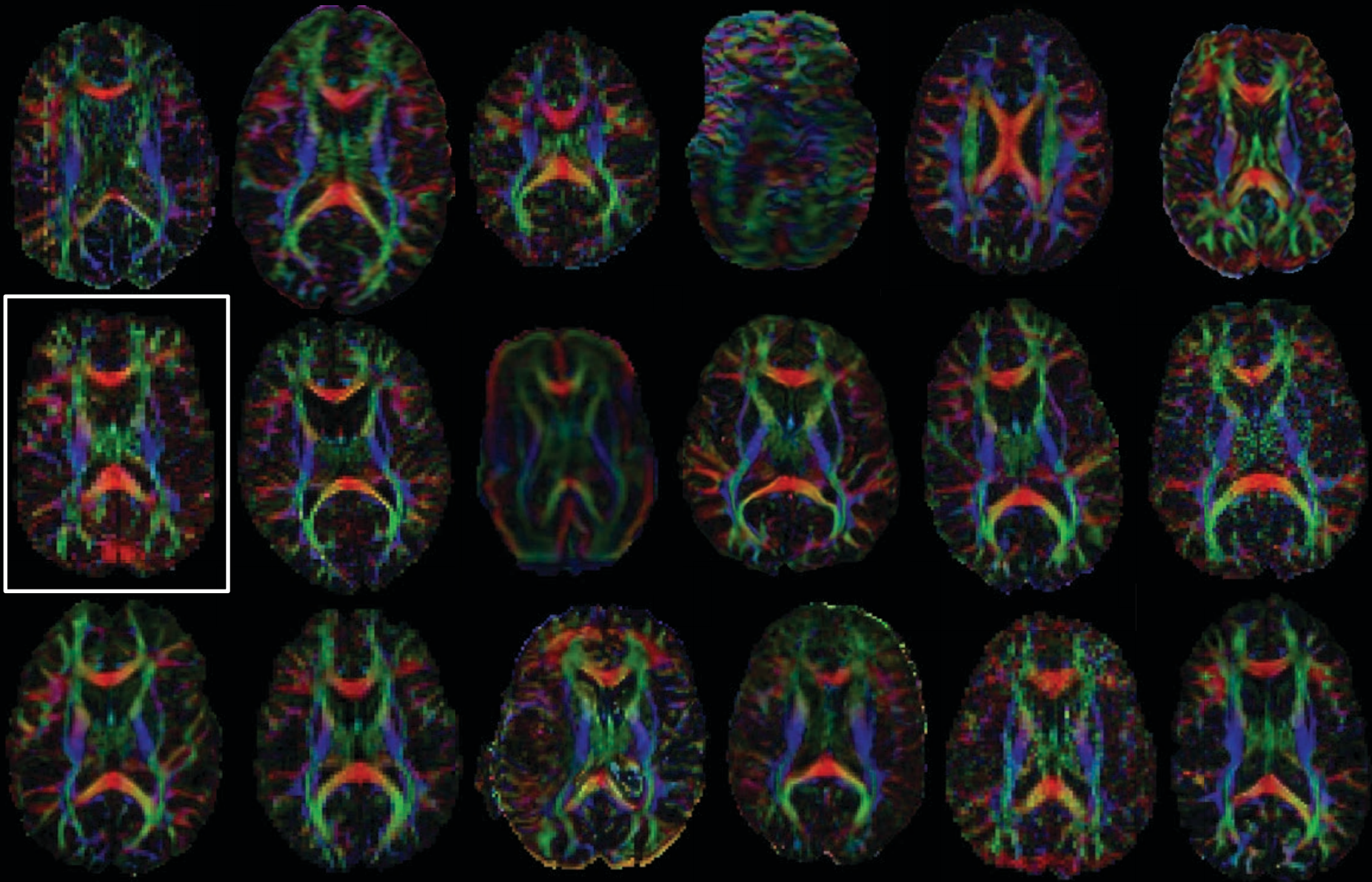
“Physically Implausible Signals” (PIS)



**After** correcting for Gibbs ringing artifacts

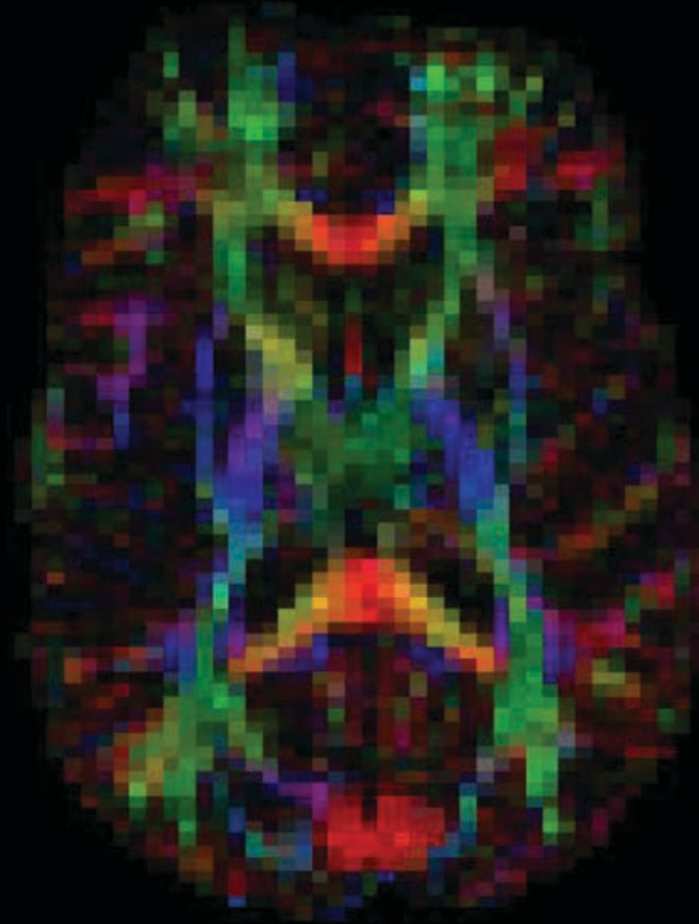


# Data quality assessment ...



# Data quality assessment ...

Residuals from the model estimation



# Data quality assessment ...

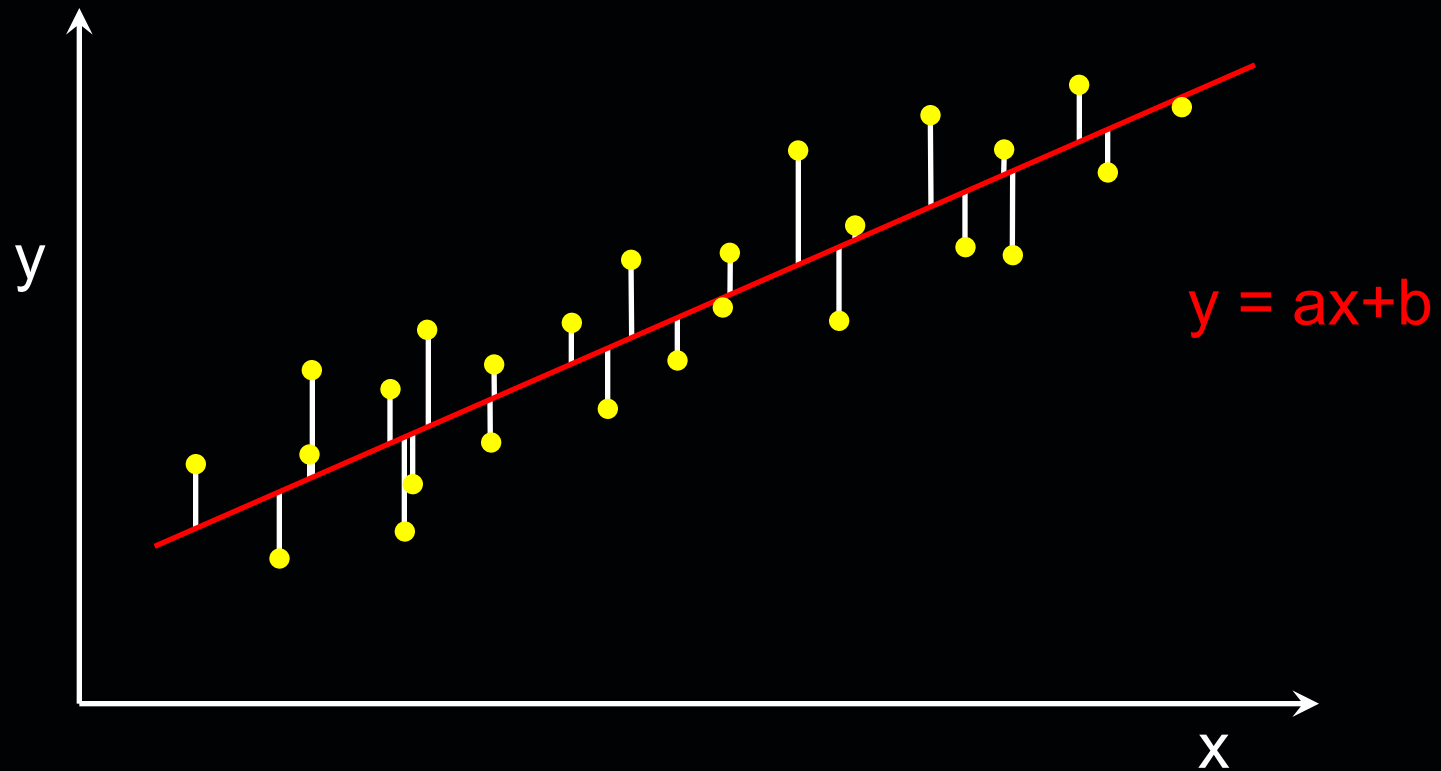
Residuals from the model estimation





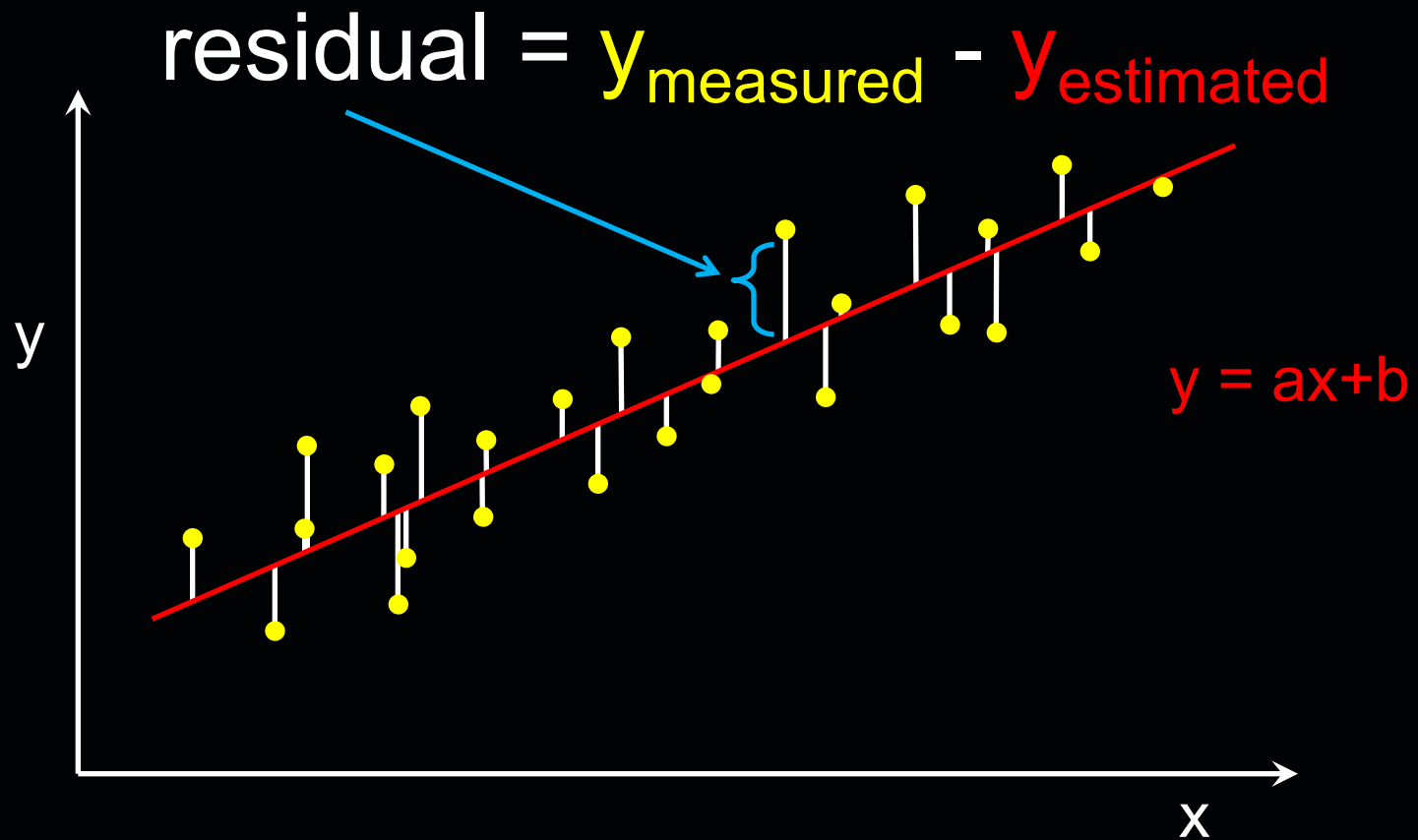
# Data quality assessment ...

Residuals from the model estimation



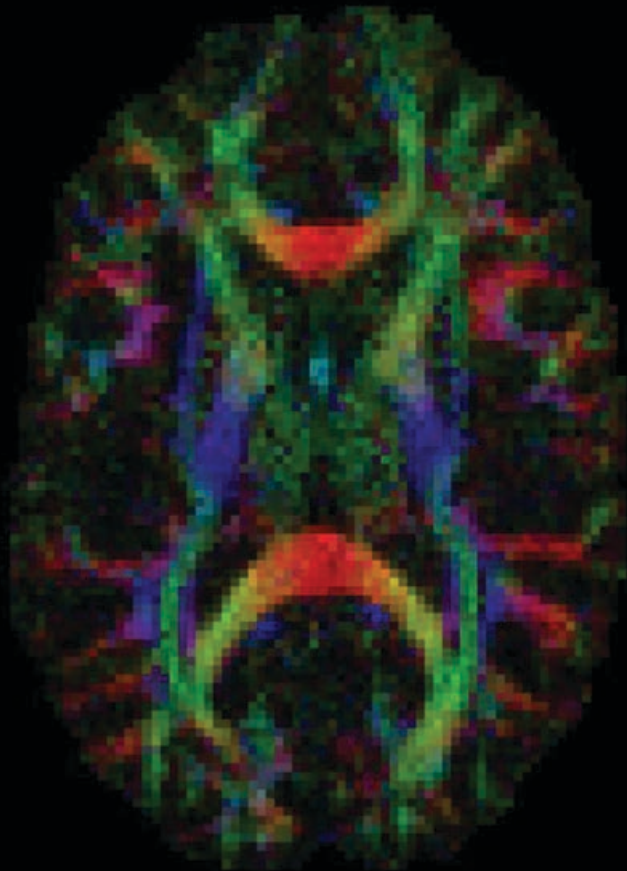
# Data quality assessment ...

Residuals from the model estimation

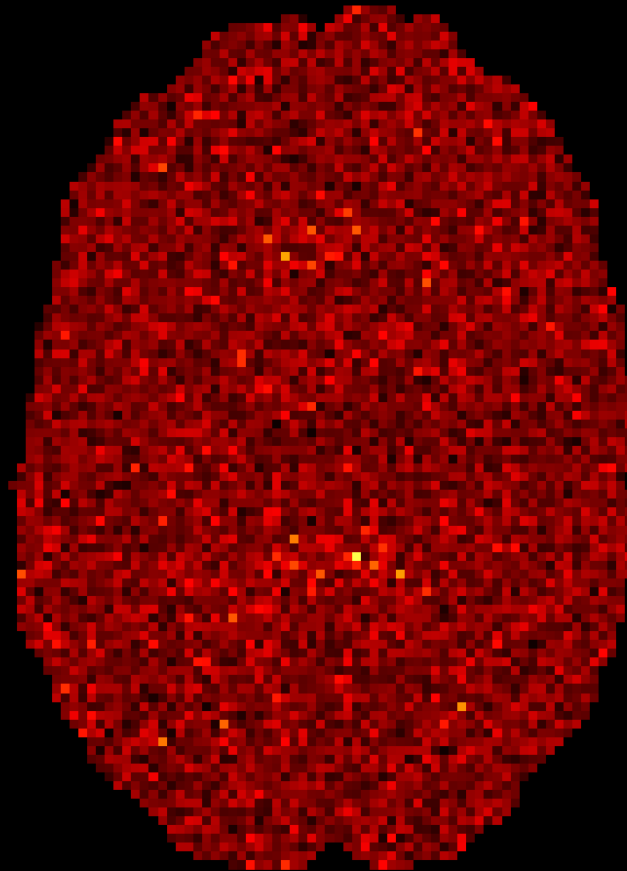


# Data quality assessment ...

Residuals from the model estimation



Good quality

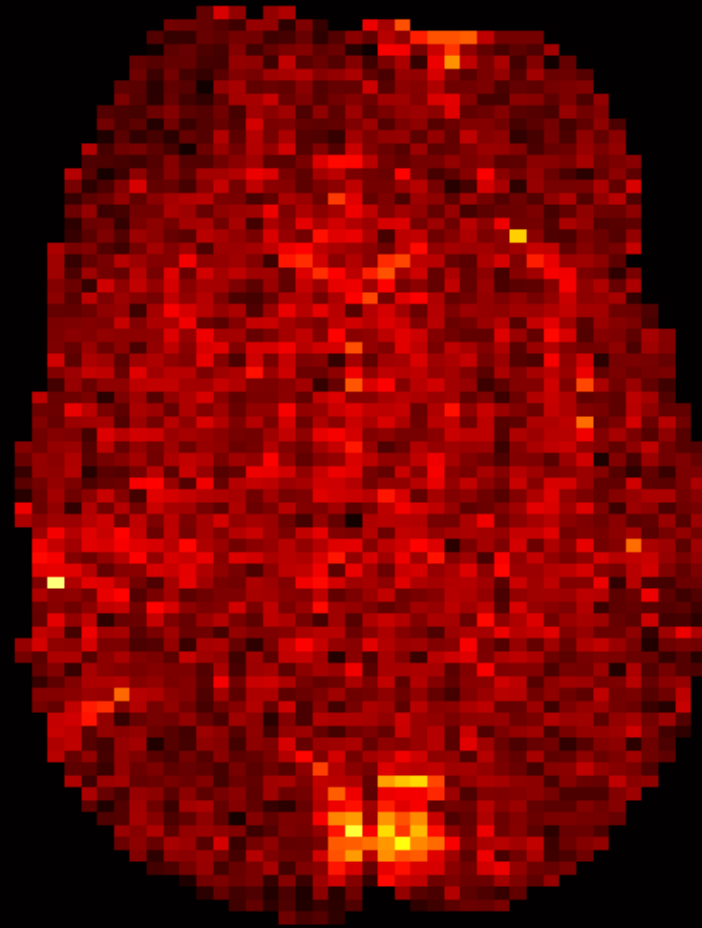
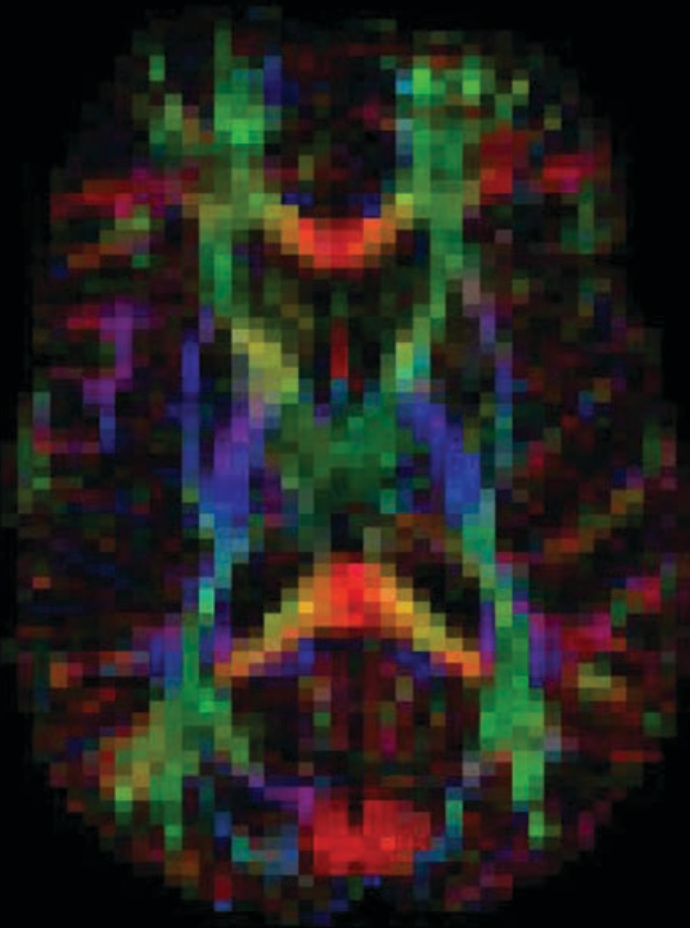


Low values / uniformity



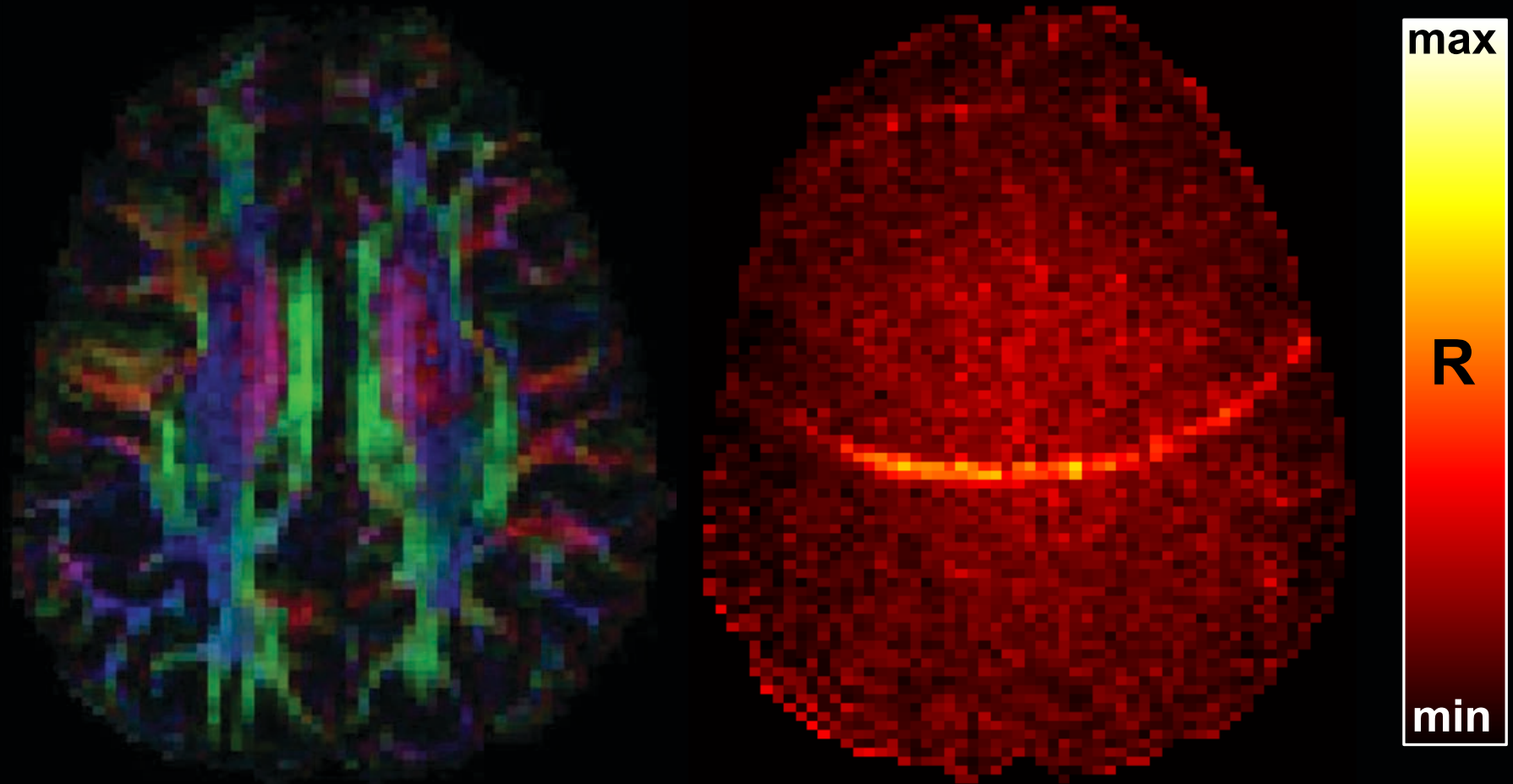
# Data quality assessment ...

Residuals from the model estimation



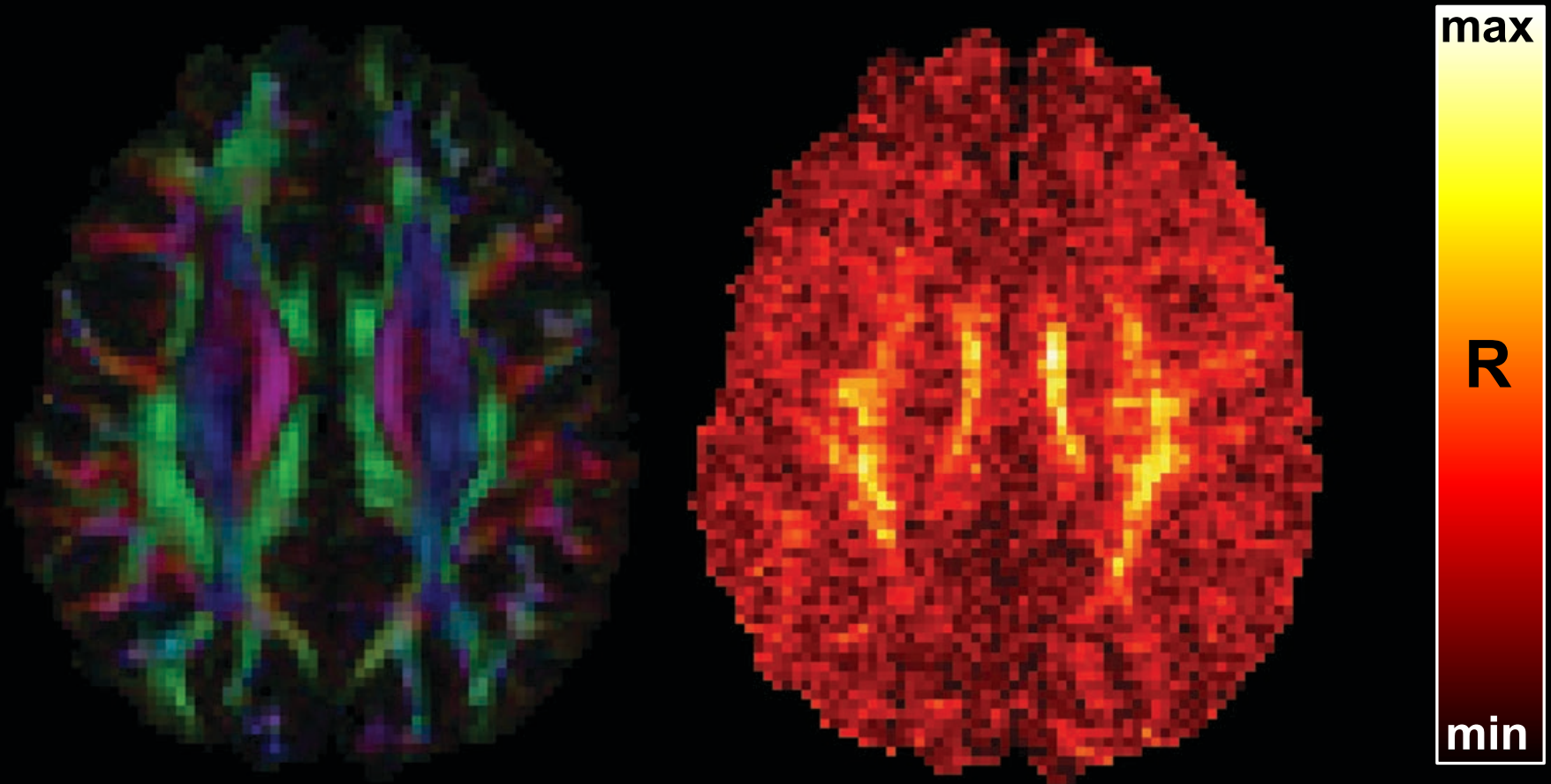
# Data quality assessment ...

Residuals from the model estimation



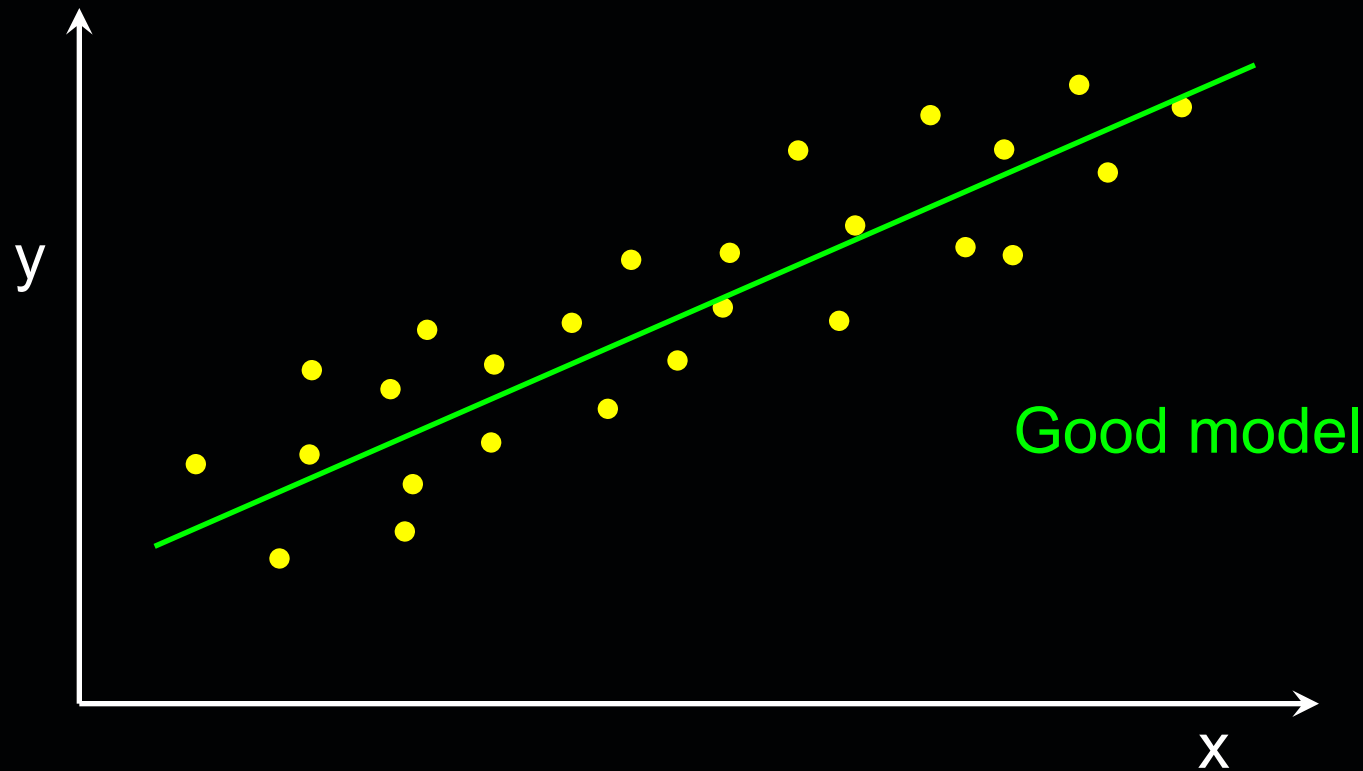
# Data quality assessment ...

Residuals from the model estimation



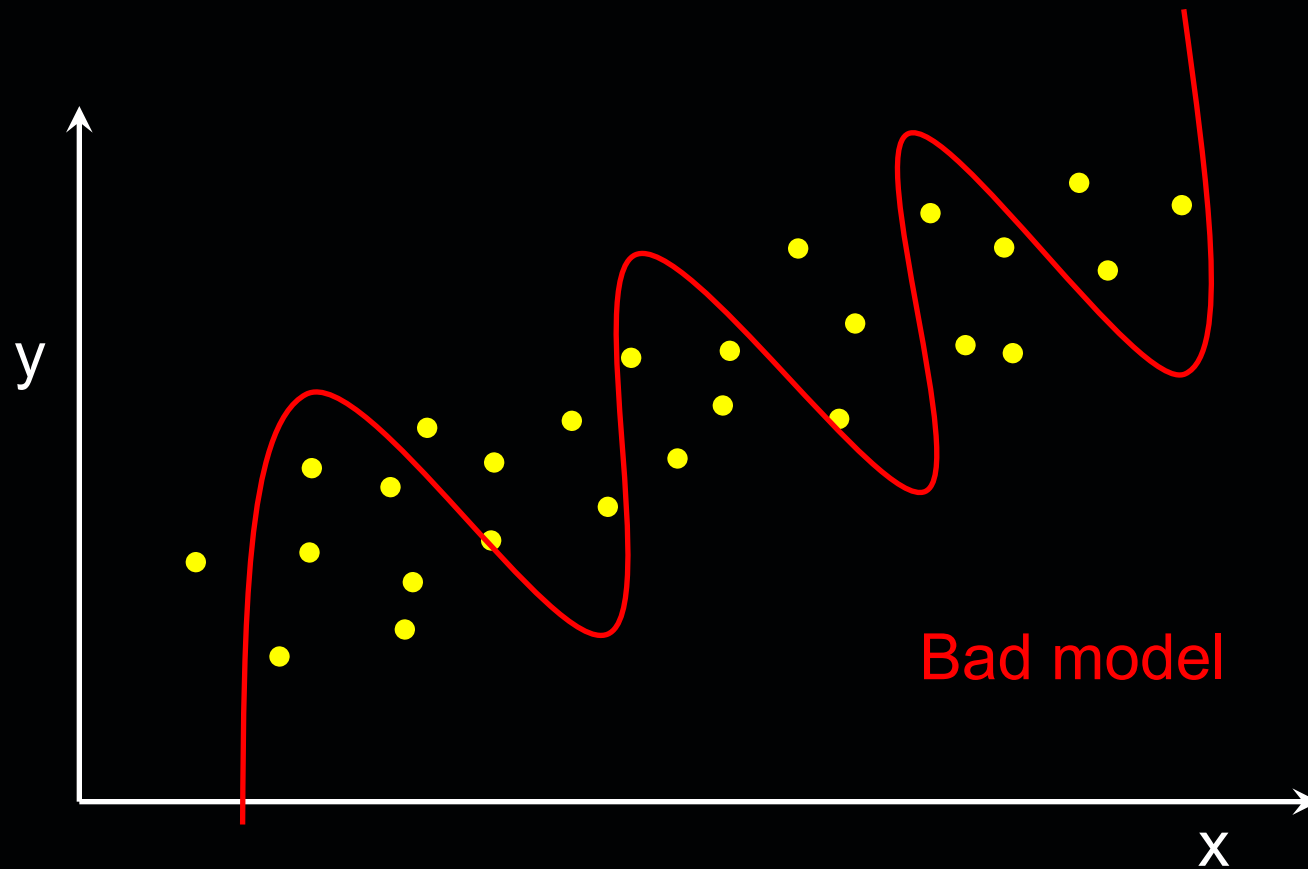
# Data quality assessment ...

Residuals from the model estimation



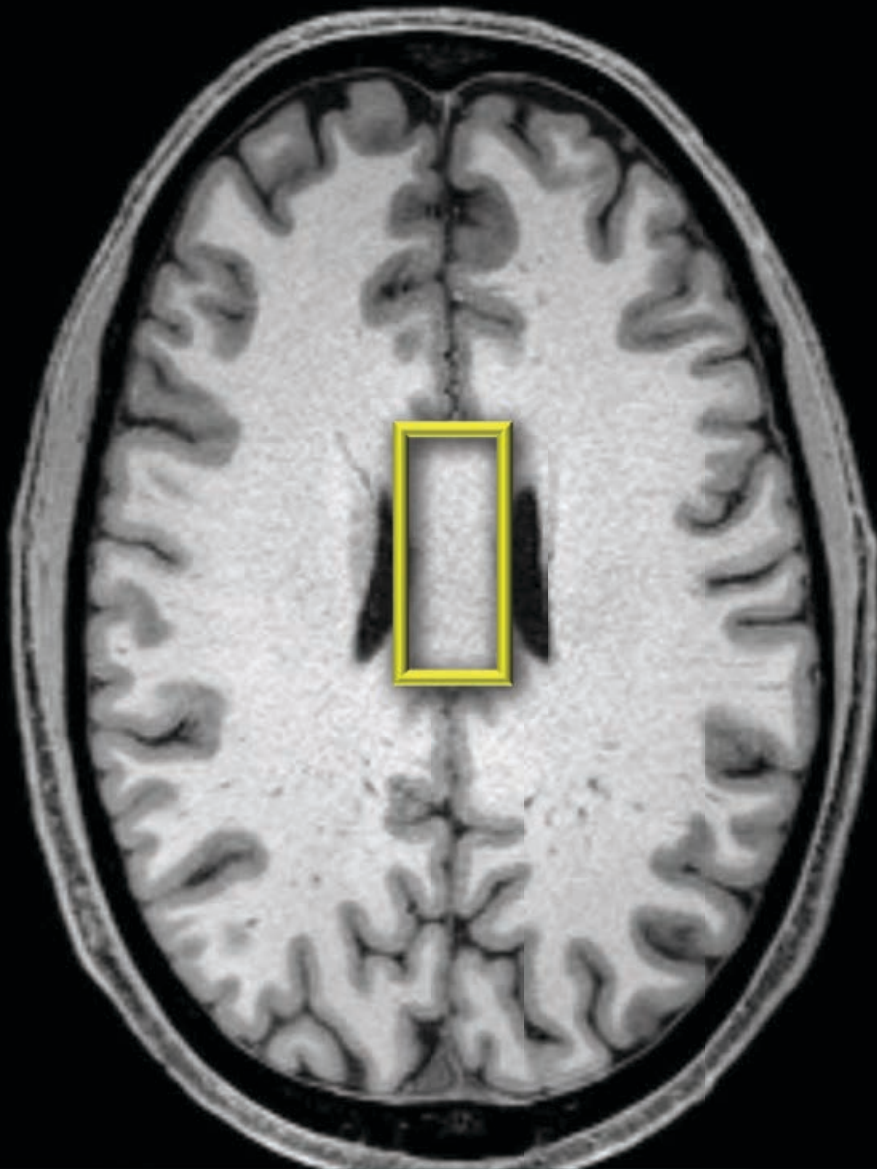
# Data quality assessment ...

Residuals from the model estimation





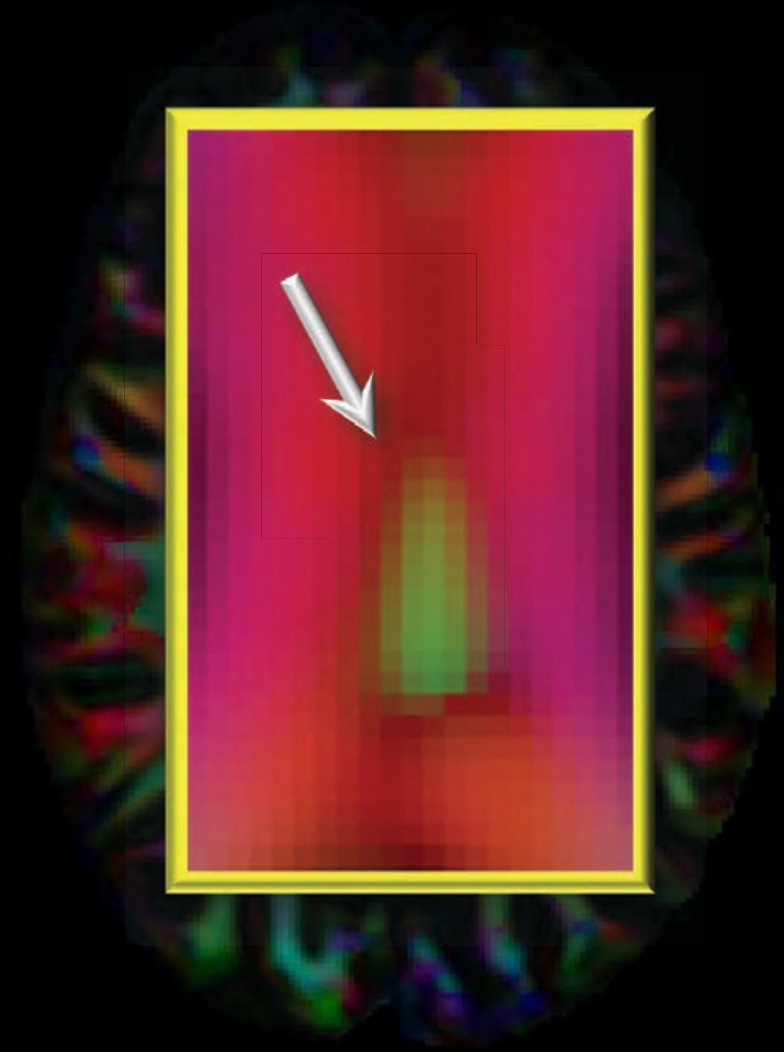
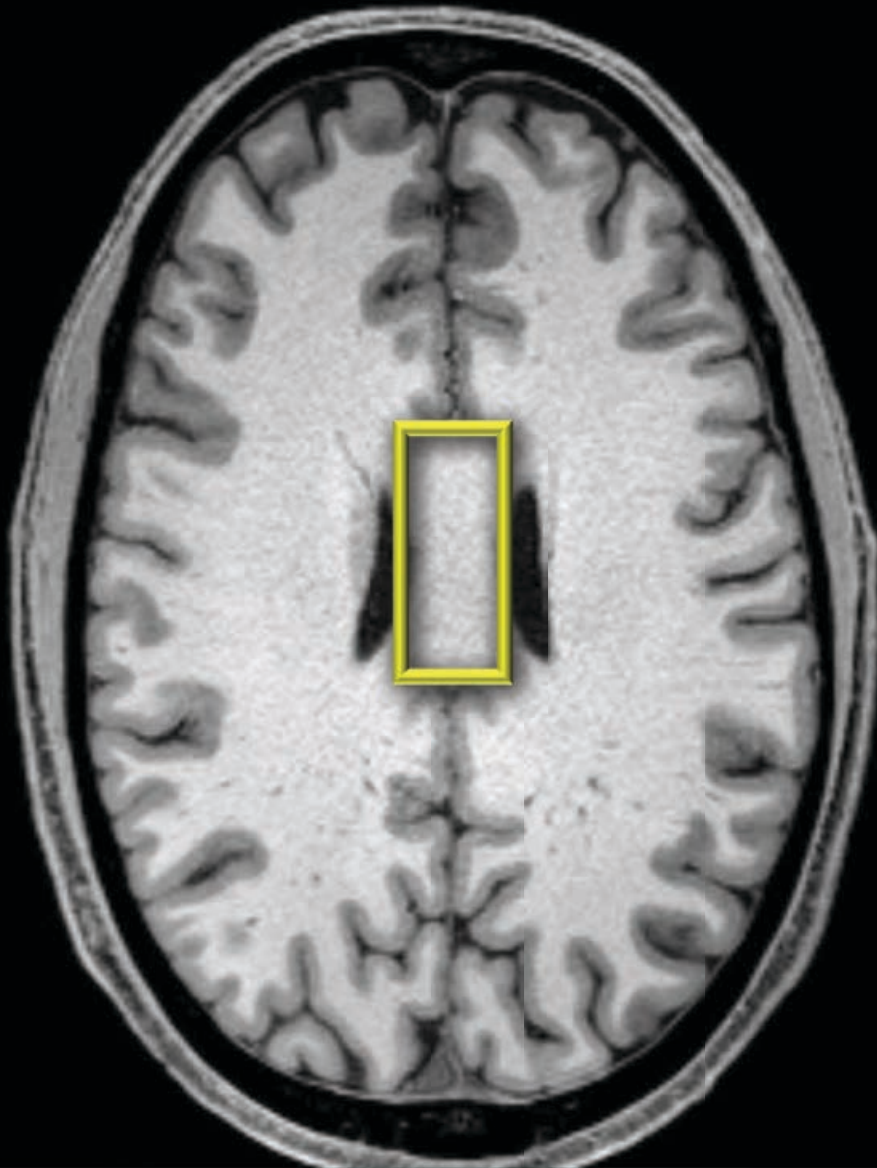
# Data quality assessment ...



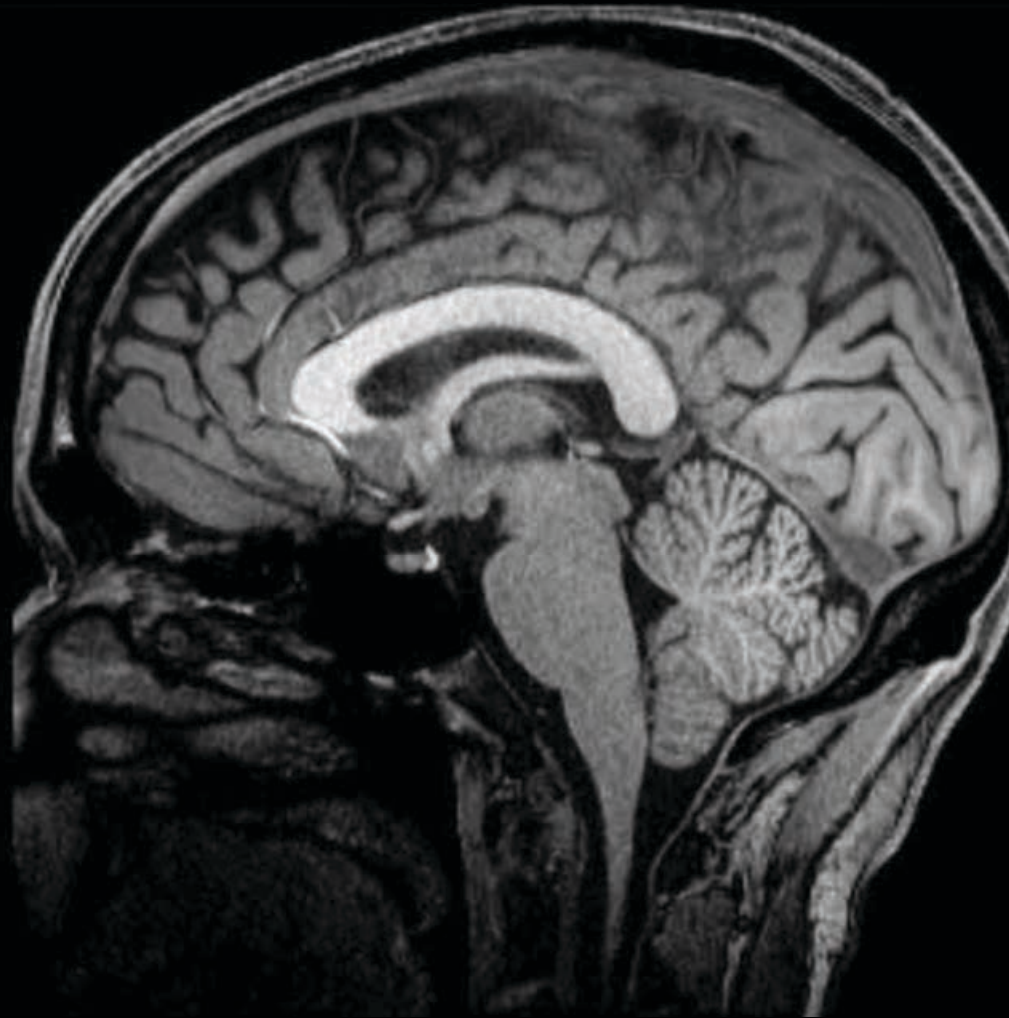
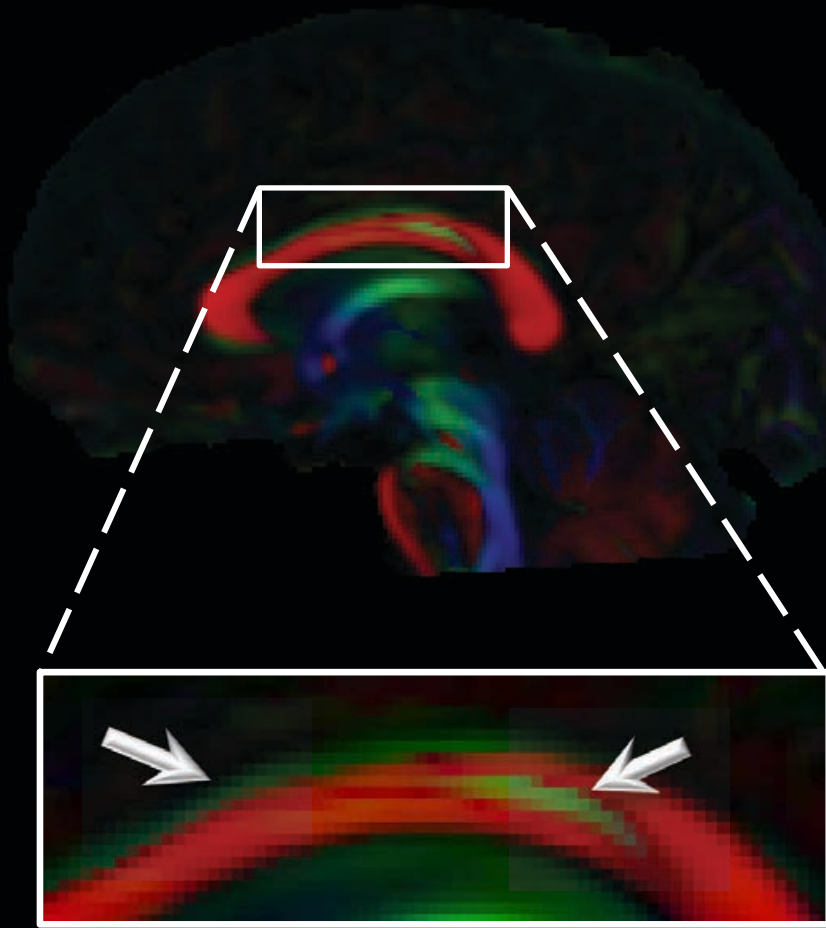
Anything “abnormal”?



# Data quality assessment ...

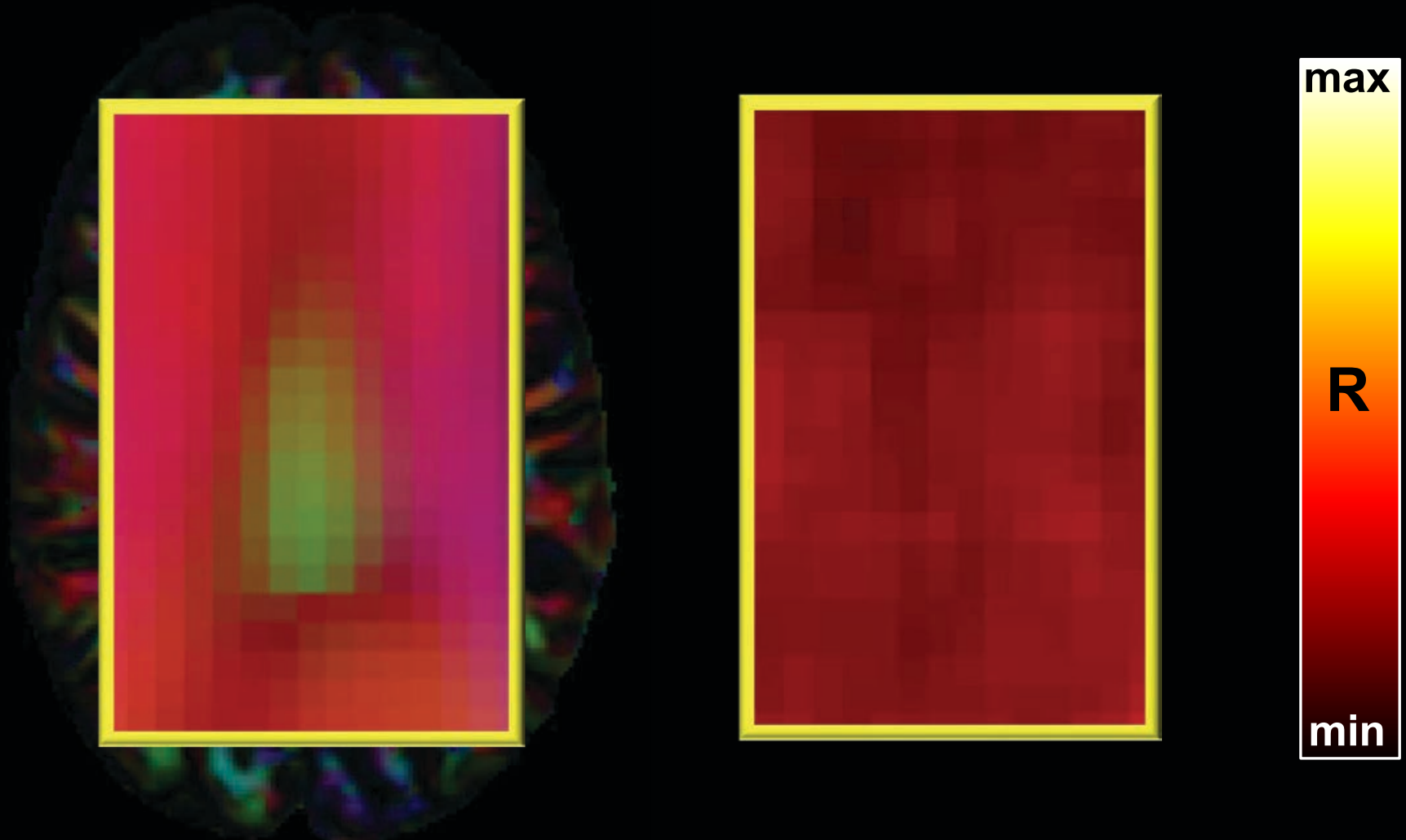


# Data quality assessment ...



# Data quality assessment ...

Residuals from the model estimation



# QA DIFFUSION

QA DIFFUSION



# Data processing steps

1. Correction for signal intensity drift
2. Correction for subject motion and eddy current induced distortions
3. Correction for EPI deformations
4. Diffusion model *estimation* approaches



Another confession by a dMRI scientist...



@Alex\_Leemans

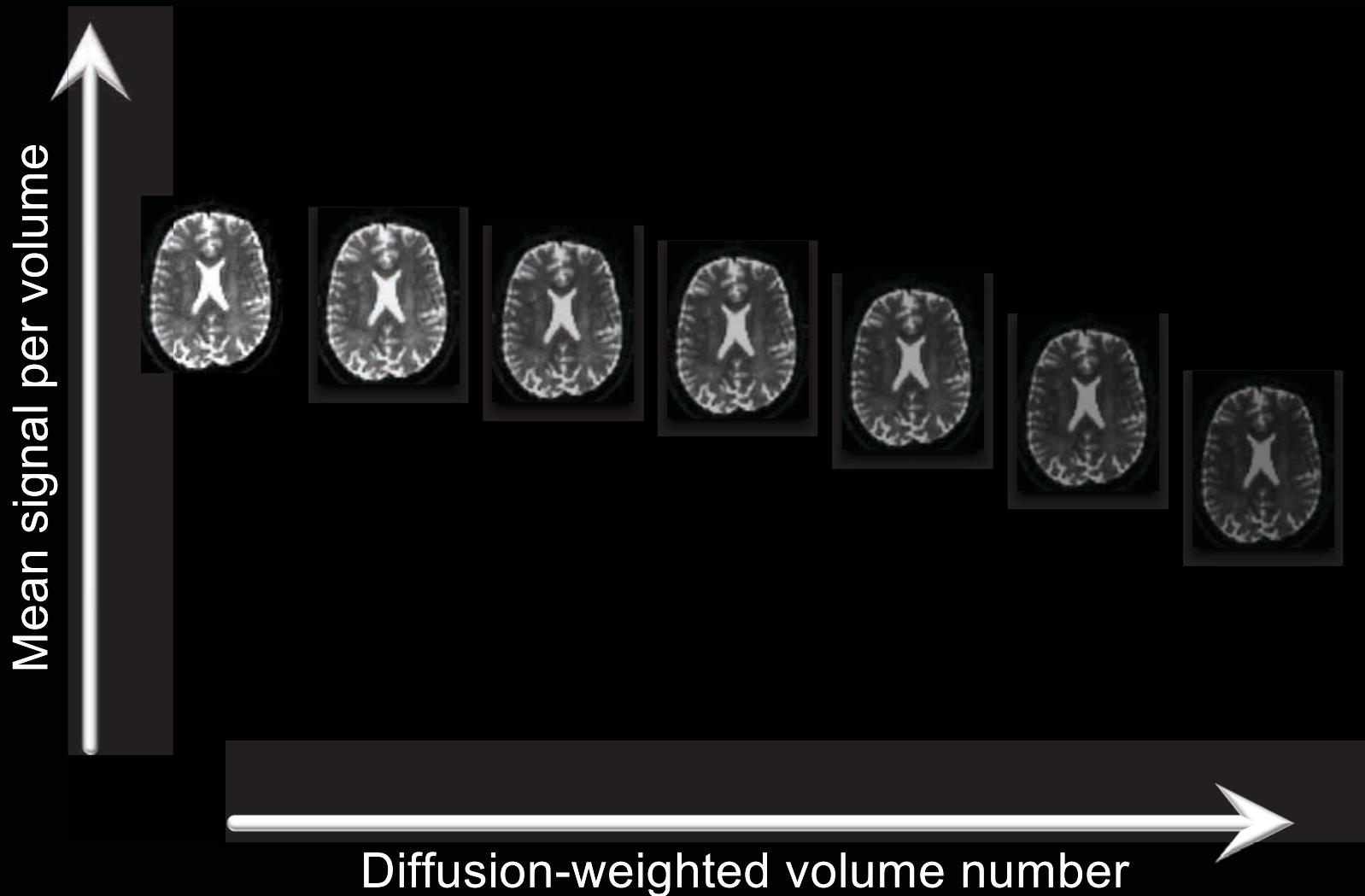
# Data processing steps

1. Correction for signal intensity drift
2. Correction for subject motion and eddy current induced distortions
3. Correction for EPI deformations
4. Diffusion model *estimation* approaches

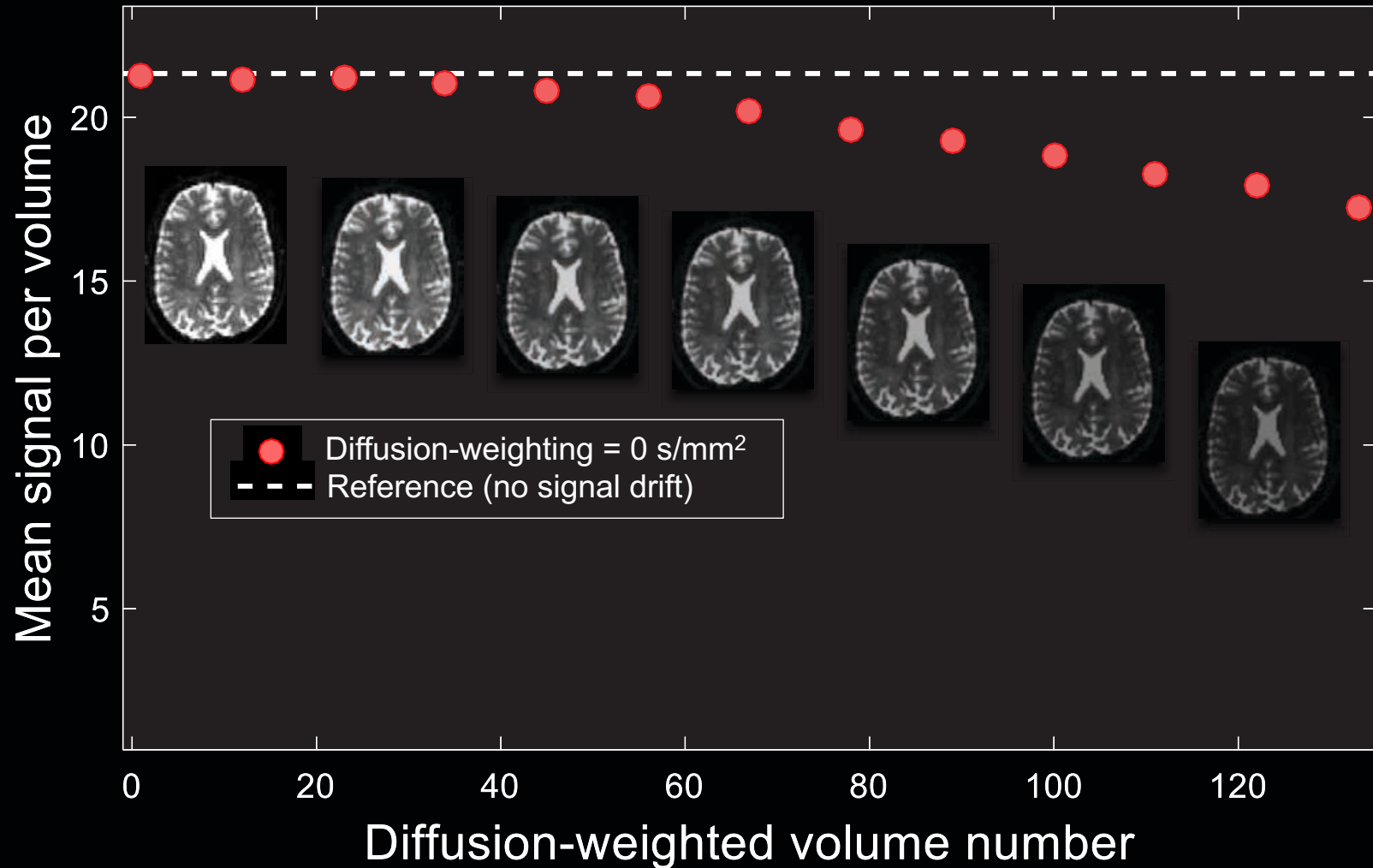




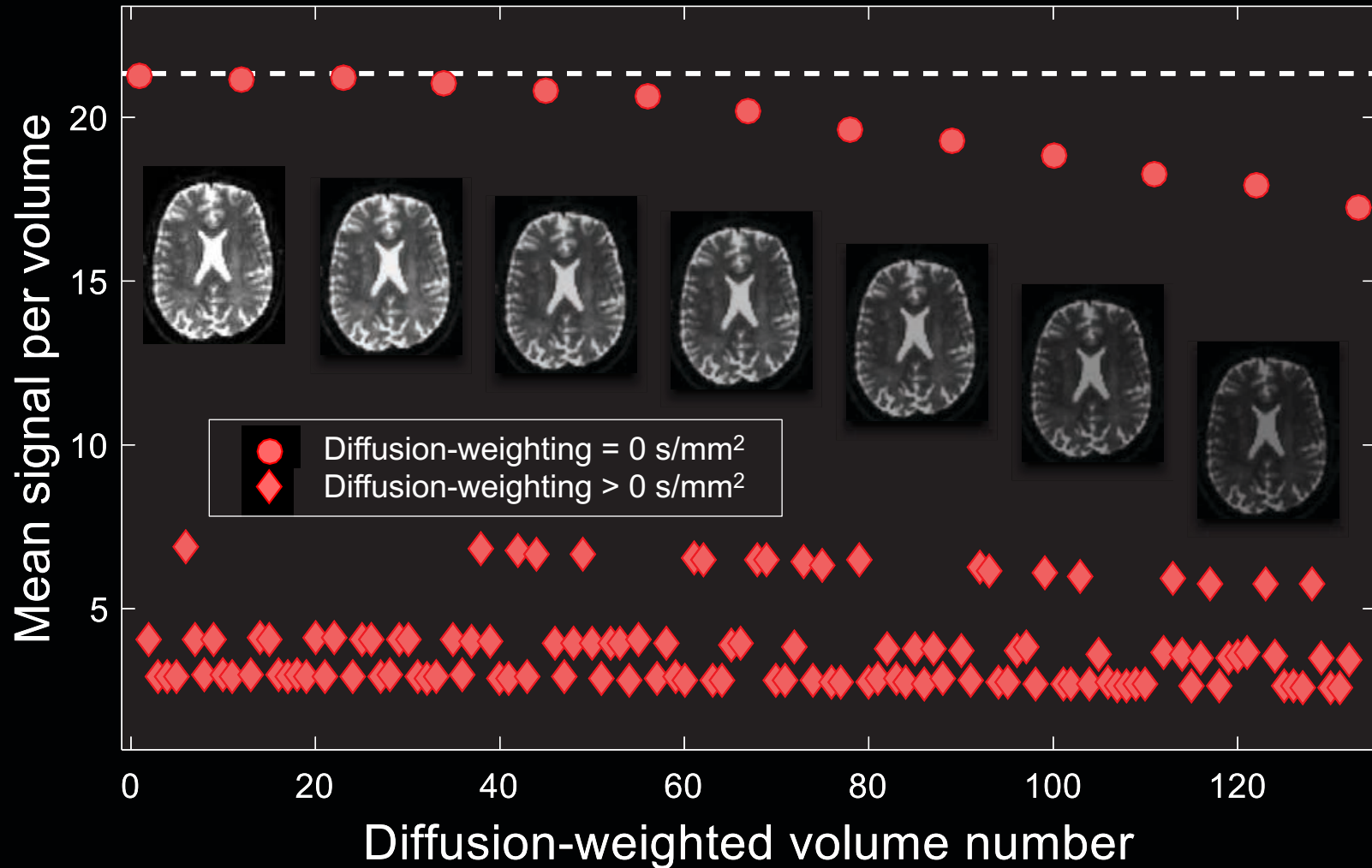
# 1. Correction for signal intensity drift



# 1. Correction for signal intensity drift

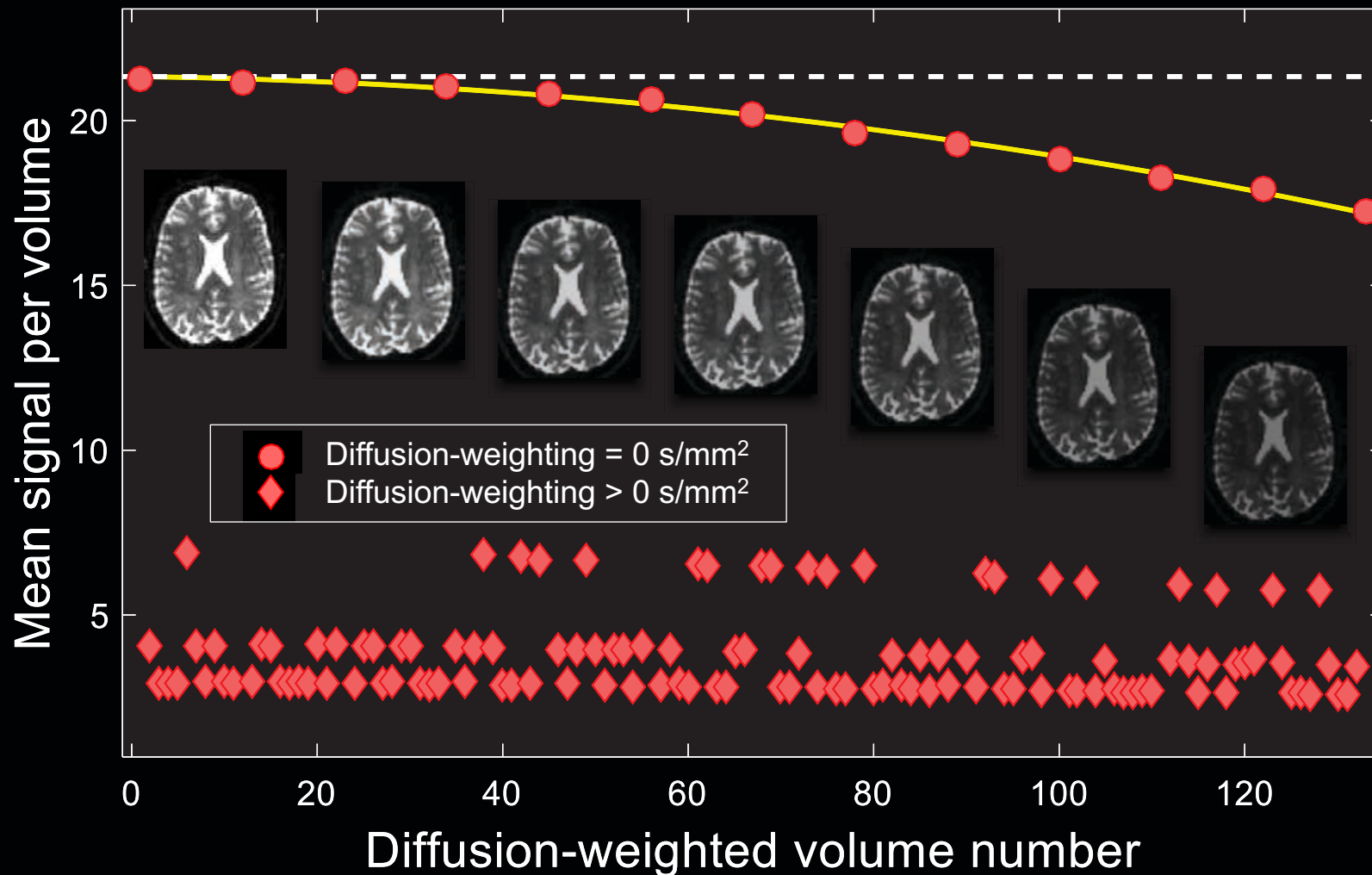


# 1. Correction for signal intensity drift



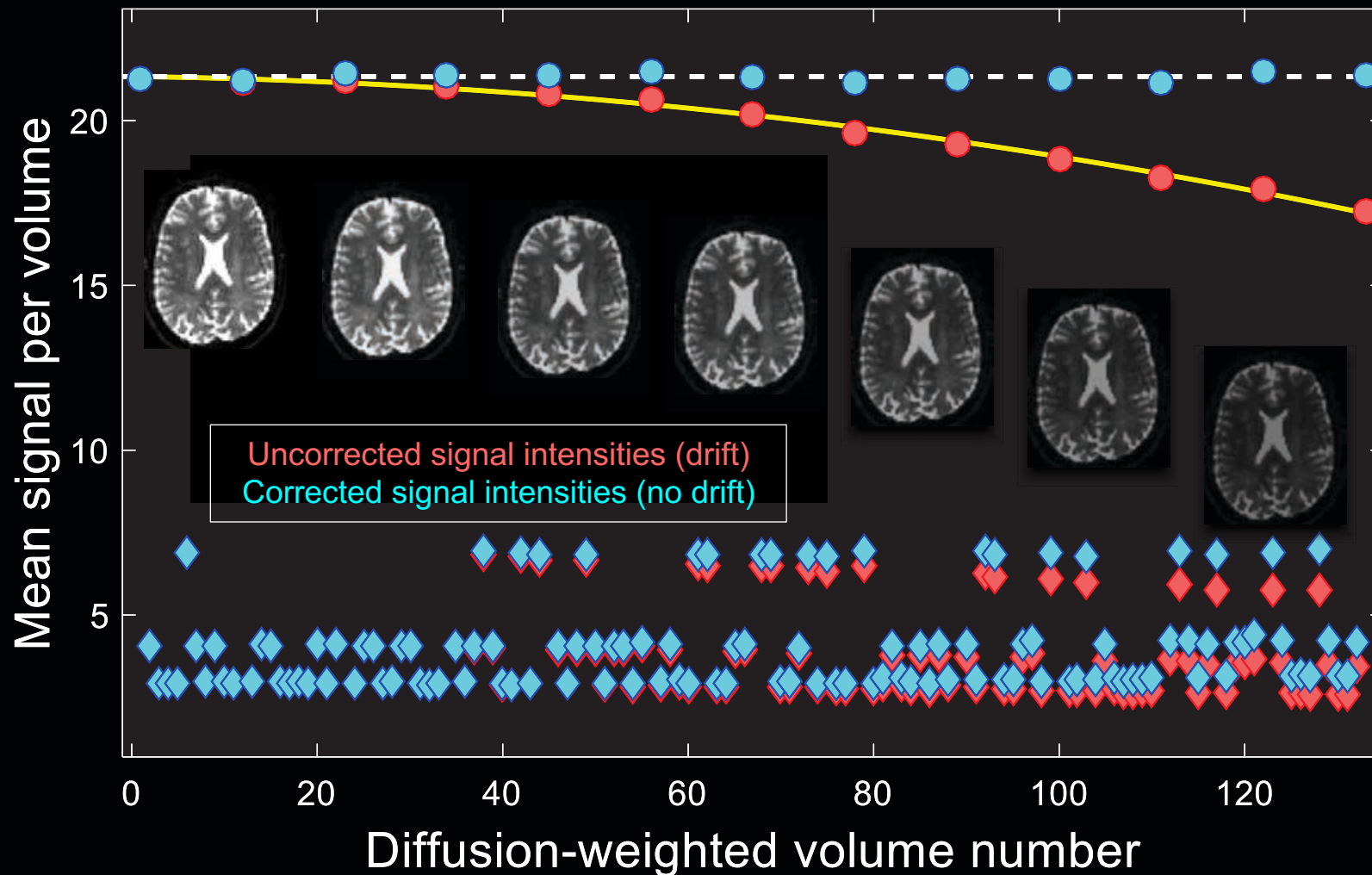
# 1. Correction for signal intensity drift

Low-degree polynomial fit to  $b = 0$  s/mm<sup>2</sup> images

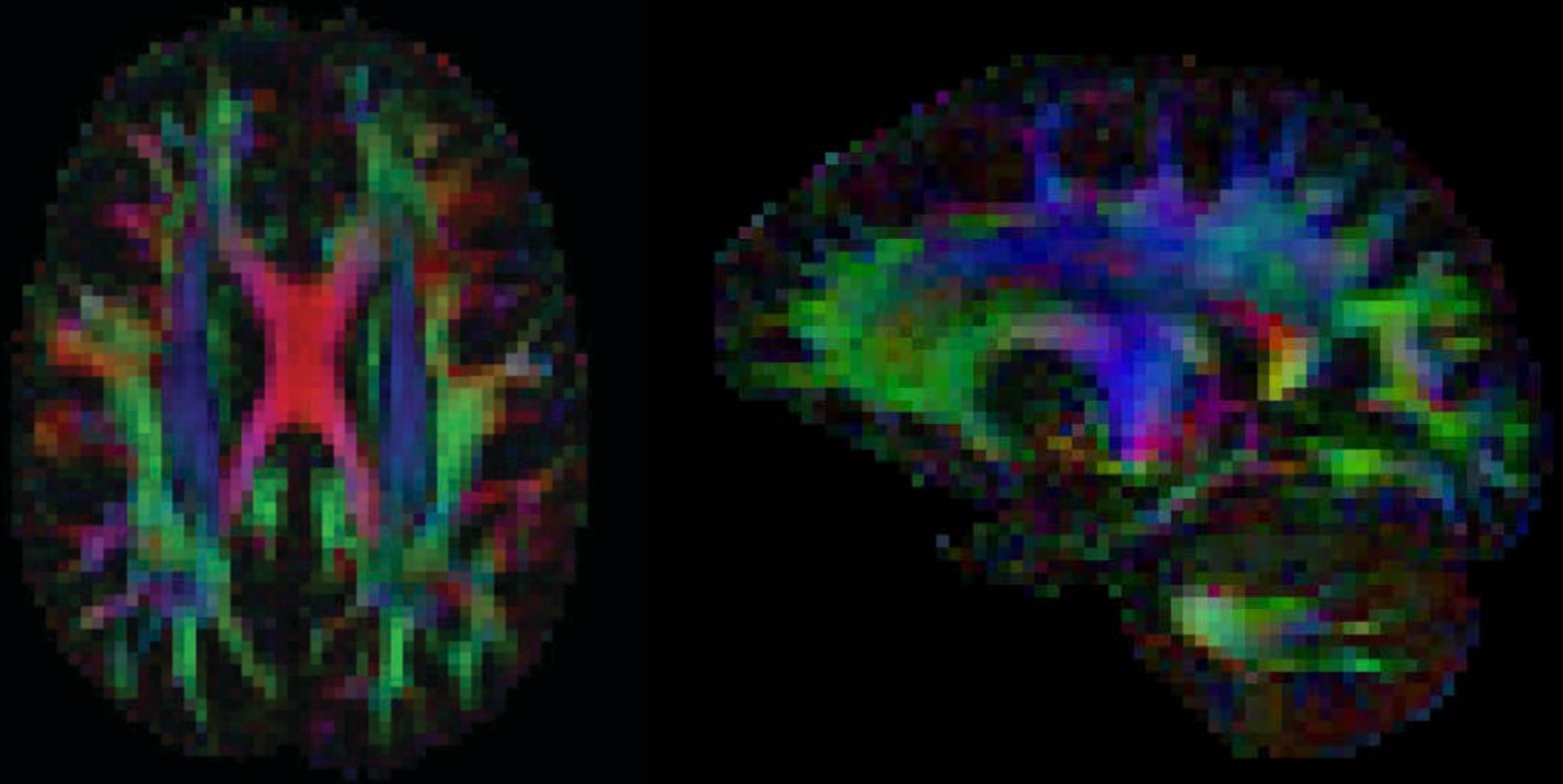


# 1. Correction for signal intensity drift

Low-degree polynomial fit to  $b = 0$  s/mm<sup>2</sup> images



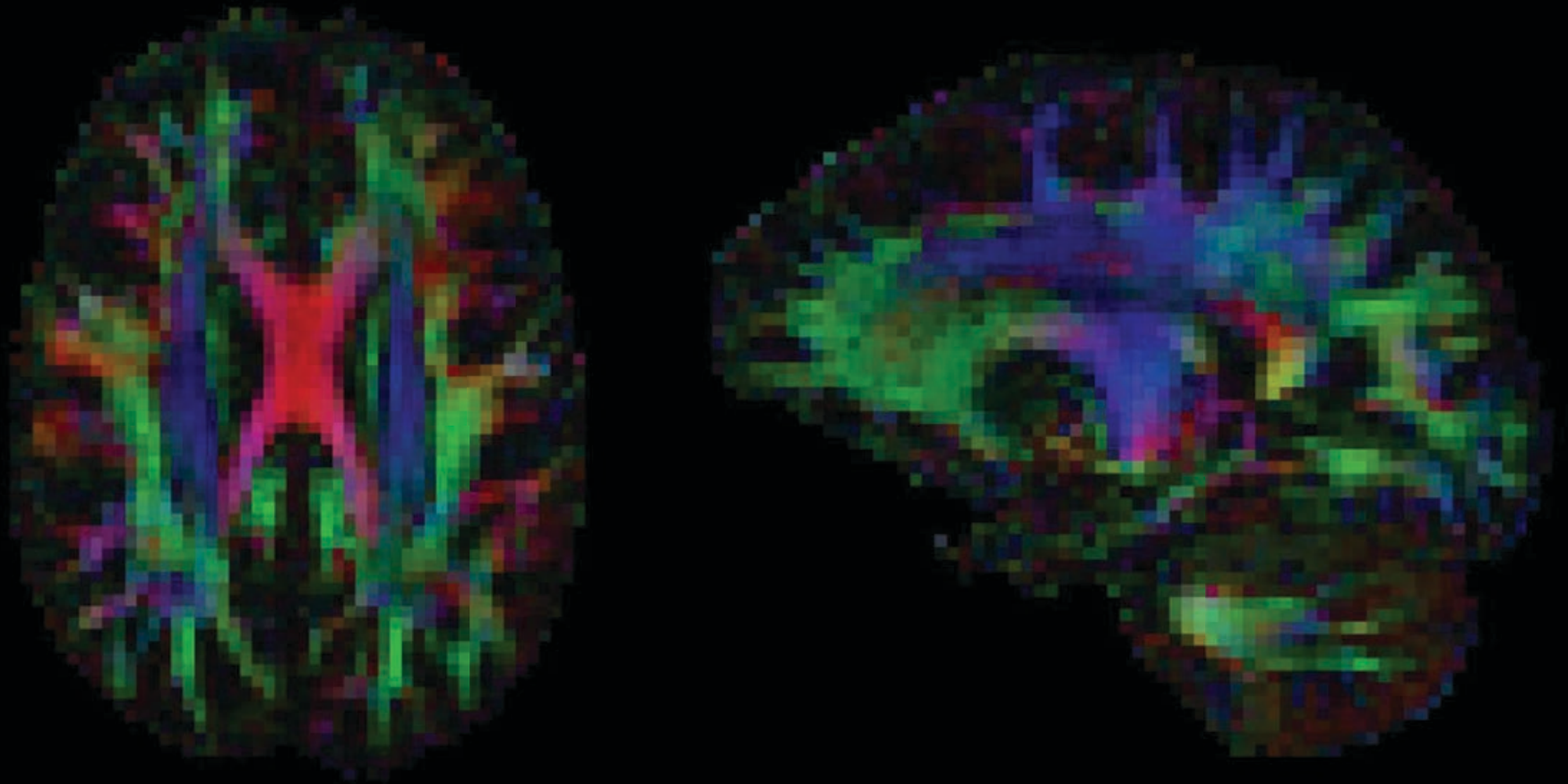
# 1. Correction for signal intensity drift



**Before** correcting for signal intensity drift



# 1. Correction for signal intensity drift

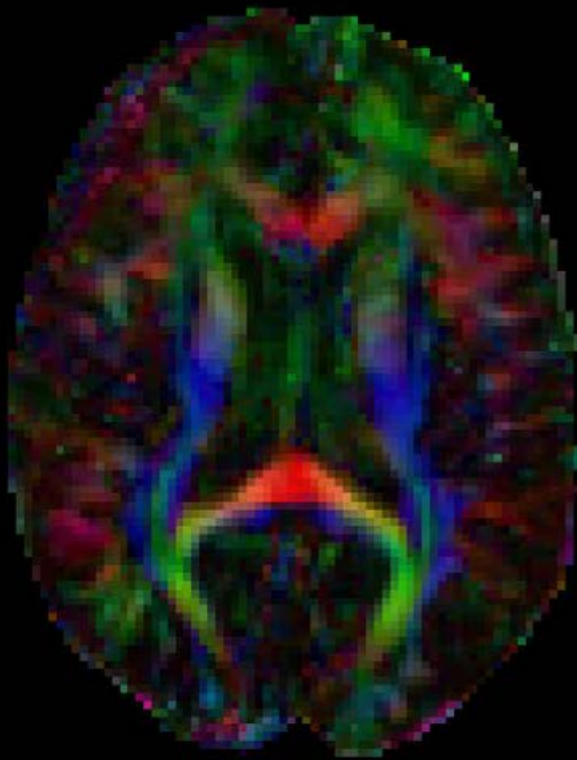


**After** correcting for signal intensity drift



## 2. Correction for subject motion and eddy current induced distortions

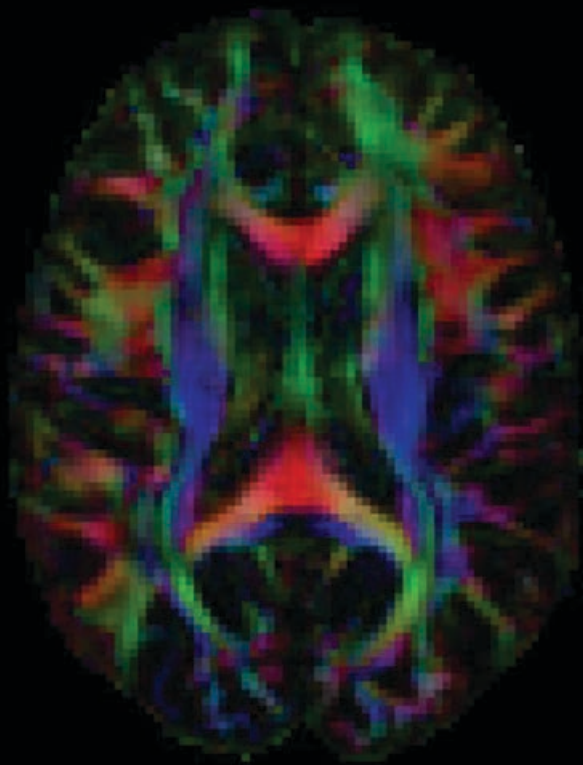
Not corrected for subject motion



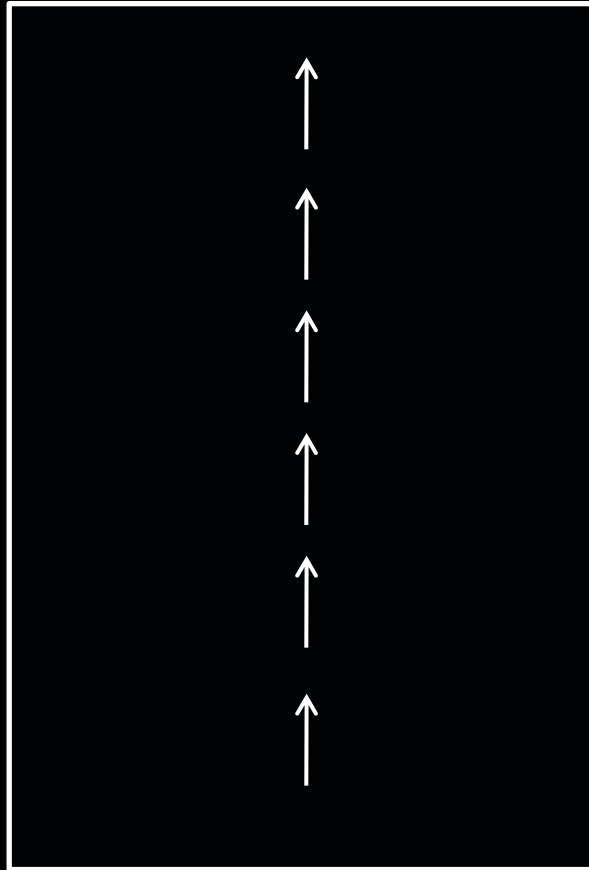


## 2. Correction for subject motion and eddy current induced distortions

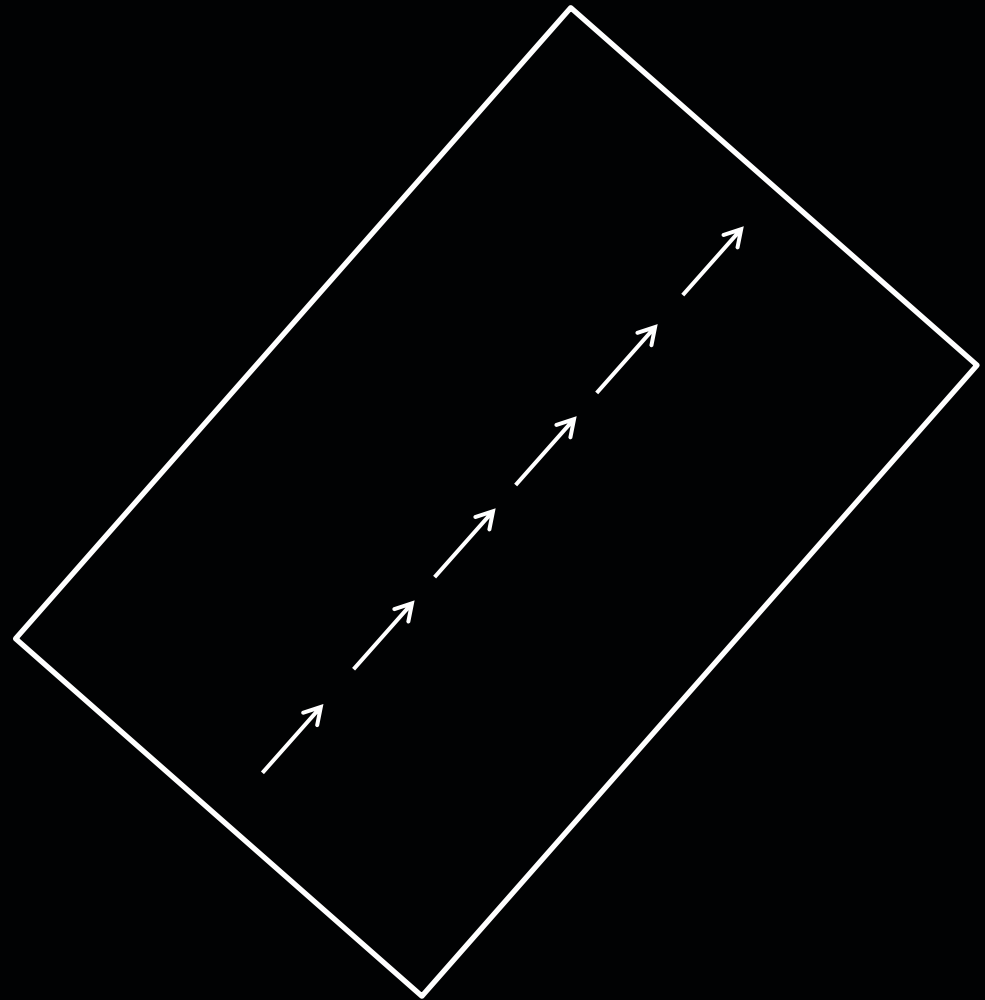
Corrected for subject motion



## 2. Correction for subject motion and eddy current induced distortions

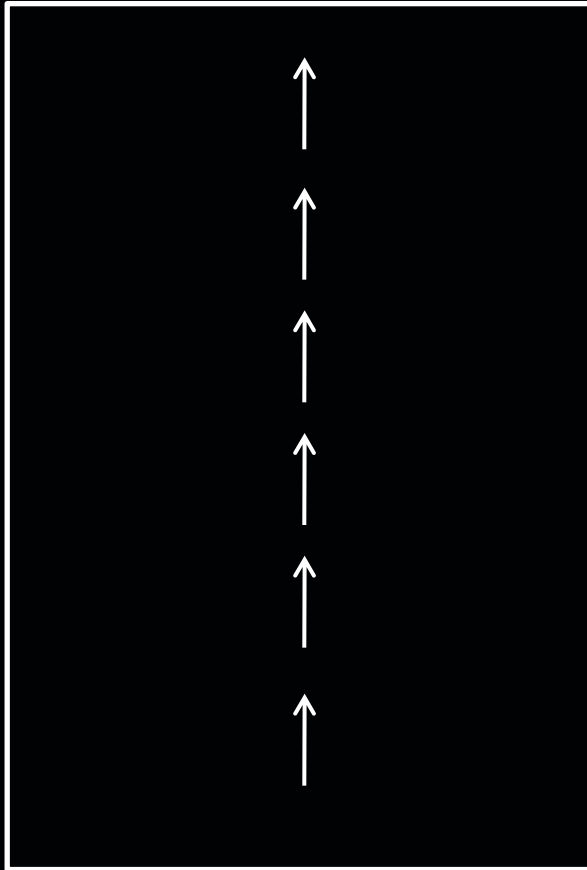


“Reference image”

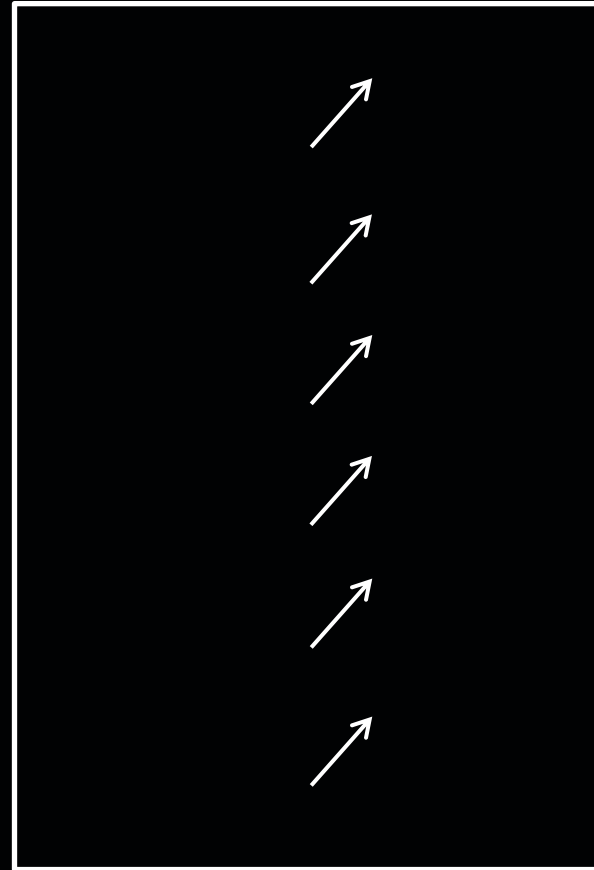


“Image with subject motion”

## 2. Correction for subject motion and eddy current induced distortions

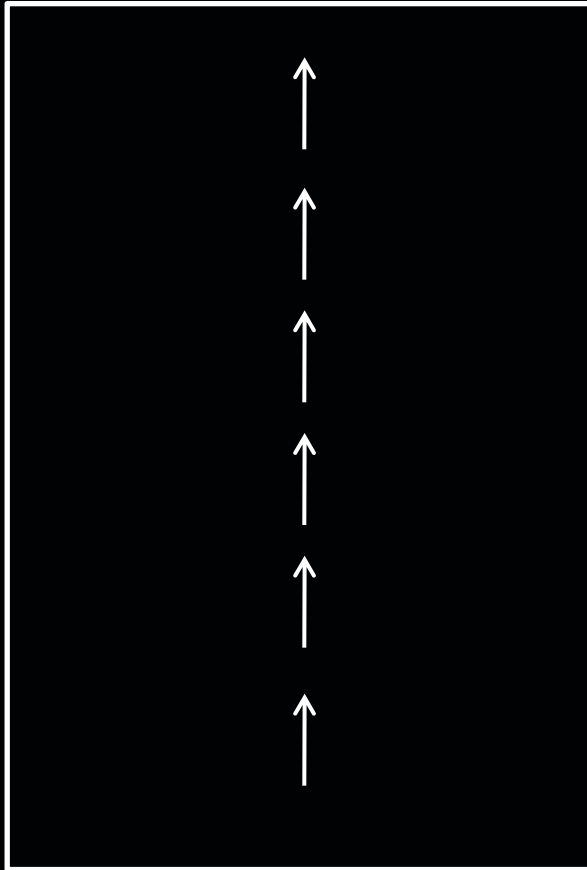


“Reference image”

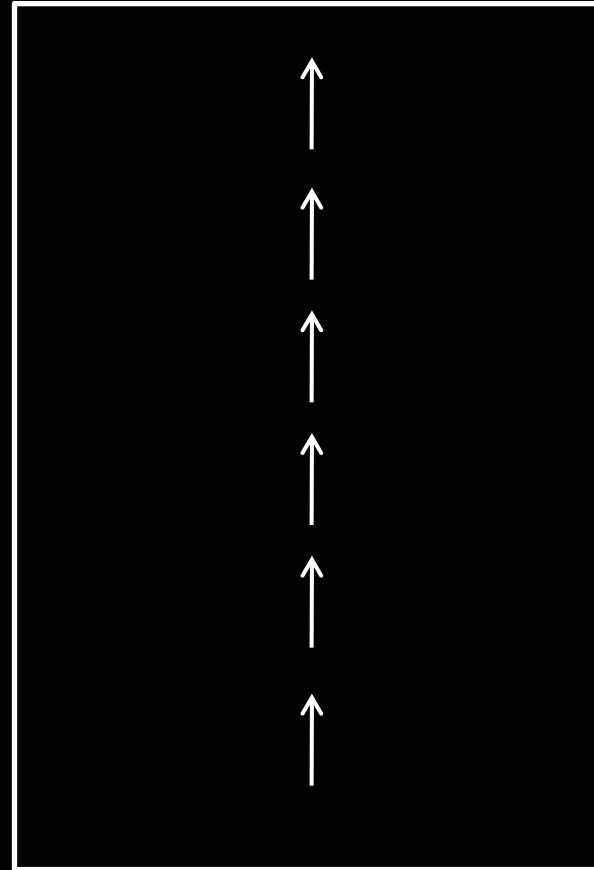


“Corrected image”  
(no B-matrix rotation)

## 2. Correction for subject motion and eddy current induced distortions



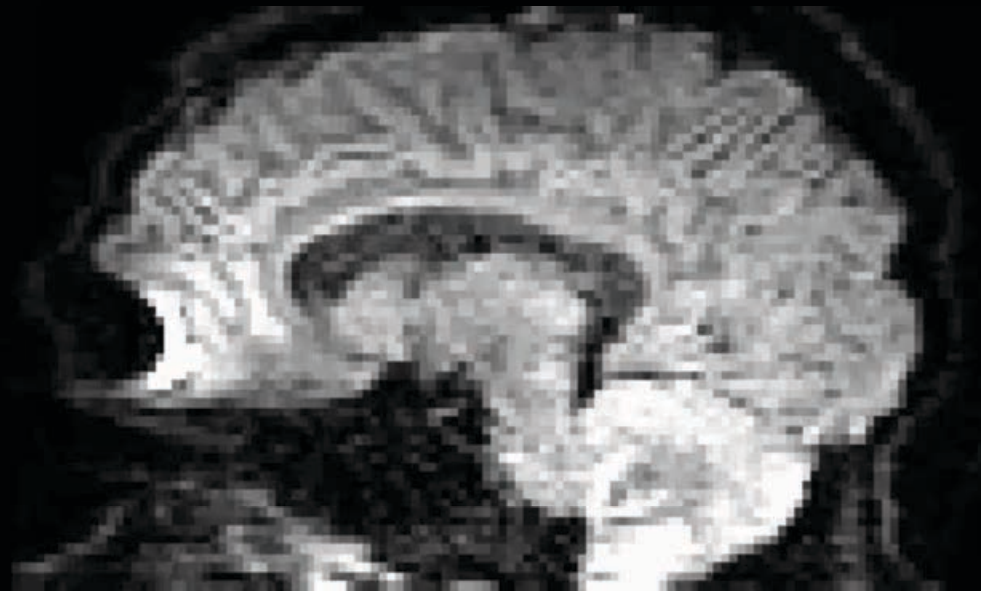
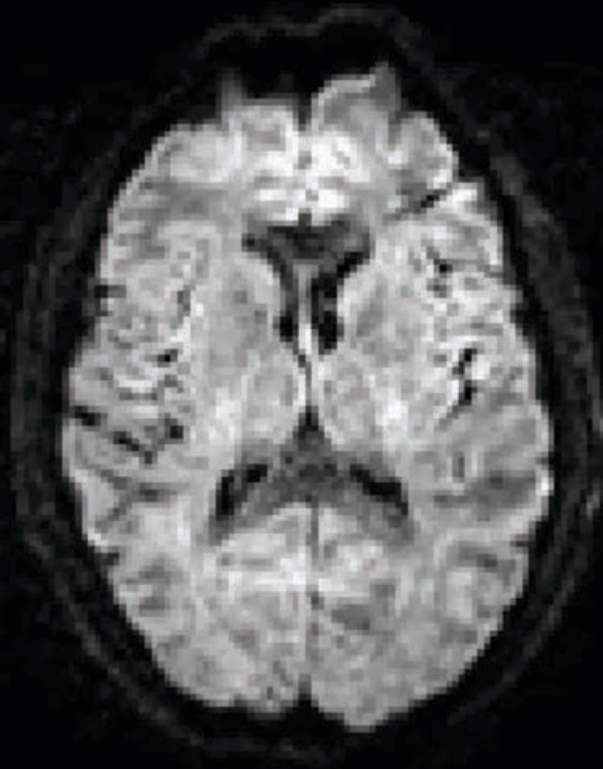
“Reference image”



“Corrected image”  
(with B-matrix rotation)

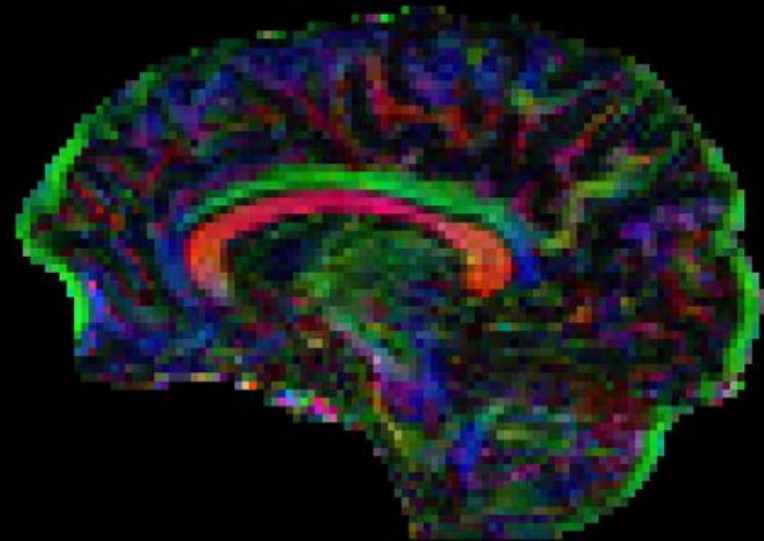
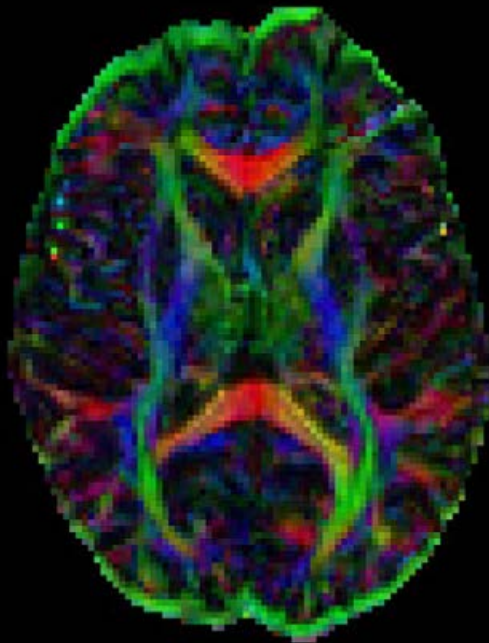
## 2. Correction for subject motion and eddy current induced distortions

“Eddy currents”



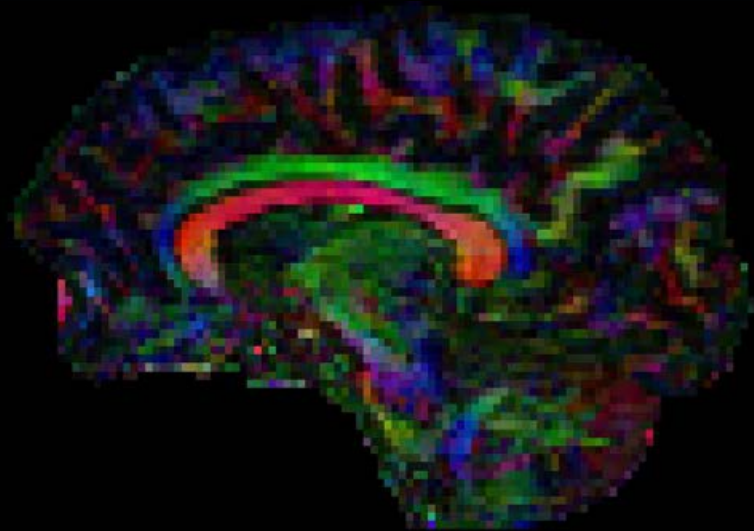
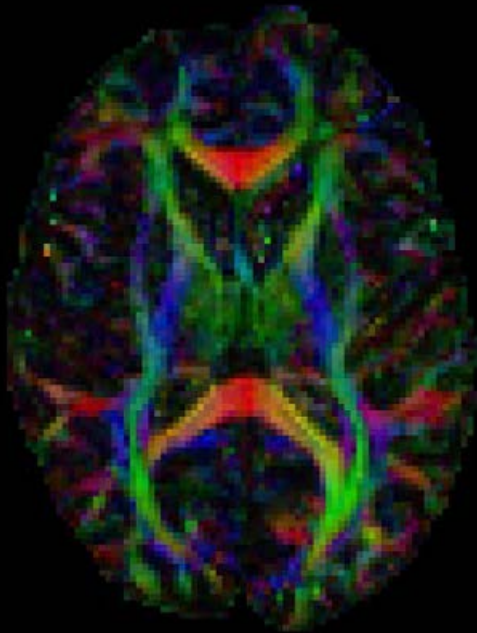
## 2. Correction for subject motion and eddy current induced distortions

**Without** eddy currents correction

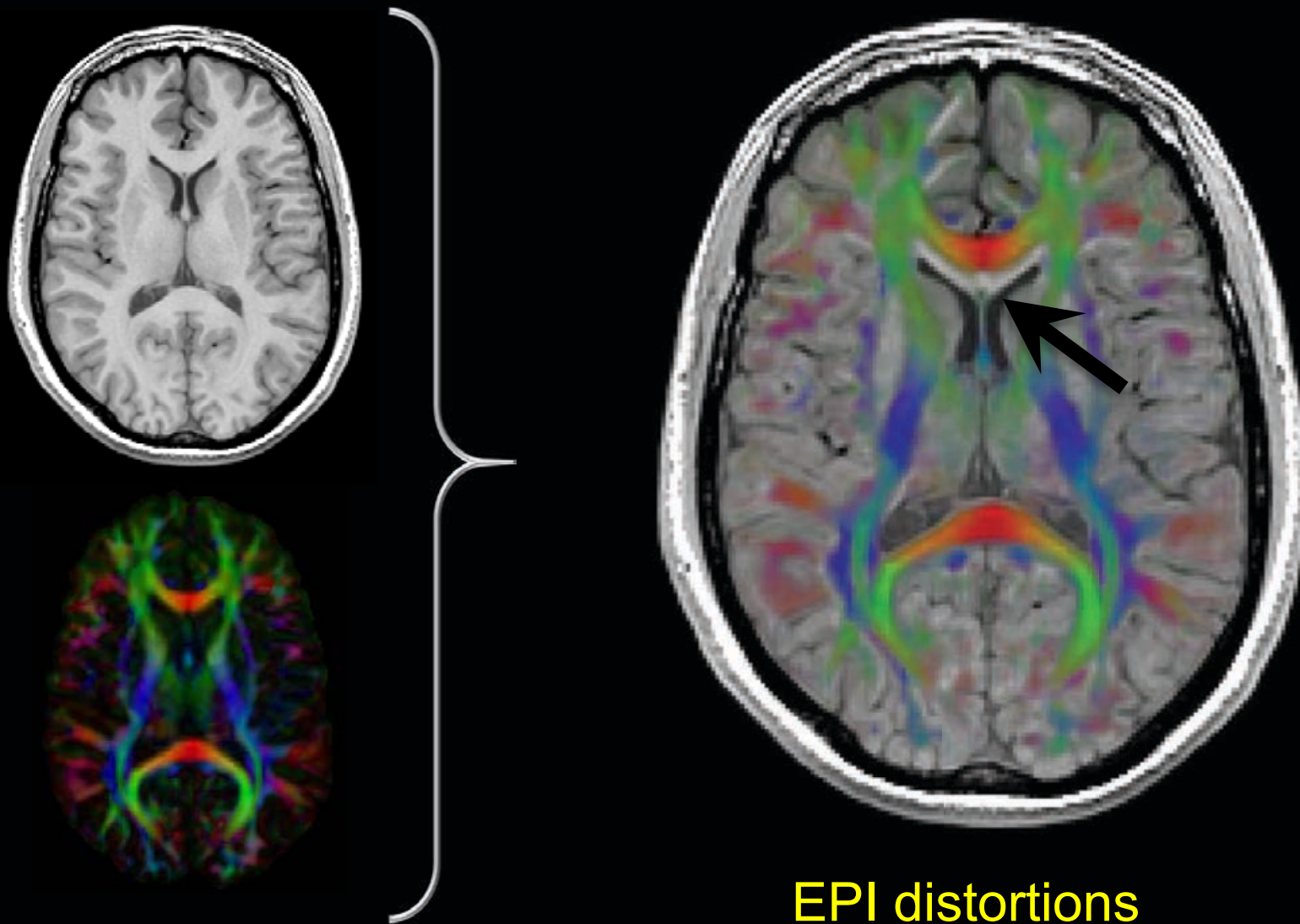


## 2. Correction for subject motion and eddy current induced distortions

**With** eddy currents correction



### 3. Correction for EPI deformations

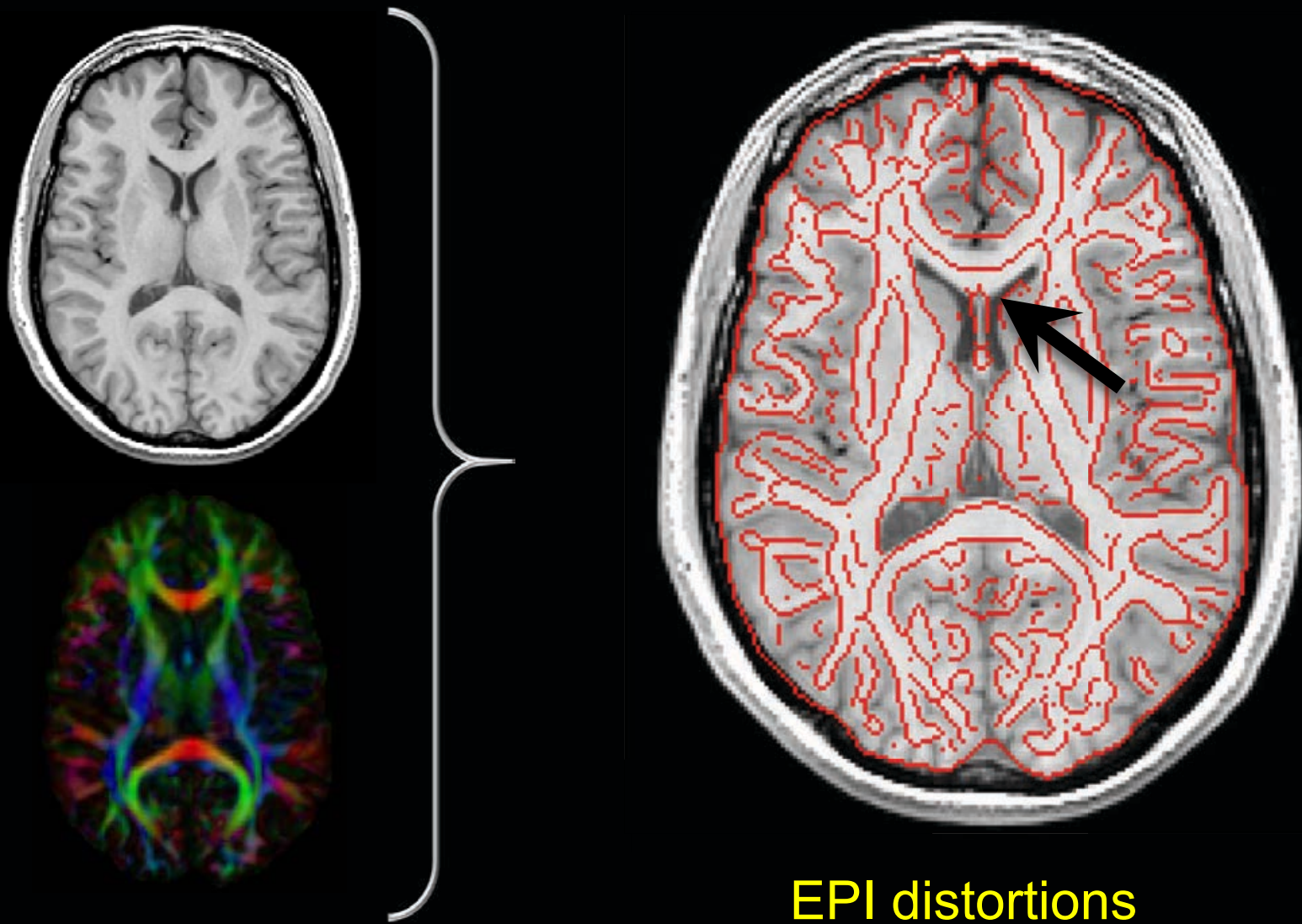


EPI distortions

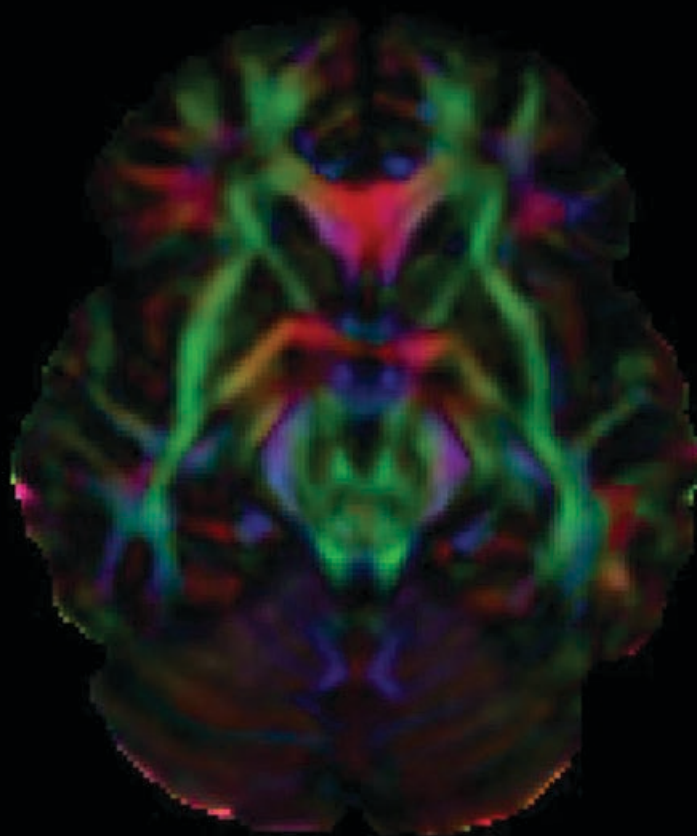
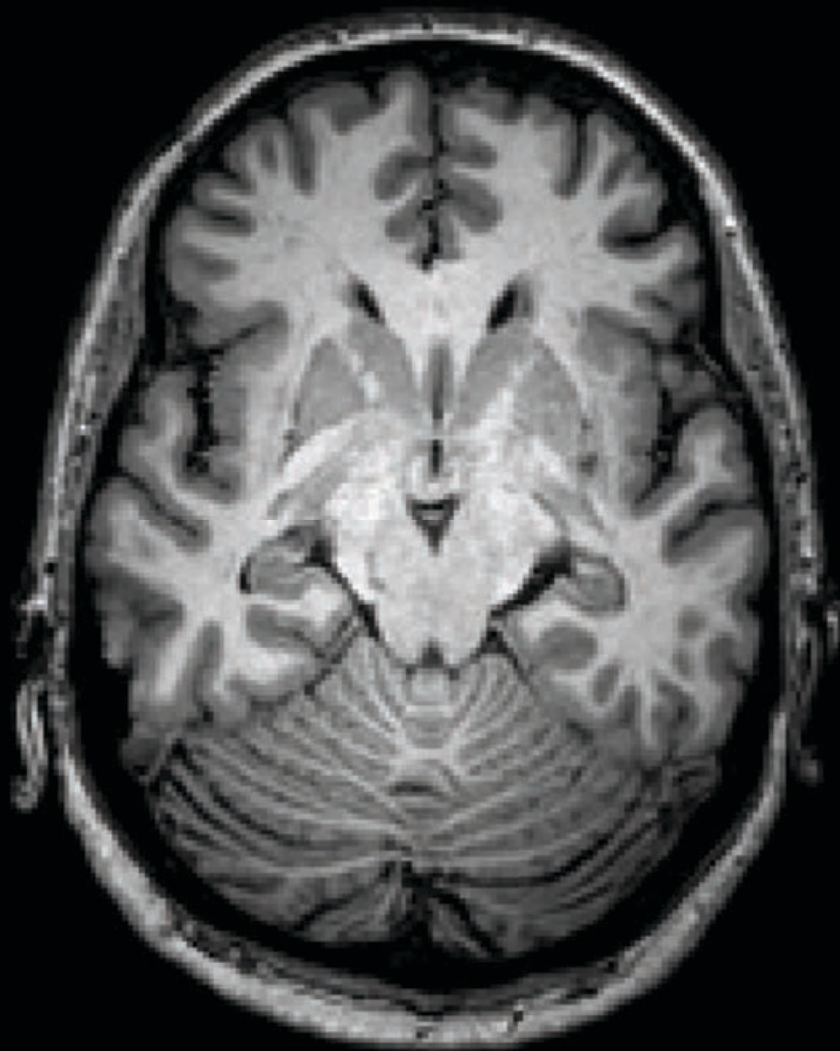




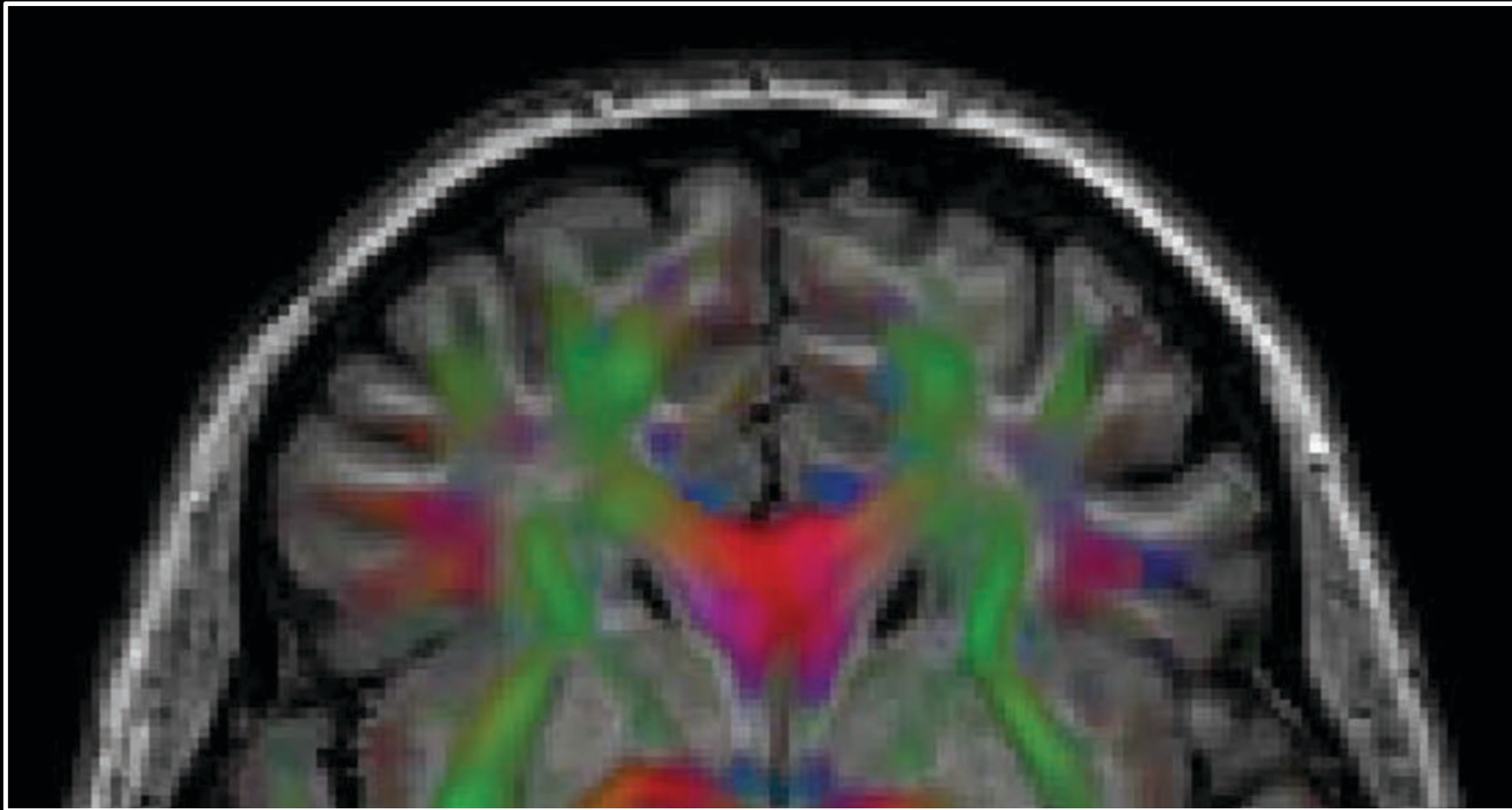
### 3. Correction for EPI deformations



### 3. Correction for EPI deformations



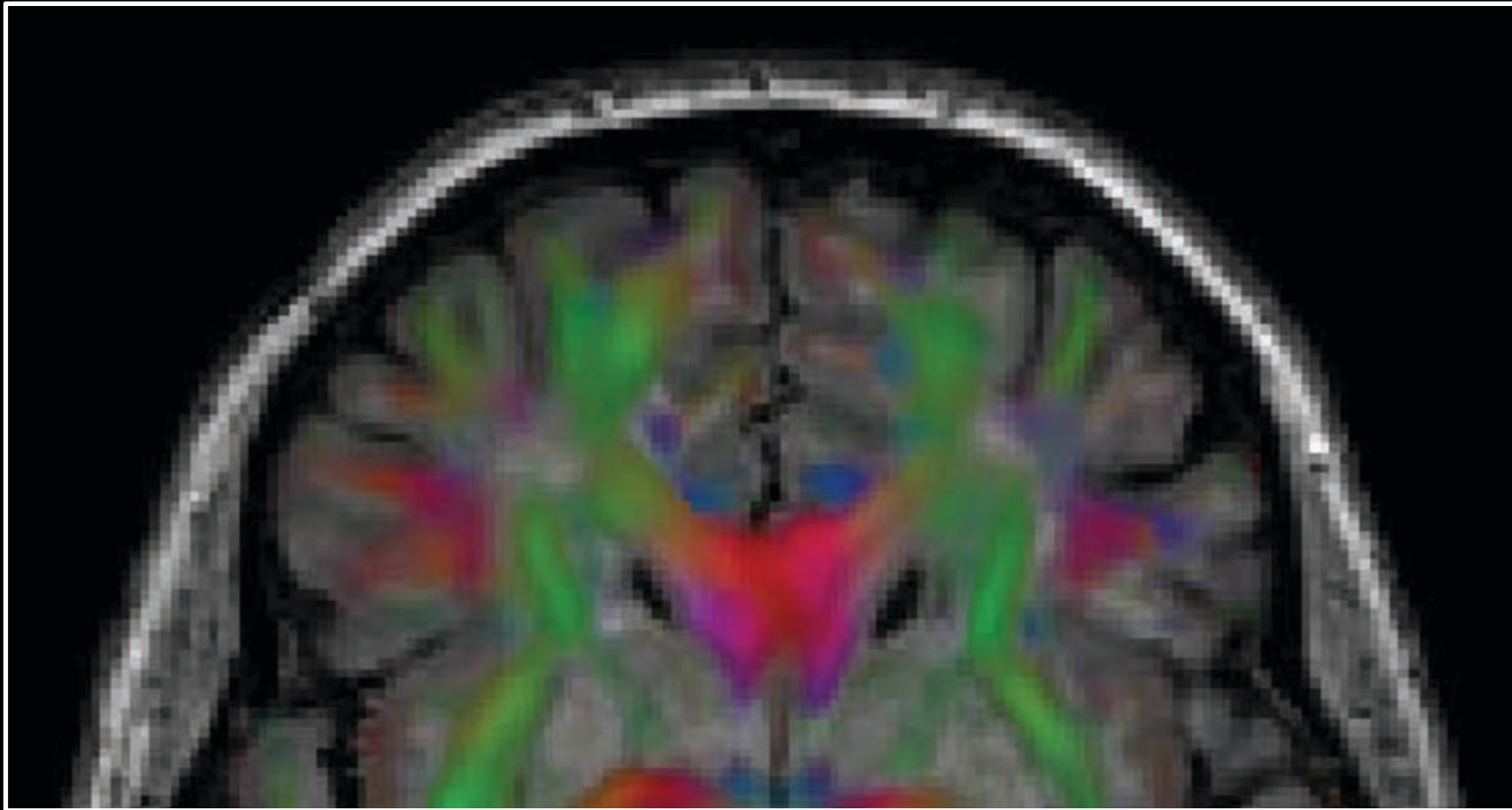
### 3. Correction for EPI deformations



**Without** EPI distortion correction

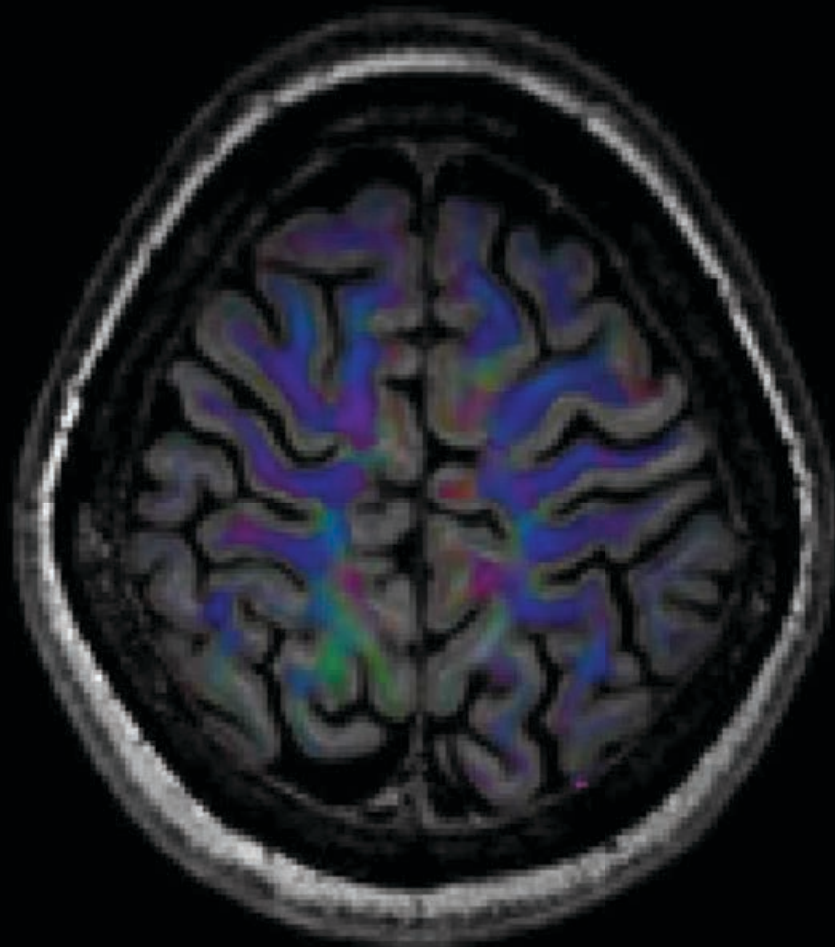


### 3. Correction for EPI deformations

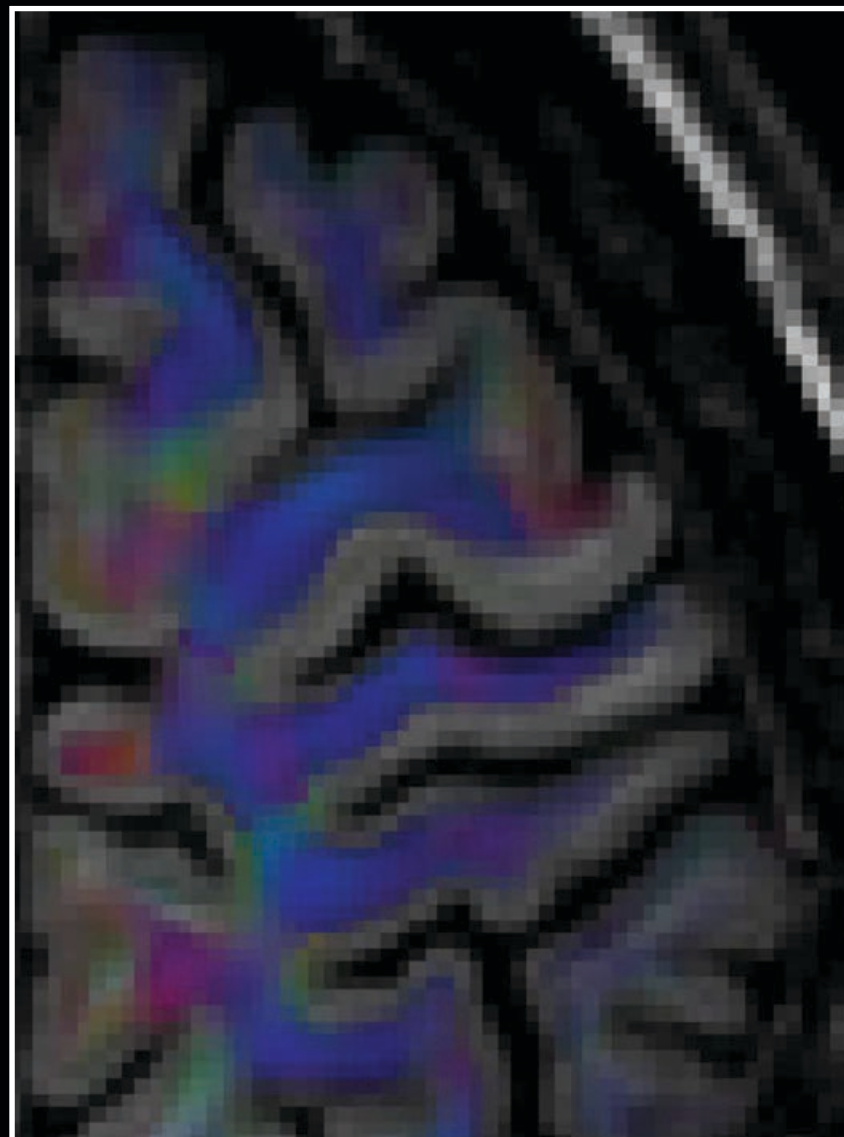


**With** EPI distortion correction

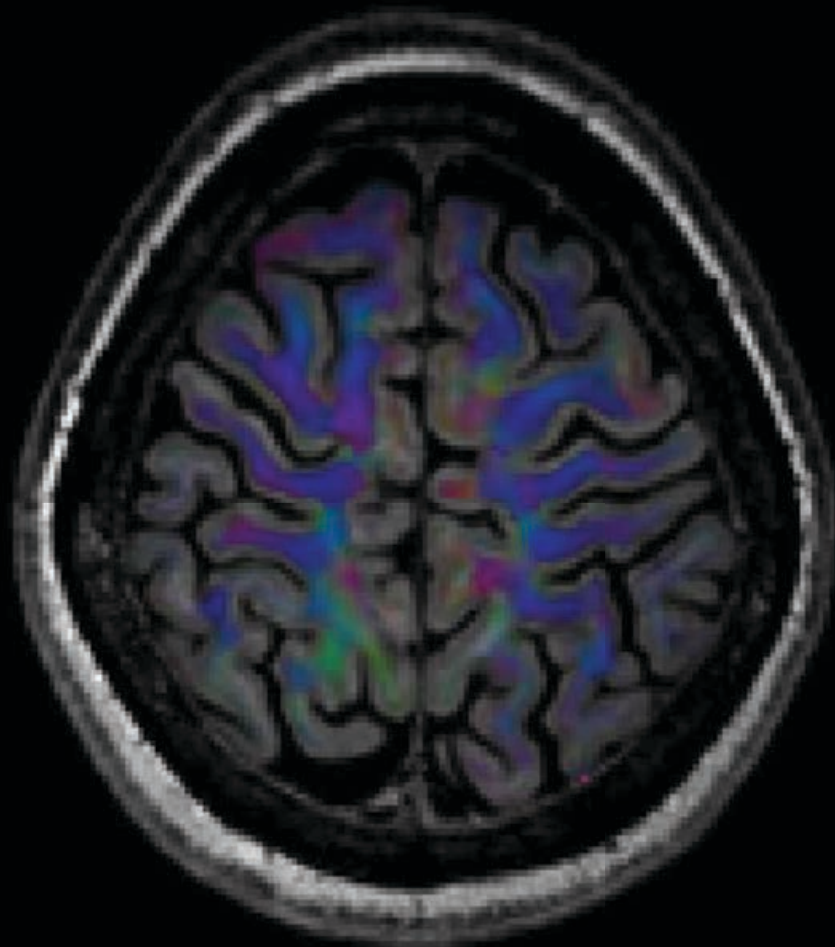
### 3. Correction for EPI deformations



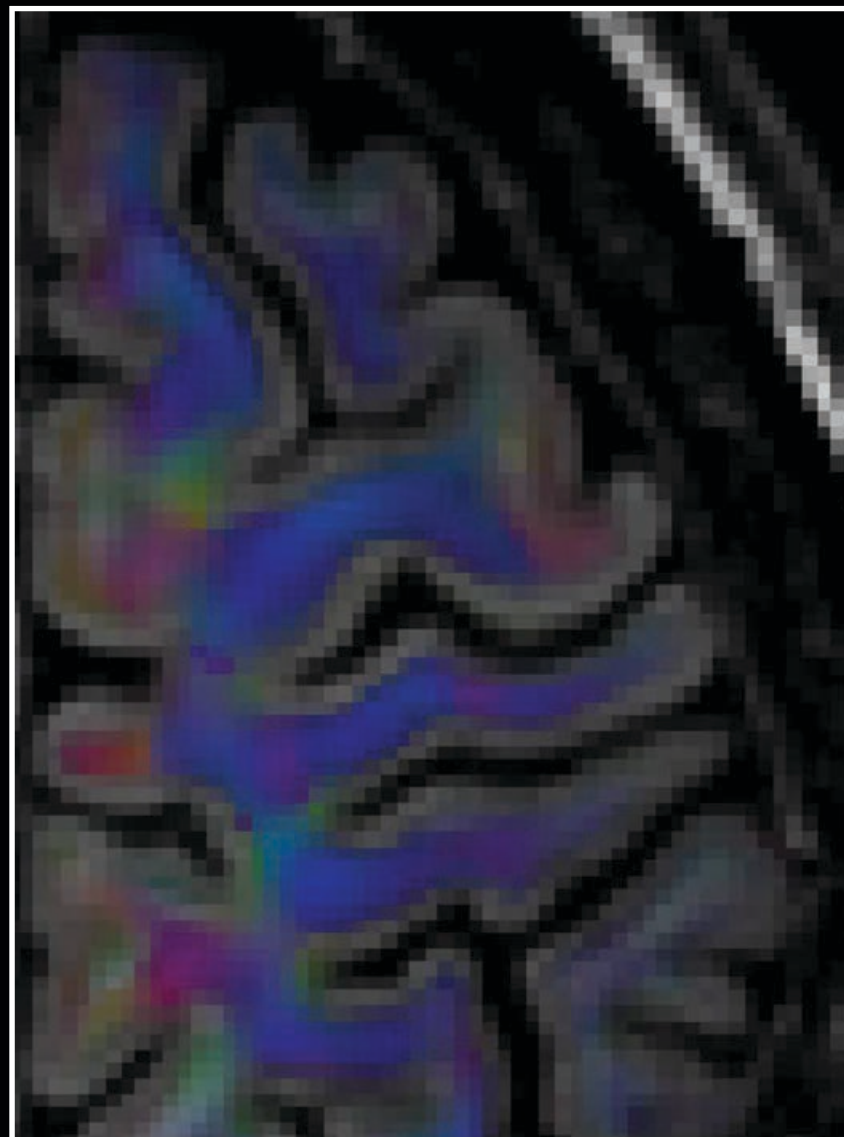
**Without** EPI distortion correction



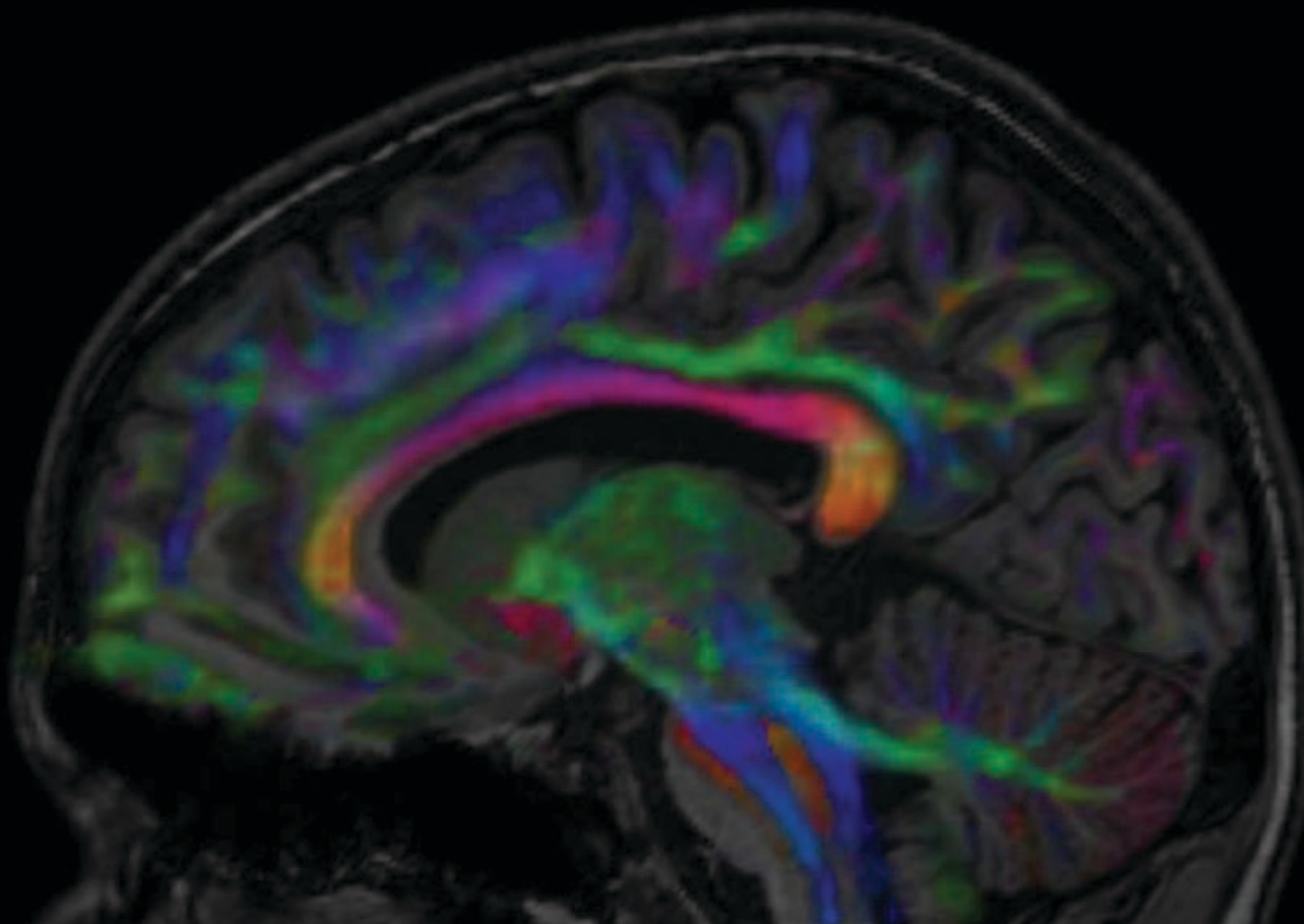
### 3. Correction for EPI deformations



With EPI distortion correction



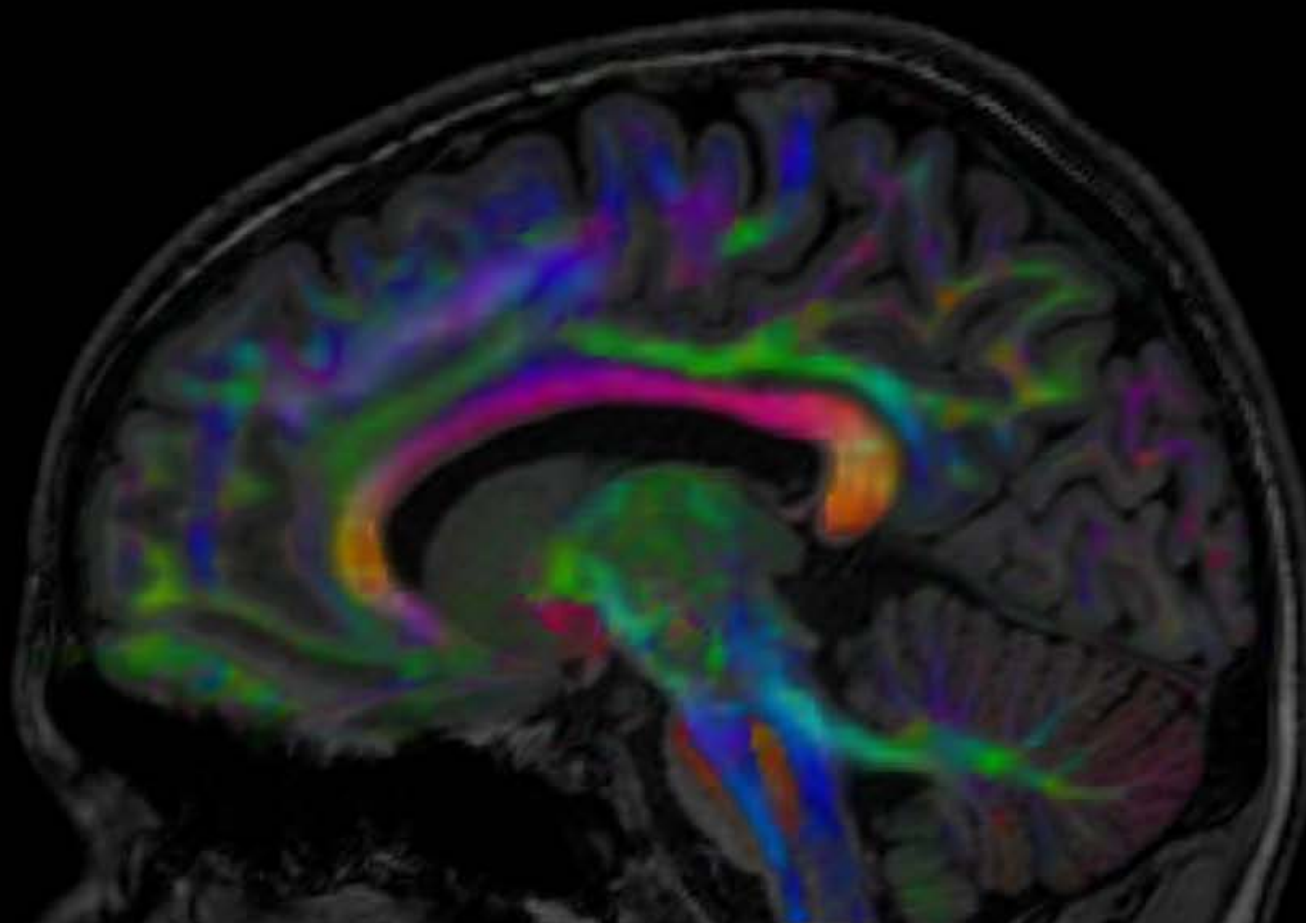
### 3. Correction for EPI deformations



**Without** EPI distortion correction



### 3. Correction for EPI deformations

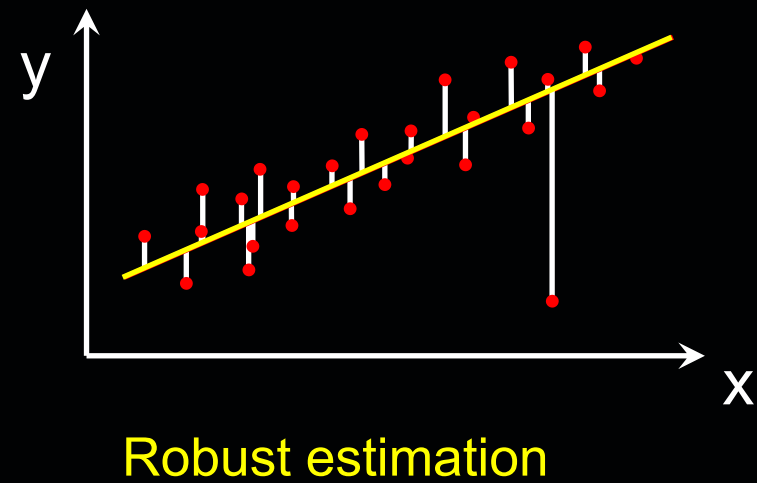
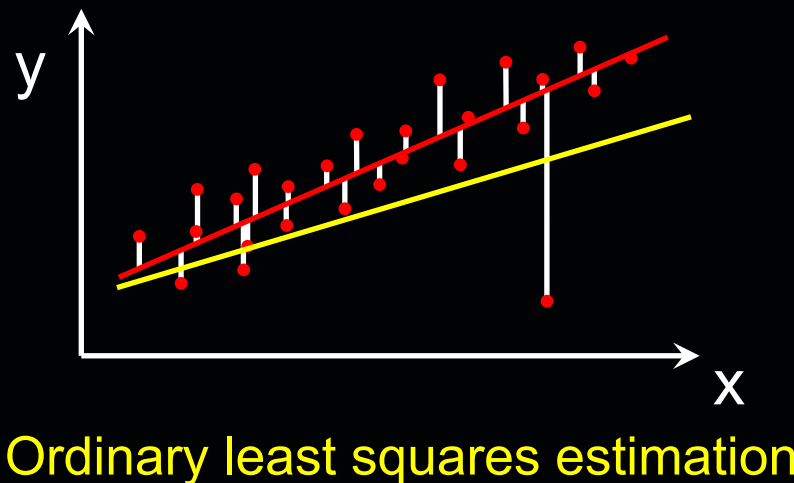
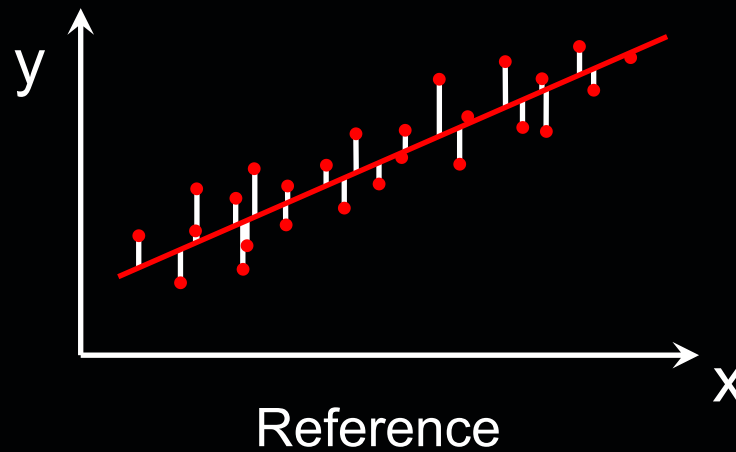


**With** EPI distortion correction

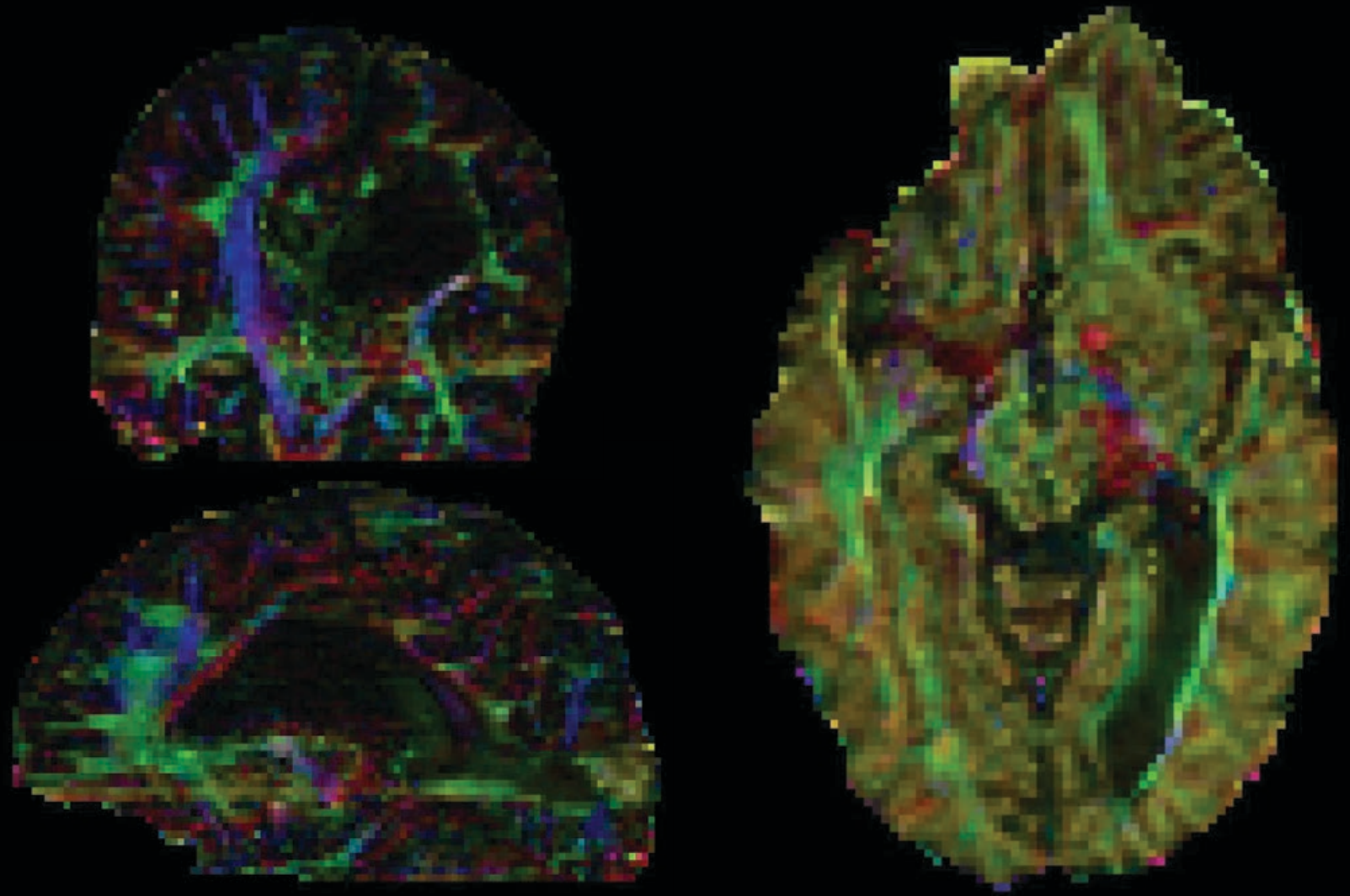




# 4. Diffusion model estimation approaches



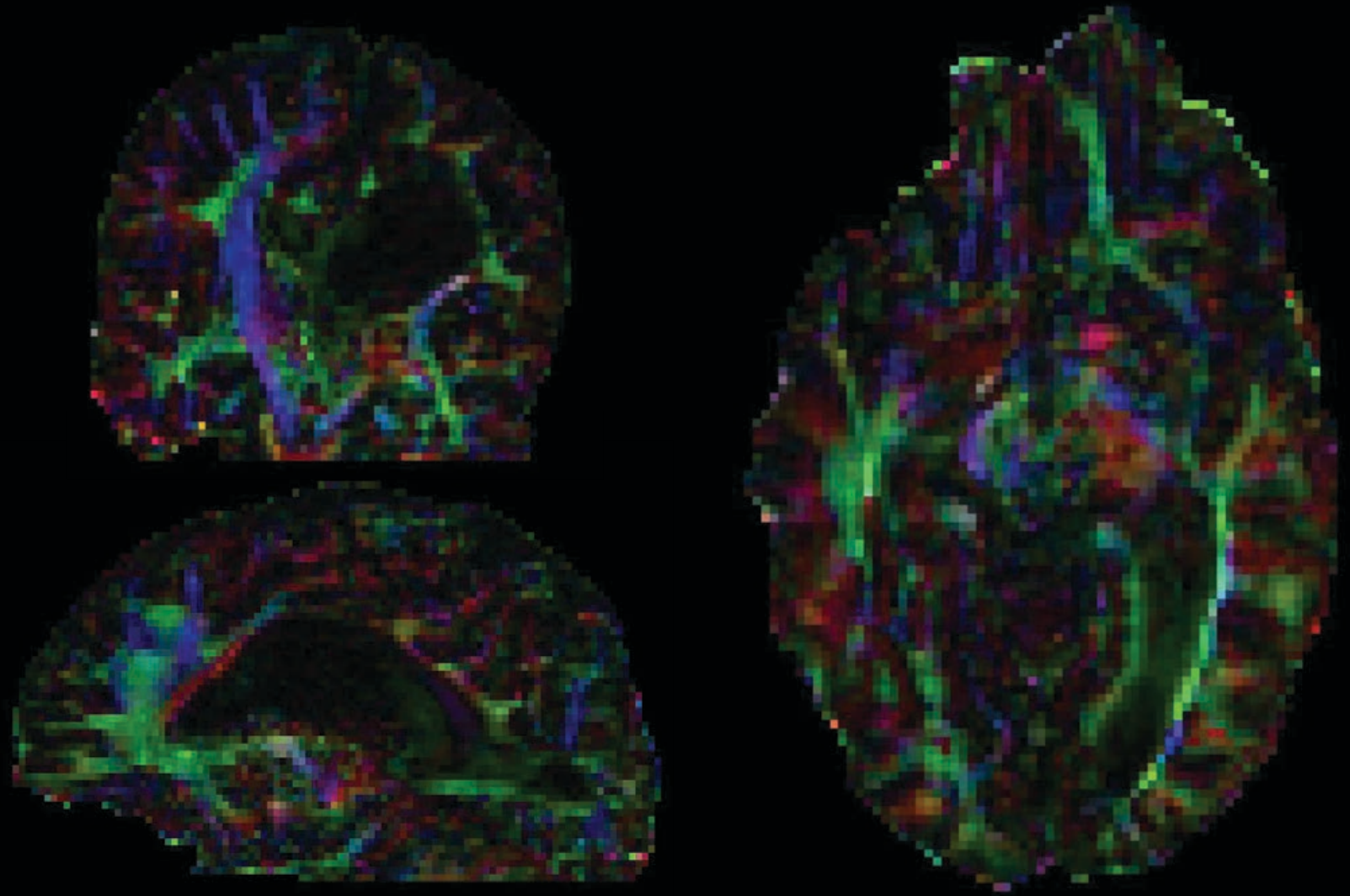
## 4. Diffusion model estimation approaches



Ordinary least squares estimation



## 4. Diffusion model estimation approaches



Robust estimation



# Acknowledgements

[www.ExploreDTI.com](http://www.ExploreDTI.com)



Stefan Sunaert  
Christian Beaulieu  
Donald Tournier  
Tomas Paus  
Susumu Mori  
Russ Poldrack  
Derek Jones  
Drew Berry  
Niek van der Aa  
Yael Reijmer  
Karen Caeyenberghs



@Alex\_Leemans

# PROVIDI Lab

## PROcessing & VI-sualization in Diffusion Imaging



J. Kok



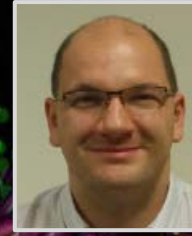
W. Haakma



H.M. Hulshof



T. Roine



S. Dávid



O. Odish



E. O'Hanlon



H. Mesri



B. Robalo



D. Aquino



A. De Luca



F. Guo



U. Roine



S. St-Jean

*Alumni who moved on to bigger & better...*



W. Van Hecke



B. Jeurissen



S.B. Vos



J.-L. Hsu



J. Gooijers



C.M.W. Tax



D. Perrone



A. Heemskerk

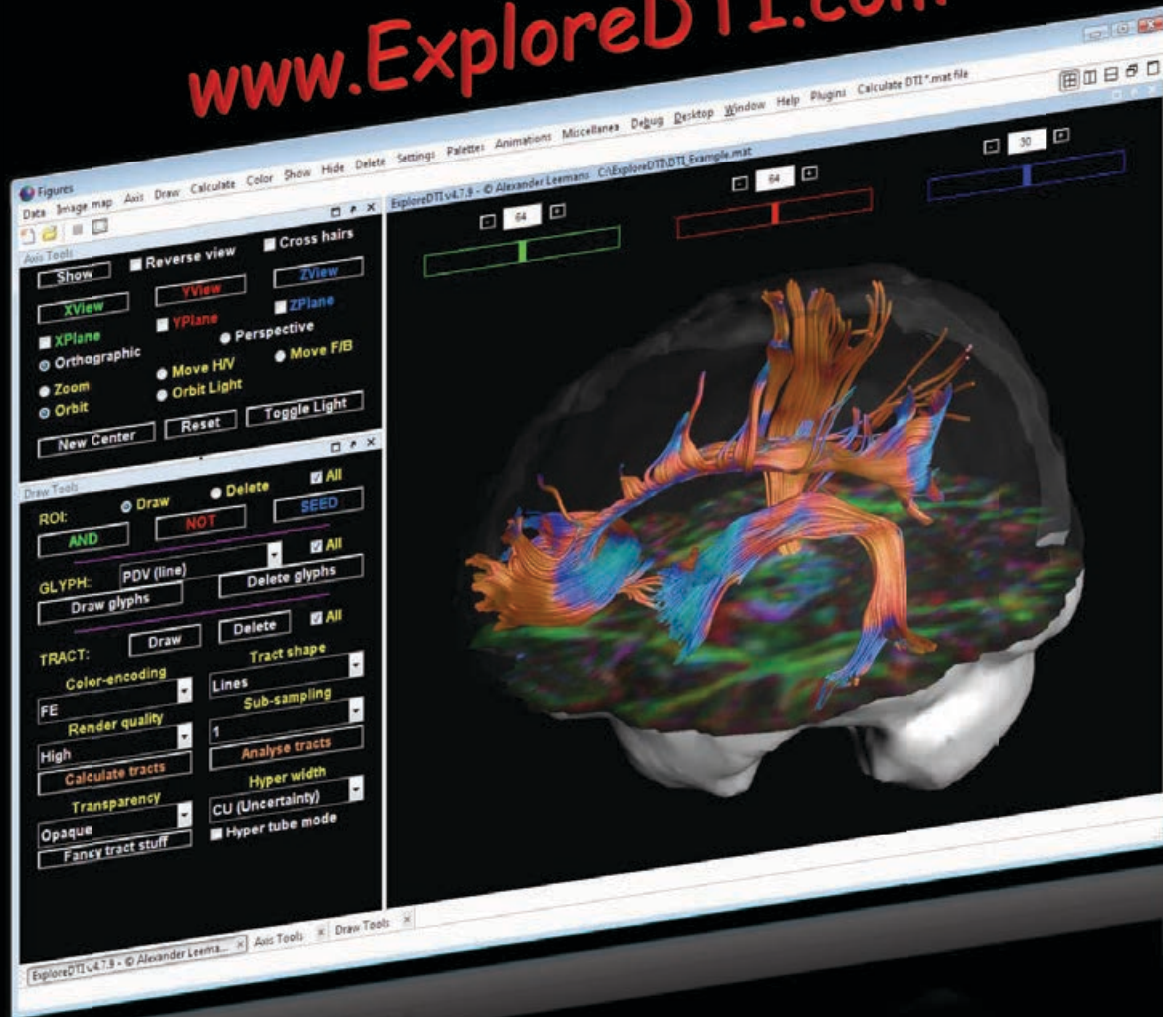
Merci de votre attention!



@Alex\_Leemans

# Part 2 ...

[www.ExploredTI.com](http://www.ExploredTI.com)



@Alex\_Leemans

# Part 2 ...

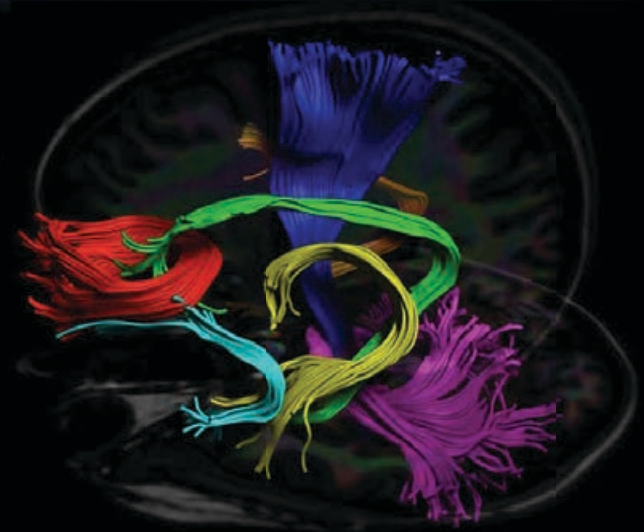
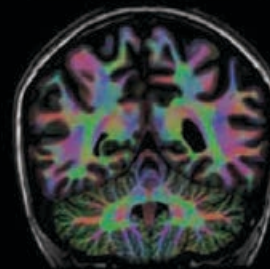
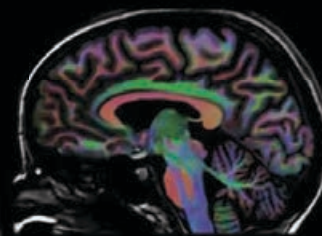
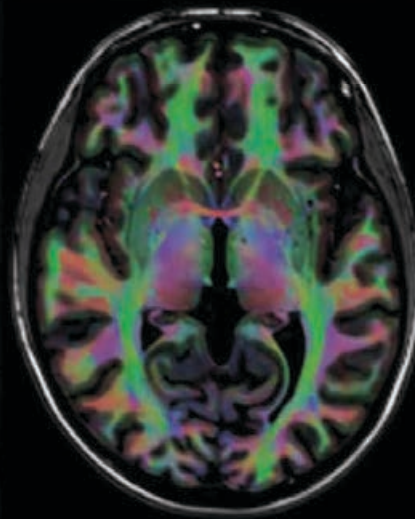
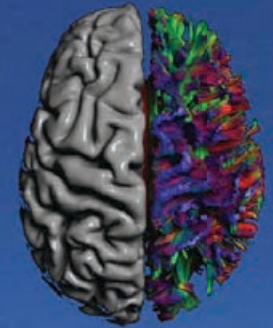
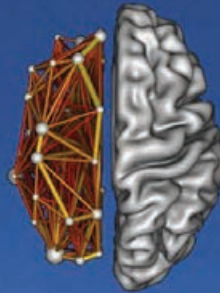


## ExploreDTI Workshop

12-14 March, 2018

Utrecht, the Netherlands

[www.ExploreDTI.com/workshop](http://www.ExploreDTI.com/workshop)



@Alex\_Leemans