

Improved Image Classification with Coarse and Fine Labels

Anuvabh Dutt, Denis Pellerin, Georges Quénot



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 - * AVS, MED OEx
- Convert query into a list of target concepts with weights and possibly Boolean formula.
- Need to calibrate probabilities for using (and combining) concepts from various models
 - * ImageNet, Places, etc

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- **Classification** $\hat{y} = \underset{j}{\operatorname{argmax}} \sigma(\mathbf{z})_j$ an image.
* Metric: Top $\sigma(\mathbf{z})_j = \frac{e^{z_j}}{\sum_{k=1}^K e^{z_k}}$ soft-max.

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- Scores ranges from $-\infty$ to $+\infty$
- Probabilities are expected to range from 0 to 1
- Sigmoid transform: $p(\text{score}) = 1/(1+e^{(A*\text{score}+B)})$
- Additional hint: among the samples within a small interval around p , a fraction of about p would have positive labels
- Platt's method: learn A and B by cross-validation to optimally satisfy the above hint

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- In both cases: average over a number of images to be categorized or over a number of concepts to be retrieved.
- Refine concept categories, from coarse to fine grained.

Related Work

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- YOLO9000: Better, Faster, Stronger
Joseph Redmon, Ali Farhadi [arxiv:1612.08242]

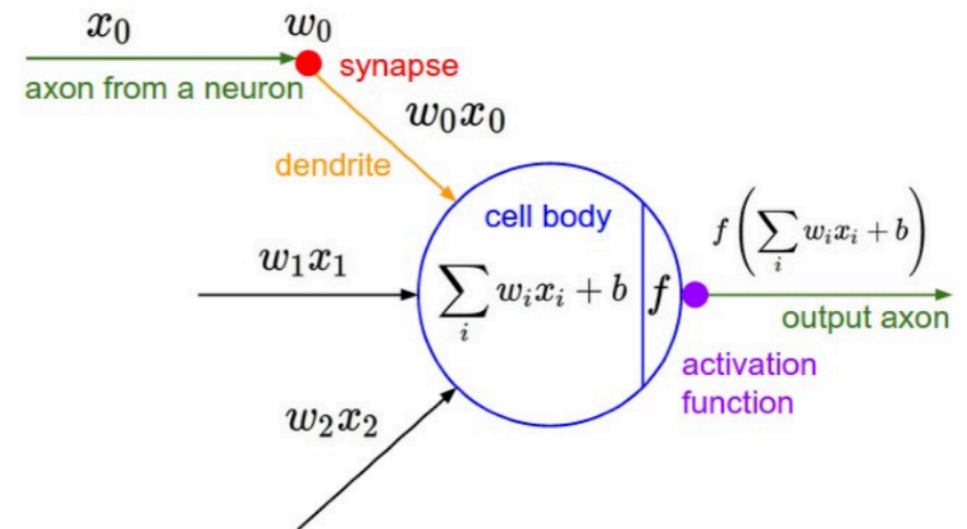
Related Work

- YOLO9000: Better, Faster, Stronger
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- Classifier adaptation at prediction time.
Amelie Royer and Christoph H Lampert. CVPR, 2015.

Background

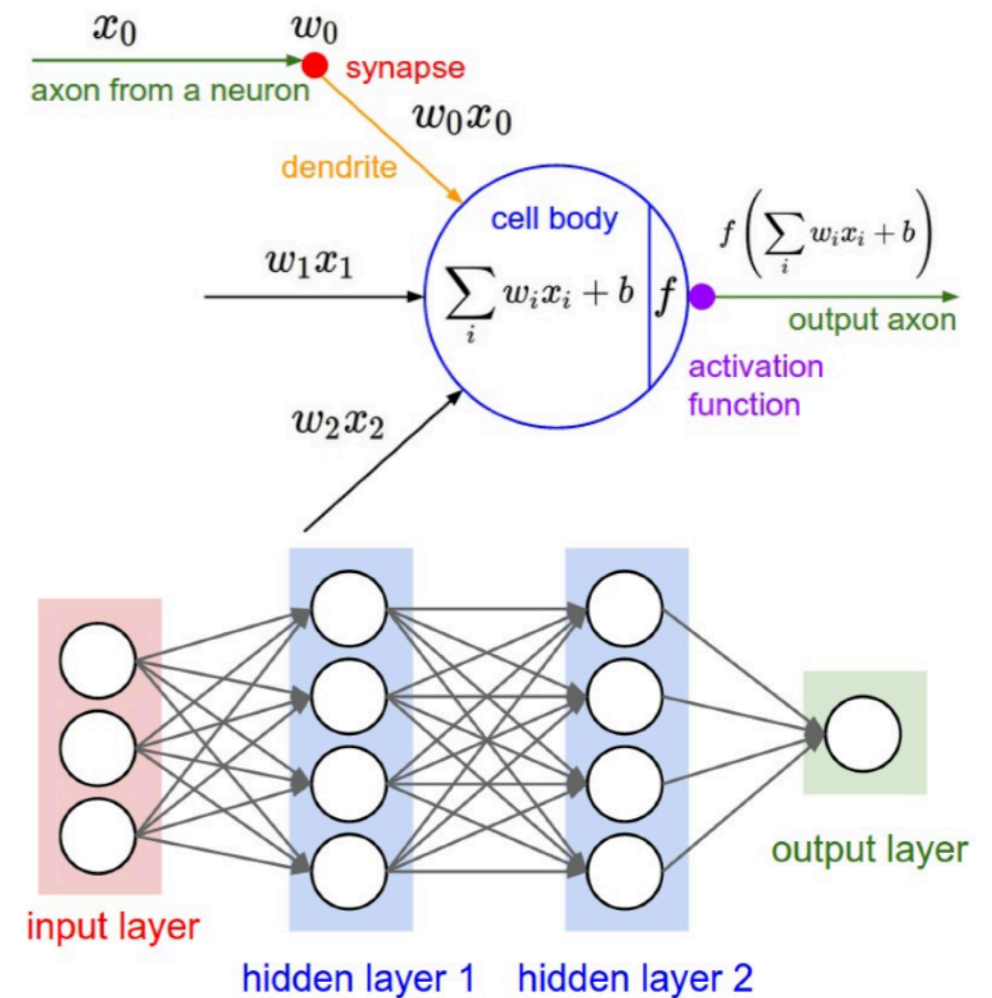
Background

- Neural Network



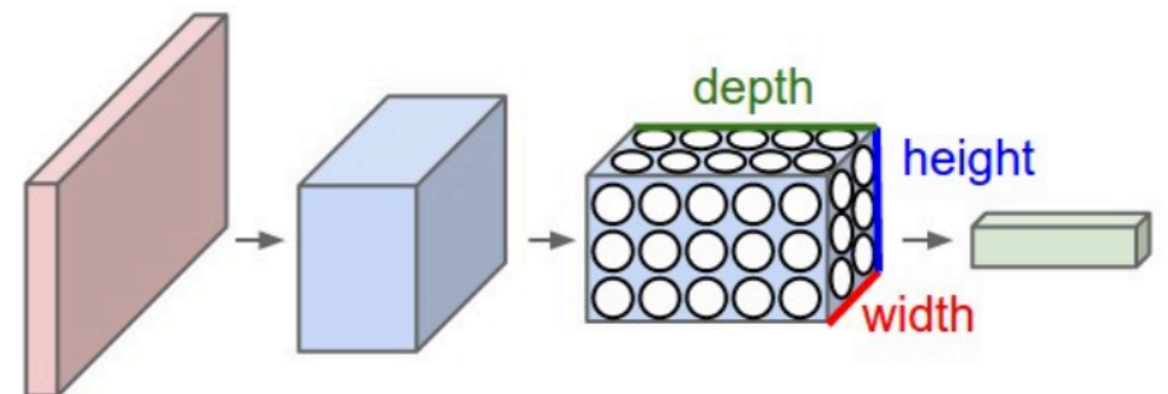
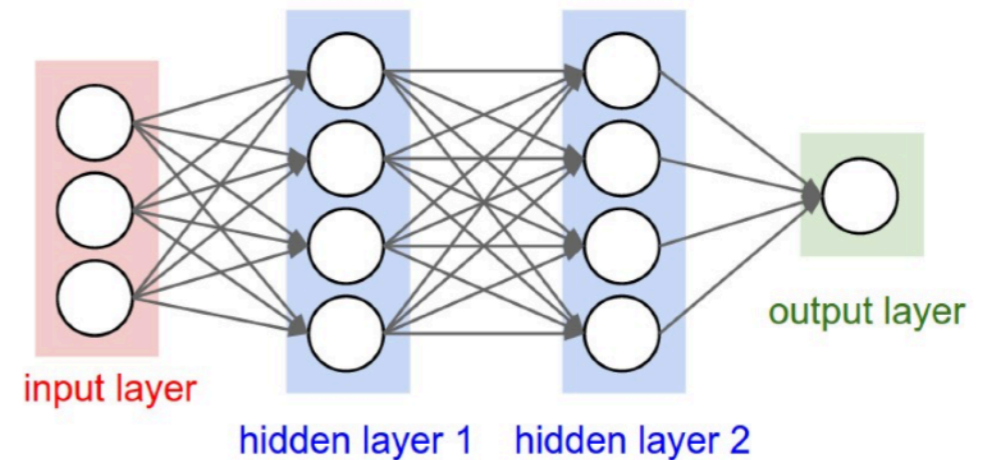
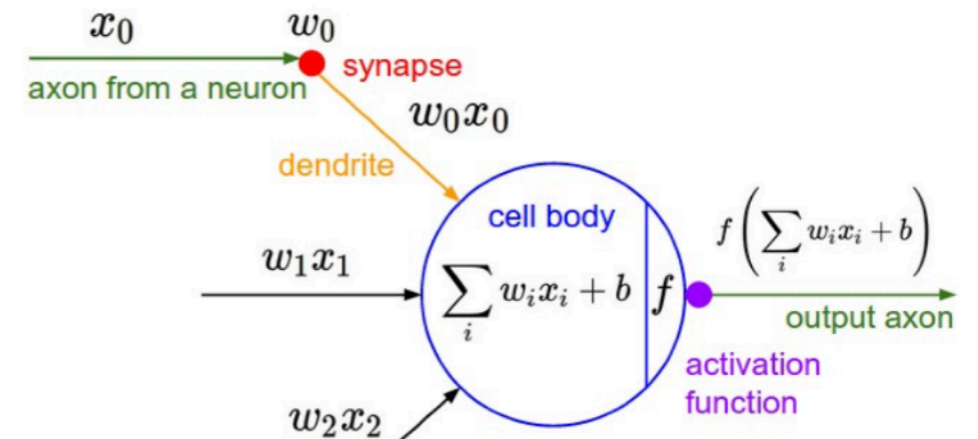
Background

- Neural Network
- Deep Neural Network



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- Deep Convolutional Network



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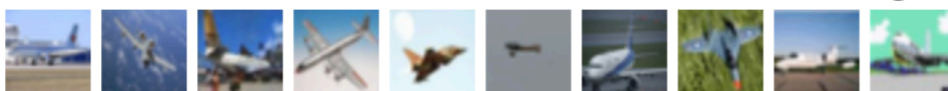
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- State-of-the art models in vision: ResNet, DenseNet
- After training, the classifier predicts a probability distribution over the categories.
 - * The value assigned to a category is the “confidence” of the classifier for that category

Problem Setting

- Image classification
- Labels with semantic relationship
- Example:
 - Coarse label: vehicle
 - Corresponding fine label(s): car, truck, bike

Problem Setting

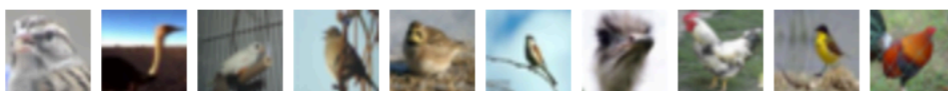
airplane



automobile



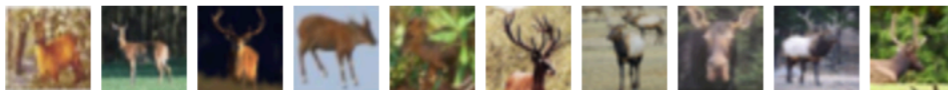
bird



cat



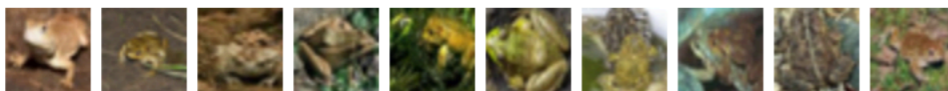
deer



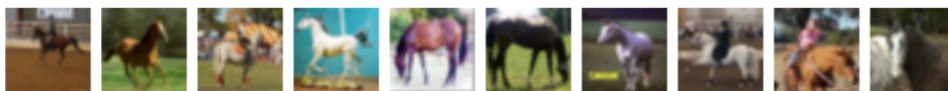
dog



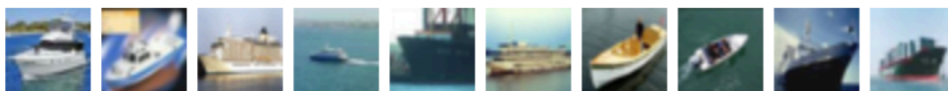
frog



horse



ship

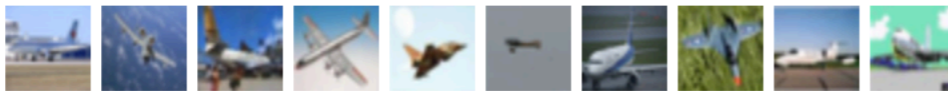


truck



Problem Setting

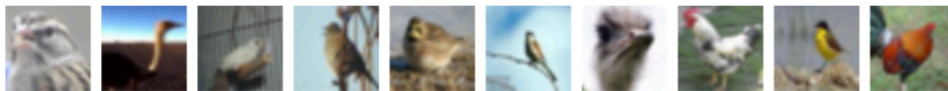
airplane



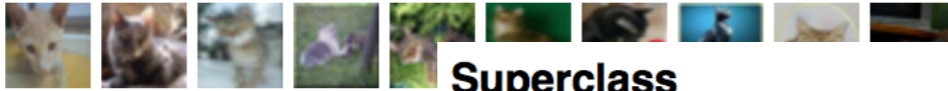
automobile



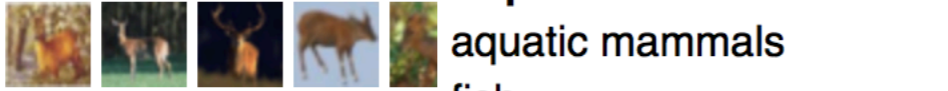
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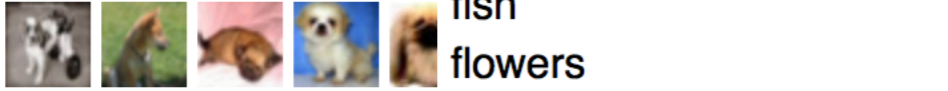
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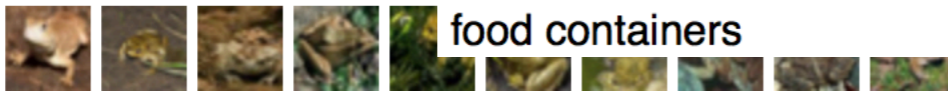
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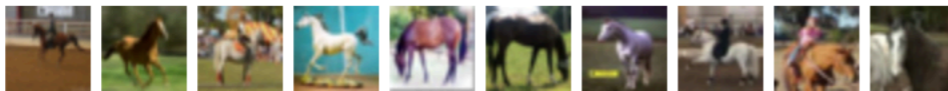
dog



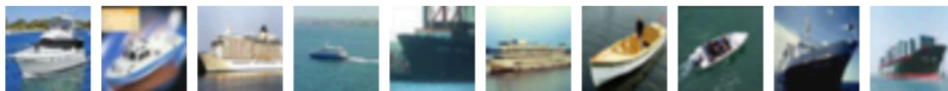
frog



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ship



truck



Superclass

aquatic mammals

fish

flowers

food containers

Classes

beaver, dolphin, otter, seal, whale

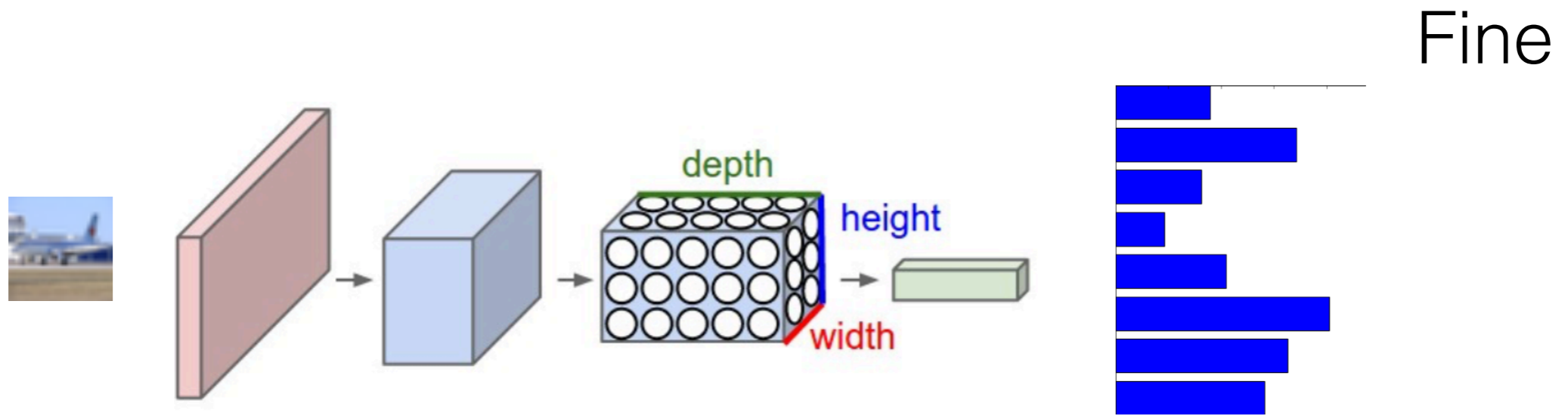
aquarium fish, flatfish, ray, shark, trout

orchids, poppies, roses, sunflowers, tulips

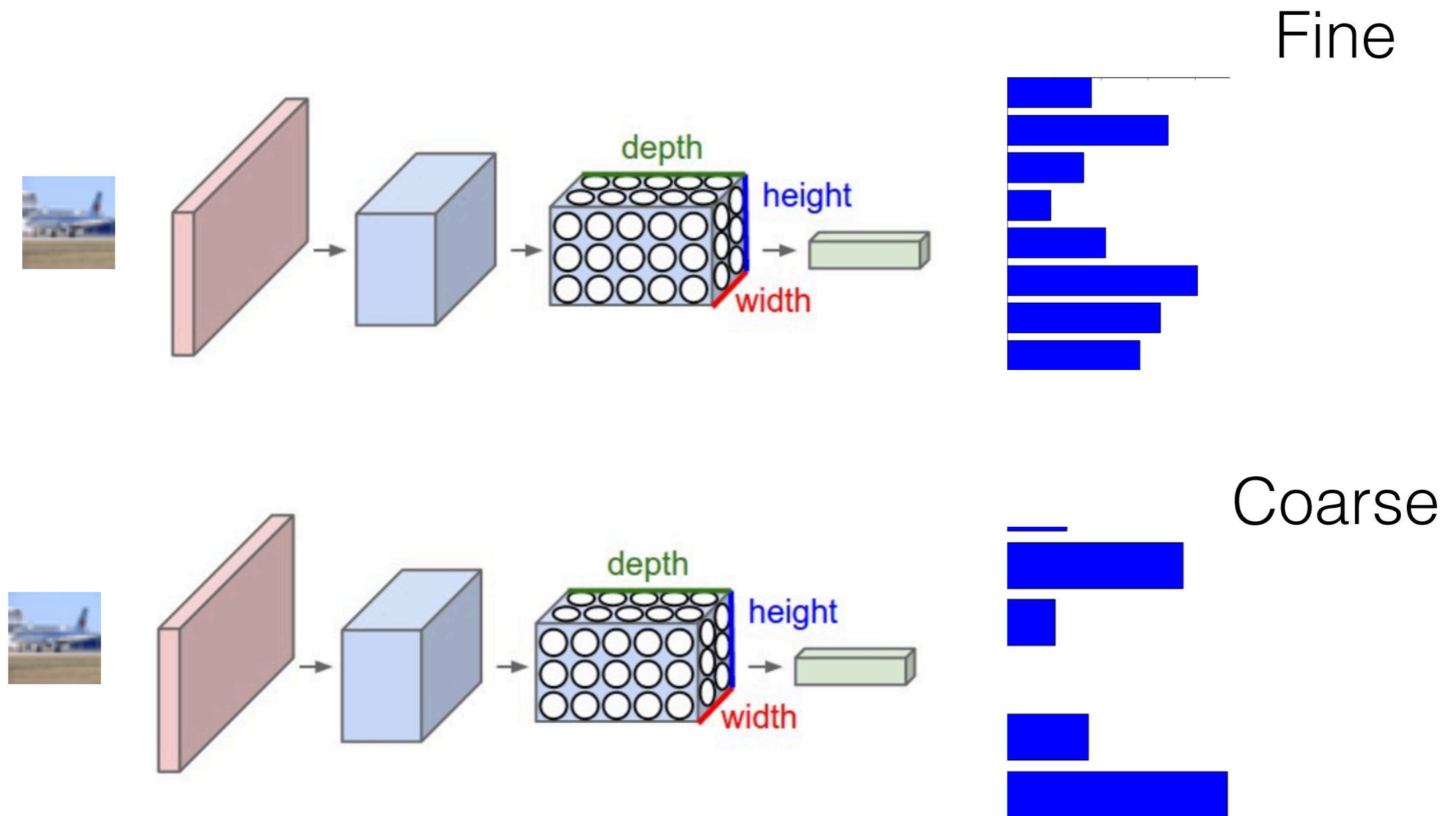
bottles, bowls, cans, cups, plates

Classifier Confidence

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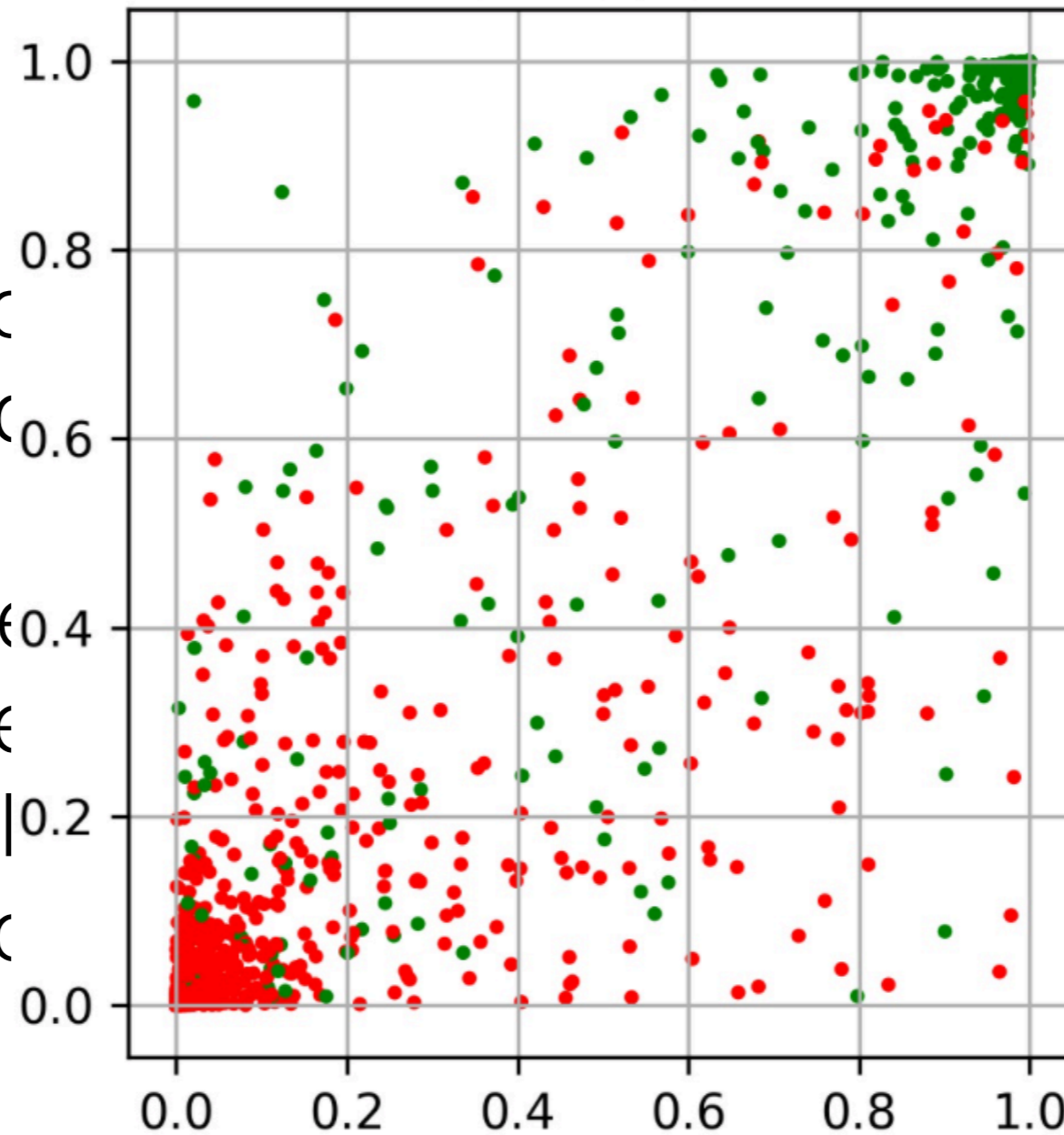


Motivation

- Trained models have a confidence value for the coarse and fine categories, respectively.
- If the model captures the ***semantic*** structure, the confidence in the coarse category should be similar to the total confidence in the corresponding fine categories.

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- If the model confidence is similar to the fine category, the model should be responding



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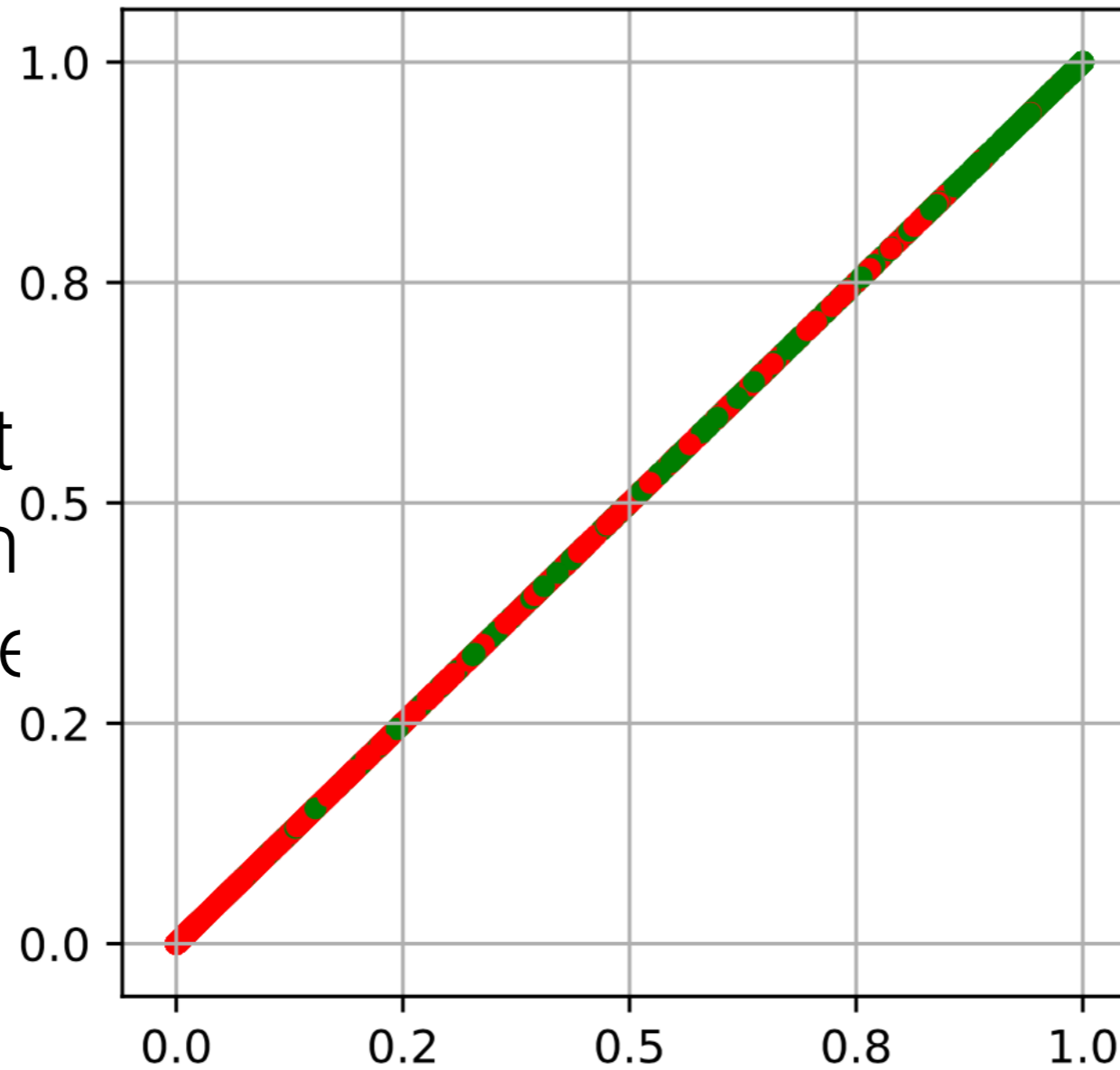
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- We want to enforce the condition that the confidence of the coarse category should be distributed among its 'fine' categories.

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- We want confidence distribution

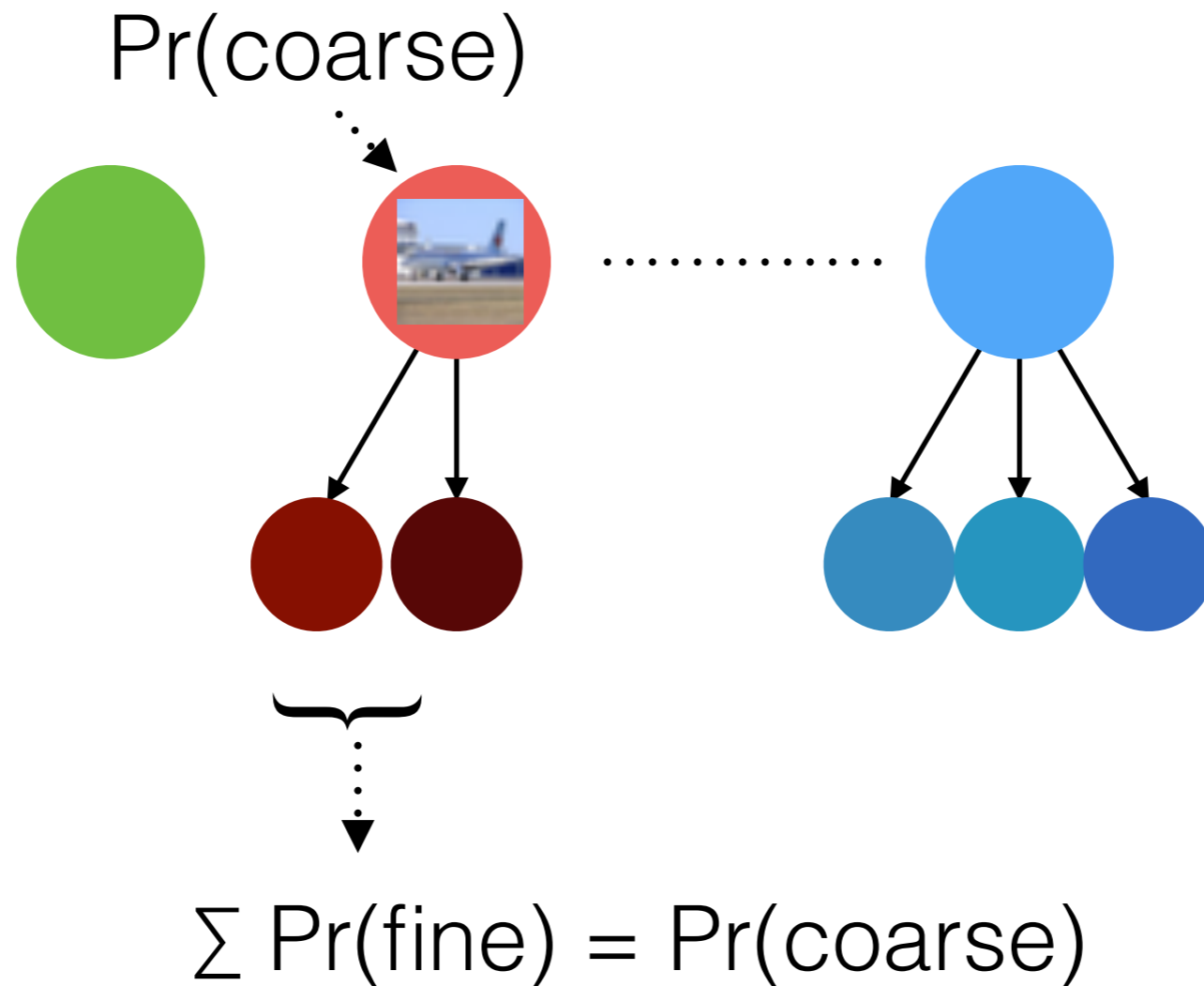


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Fine and Coarse Labels



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- Obtain probability values for test image from coarse and fine models.

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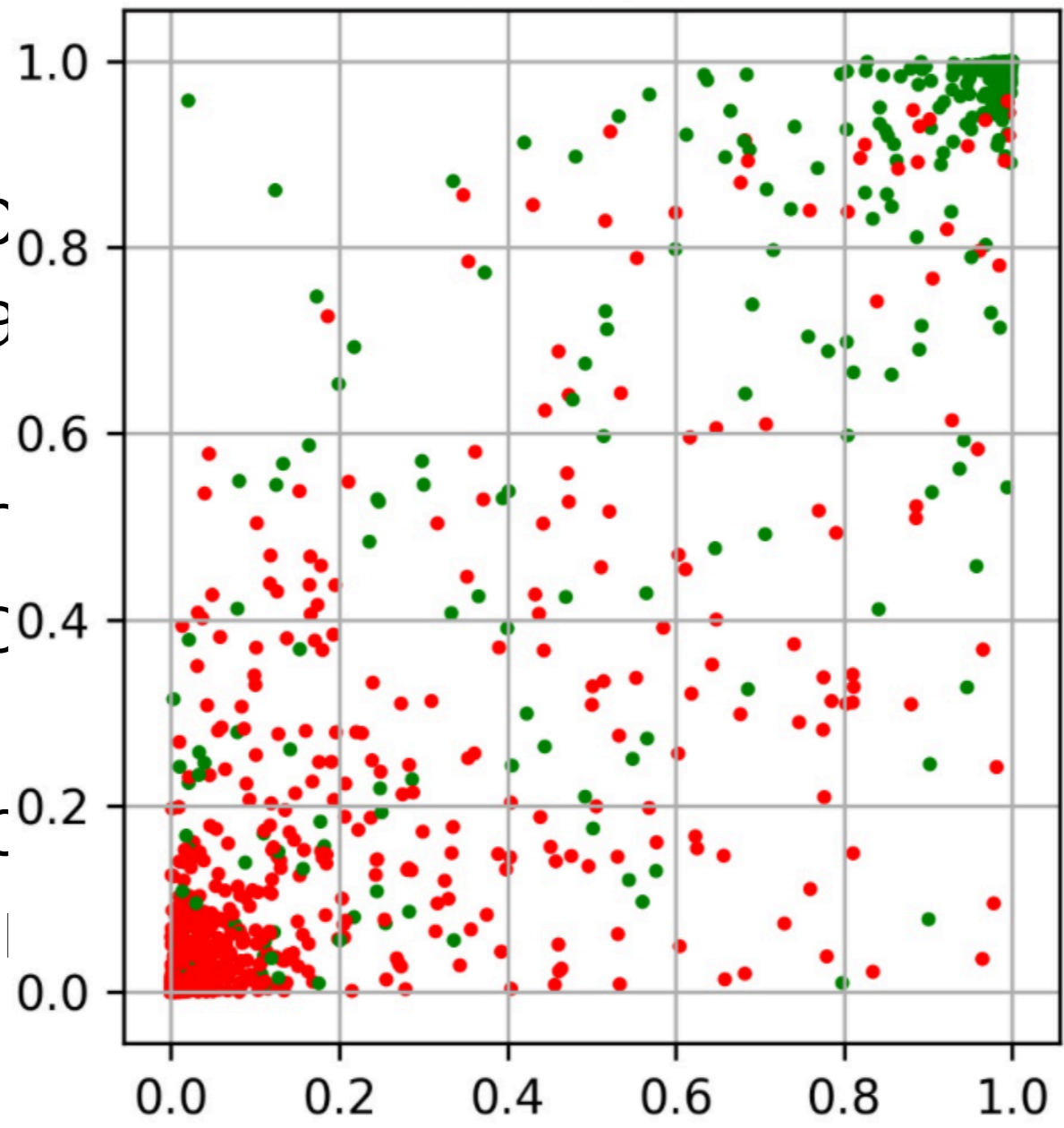
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- For each coarse category, adjust classifier prediction values such that: $\sum \text{Pr}(\text{fine}) = \text{Pr}(\text{coarse})$
- Predict category which has maximum probability (confidence).

Method

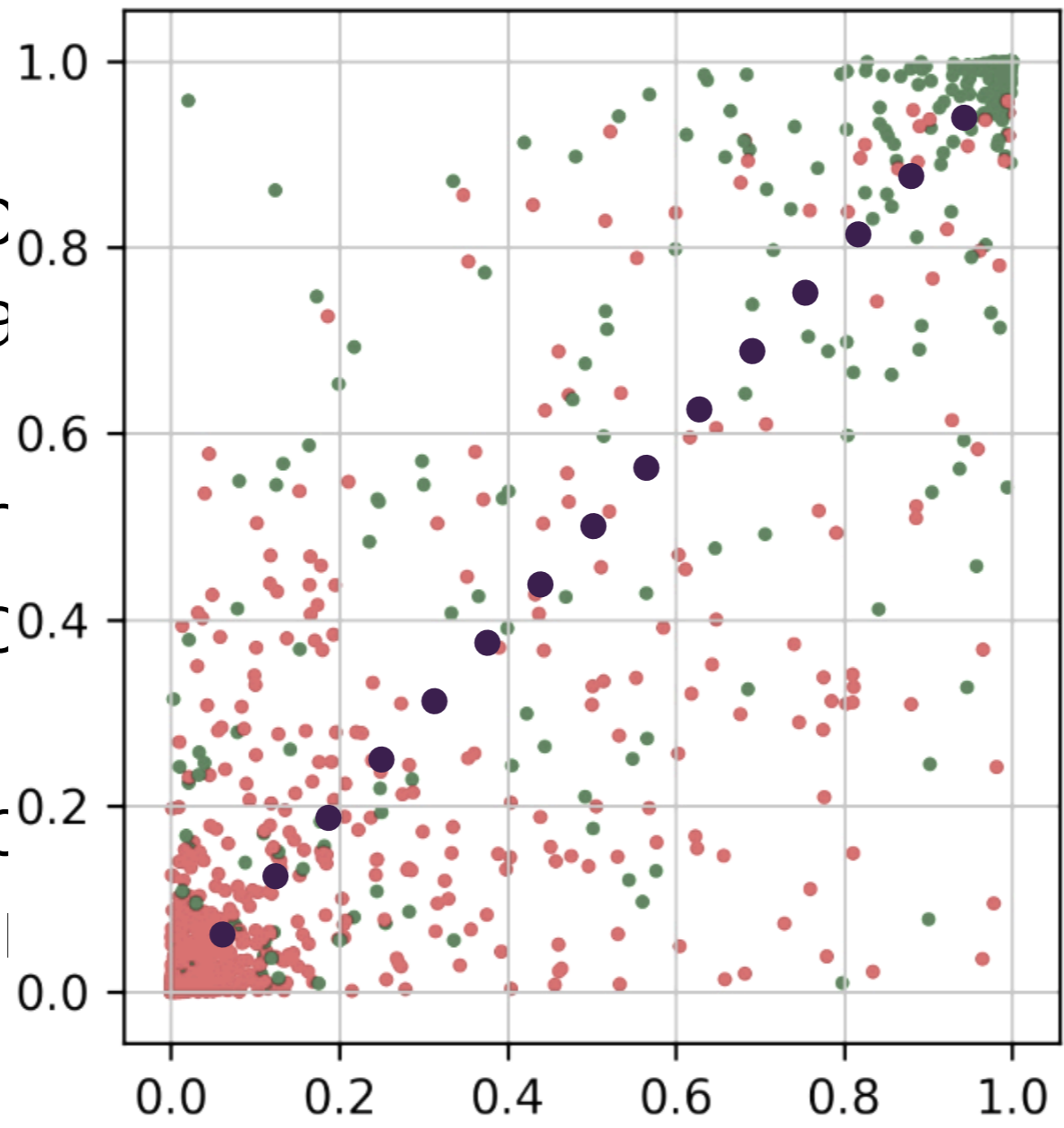
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- For each predictor
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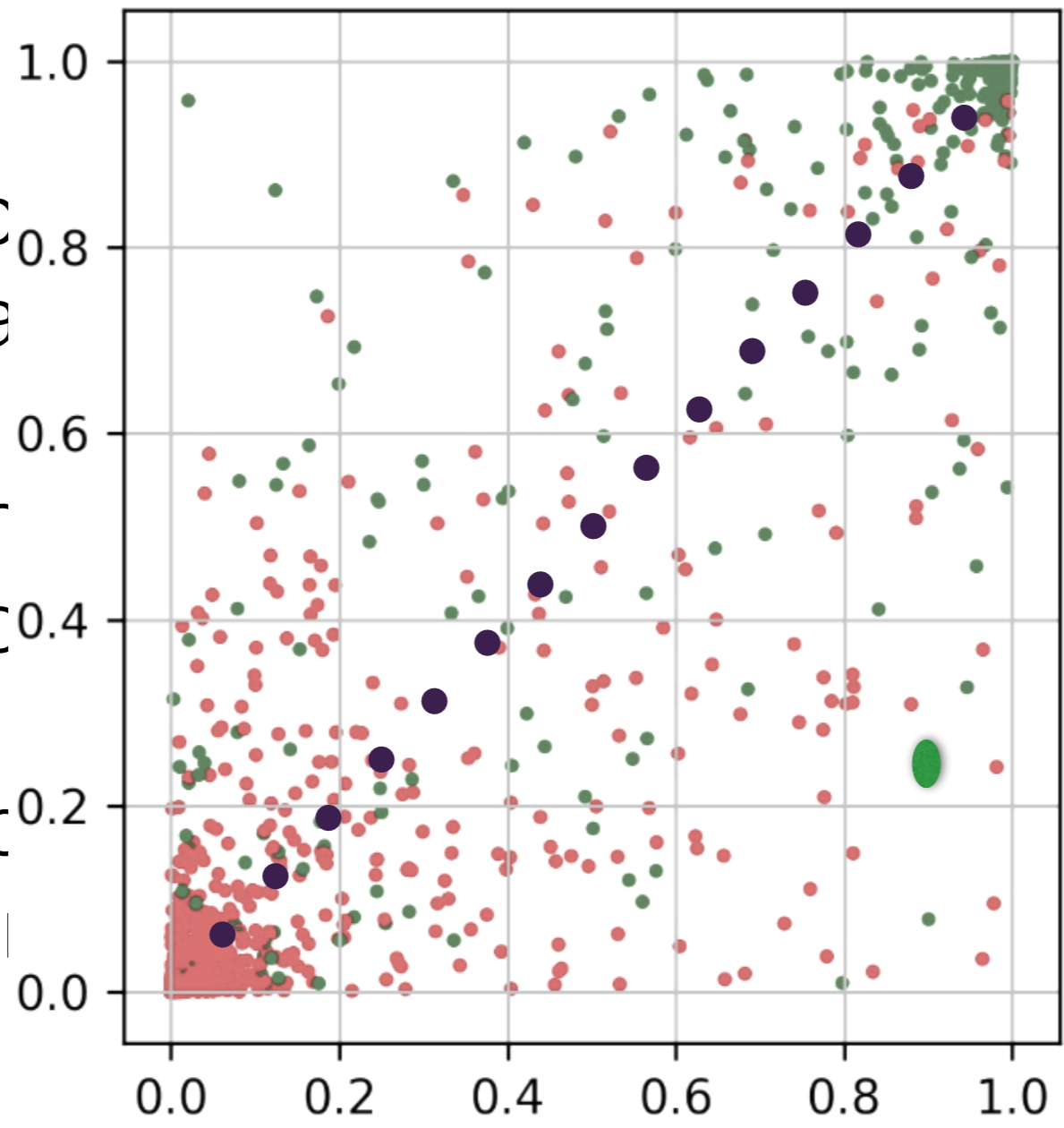
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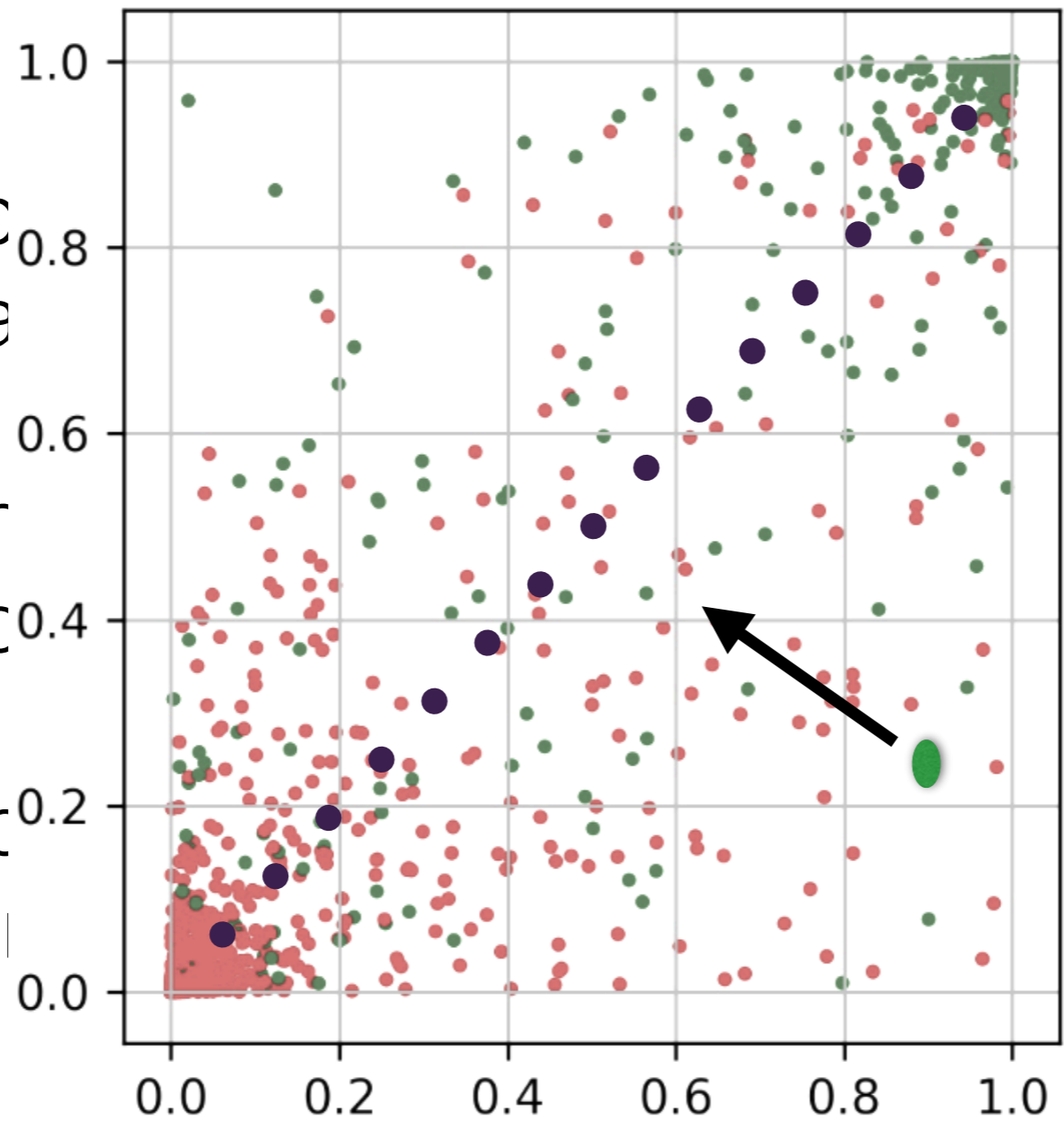
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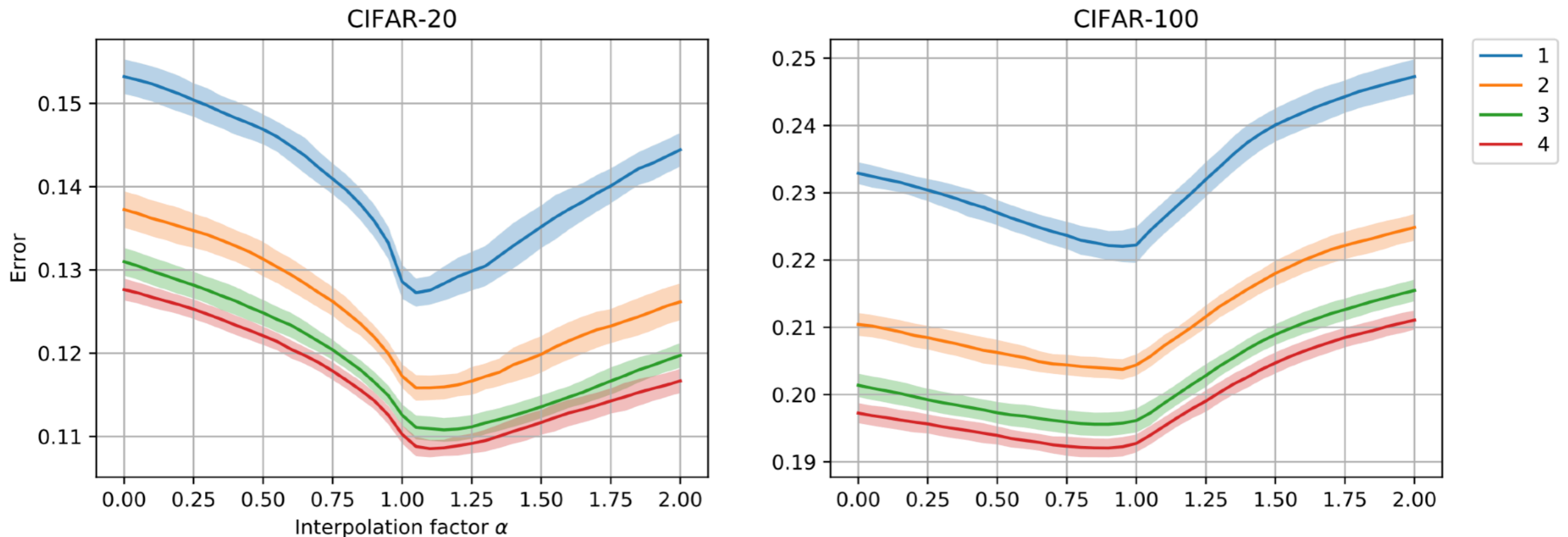
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Results



- Error rate for the ResNet model after applying our adjustment scheme.
- The x-axis shows how the error changes when we move from the initial probability values to the ones enforced by our scheme.
- We observe that we steadily lower the error rate.

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- No knowledge of ground truth categories required.

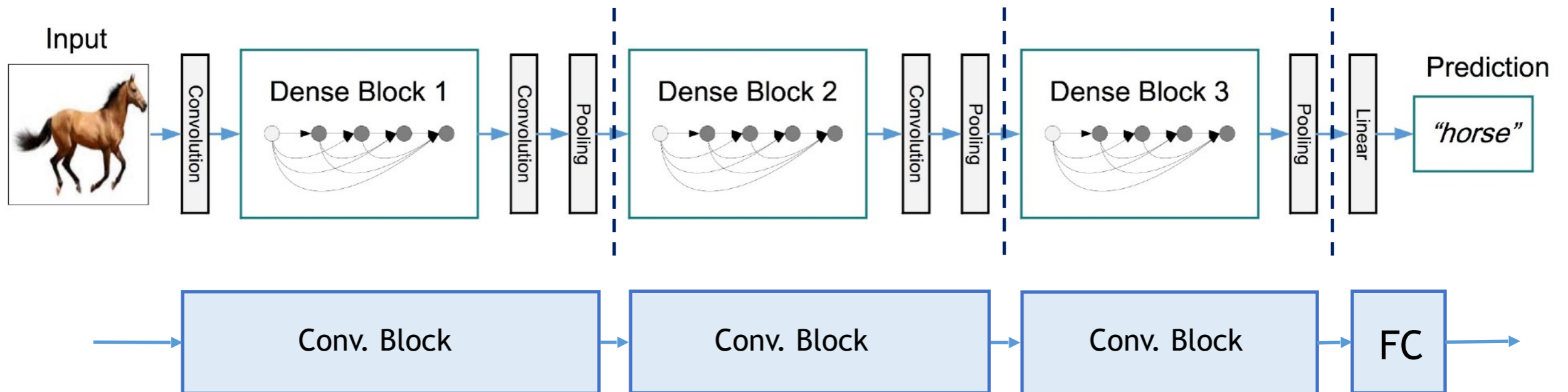
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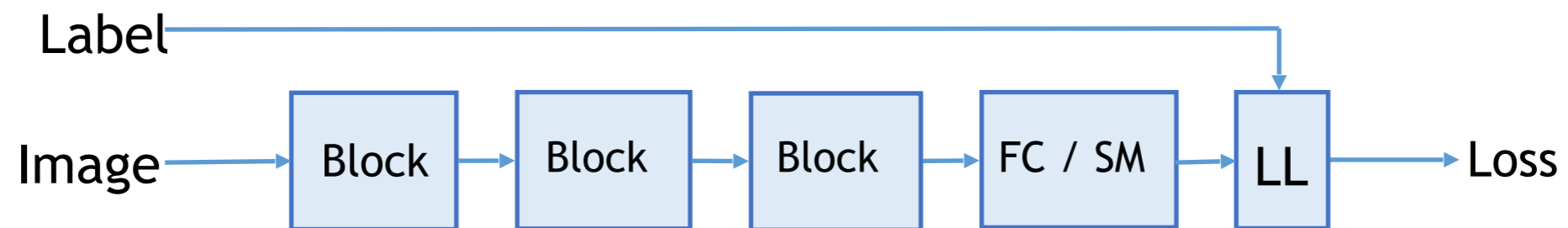
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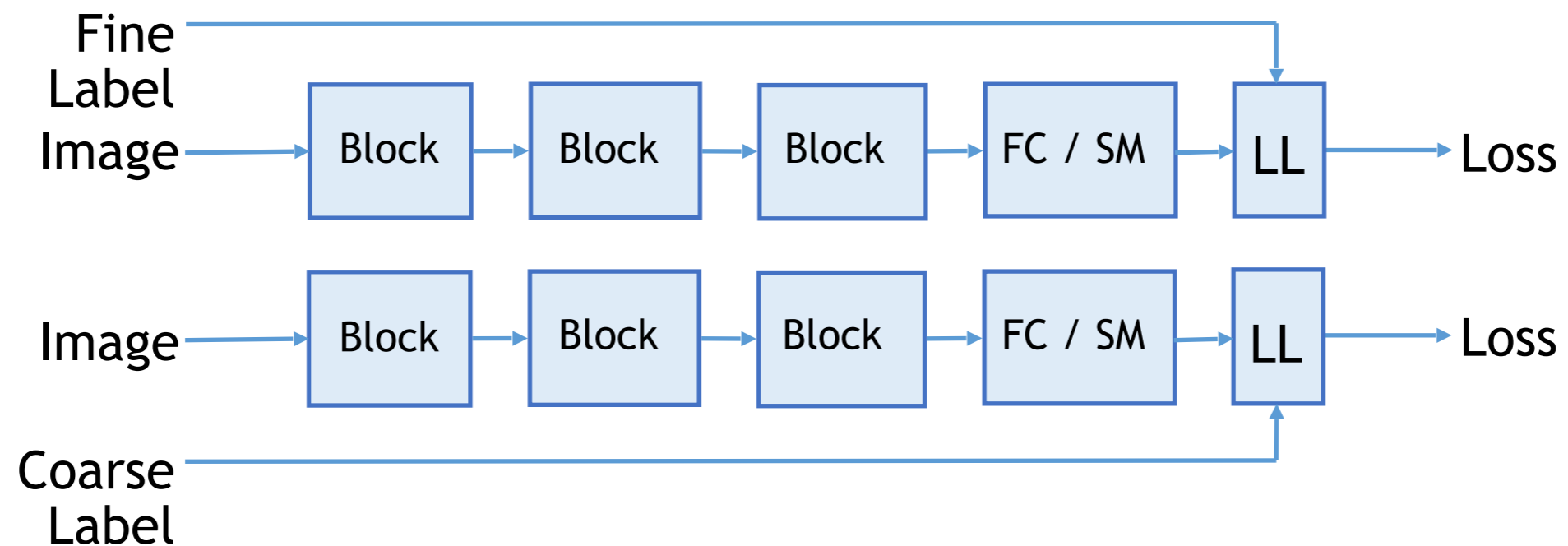
Merged Architecture



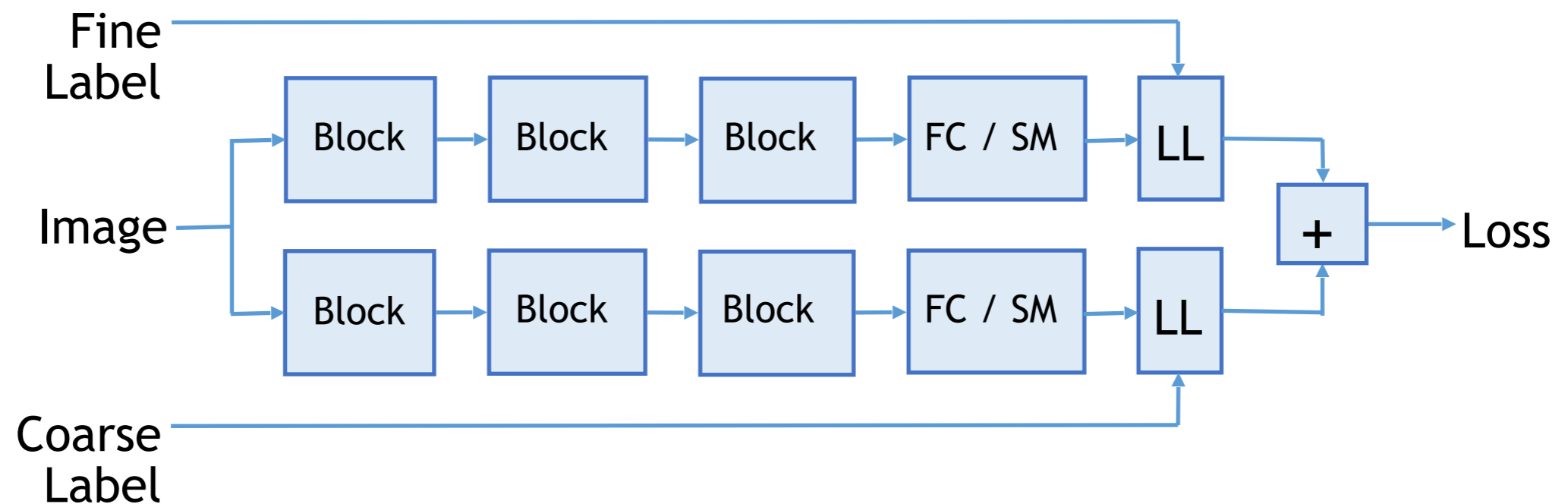
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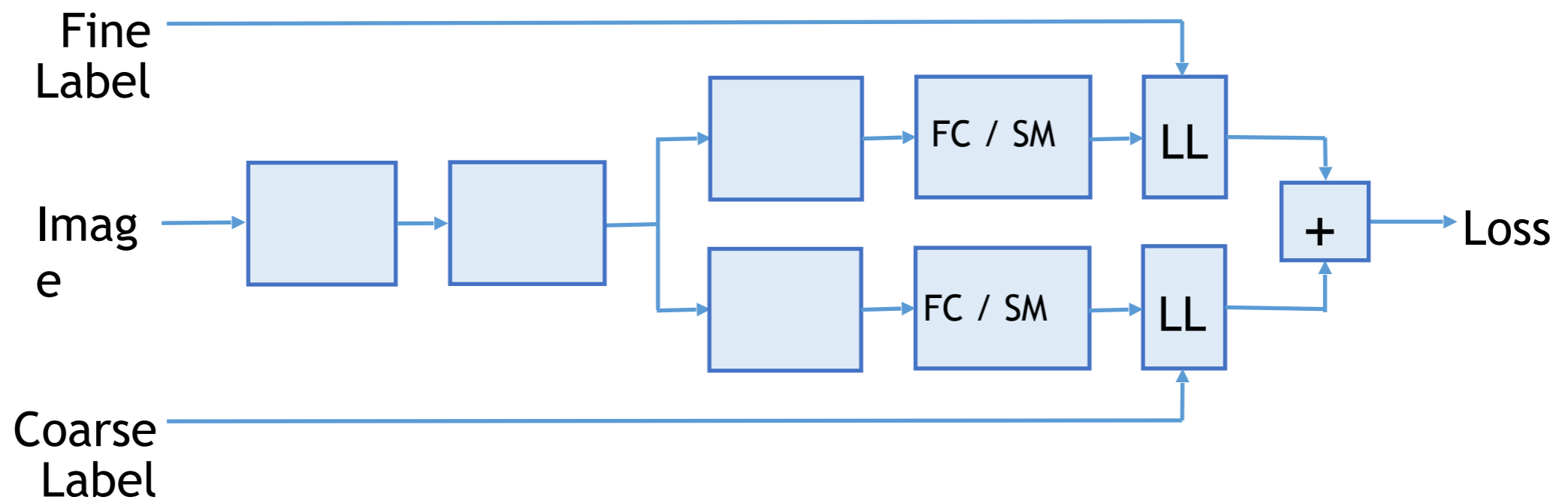
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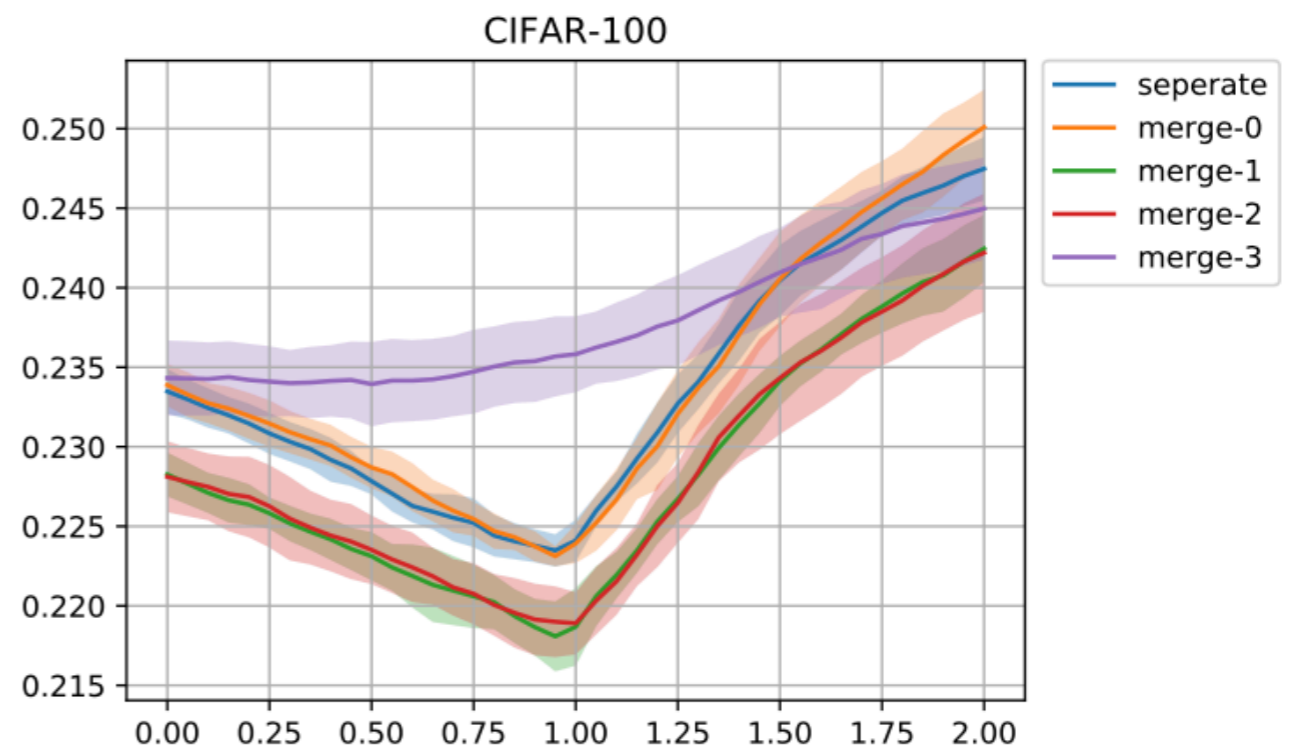
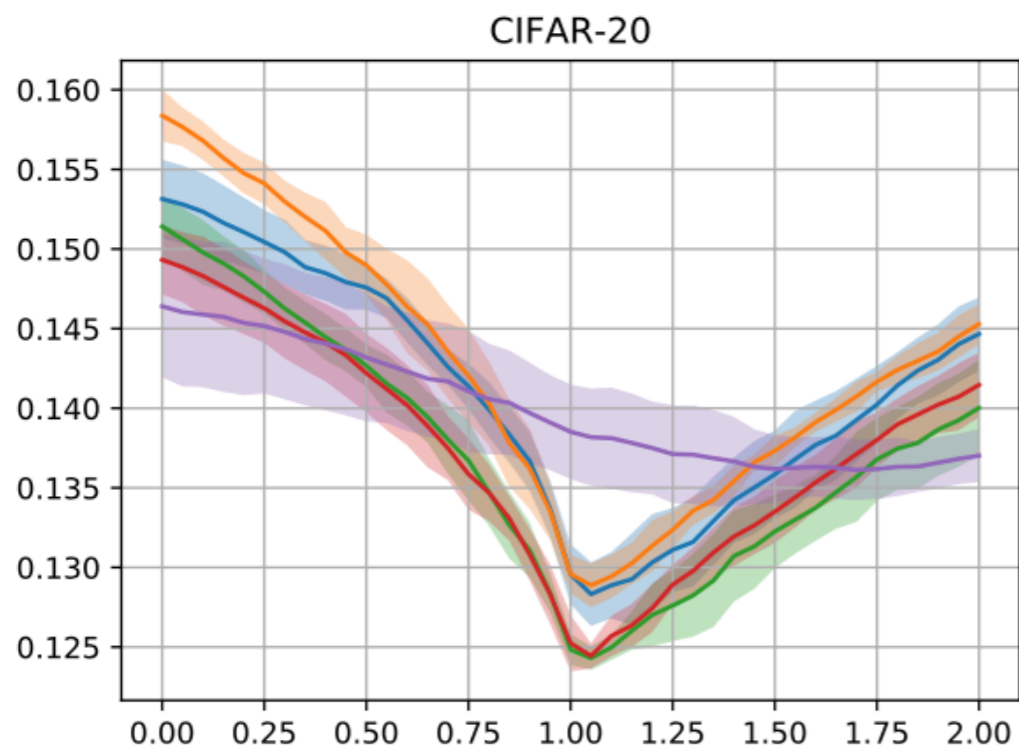


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- To appear in: *ACM International Conference on Multimedia Retrieval (ICMR), June 2017.*

Thank You.