# CONFORMAL INFERENCE FOR BIOMEDICAL IMAGE SEGMENTATION

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### UNCERTAINTY QUANTIFICATION IN MACHINE LEARNING

- Machine learning models such as a neural networks as extremely useful
- Used to perform classification, segmentation, object detection, and regression.
- However they are often black-box models and do not provide uncertainty guarantees. They can be wrong and are often over-confident in their predictions.
- Mistakes, for instance in medical fields, can be very bad and have rather negative consequences.

#### INTRODUCTION TO CONFORMAL INFERENCE



 $1 - \alpha \leq \mathbb{P}(Y_{\text{test}} \in \mathcal{C}(X_{\text{test}}))$ 

#### INTRODUCTION TO CONFORMAL INFERENCE





### INTRODUCTION TO CONFORMAL INFERENCE



POLPYS SEGMENTATION



X

POLPYS SEGMENTATION





















POLPYS SEGMENTATION



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## NOTATION

- Let  $\mathcal{V} \subset \mathbb{R}^m$  be a finite set which represents the pixels/voxels at which we observe imaging data.
- $let \mathcal{Y} = \{g : \mathcal{V} \to \{0, 1\}\}$
- Suppose that we observe a calibration dataset  $(X_i, Y_i)_{i=1}^n$  of random images, where  $X_i : \mathcal{V} \to \mathbb{R}$  represents the *i*th observed calibration image and  $Y_i : \mathcal{V} \to \{0, 1\}$  outputs labels at each  $v \in \mathcal{V}$ giving 1s at the true location of the objects in the image  $X_i$  that we wish to identify and 0s elsewhere.
- Given a function  $f : \mathcal{X} \to \mathcal{X}$ , we shall write f(X, v) to denote f(X)(v) for all  $v \in \mathcal{V}$ .

## FURTHER NOTATION

- Let  $s: \mathcal{X} \to \mathcal{X}$  be a score function such that given an image pair  $(X, Y) \in \mathcal{X} \times \mathcal{Y}, s(X)$  is a score image in which s(X, v) is intended to be higher at the  $v \in \mathcal{V}$  for which Y(v) = 1.
- 2 The score function can for instance be the logit scores obtained from a deep neural network image segmentation method to the image X.
- **③** Given  $X \in \mathcal{X}$ , let  $\hat{M}(X) \in \mathcal{Y}$  be the predicted mask.

• Let  $\mathcal{P}(\mathcal{V})$  be the set of subsets of  $\mathcal{V}$ .

## **CONFIDENCE SETS**

In what follows we will use the calibration dataset to construct a confidence functions  $I, O : \mathcal{X} \to \mathcal{P}(\mathcal{V})$  such that for a new image pair  $(X, Y) \sim \mathcal{D}$ , given error rates  $\alpha_1, \alpha_2 \in (0, 1)$  we have

$$\mathbb{P}\left(I(X) \subseteq \{v \in \mathcal{V} : Y(v) = 1\}\right) \ge 1 - \alpha_1,\tag{1}$$

(2)

and  $\mathbb{P}(\{v \in \mathcal{V} : Y(v) = 1\} \subseteq O(X)) \ge 1 - \alpha_2.$ 

# THRESHOLDING BASED ON THE NEURAL NETWORK SCORES



#### **ASSUMPTIONS FOR VALID INFERENCE**

Assumption 1. Given a new random image pair,  $(X_{n+1}, Y_{n+1})$ , suppose that  $(X_i, Y_i)_{i=1}^{n+1}$  is an exchangeable sequence of random image pairs in the sense that

 $\{(X_1, Y_1), \dots, (X_{n+1}, Y_{n+1})\} =_d \{(X_{\sigma(1)}, Y_{\sigma(1)}), \dots, (X_{\sigma(n+1)}, Y_{\sigma(n+1)})\}$ 

for any permutation  $\sigma \in S_{n+1}$ . Here  $=_d$  denotes equality in distribution and  $S_{n+1}$  is the group of permutations of the integers  $\{1, \ldots, n+1\}$ .

Assumption 2. (Independence of scores)  $(X_i, Y_i)_{i=1}^{n+1}$  is independent of the functions  $s, f_O, f_I$ .

## SCORE TRANSFORMATIONS $f_I, f_O : \mathcal{X} \to \mathcal{X}$



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#### MARGINAL INNER SET

$$\tau_i = \max_{v \in \mathcal{V}: Y_i(v) = 0} f_I(s(X_i), v)$$

**Theorem 2.1.** (Marginal inner set) Under Assumptions 1 and 2 given  $\alpha_1 \in (0, 1)$ , let

$$\lambda_I(\alpha_1) = \inf\left\{\lambda : \frac{1}{n} \sum_{i=1}^n \mathbb{1}\left[\tau_i \le \lambda\right] \ge \frac{\left\lceil (1 - \alpha_1)(n+1) \right\rceil}{n}\right\}$$

and define  $I(X) = \{v \in \mathcal{V} : f_I(s(X), v) > \lambda_I(\alpha_2)\}$ . Then,

 $\mathbb{P}\left(I(X_{n+1}) \subseteq \{v \in \mathcal{V} : Y_{n+1}(v) = 1\}\right) \ge 1 - \alpha_1.$ 

#### MARGINAL OUTER SET

$$\gamma_i = \max_{v \in \mathcal{V}: Y_i(v)=1} - f_O(s(X_i), v)$$

**Theorem 2.2.** (Marginal outer set) Under Assumptions 1 and 2 given  $\alpha_2 \in (0, 1)$ , let

$$\lambda_O(\alpha_2) = \inf\left\{\lambda : \frac{1}{n} \sum_{i=1}^n \mathbb{1}\left[\gamma_i \le \lambda\right] \ge \frac{\left\lceil (1 - \alpha_2)(n+1) \right\rceil}{n}\right\}$$

and define  $O(X) = \{v \in \mathcal{V} : f_O(-s(X), v) \leq \lambda_O(\alpha_2)\}$ . Then,  $\mathbb{P}(\{v \in \mathcal{V} : Y_{n+1}(v) = 1\} \subseteq O(X_{n+1})) \geq 1 - \alpha_2.$ 

## DISTANCE TRANSFORMED SCORES

#### Distance transformation:

$$d_{\rho}(\mathcal{A}, v) = \operatorname{sign}(\mathcal{A}, v) \min\{\rho(v, e) : e \in E(\mathcal{A})\},\$$

Distance transformed scores:

$$f_I(s(X), v) = f_O(s(X), v) = d_\rho(\hat{M}(X), v)$$

## APPLICATION TO POLYPS DATA

- We have 1798 polyps images (from different subjects)
- We divide these into a learning dataset of 298 and use the rest for inference
- Other existing approaches use the untransformed scores instead of learning the best approach.







## STUDYING THE LEARNING DATA



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#### OHISTOGRAMS OF THE SCORES ON THE LEARNING DATA



## PREPARING FOR THE CALIBRATION/VALIDATION

- From the learning data we can see that mixing the original and distance based score functions appears to the best combination.
- For our results we can then divide the remaining 1500 images into a calibration set of 1000 and a validation set of 500 images. And visualize the results.





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VERIFYING THE COVERAGE RATE



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#### HISTOGRAM OF THE COVERAGE AT 90%



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#### UNDERSTANDING THE EFFICIENCY



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#### DETERMINING THE PROPORTION CAPTURED



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### CONCLUSIONS

- Conformal inference provides uncertainty guarantees for neural networks
- Transforming the scores (with transformations chosen on a learning dataset can lead to a big boost in performance).
- Conformal confidence sets provide strong guarantees whilst allowing for meaningful inference.
- Preprint available: Davenport, Samuel. "Conformal confidence sets for biomedical image segmentation." arXiv preprint arXiv:2410.03406 (2024).

# ADVANTAGE OF THE DISTANCE TRANSFORMED SCORES

Using distance transformed scores ensure that as the predicted masks improve the confidence sets improve – not true for using the original scores

**Theorem 2.8.** For each  $v \in V$ , let  $f_O(s(X), v) = d_\rho(\hat{M}(X), v)$  and define O(X) as in Section [2.2]. Suppose that  $H_\rho(\hat{M}(X_i), Y_i) \leq k$ , some  $k \in \mathbb{R}$ , for all  $i \in J$ , for some  $J \subseteq \{1, \ldots, n\}$  such that  $\frac{|J|}{n} > 1 - \alpha_2$ . Then  $H_\rho(\hat{M}(X_{n+1}), O(X_{n+1})) \leq k$ . In particular if  $H_\rho(\hat{M}(X_{n+1}), Y_{n+1}) \leq k$ , then it follows that  $H_\rho(O(X_{n+1}), Y_{n+1}) \leq 2k$ .





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## EXISTING APPROACHES FOCUS ON BOUNDING BOXES



## JOINT INFERENCE

**Corollary 2.5.** (Joint from marginal) Assume Assumptions I and 2 hold and given  $\alpha \in (0, 1)$  and  $\alpha_1, \alpha_2 \in (0, 1)$  such that  $\alpha_1 + \alpha_2 \leq \alpha$ , define I(X) and O(X) as in Theorems 2.1 and 2.2. Then  $\mathbb{P}\left(I(X_{n+1}) \subseteq \{v \in \mathcal{V} : Y_{n+1}(v) = 1\} \subseteq O(X_{n+1})\right) \geq \frac{\left[(1 - \alpha)(n+1)\right]}{n}.$ (5)

#### A.6.5 JOINT 90% CONFIDENCE REGIONS



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#### A.6.6 MARGINAL 80 % CONFIDENCE REGIONS



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#### A.6.7 MARGINAL 95 % CONFIDENCE REGIONS



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