

Optimal transport and its (semi-)discretization

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Outline

- 1 Introduction: the JKO scheme
- 2 Continuous optimal transport
- 3 Semidiscrete optimal transport
- 4 An illustration: moving meshes

Lagrangian Formulation of (Some) PDEs

- ▶ We follow the evolution of a population of particles living in \mathbb{R}^d , described by its initial distribution $\rho_0 \in \mathcal{P}(\Omega)$ and by its **displacement**

$$X : [0, T] \rightarrow L^2(\rho_0, \mathbb{R}^d).$$

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- ▶ **Main assumption:** The energy E only depends on the distribution of particles.

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- ▶ Example of energies:

$$\mathcal{E}_{\text{ent}}(\rho) = \begin{cases} \int \rho \log \rho & \text{if } \rho \in \mathcal{P}_2^{\text{ac}}(\Omega), \\ +\infty & \text{otherwise.} \end{cases}$$

$$\mathcal{E}_{\text{inc}}(\rho) = \begin{cases} 0 & \text{if } \rho = \text{Leb}_\Omega, \\ +\infty & \text{otherwise.} \end{cases}$$

$$\mathcal{E}_{\text{cong}}(\rho) = \begin{cases} 0 & \text{if } \rho \leq \text{Leb}_\Omega, \\ +\infty & \text{otherwise.} \end{cases}$$

$$\mathcal{E}_{\text{pot}}(\rho) = \int V d\rho.$$

Lagrangian-Eulerian dictionary

	$\dot{X} \in -\partial E(X)$	$\ddot{X} \in -\partial E(X)$
\mathcal{E}_{inc}		incompressible Euler equation
$\mathcal{E}_{\text{cong}} + \mathcal{E}_{\text{pot}}$	crowd motion	pressureless Euler equation
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- ▶ *Many* mathematicians have studied connections between OT and evolution PDEs.
- ▶ The energy E is typically non-convex, with values in $\mathbb{R} \cup \{+\infty\}$: in this introduction we will remain at a very formal level.

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- ▶ We consider $\mathcal{E}(\rho) = \int f(\rho) + \rho V$ and $E(X) = \mathcal{E}(X \# \rho_0)$ with $X \in L^2(\rho_0, \mathbb{R}^d)$

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- ▶ **What is the gradient of E ?** Consider a curve X_t satisfying $\dot{X}_t = v_t(X_t)$ and its image density $\rho_t := X_t\#\rho_0$, which satisfies $\dot{\rho}_t + \operatorname{div}(\rho_t v_t) = 0$.

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- ▶ **Regular** lagrangian trajectory associated to heat flow (\neq Brownian motion!)

From Lagrangian dynamic to the JKO scheme

- **Minimizing movement scheme:** for $\tau > 0$, define a time-discretization by

$$X_\tau^{k+1} \in \arg \min_X \frac{1}{2\tau} \|X_\tau^k - X\|_{L^2(\rho_0)}^2 + E(X)$$

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- We recover the JKO scheme: $\rho_\tau^{k+1} \in \arg \min_\rho \frac{1}{2\tau} W_2^2(\rho_\tau^k, \rho) + \mathcal{E}(\rho)$.

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Optimal transport

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Wasserstein distance between $\mu, \nu \in \mathcal{P}_p(\mathbb{R}^d)$:

$$W_p(\mu, \nu) = \left(\min_{\gamma \in \Gamma(\mu, \nu)} \int \|x - y\|^p d\gamma(x, y) \right)^{1/p},$$

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- ▶ Optimal transport and Wasserstein distances W_p have found applications in geometry, functional inequalities, probabilities, PDEs, statistical learning.

1D Wasserstein space and quantiles

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$$\mu = \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{x_i} \text{ with } x_1 \leq \dots \leq x_N \implies T_\mu = x_i \text{ on } \left[\frac{i-1}{N}, \frac{i}{N} \right]$$

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$$W_p^p(\mu, \nu) = \frac{1}{N} \sum_{1 \leq i \leq N} \|x_i - y_i\|^p = \|T_\mu - T_\nu\|_{L^p([0,1])}^p.$$



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$$\mu = \frac{1}{N} \sum_{1 \leq i \leq N} \delta_{x_i} \text{ with } x_1 \leq \dots \leq x_N \implies T_\mu = x_i \text{ on } \left[\frac{i-1}{N}, \frac{i}{N} \right]$$

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$$W_p^p(\mu, \nu) = \frac{1}{N} \sum_{1 \leq i \leq N} \|x_i - y_i\|^p = \|T_\mu - T_\nu\|_{L^p([0,1])}^p.$$



- ▶ The above formula remains true for any probability measures $\mu, \nu \in \mathcal{P}(\mathbb{R})$, i.e.

Theorem: $\mu \mapsto T_\mu$ is an isometry: $W_p^p(\mu, \nu) = \|T_\mu - T_\nu\|_{L^2(\lambda)}^p$.

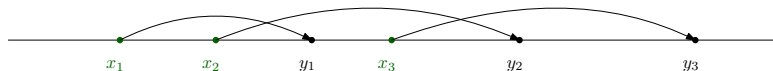
1D Wasserstein space and quantiles

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- ▶ When μ is a density and $\nu = \sum_{i=1}^N \alpha_i \delta_{y_i}$, the optimal transport plan induces a partition (a mesh?) of $\text{spt}(\mu)$ into intervals $(V_i)_{1 \leq i \leq N}$ with $\mu(V_i) = \alpha_i$.

Wasserstein geodesics

Proposition: Let $\mu_0, \mu_1 \in \mathcal{P}_2(\mathbb{R}^d)$, and let $\gamma \in \Gamma_{\text{opt}}(\mu_0, \mu_1)$. Then, the *curve*

$$\mu_t = \Pi_{t\#}\gamma, \text{ with } \Pi_t(x, y) = (1 - t)x + ty$$

is a minimizing geodesic between μ_0 and μ_1 .

Wasserstein geodesics

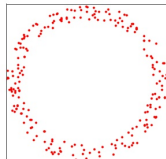
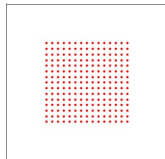
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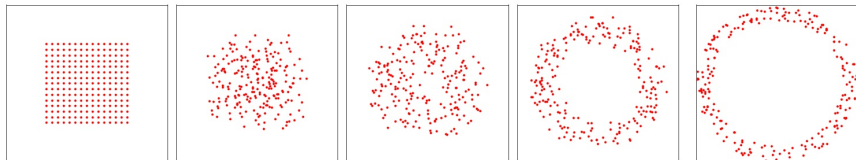
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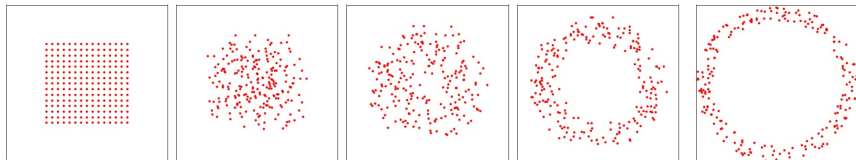
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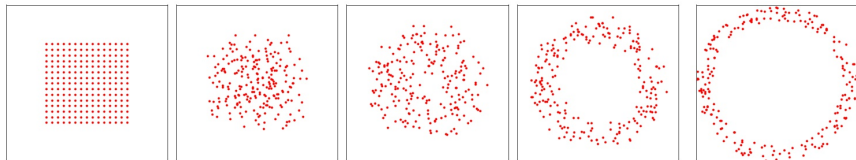
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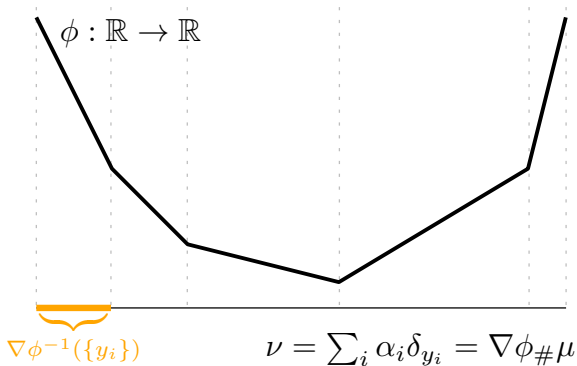


- ▶ All minimizing geodesics are of this form.
- ▶ There may exist **uncountably many geodesics**, e.g. if $\text{spt}(\mu_0) \subseteq \mathbb{R} \times \{0\}$ and $\text{spt}(\mu_1) \subseteq \{0\} \times \mathbb{R}$ on \mathbb{R}^2 , any $\gamma \in \Gamma(\mu_0, \mu_1)$ is optimal!

Characterization of quadratic optimal transport

Theorem (Brenier) Let $\mu, \nu \in \mathcal{P}_2(\mathbb{R}^d)$ with $\mu \ll \text{Leb}$. Then

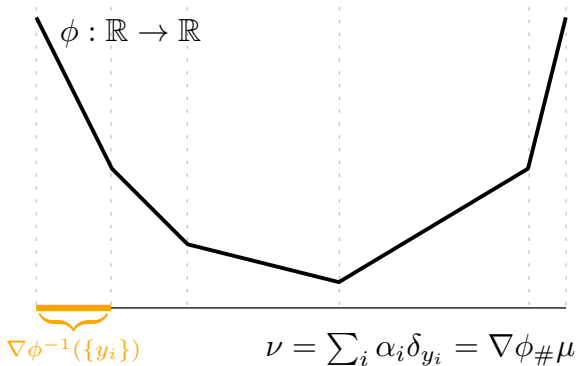
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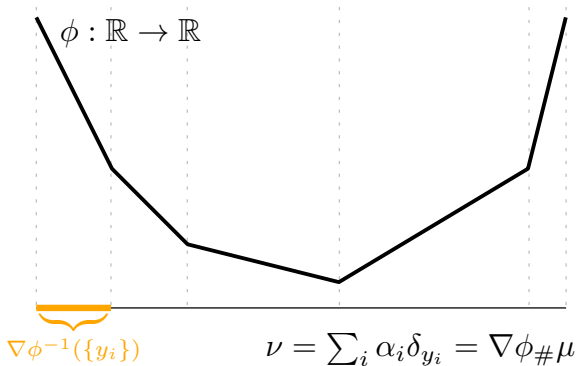
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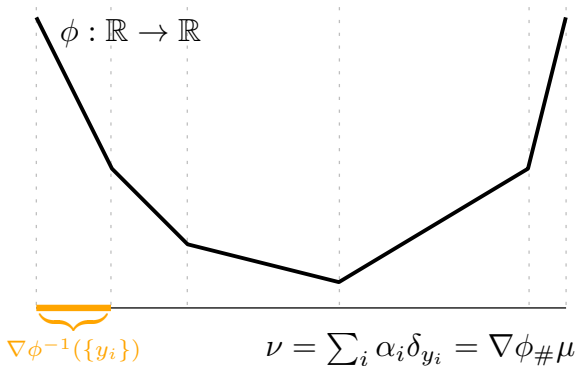
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Proof relies on the dual problem to optimal transport, due to Kantorovich.

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- ▶ Quadratic optimal transport is equivalent to the maximal correlation problem:

$$\min_{\gamma \in \Gamma(\mu, \nu)} \int \|x - y\|^2 d\gamma(x, y) = M_2(\mu) + M_2(\nu) - 2 \max_{\gamma \in \Gamma(\mu, \nu)} \int \langle x | y \rangle d\gamma(x, y).$$

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Def: We will call **Kantorovich functional** $\mathcal{K}_\mu(\psi) = \int \psi^* d\mu$, where ψ^* denotes the convex conjugate of ψ , i.e. $\psi^*(x) = \max_{y \in Y} \langle x|y \rangle - \psi(y)$

- ▶ Maximum correlation problem \longleftrightarrow unconstrained convex minimization problem:

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► The Monge-Ampère operator is linearized (in $\phi = \psi^*$!) into :

$$\det(D^2(\phi + \nu)) \simeq \det(D^2 \phi) (1 + \text{Tr}(D^2 \phi^{-1} D^2 \nu))$$

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- For $\mu \equiv 1$, a Newton method for minimizing $\mathcal{K}(\cdot) + \langle v|\cdot \rangle$ at ψ will involve the linear operator $\tilde{v} \mapsto \text{div}((D^2\psi^*)^{-1}\nabla\tilde{v})$

Outline

- 1 Introduction: the JKO scheme
- 2 Continuous optimal transport
- 3 Semidiscrete optimal transport**
- 4 An illustration: moving meshes

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Then, $\psi^* = \max_i \langle \cdot | y_i \rangle - \psi_i$ is affine on each **power (or Laguerre) cell**

$$V_i(\Psi) = \{x \in \mathbb{R}^d \mid \forall j, \langle x | y_i \rangle - \psi_i \geq \langle x | y_j \rangle - \psi_j\}.$$

Kantorovich functional and computational geometry

Kantorovich functional: $\mathcal{K}_\mu(\psi) = \int \psi^* d\mu$, where ψ^* is the convex conjugate of ψ

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- ▶ In general, y_i does **NOT** belong to its Laguerre cell $V_i(\Psi)$.

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Theorem Finding an *optimal transport* between a probability density μ on \mathbb{R}^d and $\nu = \sum_i \alpha_i \delta_{y_i}$ amounts to maximizing $\Psi \in \mathbb{R}^N \mapsto \mathcal{K}_\mu(\Psi) + \sum_i \alpha_i \Psi_i$, where

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Moreover, Ψ is \mathcal{C}^1 and $\partial_{y_i} \mathcal{K}_\mu(\Psi) = -\mu(V_i(\Psi))$. [Aurenhammer, Hoffman, Aronov]

$\nabla \mathcal{K}(\Psi)$ is consistent with continuous case: $\nabla \mathcal{K}(\psi) = -\nabla \psi^*_{\#} \mu = \sum_i \mu(V_i(\Psi)) \delta_{y_i}$.

Optimal transport and mass-constrained power diagrams

Theorem Finding an *optimal transport* between a probability density μ on \mathbb{R}^d and $\nu = \sum_i \alpha_i \delta_{y_i}$ amounts to maximizing $\Psi \in \mathbb{R}^N \mapsto K_\mu(\Psi) + \sum_i \alpha_i \Psi_i$, where

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demo

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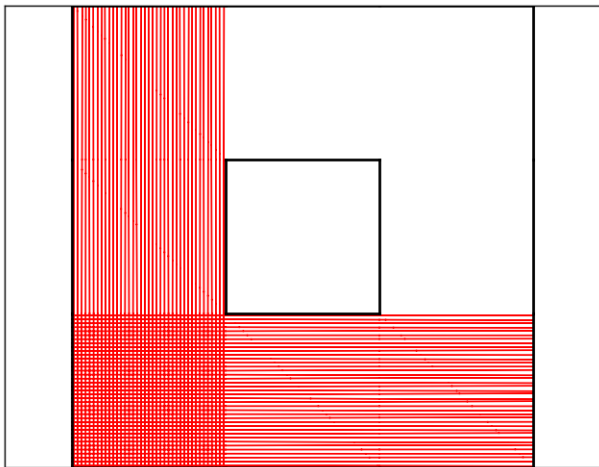
demo

► Computing $DG(\Psi)$ is as costly as computing $G \rightsquigarrow$ Newton's method

$$\Psi^{k+1} = \Psi^k - DG(\Psi^k)^{-1}(G(\Psi^k) - \nu).$$

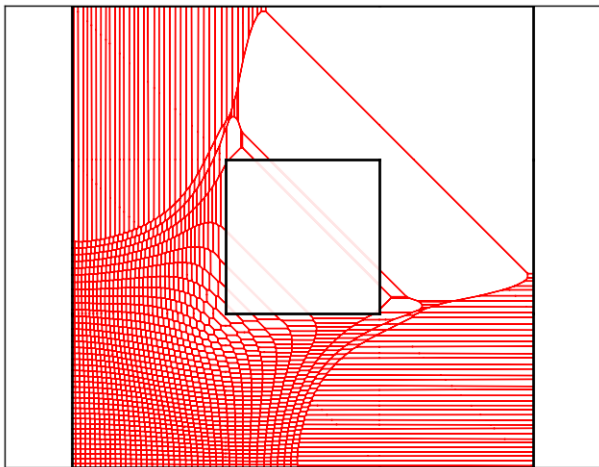
Difficulty: $DG(\Psi^k)$ is in general not invertible \rightsquigarrow damping.

Numerical example: Newton iterations



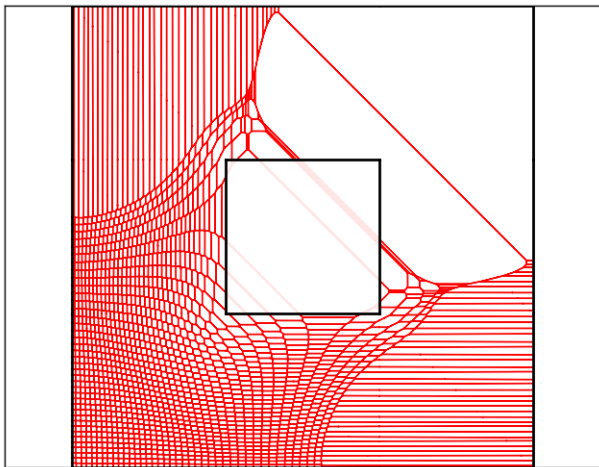
Source: Piecewise linear density on $X = [0, 3]^2$ / **Target:** Uniform grid in $[0, 1]^2$.

Numerical example: Newton iterations



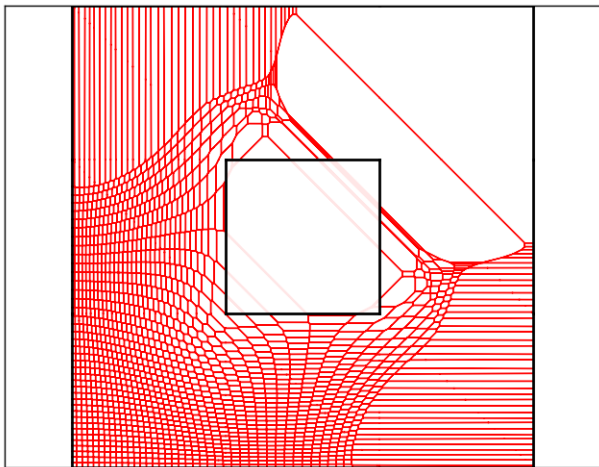
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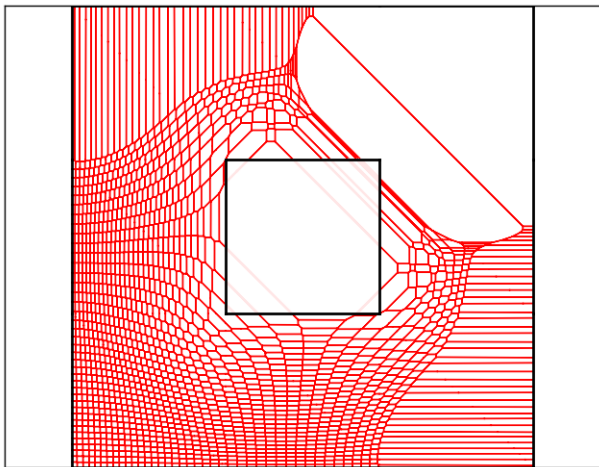
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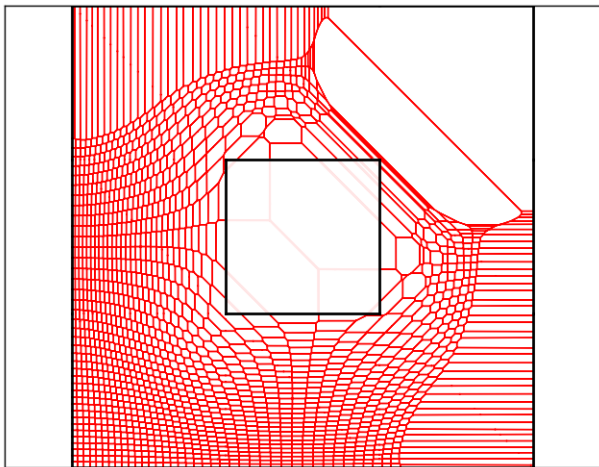
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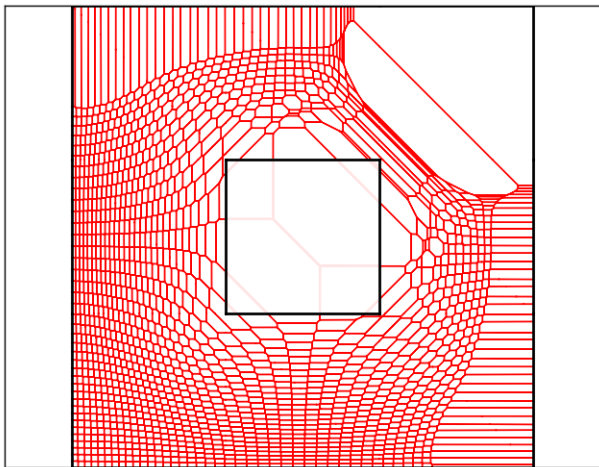
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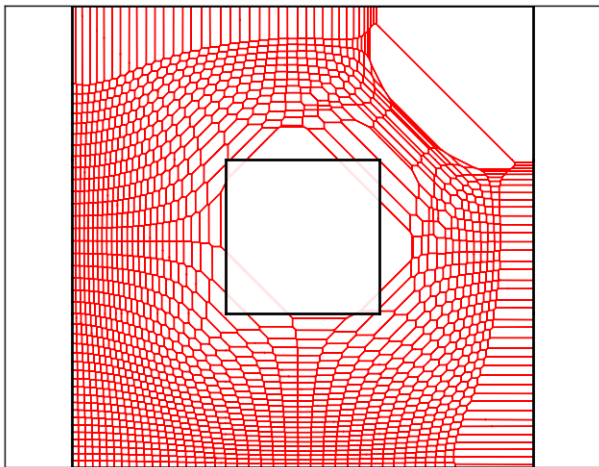
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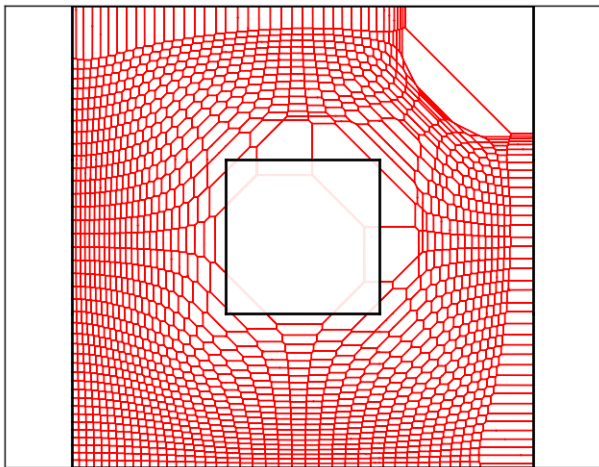
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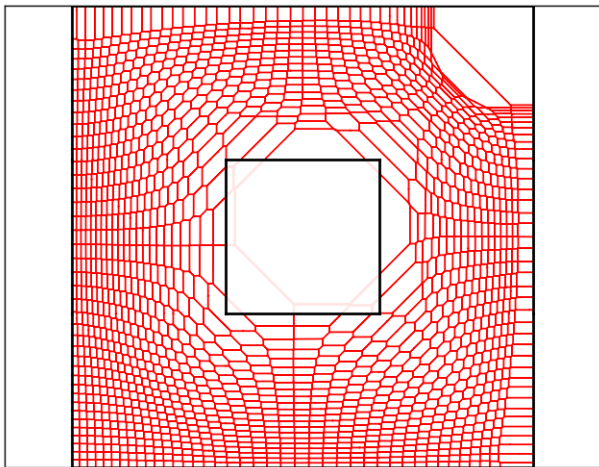
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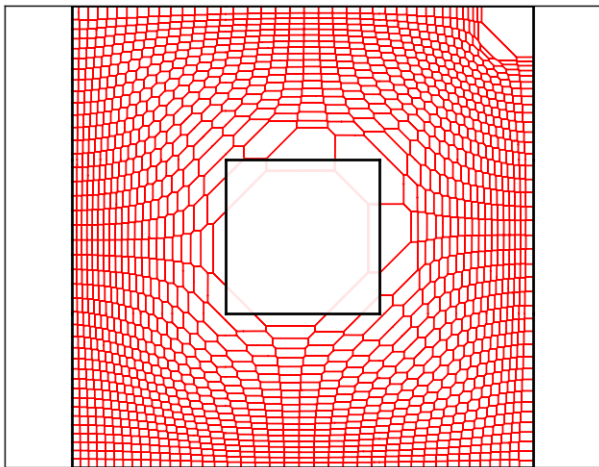
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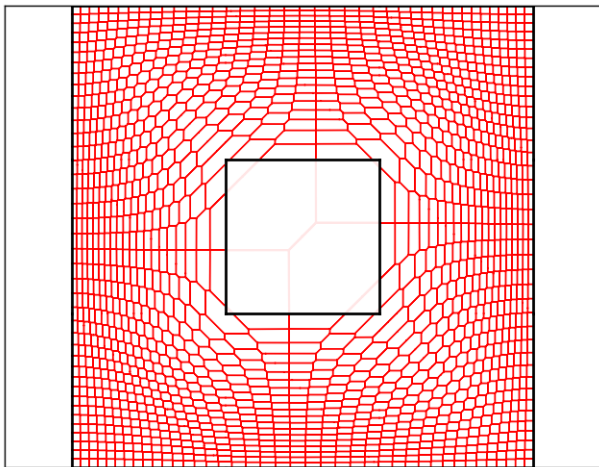
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Newton's method for semi-discrete OT is able to handle huge problems in 2D/3D, up to $N \sim 10^8$ in 3D. See e.g. Geogram (Bruno Lévy) or SDOT (Hugo Leclerc).

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Denote $G(\Psi) = -\nabla\mathcal{K}(\Psi) = (\mu(V_i(\Psi)))_{1 \leq i \leq N}$.

Prop.: Assume $\mu \in \mathcal{C}^0(X)$, X convex and $\Psi \in \mathbb{R}^N$ is such that $\forall i, G_i(\Psi) > 0$. Then,

$$\begin{aligned} \forall i \neq j, \quad \frac{\partial G_i}{\partial \psi_j}(\Psi) &= \frac{1}{\|y_i - y_j\|} \int_{\Gamma_{ij}(\psi)} \rho(x) d\mathcal{H}^{d-1}(x) && \left[= -\frac{\partial^2 \mathcal{K}}{\partial \psi_j \psi_i}(\Psi) \right] \\ \forall i, \quad \frac{\partial G_i}{\partial \psi_i}(\Psi) &= -\sum_{j \neq i} \frac{\partial G_i}{\partial \psi_j}(\Psi) && \left[= -\frac{\partial^2 \mathcal{K}}{\partial \psi_i^2}(\Psi) \right] \end{aligned}$$

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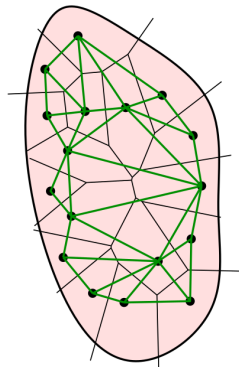
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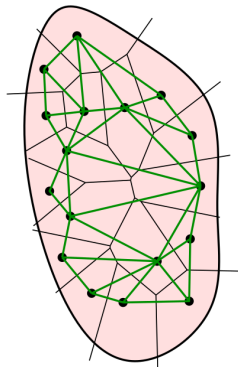
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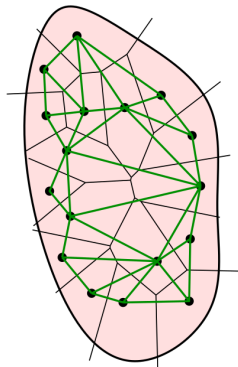
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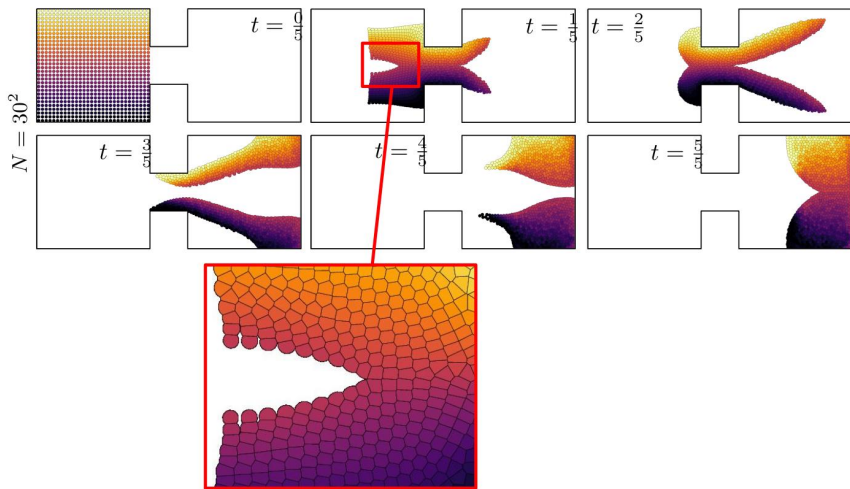
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- ▶ Finite-volume discretization of $\tilde{v} \mapsto \text{div}((D^2\psi^*)^{-1}\nabla\tilde{v})$?

Outline

- 1 Introduction: the JKO scheme
- 2 Continuous optimal transport
- 3 Semidiscrete optimal transport
- 4 An illustration: moving meshes**

Crowd motion



- ▶ Macroscopic crowd motion model [Maury, Roudneff-Chupin, Santambrogio]
- ▶ Particle discretization relies on a Moreau-Yosida regularization of the Lagrangian energy $\mathcal{E}_{\text{cong}}$ (\rightsquigarrow partial optimal transport) [M., Santambrogio, Stra]
- ▶ By OT, a moving mesh is automatically associated to the moving particle cloud!

Summary/questions

- ▶ OT can be used to interpret/reformulate some PDEs from fluid mechanics.
- ▶ This leads to new Eulerian numerical schemes (which will be the main object of this workshop), but also to Lagrangian (particle) discretization of evolution PDE.

<https://github.com/sd-ot>

<https://github.com/BrunoLevy/geogram>

- ▶ Can OT be useful to construct (moving) meshes for finite volumes ?