

# Recent Algorithmic Advances in Topological Data Analysis

**Michael Kerber**

Gudhi workshop, Porquerolles, France, Oct 19, 2016

# Computational Topology@TU Graz



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## Our mission

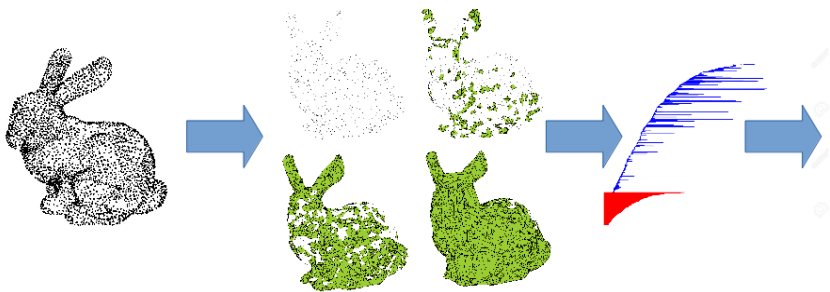
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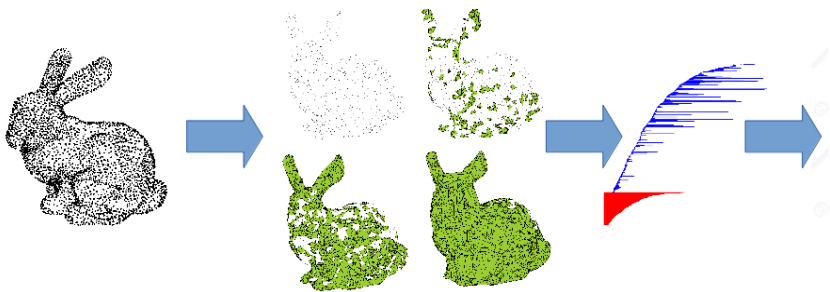
Algorithmic foundations, implementations, and  
software in computational topology and geometry.

# The algorithmic pipeline



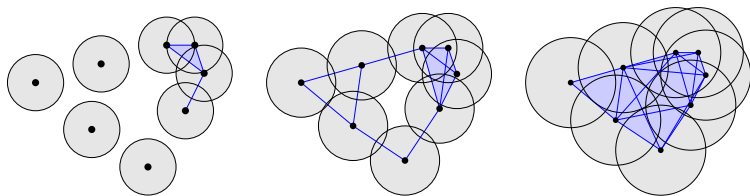
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2. Compute topological invariants
3. Draw conclusions about the input

# The algorithmic pipeline



1. **Turn input into multi-scale representation**
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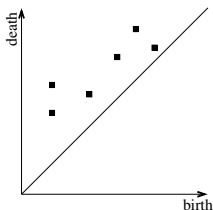
# Čech filtrations



- Nested sequence of simplicial complexes
- Important in topological data analysis
- Vietoris-Rips complexes: Closely related
- **Problem:** Size of  $k$ -skeleton is  $\binom{n}{k+1} = O(n^{k+1})$

# Topological approximation

Persistence diagram of the Čech filtration:

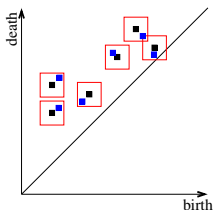


**Question:** Can we find a small filtration whose persistence diagram is provably close to the Čech diagram?



# Topological approximation

Persistence diagram of the Čech filtration:



**Question:** Can we find a small filtration whose persistence diagram is provably close to the Čech diagram?

## Previous work

- Sparse Rips complex [Sheehy 2012]
- $(1 + \varepsilon)$ -approximation of size

$$n \cdot \left(\frac{1}{\varepsilon}\right)^{O(\Delta k)}$$

with  $\Delta$  the doubling dimension of the point set

- Various related approaches [Dey, Fan, Wang 2012]  
[K., Sharathkumar 2013] [Botnan, Spreemann 2015]  
[Buchet et al. 2015] [Cavanna, Jahanseir, Sheehy 2015]

# Our contributions [\[Choudhary,K.,Raghvendra, SoCG 2016\]](#)

- $6(d + 1)$ -approximation of size

$$n \cdot 2^{O(d \log k)}$$

per scale for  $n$  points in  $\mathbb{R}^d$ .

# Our contributions [\[Choudhary,K.,Raghvendra, SoCG 2016\]](#)

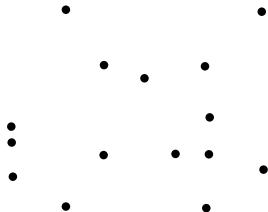
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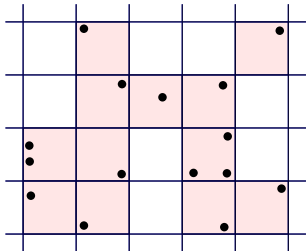
per scale for  $n$  points in  $\mathbb{R}^d$ .

- Combined with dimension reduction:  
 $O(\log^{3/2} n)$ -approximation of size  $n^{O(1)}$ .

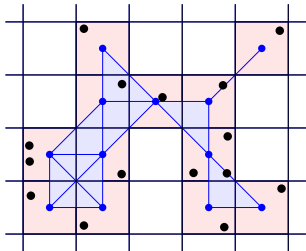
# Approximation by lattices I



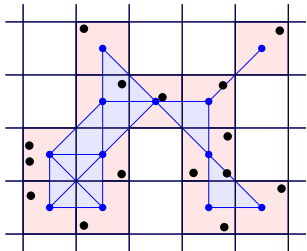
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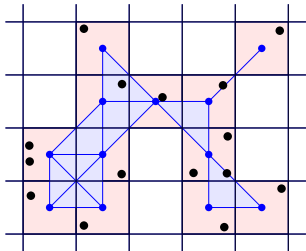


- Diameter of a cell:  $\alpha \cdot \sqrt{d}$
- Two non-adjacent cells are at least  $\alpha$  apart

$\Rightarrow \sqrt{d}$ -approximation!



# Approximation by lattices I

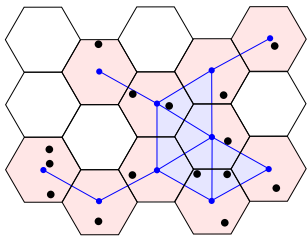


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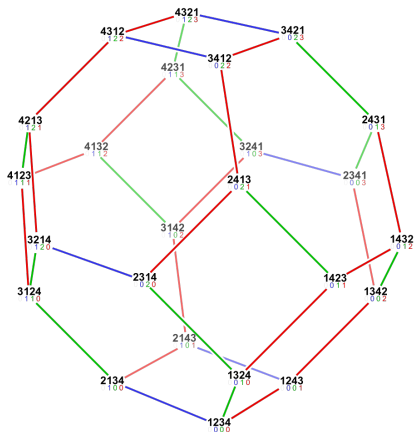
But highly degenerate:  $2^d$   
cells intersect in a point  
(leads to size  $n \cdot 2^{O(dk)}$ )

## Approximation by lattices II



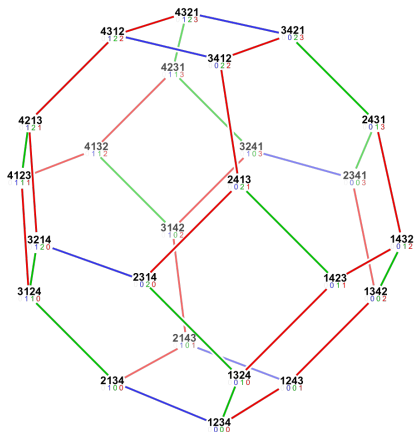
- Hexagonal grid
- How to generalize in higher dimensions?

# The permutahedron



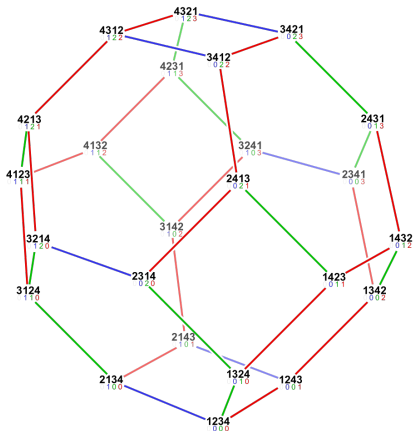
- Voronoi region of  $A_d^*$ -lattice

# The permutahedron



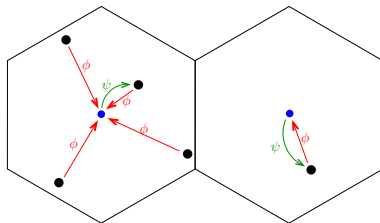
- Voronoi region of  $A_d^*$ -lattice
- Diameter:  $O(\alpha \cdot \sqrt{d})$
- Lemma: Non-intersecting cells are at least  $\alpha \cdot \sqrt{2}/(d+1)$  apart.

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- Diameter:  $O(\alpha \cdot \sqrt{d})$
- Lemma: Non-intersecting cells are at least  $\alpha \cdot \sqrt{2}/(d+1)$  apart.
- Size of the dual  $k$ -skeleton:  $n2^{O(d \log k)}$

# Interleaving



$$\begin{array}{ccccccc}
 \dots & \longrightarrow & \mathcal{R}_{\beta 2(d+1)} & \xrightarrow{g} & \mathcal{R}_{\beta 8(d+1)^3} & \longrightarrow & \dots \\
 & & \nearrow \psi & & \searrow \psi & & \\
 \dots & \longrightarrow & X_{\beta} & \xrightarrow{\theta} & X_{\beta 4(d+1)^2} & \longrightarrow & \dots \\
 & & & & \nearrow \psi & & 
 \end{array}$$

# The Johnson-Lindenstrauss Lemma

For a point set  $S \subset \mathbb{R}^d$  of  $n$  points and  $0 < \varepsilon < 1$ , there is a map

$$f : \mathbb{R}^d \rightarrow \mathbb{R}^m$$

with  $m = O\left(\frac{\log n}{\varepsilon^2}\right)$  such that for any two points  $s, t \in S$ :

$$(1 - \varepsilon)\|s - t\| \leq \|f(s) - f(t)\| \leq (1 + \varepsilon)\|s - t\|.$$

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Moreover, a random (scaled) projection from  $\mathbb{R}^d$  to  $\mathbb{R}^m$  has that property with a probability of at least  $\frac{1}{2}$ .



# Dimension reduction

- Size per scale  $n \cdot 2^{O(d \log k)}$
- [Johnson, Lindenstrauss 1984]:  $d \approx \log n$  (constant distortion)  
⇒ size  $n^{O(\log k)}$ , total distortion  $O(\log n)$

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 $\Rightarrow$  size  $n^{O(1)}$ , total distortion  $O(\log^2 n)$
- [Bourgain 1985]: General metric space: Embed to  $O(\log^2 n)$  dimensions with distortion  $O(\log n)$   
 $\Rightarrow$  size  $n^{O(1)}$  and total distortion  $O(\log^3 n)$

# Our contributions [\[Choudhary,K.,Raghvendra, SoCG 2016\]](#)

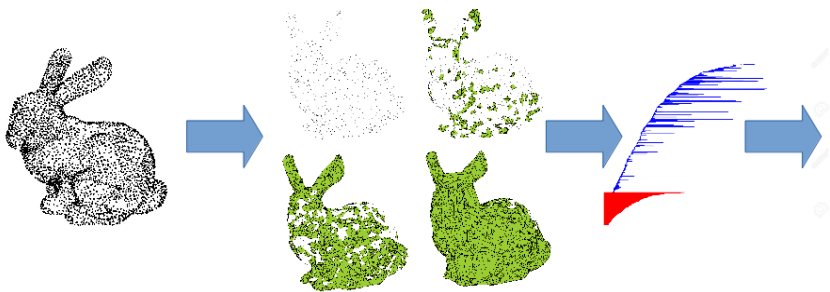
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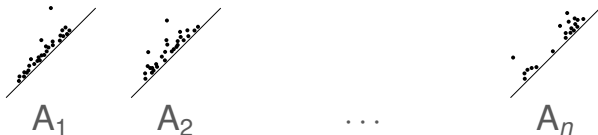
- Combined with dimension reduction:  
 $O(\log^{3/2} n)$ -approximation of size  $n^{O(1)}$ .
- Lower bound: Any  $(1 + \delta)$ -approximation scheme has to be of size  $n^{\Omega(\log \log n)}$  if  $\delta < \frac{1}{96 \log^{1.001} n}$ .

# The algorithmic pipeline



1. **Turn input into multi-scale representation**
2. Compute topological invariants
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# Distances between persistence diagrams

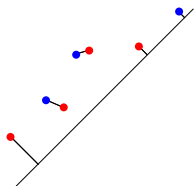


	$A_1$	$A_2$	...	$A_{n-1}$	$A_n$
$A_1$					
$A_2$					
$\vdots$					
$A_{n-1}$					
$A_n$					

$d(A_i, A_j)$

- $n$  diagrams  $\Rightarrow \binom{n}{2}$  distances
- Often the computational bottleneck

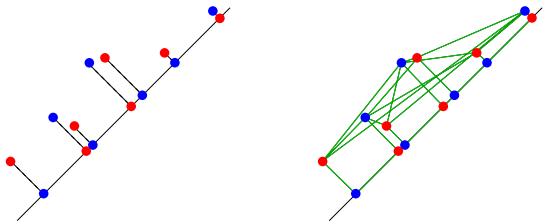
# Distance measures



- One-to-one pairing of points
- Every point must be paired
- Pairing with diagonal allowed

- Cost of a pair  $(p, q)$ :  $\|p - q\|_\infty$
- **Bottleneck distance**: Minimize maximal cost
- **1-Wasserstein distance**: Minimize  $\Sigma$  of the costs
- Stability [Cohen-Steiner et al. 2007]
- Other distances

# From diagram distance to graph matching



- Weighted complete bipartite graph  $G$
- Weight of an edge:  $L_\infty$  distance of the points
- EXCEPT: weight is zero if both points are on diagonal
- Use graph matching algorithm (Hopcroft-Karp, Hungarian, . . .)



# Does geometry help?

- $G$  is “almost” metric (modulo diagonal)
- Asymptotically faster algorithms are known for this case
- [Efrat, Itai, Katz: Geometry Helps in Bottleneck Matching... 2001]
- [Vaidya: Geometry Helps in Matchings. 1989] (opt. assignment)
- Adaption to persistence diagrams straight-forward  
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## Answer

**Yes**, in theory

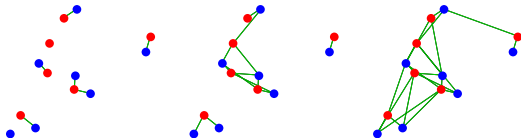
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## Our contribution

**Yes**, also in practice! [K., Morozov, Nigmatov, ALENEX 2016]

- We compare geometric and non-geometric implementations of bottleneck matchings and optimal assignment (for  $\mathbb{R}^2$ )
- We show experimentally that geometry improves performance
- We outperform Dionysus, the only publically available software for distances of persistence diagrams
- Our code is freely available:  
[https://bitbucket.org/grey\\_narn/hera](https://bitbucket.org/grey_narn/hera)

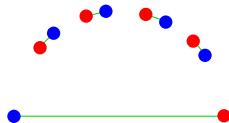
# The bottleneck case



- Let  $G[\alpha]$  be the graph  $G$  with all edges of weight  $> \alpha$  deleted
- Observation: If  $G[\alpha]$  has a perfect matching, the bottleneck distance is at most  $\alpha$ .

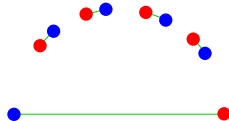
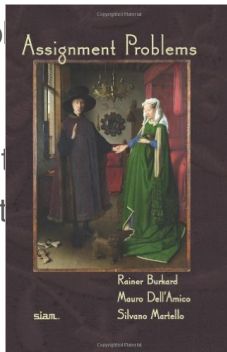
# The Wasserstein case

- Assignment problem: Find perfect matching with minimal sum of costs.
- Discrete optimal transport
- Hungarian algorithm



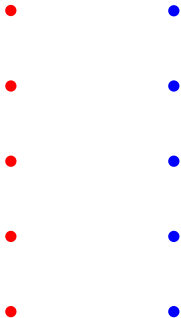
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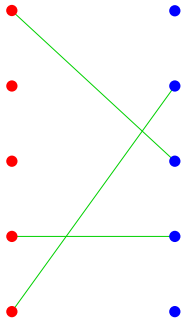
# The auction algorithm [\[Bertsekas 1988\]](#)

- $n$  bidders (left),  $n$  objects (right)



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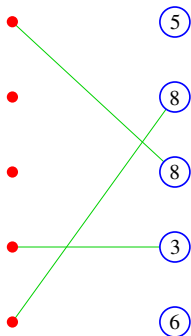
- $n$  bidders (left),  $n$  objects (right)
- Maintain (partial) matching





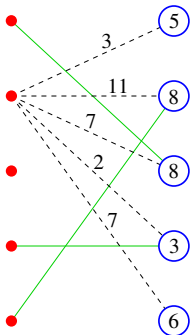
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- Objects have (global) **prices**



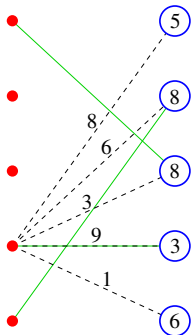
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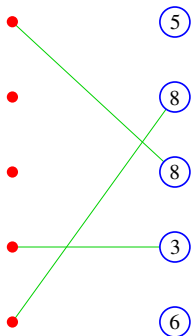
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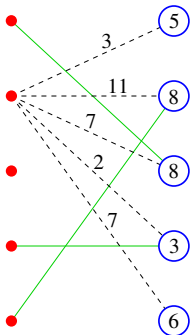


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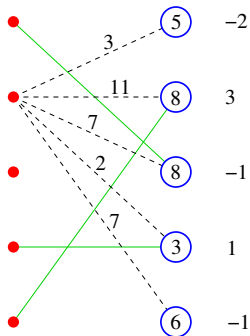


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- Value of object: appreciation - price

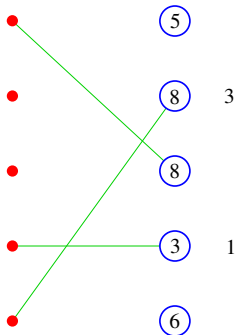


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Repeat:

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- Value of object: appreciation - price
- Pick best and 2nd-best valued objects

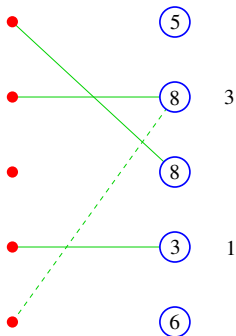


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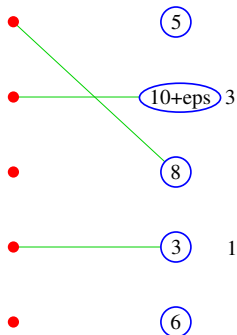
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- Assign bidder to best valued object





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Repeat:

- Pick an unassigned bidder
- Value of object: appreciation - price
- Pick best and 2nd-best valued objects
- Assign bidder to best valued object
- Increase price by difference of values, plus  $\varepsilon > 0$

# Why auction?

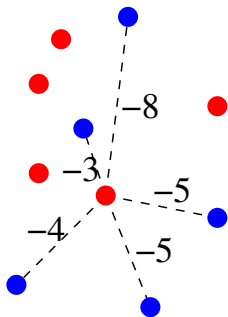
## Theorem [Bertsekas 1988]

Let  $\text{opt}$  denote the cost of the optimal assignment, and  $d$  the cost returned by the auction. Then

$$\text{opt} - n\varepsilon \leq d \leq \text{opt}$$

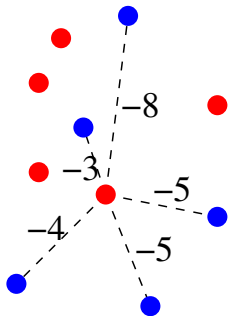
- Large  $\varepsilon$ : Fast, rough approximation
- Small  $\varepsilon$ : Slow, accurate approximation
- $\varepsilon$ -scaling [Bertsekas, Castanon 1991]
- Remark: Getting exact result possible, but very slow

## How geometry helps



- Appreciation = -distance to object
- Crucial query: Find the best and second best object for an unassigned bidder.

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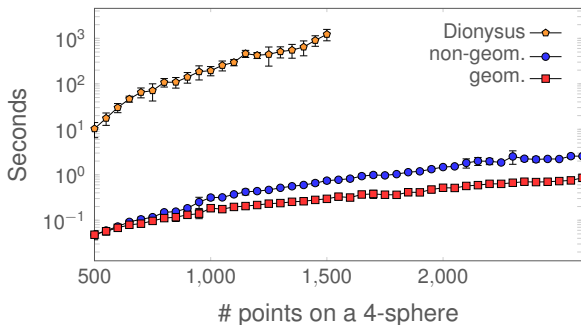


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### Our approach

- k-d-tree with weight per node
- Weight=minimal price
- Prune search in subtrees if better candidates are known

# Experimental comparison

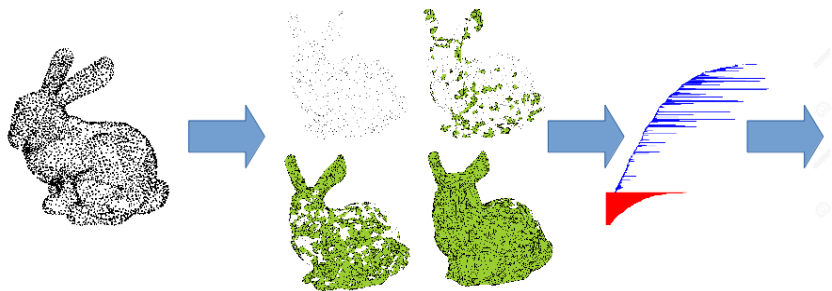


- Linear space (geometric) vs quadratic space (non-geometric)
- Exact distance (Dionysus) vs relative 1%-approximation

# The Hera library

- URL: [https://bitbucket.org/grey\\_narn/hera](https://bitbucket.org/grey_narn/hera)
- Code for bottleneck (LGPL) and Wasserstein (BSD)
- Supports  $q$ -Wasserstein distance and different choice of inner metric (instead of  $L_\infty$ )
- Download it! Use it! Tell us your experience!

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