### IQ-Means

#### **Evangelos Anagnostopoulos**

National and Kapodistrian University of Athens

March 31, 2017

3

-

• • • • • • • • • • • •

#### 1 Preliminaries

- Problem Definition
- Practical Information

### 2 IQ-Means

### 3 Dynamic IQ-Means

3

3

### **Problem Definition**

#### Definition (Clustering)

Given a set of objects partition them into disjoint sets such that objects within a group are more "similar" compared to those in other groups.

#### Definition (k-means Clustering)

Given a pointset  $X \subset \mathbb{R}^d$  of n points and a parameter k, find k point centers  $C^* = \{c_1, c_2, \ldots, c_k\} \subset \mathbb{R}^d$  such that the sum of squared distances of each point in X to its nearest center is minimized.

Objective function:

$$\min\sum_{x\in X}||x-c(x)||^2,$$

where  $c(x) \in C^*$  is the center closest to x.



Figure: A *k*-means clustering example. Notice how the cluster regions correspond to a a Voronoi diagram of the centroids.

## Base Algorithm (Lloyd's)

Input: X s.t. |X| = n, k, j optional Output:  $C^*$ 

- Initialize  $C^*$  to k points selected uniformly at random from X.
- Until convergence (or for *j* iterations)
  - Assignment step:

Assign each point to its nearest center

Update step:

Compute the mean  $\mu_i$  of each cluster *i*, and assign that as the new center  $c_i$ 

Complexity: O(nkd(j))

### Related work

#### • Approximate *k*-means

[Philbin et al. '07] Replace assignment step with approximate nearest neighbor (ANN) from points to centers.

#### • Binary k-means

[Gong et. al '15] Binarize points and centers, followed by ANN in Hamming space

#### Ranked Retrieval

[Broder et al. '14] ANN queries from centroids to points

### Related work cont.

• Dimensionality-Recursive Vector Quantization (DRVQ) [Avrithis '13] Centroids to point queries on a two-dimensional grid

#### • Expanding Gaussian Mixtures (EGM)

[Avrithis et al. '12] On the fly estimation of the number of clusters by a statistical approach.

#### Preliminaries

#### 2 IQ-Means

- Vector Quantization
- Algorithm
- Experiments

### 3 Dynamic IQ-Means

ም.

### **IQ-Means**

**Goal**: Web scale clustering (i.e. hundreds of millions of points into millions of clusters)

IQ-Means combined with powerful deep learned representations, achieves clustering of a 100 million image collection on a single machine in less than one hour.[Avrithis '15].

Compare to distributed k-means on 300 machines which takes 2.2 hours per iteration on average, i.e. one order of magnitude slower.

### IQ-Means idea

- Adopt subspace quantization from DRVQ.
- Modify search algorithm to imitate Ranked Retrieval's approach.
- Estimate k dynamically by purging clusters, as in EGM.



Figure: Different k-means variants.

### Vector Quantization

Given a pointset  $X \subset \mathbb{R}^d$ , where |X| = n and assuming that d is even:

#### Dimension Decomposition

 $\mathbb{R}^d$  is expressed as the Cartesian product of two orthogonal subspaces  $S^1, S^2$ . In the simplest form  $S^1 = S^2 = \mathbb{R}^{d/2}$ , i.e.

$$x = (x^1, x^2)$$
, where  $x^1 \in S^1 = \mathbb{R}^{d/2}, x^2 \in S^2 = \mathbb{R}^{d/2}$ 

This can continue recursively until we reach  $\mathbb{R}$  and then we can perform a one-dimensional clustering.

### Vector Quantization cont.

$$X \subset \mathbb{R}^d$$
,  $|X| = n$ ;  $\mathbb{R}^d = S^1 \times S^2$ 

#### Representation of Points

Assume two clusters  $U^1$ ,  $U^2$  trained indepedently on the projection of P onto  $S^1$  and  $S^2$ , where each cluster contains *s* centroids. Then,  $U = U^1 \times U^2$  contains  $s \times s$  centroids and partitions  $\mathbb{R}^d$  into  $s \times s$  cells.

We view U as a two-dimensional grid and map each  $p \in P$  to cell  $q(x) = (q^1(x^1), q^2(x^2))$ , where  $q^i(x^i)$  is the closest centroid to  $x^i$  in  $U^i$ .

#### Quantization

For each cell  $u_{\alpha}, \alpha \in I = [s] \times [s]$ , compute:

• Empirical frequency:  $p_{\alpha} = |X_{\alpha}|/n$ , where  $X_{\alpha} = \{x \in X \mid q(x) = u_{\alpha}\}$ .

• Mean: 
$$\mu_{\alpha} = \frac{1}{|X_{\alpha}|} \sum_{x \in X_{\alpha}} x$$

We can now discard X.

イロト 不得 トイヨト イヨト 二日



Figure: Example of a two-dimensional grid U, composed of the Cartesian product of two sub-codebooks  $U^1$ ,  $U^2$ . The points can now be mapped onto this grid and be discarded.

### IQ-Means Algorithm - I

Start with an arbitrary set C of k centroids.

Update Step

For all centroids  $c_m \in C$ :

$$c_m \leftarrow \frac{1}{P_m} \sum_{\alpha \in A_m} p_\alpha \mu_\alpha,$$

$$A_m = \{ \alpha \in I \mid \hat{q}(u_\alpha) = m \}$$
 and  $\hat{q}(u) = \operatorname*{arg\,min}_{c_m \in C} ||u - c_m||$  and  
 $P_m = \sum_{\alpha \in A_m} p_\alpha$ 

3

< 🗇 🕨 < 🖃 🕨

### IQ-Means Algorithm - II

#### Assignment Step

For each centroid  $c_i$  the *w* nearest sub-centroids are found in  $U^1$ ,  $U^2$  and ordered by ascending distance to  $c_i$ .

The  $w \times w$  cells are then visited in order via a priority queue.

Upon visiting a cell a function f is called. In this case, it updates the curent assignment  $\alpha$  and lowest distance *dist* found for each cell  $u_{\alpha}$ . It also terminates upon visiting a specified target T of points.



Figure: Example assignment step. For the centroids  $c_1, c_2$  we have computed the  $w \times w$  nearest cells and re-arranged them such that nearest cells appear in the top left corner.

### Small Scale Experiments I



Figure: Average distortion and total time for 20 iterations on SIFT1M for varying number of clusters k. Time for IQ-means includes encoding of data points that is constant in k, but not codebook learning, which is performed on a different dataset.

### Small Scale Experiments II



Figure: Average distortion and total time for 20 iterations on SIFT1M for  $k = 10^4$  and varying number of data points n. Time for IQ-means includes encoding of data points that is linear in n, but not codebook learning.

### Large Scale Experiments



Figure: Mining example: subsets of similar clusters for (a) Paris and (b) Paris+YFCC100M. Images in red outline are from the Paris ground truth.



#### 2 IQ-Means



3

- ∢ ≣ →

Image: A math a math

### Dynamic IQ-Means

#### No-cost purging

Quantize centroids by assigning each centroid  $c_i$  to cell  $u_{\alpha}$  by using the nearest sub-centroids returned in the assignment step above.

Maintain a list for each centroid keeping the other centroids encountered in search.

Model the distribution of points assigned to a centroid  $c_m$  by an isotropic normal density  $\mathcal{N}(x|c_m, \sigma_m)$ , where

$$\sigma_m^2 \leftarrow \frac{1}{P_m} \sum_{\alpha inA_m} p_\alpha ||\mu_\alpha - c_m||^2$$

Iterate over all centroids in descending order of population and purge clusters that overlap too much with previous ones.

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

### Dynamic IQ-Means Experiments



Figure: Final k' versus initial k number of centroids on SIFT1M for varying overlap threshold  $\tau$ .

# Thank you!

3

・ロト ・聞 ト ・ヨト ・ヨト

### References I

Y. Avrithis, Y. Kalantidis, E. Anagnostopoulos, I. Z. Emiris Web-scale Image Clustering revisited ICCV 2015

#### Y. Avrithis.

Quantize and Conquer: A dimensionality-recursive solution to clustering, vector quantization, and image retrieval ICCV 2013



A. Broder, L. Garcia-Pueyo, V. Josifovski, S. Vassilvitskii, and S. Venkatesan Scalable k-means by ranked retrieval Web Search and Data Mining 2014.

### References II

 Y. Gong, M. Pawlowski, F. Yang, L. Brandy, L. Boundev, and R. Fergus
Web scale photo hash clustering on a single machine CVPR 2015

- J. Philbin, O. Chum, M. Isard, J. Sivic, and A. Zisser- man. Object retrieval with large vocabularies and fast spatial matching CVPR 2017
- Y. Avrithis, Y. Kalantidis Approximate Gaussian Mixtures for Large Scale Vocabularies ECCV 2012.