

NN-based Hierarchical Choquet Integrals: explainability by design

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Multi-criteria decision aids

Decision Problems

Sobrie, 2015

- ▶ Selection: choosing the best *alternative* in a given set;
- ▶ Ranking: ordering the *alternatives* by preference;
- ▶ Sorting: assigning to any *alternative* a preference label (e.g. *good, bad...*)

Scoring Model

$$\mathcal{F} : X \rightarrow \mathbb{R}$$

$$\mathcal{F}(\mathbf{x}) \geq \mathcal{F}(\mathbf{y}) \iff \mathbf{x} \text{ is at least as good as } \mathbf{y}$$

$$\mathcal{F}(\mathbf{x}) > \mathcal{F}(\mathbf{y}) \iff \mathbf{x} \text{ is better than } \mathbf{y}$$

Requirement: Trustability

Jiang et al., 18; Varshney 16

- ▶ intelligibility
- ▶ unicity of the interpretation = identifiability of the model

Building models

MCDA constraint-based approaches

- ▶ formally-valid models
- ▶ time-expensive (requires an interaction with an expert)
- ▶ can lead to global inconsistencies
- ▶ vulnerable to errors

Machine Learning

- ▶ learn from data
- ▶ statistically valid
- ▶ (in general) not interpretable

Summary of the talk

- ▶ Present MCDA, Hierarchical Choquet Integrals
- ▶ Learn HCIs from data
- ▶ PhD: identifiability property

Contexte

Hierarchical Choquet Integrals

Neur-HCI

Experimental validation

Conclusion – Perspectives

Formal background

Notations

Variables x_1, \dots, x_n ; x_i defined on domain X_i

Marginal Utilities

$$u_i : X_i \mapsto \mathbb{R}$$

A marginal utility denotes a preference relation on the values of a attribute i :

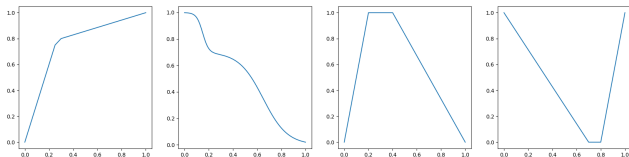
$$u_i(a_i) \geq u_i(b_i) \iff a_i \succeq_i b_i$$

Criterion == attribute i and marginal utility u_i

Marginal utilities

Constraints

- ▶ $\max_{x_i \in X_i} (u_i(x_i)) = 1$ (total satisfaction)
- ▶ $\min_{x_i \in X_i} (u_i(x_i)) = 0$ (total dissatisfaction)
- ▶ u_i is continuous, piecewise- C^1
- ▶ u_i is either monotonic or peak-shaped or valley-shaped



Four types of monotonicities

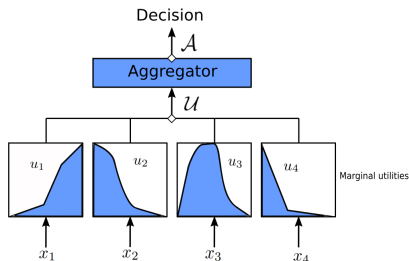
Decomposable Models

Krantz et al. 71

Definition \mathcal{F} is decomposable iff

$$\mathcal{F}(\mathbf{x}) = \mathcal{A}(u_1(x_1), \dots, u_n(x_n)) \quad (1)$$

with aggregator \mathcal{A} non-decreasing.



Decomposable model with dimension 4

Example

Houses

House	Surface m ²	Garden m ²	Garage (yes/no)	Road km	Transp. km	Downtown km	Price €
h_1	50	100	No	0.1	0.	0.	400,000
h_2	110	150	Yes	0.5	3.	4.	500,000
h_3	150	0	No	1.	0.5	0.5	450,000
h_4	150	30	No	0.1	5.	3.	300,000
h_5	500	1000	Yes	5.	5.	10.	1,500,000

Notations

- ▶ 7 features
- ▶ Domains $X_1 = X_2 = X_4 = X_5 = X_6 = X_7 = \mathbb{R}_+$
- ▶ Domain $X_3 = \{\text{Yes, No}\}$

Weighted Sum of utilities

$$\mathcal{A}(u_1, \dots, u_n) = \sum_{i=1}^n w_i a_i \text{ with, } \forall i \in N, w_i \geq 0 \text{ and } \sum_{i=1}^n w_i = 1.$$

Fuzzy measure μ on set N

$$\mu : 2^N \rightarrow [0, 1]$$

- ▶ $\mu(N) = 1$
- ▶ $\mu(\emptyset) = 0$
- ▶ $\forall B \subseteq A \subseteq N, \mu(B) \leq \mu(A)$

Representation power Let A, B be two non-empty, disjoint **coalitions** of criteria (subsets of N).

- ▶ $\mu(A \cup B) \leq \mu(A) + \mu(B)$: redundancy (downtown / public transportation)
- ▶ $\mu(A \cup B) = \mu(A) + \mu(B)$: independence (downtown / garden)
- ▶ $\mu(A \cup B) \geq \mu(A) + \mu(B)$: synergy (garage / road)

Choquet Integral

Definition

Choquet 54

Given μ , the **Choquet integral (CI)** (a_1, \dots, a_n) is defined as:

$$C_\mu(a) = \sum_{i=1}^N \mu(\{\tau(i), \tau(i+1), \dots, \tau(n)\}) (a_{\tau(i)} - a_{\tau(i-1)}) \quad (2)$$

with τ a permutation in N s.t. $\forall i \in N, a_{\tau(i)} \leq a_{\tau(i+1)}$ and $a_{\tau(0)} = 0$.

Properties

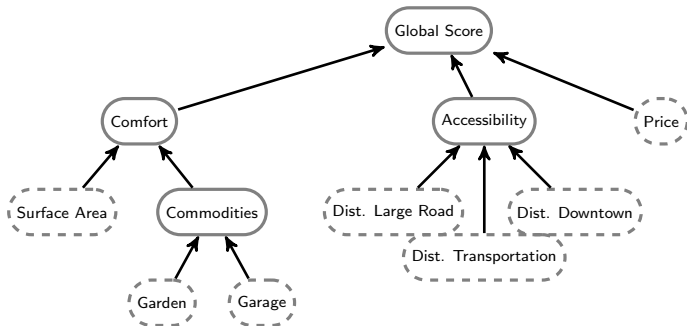
Grabisch & Labreuche 08

- ▶ continuous
- ▶ non-decreasing w.r.t. arguments
- ▶ piecewise linearity
- ▶ interpretable
- ▶ 1-Lipschitz

Hierarchical Aggregation

Hierarchical CI: a hierarchical model with CI aggregators.

Example



▶ $S_{Global} = \mathcal{A}_{Global}(S_{Comfort}, S_{Accessibility}, S_{Price})$

▶ $S_{Comfort} = \mathcal{A}_{Comfort}(S_{Area}, S_{Commodities})$

▶ ...

Utilitarianistic Hierarchical Choquet Integral

$$\begin{aligned}\mathcal{F} : X = (X_1, \dots, X_n) &\rightarrow [0, 1] \\ x &\mapsto \mathcal{A}(u_1(x_1), \dots, u_n(x_n))\end{aligned}$$

with \mathcal{F} an HCI and, $\forall i \in N$, u_i a marginal utility.

Contexte

Hierarchical Choquet Integrals

Neur-HCI

Experimental validation

Conclusion – Perspectives

SoA on Learning MAUT UHCIs

UHCI learning

- ▶ U: marginal utilities
- ▶ H: hierarchical models
- ▶ CI: Choquet integral

U	H	CI	References
		✓	Grabisch et al. 08; Alavi et al. 09 Fallah Tehrani et al. 12; Hüllermeier & Fallah Tehrani 12; Benabbou et al. 17; Havens & Anderson 18; Bourdache et al. 19
✓			Bous & Pirlot 13
✓		✓	Fallah Tehrani et al. 14
✓	✓		Huang et al. 08; Senge & Hüllermeier 11
✓	✓	✓	Bresson et al. 20

Overview

Neur-HCI

- ▶ Neural Network framework
- ▶ Learns the parameters of a UHCI
 - ▶ weights of the CIs
 - ▶ marginal utilities
- ▶ all UHCI constraints verified by design

Settings

- ▶ Regression
- ▶ Classification
- ▶ Pairwise preferences

Structure

Tree-Hierarchy given by expert

Learning

- ▶ Marginal Utilities
 - ▶ Monotonic
 - ▶ Peak or valleyed-shape
 - ▶ Selector
- ▶ Aggregators
 - ▶ 2-additive
 - ▶ 0 – 1-based 3-additive
 - ▶ general

Representation theorems

- ▶ For each type of module, in large sample limit.

Monotonic Marginal Utility

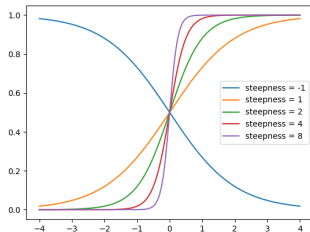
Requirement

- ▶ u_i is non-decreasing on X_i
- ▶ $\lim_{x_i \rightarrow -\infty} u_i(x_i) = 0$
- ▶ $\lim_{x_i \rightarrow +\infty} u_i(x_i) = 1$

Search space: a convex sum of sigmoids:

$$u_i(x_i) = \sum_{k=0}^p \frac{r_i^k}{1 + e^{-(\eta_i^k x_i - \beta_i^k)}},$$

Parameters learned : $r_i^k, \eta_i^k, \beta_i^k$.
 p is a hyperparameter.



With:

- ▶ $\sum_{k=1}^p r_i^k = 1$ and $\forall k, r_i^k \geq 0$
- ▶ $\forall k, \eta_i^k \geq 0$

Monotonic Marginal Utility

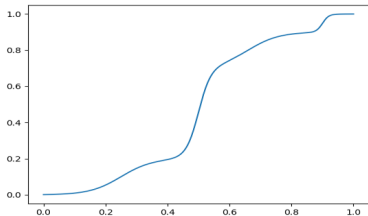
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Parameters learned : $r_i^k, \eta_i^k, \beta_i^k$.
 p is a hyperparameter.



With:

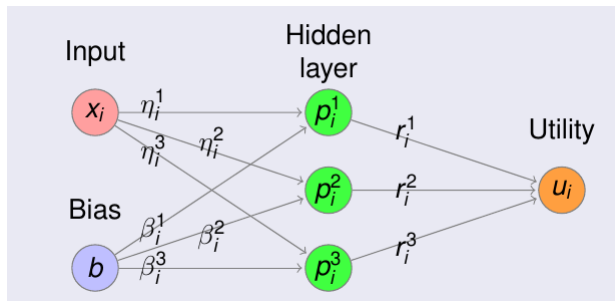
- ▶ $\sum_{k=1}^p r_i^k = 1$ and $\forall k, r_i^k \geq 0$
- ▶ $\forall k, \eta_i^k \geq 0$

Monotonic Marginal Utility Module

Structure

$$u_i(x_i) = \sum_{k=0}^p \frac{r_i^k}{1 + e^{-(\eta_i^k x_i - \beta_i^k)}}$$

- ▶ $\sum_{k=1}^p r_i^k = 1$ and $\forall k, r_i^k \geq 0$
- ▶ $\forall k, \eta_i^k \geq 0$



Other Marginal Utility Modules

Single-peaked/single-valleyed utilities

- ▶ Additional parameter: location of maximum/minimum
- ▶ built from monotonic modules

Selectors

- ▶ selects automatically the best type of monotonicity
- ▶ based on a switching mechanism

2-additive Choquet integral

Characterization

$$C_w(a) = \sum_{i=1}^n w_i a_i + \sum_{i=1}^n \sum_{j=i+1}^n w_{i,j}^{\wedge} (a_i \wedge a_j) + \sum_{i=1}^n \sum_{j=i+1}^n w_{i,j}^{\vee} (a_i \vee a_j) \quad (3)$$

where \wedge (resp \vee) denote the min (resp max) operators, with:

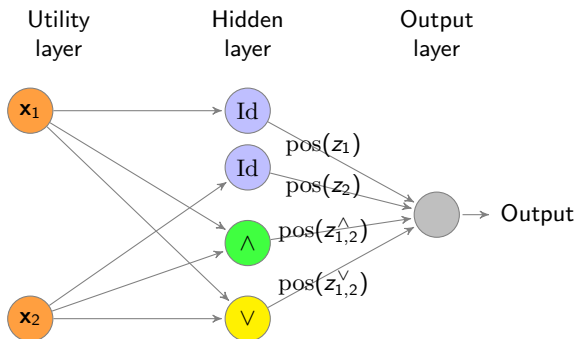
- ▶ **Monotonicity:** $\forall i \in N, \forall j \in N, w_i \geq 0, w_{i,j}^{\wedge} \geq 0, w_{i,j}^{\vee} \geq 0$
- ▶ **Normalization:** $\sum_{i=1}^n w_i + \sum_{1 \leq i < j \leq n} w_{i,j}^{\wedge} + \sum_{i=1}^n \sum_{j=i+1}^n w_{i,j}^{\vee} = 1$

Choquet Modules

2-additive CI

$$C_w(a) = \sum_{i=1}^n \text{pos}(z_i) a_i + \sum_{i=1}^n \sum_{j=i+1}^n (\text{pos}(z_{i,j}^{\wedge})(a_i \wedge a_j) + \text{pos}(z_{i,j}^{\vee})(a_i \vee a_j))$$

$z_i, z_{i,j}^{\vee}, z_{i,j}^{\wedge} \in \mathbb{R}$; pos non-negative.



Other Aggregator Models

- ▶ A subset of the 3-additive CIs
- ▶ General CIs

Assembled Network - UHCI

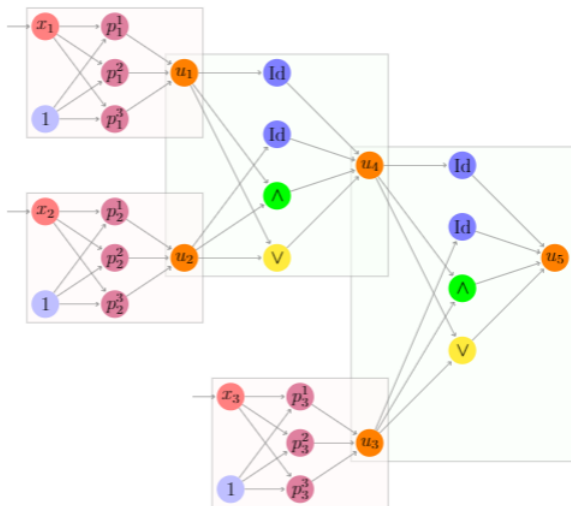


Figure 8.5: Example of the combination of the two modules on a tree with three monotonic marginal utility functions and two aggregation nodes.

Contexte

Hierarchical Choquet Integrals

Neur-HCI

Experimental validation

Conclusion – Perspectives

Experimental validation on benchmarks

Settings

- ▶ Regression (mean squared error)
- ▶ Classification (binary) (Misclassification rate)
- ▶ Pairwise Learning (Ranking inversion rate)

Experimental setting

- ▶ 1000 random splits of each dataset train/test
- ▶ Baselines:
 - ▶ same-size MLP
 - ▶ linear model
 - ▶ Choquistic utilitaristic regression (binary classif.)
- ▶ Benchmarks: 9 datasets (CPU, CEV, LEV, MPG, DB, MG, Journal, Boston)

Performance on Real Data

Dataset	MLP	Logistic Reg.	CUR	NCI	NCI+U	NHCI	NHCI+U
CPU	0.015 ± 0.021	0.091±0.051	0.024 ± 0.025	0.045±0.039	0.023±0.024	0.030±0.027	0.023±0.026
CEV	0.004 ± 0.004	0.110±0.023	0.084±0.067	0.059±0.012	0.051±0.023	0.035±0.009	0.019±0.017
LEV	0.135 ± 0.021	0.161± 0.022	0.143±0.0213	0.136 ± 0.022	0.135 ± 0.019	N/A	N/A
MPG	0.113 ± 0.036	0.090 ± 0.030	0.112 ± 0.099	0.086 ± 0.027	0.079 ± 0.027	0.085 ± 0.029	0.082 ± 0.027
DB	0.143 ± 0.069	0.164±0.071	0.235 ± 0.017	0.139±0.067	0.132 ± 0.068	0.141 ± 0.068	0.135 ± 0.068
MG	0.179 ± 0.028	0.196 ± 0.027	0.166 ± 0.022	0.195 ± 0.027	0.166 ± 0.026	0.201 ± 0.030	0.191 ± 0.028
Journal	0.180 ± 0.063	0.250±0.070	0.218±0.086	0.207±0.065	0.197±0.060	0.219±0.065	0.216±0.062
Boston	0.124 ± 0.030	0.145±0.033	0.1360± 0.085	0.127±0.031	0.129±0.032	0.121±0.032	0.129±0.031
Titanic	0.182 ± 0.025	0.202 ± 0.027	0.185 ± 0.041	0.192±0.0264	0.193 ± 0.027	0.203±0.027	0.194±0.027

Table 1: NEUR-HCI, Classification setting: Classification error (average and variance over 1,000 runs).

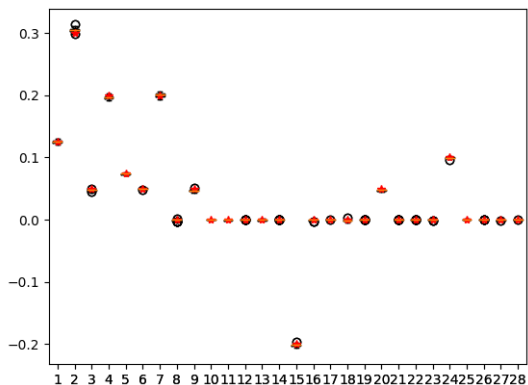
Dataset	MLP	Linear Reg.	NCI	NCI+U	NHCI	NHCI+U
CPU	0.0005 ± 0.0016	0.0022±0.0019	0.0023±0.0032	0.0009±0.0013	0.0026±0.0023	0.0009±0.0011
CEV	0.0094 ± 0.003	0.0434±0.0442	0.0437±0.0037	0.0264±0.0027	0.0197±0.0017	0.0176±0.0017
LEV	0.0312 ± 0.0254	0.0252 ± 0.0029	0.0252 ± 0.0031	0.0252 ± 0.0029	N/A	N/A
MPG	0.0047 ± 0.0008	0.0089±0.0019	0.0084±0.0018	0.0056±0.0013	0.0091±0.0018	0.0057±0.0012
Journal	0.0410 ± 0.010	0.0524±0.0128	0.0631±0.0127	0.0385 ± 0.0112	0.0629 ± 0.0127	0.0391 ± 0.0117
Boston	0.0079 ± 0.0030	0.0174±0.0038	0.0157 ± 0.0037	0.0072 ± 0.0023	0.0151 ± 0.0033	0.0077 ± 0.0023

Table 2: NEUR-HCI, Regression setting: Mean square error (average and variance over 1,000 runs)

Dataset	MLP	Linear Reg.	NCI	NCI+U	NHCI	NHCI+U
CPU	0.0005 ± 0.0002	0.0006 ± 0.0003	0.0007 ± 0.003	0.0006 ± 0.0003	0.0009 ± 0.003	0.0010 ± 0.004
CEV	0.0174 ± 0.012	0.0642±0.011	0.0243±0.005	0.0099±0.002	0.0165±0.004	0.0088 ± 0.003
LEV	0.0178 ± 0.025	0.0179 ± 0.023	0.0178 ± 0.024	0.0177 ± 0.023	N/A	N/A
MPG	0.0613 ± 0.012	0.0642±0.011	0.0610 ± 0.011	0.0612 ± 0.011	0.0633±0.012	0.0621±0.011
DB	0.1355 ± 0.0796	0.1257±0.079	0.1216±0.081	0.0942 ± 0.069	0.1231 ± 0.092	0.0962 ± 0.081
MG	0.2601 ± 0.046	0.2661±0.047	0.2668±0.045	0.2381 ± 0.037	0.2701±0.052	0.2446 ± 0.036
Journal	0.1801 ± 0.064	0.1802±0.065	0.1761±0.063	0.1838±0.066	0.1711 ± 0.063	0.1889±0.065
Boston	0.0659 ± 0.016	0.0790±0.014	0.0790±0.015	0.0669 ± 0.012	0.0752 ± 0.014	0.0681 ± 0.014
Titanic	0.1521 ± 0.027	0.1651 ± 0.029	0.1632 ± 0.028	0.1533 ± 0.028	0.166 ± 0.028	0.1542 ± 0.029
Arguments 1	0.0157 ± 0.015	0.0195±0.016	0.0145±0.012	0.0141 ± 0.012	0.0141 ± 0.012	0.0140 ± 0.012
Arguments 2	0.0588 ± 0.028	0.0653±0.031	0.0644±0.028	0.0581±0.027	0.0572 ± 0.027	0.0572 ± 0.028
Arguments 3	0.0740 ± 0.039	0.0941±0.042	0.0783±0.040	0.0784±0.040	0.0761 ± 0.039	0.0771 ± 0.041

Table 3: NEUR-HCI, Ranking setting: percentage of mis-ordered pairs (average and variance over 1,000 runs)

On artificial data (large sample limit)



Distribution of the weights of 50 Cls trained on 50 different datasets of 10,000 examples generated by a ground-truth model (red stars).

Artificial Data, followed

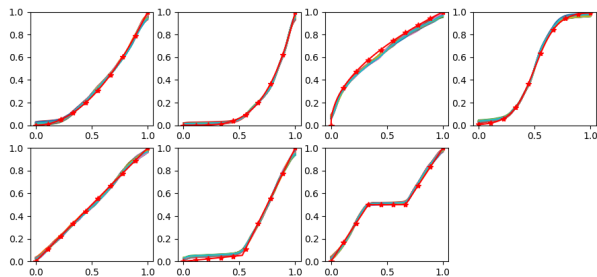


Figure: Marginal utilities of 50 UHCI models trained on 50 different datasets of 10,000 examples generated by a ground-truth model (red stars).

Sensitivity to Noise

Noise	Tree	Flat
0.	$7.1 \times 10^{-7} \pm 4.4 \times 10^{-6}$	$2.5 \times 10^{-6} \pm 7.2 \times 10^{-7}$
0.05	$1.1 \times 10^{-4} \pm 4.6 \times 10^{-5}$	$1.7 \times 10^{-4} \pm 4.8 \times 10^{-5}$
0.1	$4.4 \times 10^{-4} \pm 1.6 \times 10^{-4}$	$6.3 \times 10^{-4} \pm 1.8 \times 10^{-4}$
0.2	$1.6 \times 10^{-3} \pm 7.6 \times 10^{-4}$	$1.7 \times 10^{-3} \pm 6.1 \times 10^{-4}$

Table: Mean Squared Error in regression setting, 50 models training on 50 different datasets of 300 noisy examples. Tested on noiseless examples, the error is lower than the noise.

Real Data - MPG Dataset

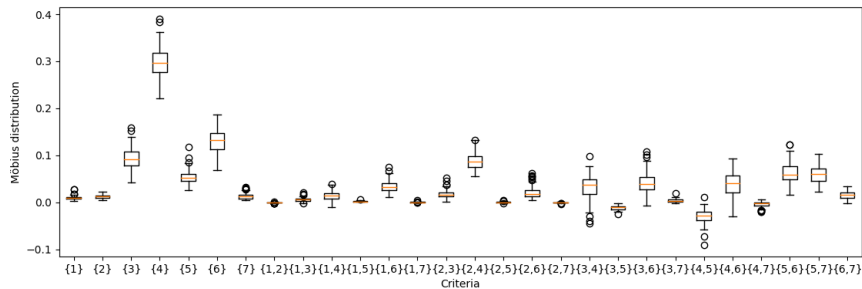


Figure: Distribution of weights, 50 models trained on different splits of the MPG dataset.

Real Data - MPG Dataset

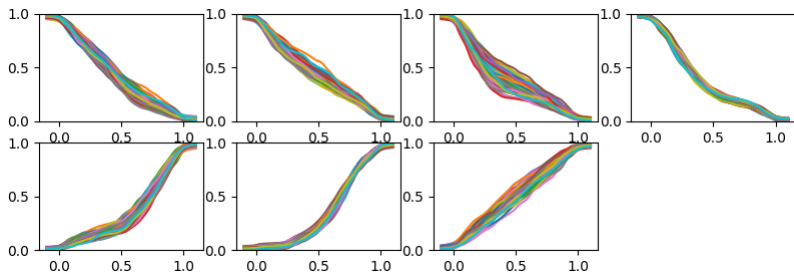


Figure: Marginal utilities, 50 models trained on different splits of the MPG dataset.

Conclusion

- ▶ This was made possible as HCI constraints can be included in NN architecture *by design*

Next

- ▶ Revise a NN with Hierarchical Choquet head.