

Multi-marginal optimal transport and applications

Brendan Pass

University of Alberta

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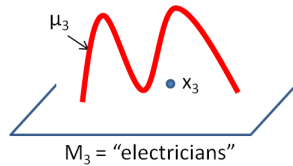
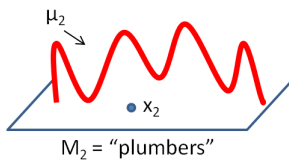
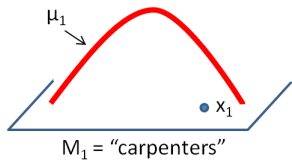
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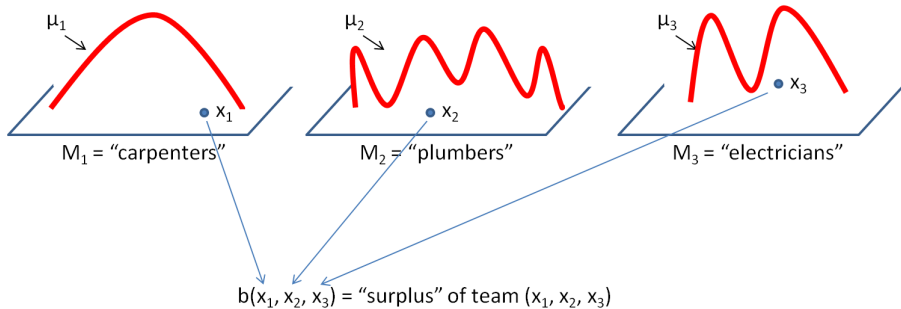
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- Want to construct teams to make overall process as efficient as possible.

Introduction



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Multi-marginal problem: Monge formulation

- $M_i \subseteq \mathbb{R}^n$, open and bounded, $i = 1, 2, \dots, m$.
- μ_i Borel probability measures on M_i .
- $b : M_1 \times M_2 \times \dots \times M_m \rightarrow \mathbb{R}$ smooth *surplus* function.

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Monge Problem:

maximize:

$$\int_{M_1} b(x_1, F_2(x_1), F_3(x_1), \dots, F_m(x_1)) d\mu_1(x_1)$$

among $(m - 1)$ -tuples of maps (F_2, F_3, \dots, F_m) such that $F_i : M_1 \rightarrow M_i$ pushes μ_1 to μ_i .

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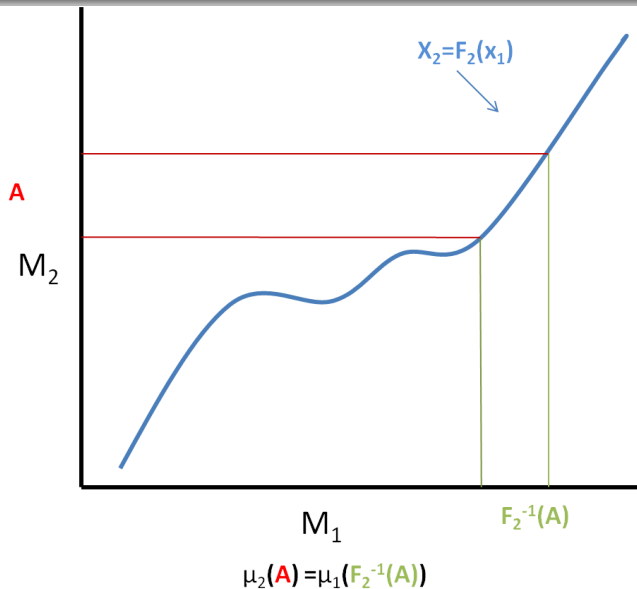
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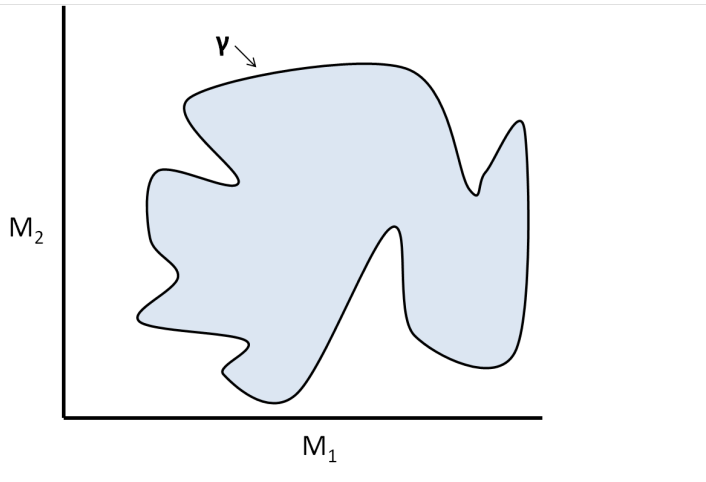
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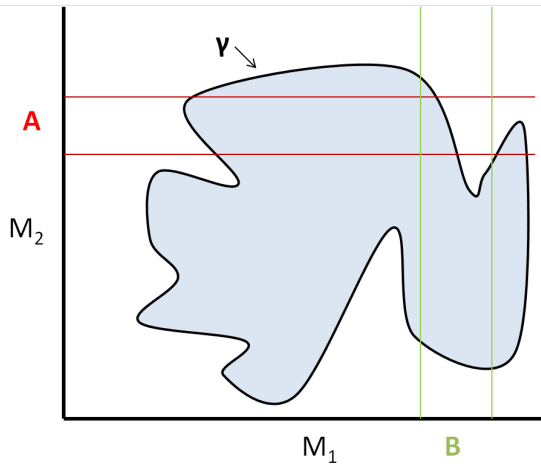
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$$\mu_2(\mathbf{A}) = \gamma(M_1 \times \mathbf{A})$$

$$\mu_1(\mathbf{B}) = \gamma(\mathbf{B} \times M_2)$$

Background on (two marginal) optimal transportation

- Optimal transportation with **two marginals** ($m = 2$) is an active and well established area of research.
- Many diverse applications, including: fluid mechanics, cosmology, interacting gases, meteorology, image processing, economics, etc.
- Brenier '87, Gangbo '95, Caffarelli '96, Gangbo-McCann '96, Levin '96: Assume $\mu_1 \ll dx_1$ and that b is **twisted**, ie:

$$x_2 \mapsto D_{x_1} b(x_1, x_2) \text{ is injective.}$$

Then γ is concentrated on the graph of a function over x_1 and is unique.

- Example: $b(x_1, x_2) = -|x_1 - x_2|^2$.

Background on multi-marginal problems: good surpluses

- Multi-marginal problems have many emerging applications, in economics, physics, m -monotonicity, image processing, financial math, statistics, etc., but are not well understood.
- For certain *special* surplus functions, the optimal γ is unique and is concentrated on a graph over x_1 :

$$\{(x_1, F_2(x_1), \dots, F_m(x_1))\}.$$

- **Gangbo-Swiech '98:** $b(x_1, x_2, \dots, x_m) = -\sum_{i \neq j} |x_i - x_j|^2$
- **Heinich '02:** $b(x_1, x_2, \dots, x_m) = h(x_1 + x_2 + \dots + x_m)$ where $h : \mathbb{R}^n \rightarrow \mathbb{R}$ is strictly convex.
- **P '11:** Strong second order conditions on b . For example, when $m = 3$, we require, for all $x_1, \bar{x}_1 \in M_1$, $x_2 \in M_2$, $x_3, \bar{x}_3 \in M_3$, we have:

$$D_{x_2 x_3}^2 b [D_{x_1 x_3}^2 b]^{-1} D_{x_1 x_2}^2 b(x_1, x_2, x_3) - D_{x_2 x_2}^2 b(x_1, x_2, x_3) + D_{x_2 x_2}^2 b(\bar{x}_1, x_2, \bar{x}_3) > 0.$$

- **Kim-P '13:** $b(x_1, x_2, \dots, x_m) = -\inf_{y \in M} [\sum_{i=1}^m d^2(x_i, y)]$ on a Riemannian manifold M .

Background on multi-marginal problems: bad surpluses

- For other surplus functions, solutions can be **non-unique** and have **high dimensional support**. Examples:
- $b(x_1, x_2, \dots, x_m) = -\sum_{i \neq j}^m \frac{1}{|x_i - x_j|}$, arises in density functional theory for Coulombic electronic interactions in quantum physics ([Cotar-Friesecke-Kluppelberg '11](#) and [Buttazzo-De Pascale-Gori-Giorgi '12](#)).
- $b(x_1, x_2, \dots, x_m) = \sum_{i \neq j}^m |x_i - x_j|^2$, arises when Coulombic interactions are replaced by repulsive, harmonic oscillator interactions.
- $b(x_1, x_2, \dots, x_m) = \det(x_1, x_2, \dots, x_m)$ (when $n = m$)
[Carlier-Nazaret '06](#) .
- $b(x_1, x_2, \dots, x_m) = h(x_1 + x_2 + \dots + x_m)$, h strictly concave .

Example application 1: multi-agent matching

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- Buyer x_1 has a preference $f_1(x_1, z)$ for a house type $z \in Z \subseteq \mathbb{R}^n$; worker x_i ($i \geq 2$) has a preference $f_i(x_i, z)$ to build house of type z .

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- Finding an equilibrium in this market is equivalent to solving an optimal transport problem with surplus

$$b(x_1, x_2, \dots, x_m) = \sup_{z \in Z} \sum_{i=1}^m f_i(x_i, z)$$

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- Leads to an optimal transport problem with
$$b(x_1, x_2, \dots, x_m) = - \sum_{i \neq j} \frac{1}{|x_i - x_j|}.$$

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- Coordinate invariant condition: $\frac{\partial^2 b}{\partial x_1 \partial x_2} \left[\frac{\partial^2 b}{\partial x_3 \partial x_2} \right]^{-1} \frac{\partial^2 b}{\partial x_3 \partial x_1} > 0$.

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- $(D_{x_1 x_2}^2 b)[(D_{x_3 x_2}^2 b)]^{-1}(D_{x_3 x_1}^2 b) > 0$ makes sense!

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- Some rotations fix x but not y , assuming x and y are not co-linear (get non Monge solutions).
- These rotational directions are extra spacelike directions for G .

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- Optimal maps factor through a measure on Z (the *generalized barycenter*) **Agueh-Carlier '10**.

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$$b(x_1, x_2, x_3) = \sup_{z \in Z} \sum_{i=1}^3 f_i(x_i, z)$$

- This class includes $-\sum_{i=1}^3 |x_i - x_j|^2$ (**Gangbo-Swiech** surplus), $h(x_1 + x_2 + x_3)$, for strictly convex h , (**Heinich** surplus).
- Optimal maps factor through a measure on Z (the *generalized barycenter*) **Agueh-Carlier '10**.
- Can easily calculate $(D_{x_1 x_2}^2 b)[(D_{x_3 x_2}^2 b)]^{-1}(D_{x_3 x_1}^2 b) > 0$ (under mild conditions on the f_i).

Monge solution and uniqueness results

- For which surplus functions is the optimizer concentrated on the graph of a function over x_1 ?
- For $m = 2$, the twist, injectivity of $x_2 \mapsto D_{x_1} b(x_1, x_2)$, suffices.
- For $m = 3$, these type of results hold for

$$b(x_1, x_2, x_3) = \sup_{z \in Z} \sum_{i=1}^3 f_i(x_i, z)$$

- This class includes $-\sum_{i=1}^3 |x_i - x_j|^2$ (**Gangbo-Swiech** surplus), $h(x_1 + x_2 + x_3)$, for strictly convex h , (**Heinich** surplus).
- Optimal maps factor through a measure on Z (the *generalized barycenter*) **Agueh-Carlier '10**.
- Can easily calculate $(D_{x_1 x_2}^2 b)[(D_{x_3 x_2}^2 b)]^{-1}(D_{x_3 x_1}^2 b) > 0$ (under mild conditions on the f_i).
- One can also prove Monge solutions and uniqueness under strong differential conditions on b (**P '11**), or under a twist like condition on special sets (**Kim-P (in preparation)**).

- In the limit as $m \rightarrow \infty$, the differences become even more pronounced.
- For the surplus $-\int_0^1 \int_0^1 |x_s - x_t|^2 ds dt$, we get unique Monge type solutions (P '13).
- For $-\lim_{m \rightarrow \infty} \frac{1}{\binom{m}{2}} \sum_{i \neq j}^m \frac{1}{|x_i - x_j|}$; the (unique) optimal measure is product measure (Cotar-Friesecke-P (in preparation)).