

Optimal
transport

Jean-Marie
Mirebeau

Discretization

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Quantization

Euler

JKO

Convexity

Applications

involving a

modified

transport

cost

Reflector

design

Unbalanced

transport

Optimal

mining

Semi-Discrete Optimal Transport and its applications

Jean-Marie Mirebeau

CNRS, University Paris Sud

November 18, 2015

Joint work with Q. Merigot
Journées de Géométrie Algorithmique, Cargèse, 2015

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Applications with the standard quadratic cost

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Euler equations of incompressible fluids

Evolution PDEs via the JKO flow

Optimization under the constraint of convexity

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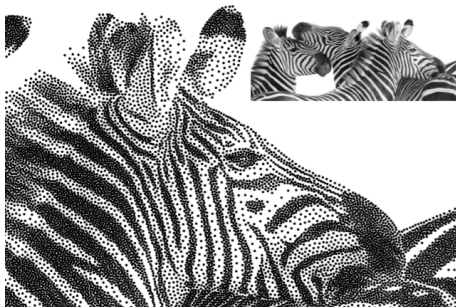
Image quantization

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- ▶ Use semi-Discrete Optimal transport to measure the distance from a collection of Dirac masses to a density.

$$W \left(\sum_{1 \leq i \leq n} \mu_i \delta_{x_i}, \rho \text{Leb} \right)$$

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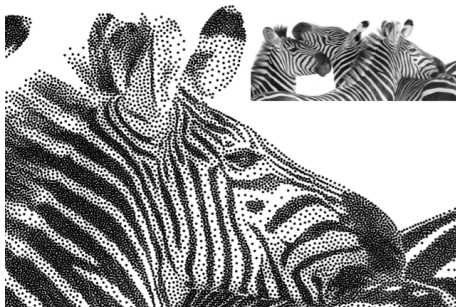
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Euler equations of incompressible fluids

- ▶ **Incompressible fluid** in domain X , $|X| = 1$. **No viscosity**.

$$\partial_t v + (v \cdot \nabla)v = \nabla p, \quad \operatorname{div} v = 0.$$

- ▶ Observe Initial $x_{0,i}$ and final $x_{T,i}$ positions of N particles.
- ▶ Reconstruct intermediate positions $x_{t,i}$ by minimizing

$$\underbrace{\frac{T}{N} \sum_{0 \leq t < T} \sum_{1 \leq i \leq N} |x_{t,i} - x_{t+1,i}|^2}_{\text{Kinetic energy}} + \lambda \underbrace{\sum_{1 \leq t < T} W \left(\frac{1}{N} \sum_{1 \leq i \leq N} \delta_{x_{t,i}}, \operatorname{Leb}_X \right)}_{\text{Penalization of compression}}$$

- ▶ Motivation: geodesics on $\mathcal{SDiff} = \{s \in C^\infty(X, X); \det \nabla s = 1\}$, w.r.t the L^2 metric, obey Euler equations, in Lagrangian coordinates. Arnold (66)
- ▶ Convergence: as $N, T, \lambda \rightarrow \infty$ suitably, minimizers converge to a Generalized flow (Brenier 89), i.e. a measure on $C^0([0, 1], X)$, solving a relaxation of Euler equations.

📄 Merigot, M, Minimal geodesics along volume preserving maps through semi-discrete optimal transport, Preprint.

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$$\ddot{s}_t = \nabla p \circ s_t. \quad (1)$$

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- ▶ JKO \Leftrightarrow implicit gradient descent w.r.t Wasserstein metric

$$\mu_{n+1} := \operatorname{argmin}_{\mu \in \operatorname{Prob}(\Omega)} \frac{1}{2\tau} W(\mu_n, \mu) + \mathcal{F}(\mu).$$

- ▶ Formally converges to an evolution PDE as $\tau \rightarrow 0$

$$\mathcal{F}(\rho \operatorname{Leb}_\Omega) = \int_{\Omega} F(x, \rho(x)) dx \quad \Rightarrow \quad \partial_t \rho = \operatorname{div}(\rho \nabla \partial_\rho F(\cdot, \rho)).$$

- ▶ Theoretical scheme proposed by Jordan, Kinderlehrer and Otto, to obtain existence results for these PDEs.

Figure : Simulation of crowd motion under a congestion constraint.
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Figure : Simulation of crowd motion under a congestion constraint. Benamou, Carlier, Mérigot, Oudet (2014).

Finite set $X \subset \mathbb{R}^d$, map $u : X \rightarrow \mathbb{R}$.

- ▶ u has a convex extension iff its subgradients are non-empty

$$\partial u(x) := \{p \in \mathbb{R}^d; \forall y \in X, u(x) + \langle p, y - x \rangle \leq u(y)\}$$

- ▶ $\partial u(x) = \text{Lag}_{\psi}(x)$ with $\psi(x) = \frac{1}{2}|x|^2 - u(x)$.
- ▶ u has a strictly convex extension with gradients in Ω , where Ω is a convex bounded domain, iff

$$\infty > - \sum_{x \in X} \ln |\partial u(x) \cap \Omega|$$

This barrier function is convex in u .

- ▶ Optimal transport interpretation: the gradient of the Legendre Fenchel conjugate u^* defines an optimal transport $\nabla u^* : (\Omega, \text{Leb}_{\Omega}) \rightarrow (X, \nabla u^*_{\#} \text{Leb}_{\Omega})$, product \rightarrow customer. We penalize the image measure entropy.

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The Monopolist problem (Rochet, Chone, 98)

Jean-Marie Mirebeau

- ▶ **Monopolist** produces goods $q \in \mathbb{R}_+^d$ at cost $c(q)$, $c(0) = 0$.
- ▶ Monopolist unilaterally sets prices $\pi(q)$, $\pi(0) = 0$.
- ▶ Customer of type $z \in \mathbb{R}_+^d$ maximizes his net utility

$$U(z) = \sup_{q \in \mathbb{R}_+^d} \underbrace{\langle q, z \rangle}_{\text{Utility}} - \underbrace{\pi(q)}_{\text{Price}}$$

Customer's best product $q(z)$ is chosen to maximize net utility

$$\pi(q(z)) = c(q(z)) = c(q(z)) - U(q(z), z)$$

- ▶ Customer density μ on \mathbb{R}_+^d , is known to the monopolist

$$\text{Profit} = \int_{\mathbb{R}_+^d} \langle \nabla U(z), z \rangle - U(z) - c(\nabla U(z)) d\mu(z).$$

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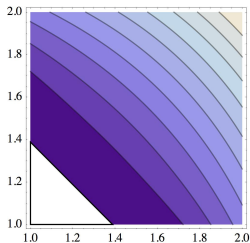



Figure : Customer density μ uniform on $\Omega = [1, 2]^2$, monopolist production cost $c(q) = \frac{1}{2}|q|^2$. Left: solution u . Center: product sales density $\nabla u \# \mu$. Right: $\Omega_k := \{\text{rank}(\nabla^2 u) = k\}$.

 J.-M. Mirebeau, Adaptive Anisotropic and Hierarchical Cones of Convex functions, Numerische Mathematik (2015).

$$\text{Profit} = \max_{u \text{ convex}} \int_{\mathbb{R}^d} \langle \nabla u(z), z \rangle - u(z) - c(\nabla u(z)) d\mu(z).$$

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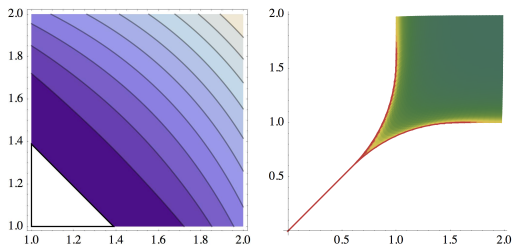



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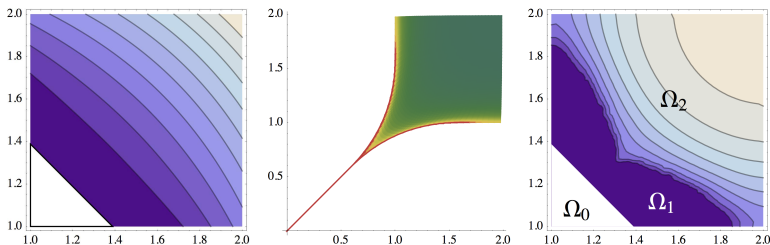


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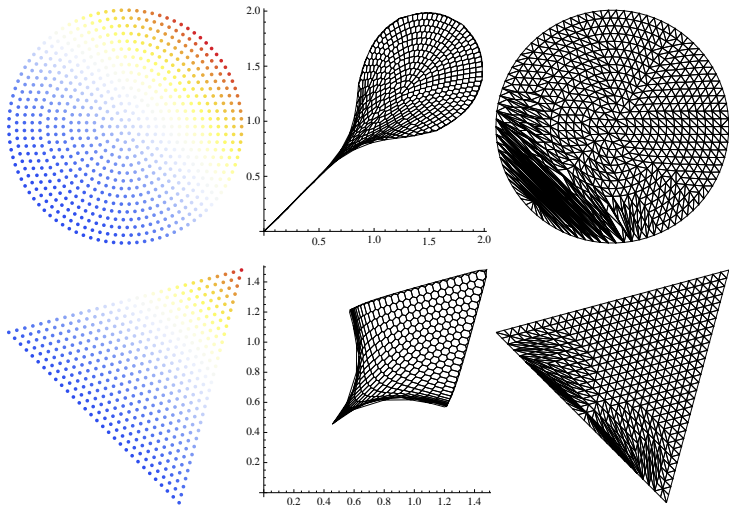


Figure : Customer density μ uniform on disk $D((3/2, 3/2), 1/2)$ or triangle centered at $(3/2, 3/2)$. Left: solution u . Center: product line (=Subgradient cells=Laguerre diagram). Right: dual triangulation. No one buys the null product in the triangle case. Joint work with Q. Merigot

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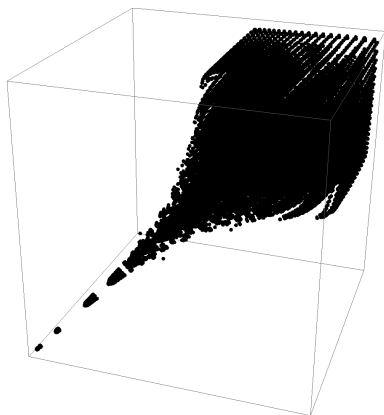


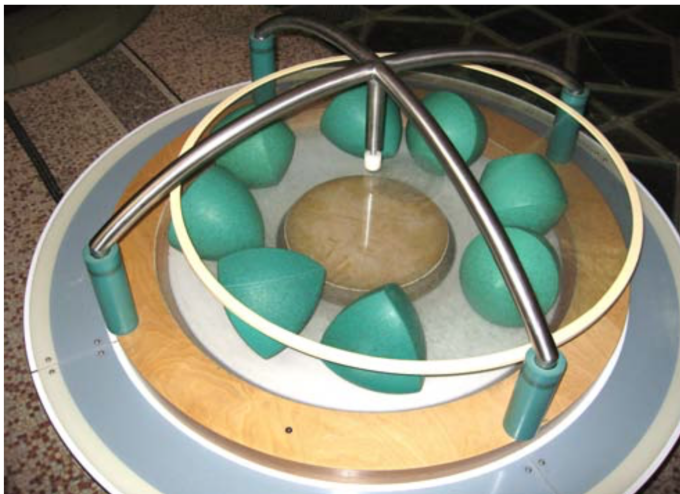
Figure : Product line for a uniform density of customers on $[1, 2]^3$

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Minimizing over convex bodies

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Figure : Several bodies of width 1. The glass surface remains flat and at height 1 (Palais de la découverte, Paris).

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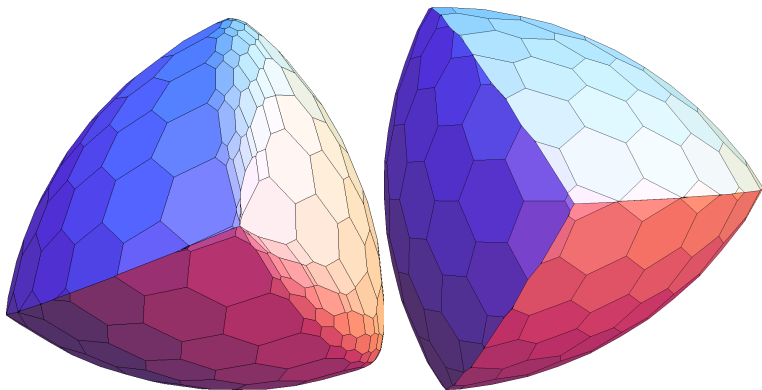


Figure : Numerical minimization of volume among convex bodies of width 1. Our experiments support Meissner's conjecture.

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Semi-Discrete Optimal Transport

Applications with the standard quadratic cost

Image quantization

Euler equations of incompressible fluids

Evolution PDEs via the JKO flow

Optimization under the constraint of convexity

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- ▶ Objective: Project a point-source light onto a uniform density, a non-blinding headlight, a logo...
- ▶ Masks loose energy \Rightarrow transport instead light by reflection
- ▶ Light rays only follow shortest paths \Rightarrow optimal transport.
- ▶ Non-quadratic cost function e.g. $c(x, y) = -\ln(1 - \langle x, y \rangle)$, for $x, y \in \mathbb{S}^2$. (concave reflector and point source.)
- ▶ Machado, Merigot, Thibert (2015) implement CGAL[®] exact geometric predicates for these Laguerre diagrams.

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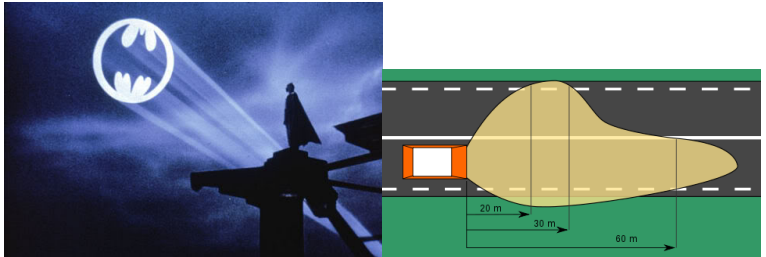


Figure : by Warner[®], Mercedes[®], Benamou, Merigot, Thibert (15)

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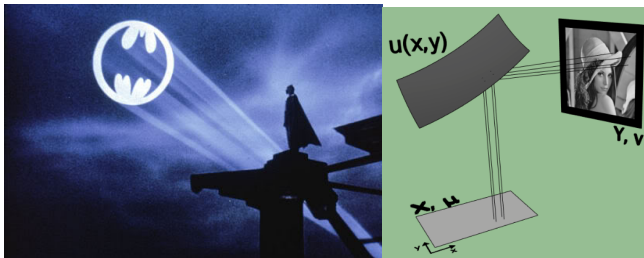


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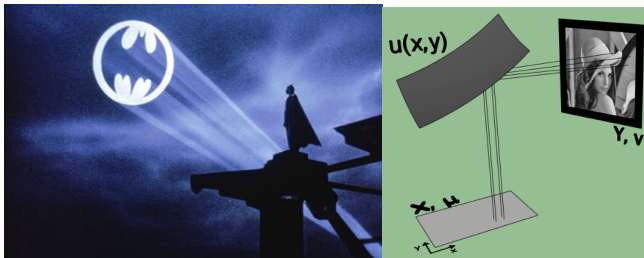


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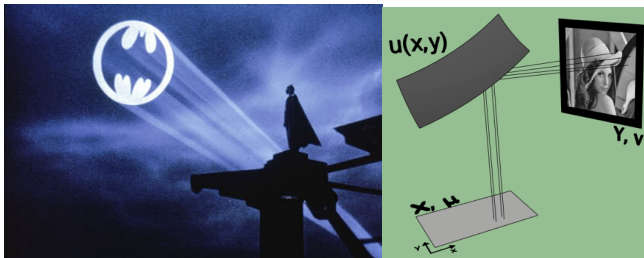


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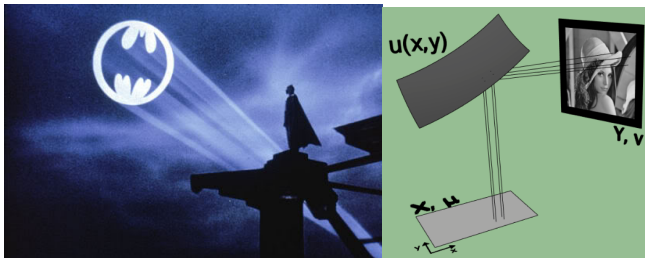


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$$W(\rho_0, \rho_1) = \inf_{\rho, m} \int_0^1 \int_{\Omega} \frac{|m|^2}{\rho} \quad \text{s.t.} \quad \begin{cases} \partial_t \rho + \operatorname{div} m = 0 \\ \rho(0) = \rho_0, \rho(1) = \rho_1 \end{cases}$$

- ▶ Optimal transport cost, with $c(x, y) = \frac{1}{2}|x - y|^2$, is the kinetic energy required to move a **pressureless fluid** from density ρ_0 to ρ_1 . Benamou, Brenier (2002).
- ▶ ρ : fluid density. m : fluid momentum.
- ▶ Possibility to add a source term σ .
Peyre et al, Savaré et al, Kondratyev et al (2015)
- ▶ \tilde{W} defines a distance between measures of distinct masses.
- ▶ Static semi-discrete formulation requires constructing cells

$$\operatorname{Lag}_{\psi}(x) := \left\{ p \in \mathbb{R}^d; \forall y \in X, \frac{\cos_+ |p - x|}{1 - \psi(x)} \geq \frac{\cos_+ |p - y|}{1 - \psi(y)} \right\}$$

$$\tilde{W}(\rho_0, \rho_1) = \inf_{\rho, m, \sigma} \int_0^1 \int_{\Omega} \frac{|m|^2 + \sigma^2}{\rho} \quad \text{s.t.} \quad \begin{cases} \partial_t \rho + \operatorname{div} m = \sigma \\ \rho(0) = \rho_0, \rho(1) = \rho_1 \end{cases}$$

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- ▶ **Open pit mining** requires excavating topsoil above ore.
- ▶ Ore at x is extracted if it pays for removal of cone $C(x)$ above, left in place otherwise. (Risk of landslide)
- ▶ Optimal pit given by an Optimal Transport problem, from ore to topsoil distributions, and with cost

$$c(x, y) = \begin{cases} 0 & \text{if } y \in C(x), \\ +\infty & \text{otherwise,} \end{cases}$$

+ two sinks. Ekeland, Queyranne (14)

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