[The QSI problem](#page-1-0) [Bayesian strategies for QSI](#page-8-0) [Estimation of small quantile sets](#page-20-0) [Numerical experiments](#page-33-0) [Conclusion](#page-39-0)

### A stepwise uncertainty reduction strategy for the estimation of small quantile sets

### Romain Ait Abdelmalek-Lomenech, Julien Bect & Emmanuel Vazquez

Université Paris-Saclay, CNRS, CentraleSupélec, L2S

MASCOT-NUM 2024, Hyères, April 3rd, 2024







## <span id="page-1-0"></span>Table of Contents

[The quantile set inversion problem](#page-1-0)

[Bayesian strategies for QSI](#page-8-0)

[Estimation of small quantile sets](#page-20-0)

[Numerical experiments](#page-33-0)

[Conclusion](#page-39-0)



Consider an expensive-to-evaluate numerical simulator, with inputs:

- $\triangleright$   $x \in X$  (deterministic design choices).
- ▶  $s \in S$  (stochastic factors).



For simplicity we assume a deterministic simulator  $f : \mathbb{X} \times \mathbb{S} \mapsto \mathbb{R}^q$ .



Consider an expensive-to-evaluate numerical simulator, with inputs:

- $\triangleright$   $x \in X$  (deterministic design choices).
- ▶  $s \in S$  (stochastic factors).



For simplicity we assume a deterministic simulator  $f : \mathbb{X} \times \mathbb{S} \mapsto \mathbb{R}^q$ .



#### Given:

- ▶  $C \subset \mathbb{R}^q$  is a critical/failure region.
- $\blacktriangleright \ \alpha \in (0,1)$  a threshold.
- $\blacktriangleright$   $\mathbb{P}_{\varsigma}$  a known distribution on S.

We focus on the quantile set inversion (QSI) problem:

**Estimate the set of all**  $x \in \mathbb{X}$  **such that the system is robust to** uncertainties, i.e

$$
\mathbb{P}\left(f(x, S) \in C\right) \leq \alpha, \qquad S \sim \mathbb{P}_S,
$$

by only using a small number  *of evaluation points* 

 $\{(X_1, S_1), \ldots, (X_N, S_N)\}.$ 



#### Given:

- ▶  $C \subset \mathbb{R}^q$  is a critical/failure region.
- $\blacktriangleright \ \alpha \in (0,1)$  a threshold.
- $\blacktriangleright$   $\mathbb{P}_{\varsigma}$  a known distribution on S.

We focus on the quantile set inversion (QSI) problem:

Estimate the set of all  $x \in X$  such that the system is robust to uncertainties, i.e

$$
\mathbb{P}\left(f(x, S) \in C\right) \leq \alpha, \qquad S \sim \mathbb{P}_S,
$$

by only using a small number  *of evaluation points* 

 $\{(X_1, S_1), \ldots, (X_N, S_N)\}.$ 



#### Given:

- ▶  $C \subset \mathbb{R}^q$  is a critical/failure region.
- $\blacktriangleright \ \alpha \in (0,1)$  a threshold.
- $\blacktriangleright$   $\mathbb{P}_{\varsigma}$  a known distribution on S.

We focus on the quantile set inversion (QSI) problem:

Estimate the set of all  $x \in X$  such that the system is robust to uncertainties, i.e

$$
\mathbb{P}\left(f(x, S) \in C\right) \leq \alpha, \qquad S \sim \mathbb{P}_S,
$$

by only using a small number  $N$  of evaluation points

 $\{(X_1, S_1), \ldots, (X_N, S_N)\}.$ 



#### Estimate the quantile set:

$$
\Gamma(f) = \{x \in \mathbb{X} : \mathbb{P}(f(x, S) \in C) \leq \alpha\},\
$$

Example of function and associated quantile set, with  $C = (-\infty, 7.5]$  and  $\alpha = 5\%$ .



Figure: Representation of the function (middle), the density of  $\mathbb{P}_S$  (left) and associated quantile set (right).

## <span id="page-8-0"></span>Table of Contents

[The quantile set inversion problem](#page-1-0)

### [Bayesian strategies for QSI](#page-8-0)

[Estimation of small quantile sets](#page-20-0)

[Numerical experiments](#page-33-0)

[Conclusion](#page-39-0)

[The QSI problem](#page-1-0) [Bayesian strategies for QSI](#page-8-0) [Estimation of small quantile sets](#page-20-0) [Numerical experiments](#page-33-0) [Conclusion](#page-39-0)

The QSI problem is related to the estimation of the excursion set





Figure: Example function. The black line delimits the set  $\gamma(f)$ .

Knowing  $\gamma(f) \implies$  knowing  $\Gamma(f)$ .

Indeed,  $\Gamma(f) = \{x \in \mathbb{X} : \mathbb{P}((x, S) \in \gamma(f)) > 1 - \alpha\}.$ 

[The QSI problem](#page-1-0) [Bayesian strategies for QSI](#page-8-0) [Estimation of small quantile sets](#page-20-0) [Numerical experiments](#page-33-0) [Conclusion](#page-39-0)

The QSI problem is related to the estimation of the excursion set





Figure: Example function. The black line delimits the set  $\gamma(f)$ .

Knowing  $\gamma(f) \implies$  knowing  $\Gamma(f)$ .

Indeed,  $\Gamma(f) = \{x \in \mathbb{X} : \mathbb{P}((x, S) \in \gamma(f)) > 1 - \alpha\}.$ 



#### **Bayesian approach:** Consider  $\xi \sim GP(\mu, k)$  a prior on f. We denote:

- **►**  $\mathbb{P}_n$  the distribution of  $\xi$  given  $\{(X_i, S_i, f(X_i, S_i)), i \leq n\}$ .
- $\blacktriangleright$   $E_n$  the expectation w.r.t.  $P_n$ .
- $\blacktriangleright$   $p_n(x, s) = \mathbb{P}_n(\xi(x, s) \notin \mathcal{C})$  the cond. probability of  $(x, s) \in \gamma(\xi)$ , with  $\gamma(\xi)$  the random excursion set associated to  $\xi$ .

Several Bayesian methods focus on estimating *γ*(f ). For example:

 $\blacktriangleright$  Maximal uncertainty sampling methods:

▶ Maximum misclassification probability [\[Bryan et al. \(2005\)](#page-43-0)]:

 $(X_{n+1},S_{n+1})\in\text{ argmax}\;\;\mathsf{min}(p_n(x,s),1-p_n(x,s))$ 

▶ [\[Ranjan et al. \(2008\)](#page-45-0); [Echard et al. \(2011\)](#page-44-0), ... ]



**Bayesian approach:** Consider  $\xi \sim GP(\mu, k)$  a prior on f. We denote:

- **►**  $\mathbb{P}_n$  the distribution of  $\xi$  given  $\{(X_i, S_i, f(X_i, S_i)), i \leq n\}$ .
- $\blacktriangleright$   $E_n$  the expectation w.r.t.  $P_n$ .
- $\blacktriangleright$   $p_n(x, s) = \mathbb{P}_n(\xi(x, s) \notin \mathcal{C})$  the cond. probability of  $(x, s) \in \gamma(\xi)$ , with  $\gamma(\xi)$  the random excursion set associated to  $\xi$ .

Several Bayesian methods focus on estimating *γ*(f ). For example:

▶ Maximal uncertainty sampling methods:

 $\triangleright$  Maximum misclassification probability [\[Bryan et al. \(2005\)](#page-43-0)]:

 $(X_{n+1},S_{n+1})\in\text{ argmax}\hspace{2mm} \text{min}(p_n(x,s),1-p_n(x,s))$ (x*,*s)∈X×S

▶ [\[Ranjan et al. \(2008\)](#page-45-0); [Echard et al. \(2011\)](#page-44-0), ... ]

#### $\triangleright$  Stepwise uncertainty reduction (SUR) methods:

▶ For instance [\[Bect et al. \(2012\)](#page-43-1); [Chevalier et al. \(2014\)](#page-44-1)]:

$$
(X_{n+1},S_{n+1})\in \underset{(x,s)\in \mathbb{X}\times \mathbb{S}}{\text{argmin}}\ \mathbb{E}_n(\mathcal{H}_{n+1}\mid (X_{n+1},S_{n+1})=(x,s))
$$

with  $\mathcal{H}_n = \int_{\mathbb{X} \times \mathbb{S}} \min(p_n(x, s), 1 - p_n(x, s)) \,dx\mathrm{d}s.$ 

▶ [\[Picheny et al. \(2010\)](#page-44-2); [Marques et al. \(2018\)](#page-44-3), ... ]

#### $\triangleright$  Stepwise uncertainty reduction (SUR) methods:

▶ For instance [\[Bect et al. \(2012\)](#page-43-1); [Chevalier et al. \(2014\)](#page-44-1)]:

$$
(X_{n+1}, S_{n+1}) \in \underset{(x,s) \in \mathbb{X} \times \mathbb{S}}{\text{argmin }} \mathbb{E}_n(\mathcal{H}_{n+1} \mid (X_{n+1}, S_{n+1}) = (x, s))
$$

with  $\mathcal{H}_n = \int_{\mathbb{X} \times \mathbb{S}} \min(p_n(x, s), 1 - p_n(x, s)) \,dx\mathrm{d}s.$ 

 $\blacktriangleright$  [\[Picheny et al. \(2010\)](#page-44-2); [Marques et al. \(2018\)](#page-44-3), ... ]



Figure: Examples of designs (red dots) obtained after  $n = 30$  steps with the maximum misclassification and the 'joint-SUR' criteria.



To estimate  $\Gamma(f)$ , one only needs to focus on **'interesting parts'** of  $\gamma(f)$ .

#### We denote:

 $\blacktriangleright$   $\Gamma(\xi)$  the random quantile set associated to  $\xi$ .

$$
\blacktriangleright \pi_n(x) = \mathbb{P}_n(x \in \Gamma(\xi)),
$$

$$
\blacktriangleright \mathcal{Q}_n = \int_{\mathbb{X}} \min(\pi_n(x), 1 - \pi_n(x)) \, dx.
$$

#### QSI-SUR sampling criterion [\[Ait Abdelmalek-Lomenech et al. \(2023\)](#page-43-2)]:

$$
(X_{n+1}, S_{n+1}) \in \underset{(x,s) \in X \times S}{\text{argmin }} \mathbb{E}_n(\mathcal{Q}_{n+1} | (X_{n+1}, S_{n+1}) = (x,s)),
$$



To estimate  $\Gamma(f)$ , one only needs to focus on 'interesting parts' of  $\gamma(f)$ .

We denote:

 $\blacktriangleright$   $\Gamma(\xi)$  the random quantile set associated to  $\xi$ .

$$
\blacktriangleright \pi_n(x) = \mathbb{P}_n(x \in \Gamma(\xi)),
$$

$$
\blacktriangleright \mathcal{Q}_n = \int_{\mathbb{X}} \min(\pi_n(x), 1 - \pi_n(x)) \, \mathrm{d}x.
$$

QSI-SUR sampling criterion [\[Ait Abdelmalek-Lomenech et al. \(2023\)](#page-43-2)]:

$$
(X_{n+1}, S_{n+1}) \in \underset{(x,s) \in X \times S}{\text{argmin }} \mathbb{E}_n(\mathcal{Q}_{n+1} | (X_{n+1}, S_{n+1}) = (x,s)),
$$

The implementation proposed in [\[Ait Abdelmalek-Lomenech et al. \(2023\)](#page-43-2)] produces good results on moderately difficult examples.



Figure: Median of the proportion of misclassified points vs. number of iterations (left). Example of design obtained (right).



The QSI-SUR criterion is based on

$$
\int_{\mathbb{X}} \min(\pi_n(x), 1 - \pi_n(x)) \, dx.
$$

- ▶ In practice, both the integral involved and the optimization of the criterion are discretized.
- $▶$  Necessity of a collection of points  $x \in \mathbb{X}$  such that their **probability** of misclassification is non-null.

**Main issue:** If  $\Gamma(f)$  is 'small' relatively to X, difficulty to sample relevant points in the set X.



The QSI-SUR criterion is based on

$$
\int_{\mathbb{X}} \min(\pi_n(x), 1 - \pi_n(x)) \, dx.
$$

- $\blacktriangleright$  In practice, both the integral involved and the optimization of the criterion are discretized.
- $▶$  Necessity of a collection of points  $x \in \mathbb{X}$  such that their **probability** of misclassification is non-null.

Main issue: If  $\Gamma(f)$  is 'small' relatively to X, difficulty to sample relevant points in the set X.

### <span id="page-20-0"></span>Table of Contents

[The quantile set inversion problem](#page-1-0)

[Bayesian strategies for QSI](#page-8-0)

#### [Estimation of small quantile sets](#page-20-0)

[Numerical experiments](#page-33-0)

[Conclusion](#page-39-0)



Idea: Multilevel splitting/subset simulation [\[Kahn and Harris \(1951\)](#page-44-4); [Au](#page-43-3) and Beck  $(2001)$ ] to efficiently sample points in  $X$ .

▶ Sequentially estimate a sequence of decreasing quantile sets

$$
\Gamma_0(f) \supset \Gamma_1(f) \supset \ldots \supset \Gamma_K(f) = \Gamma(f),
$$

using a QSI-SUR criterion.

 $\triangleright$  Such sets can be defined by setting

 $\Gamma_k(f) = \{x \in \mathbb{X} : \mathbb{P}(f(x, S) \in C_k) \leq \alpha_k\},\$ 

with  $\alpha_k > \alpha_{k+1}$  and  $C_k \subset C_{k+1}$ .



Idea: Multilevel splitting/subset simulation [\[Kahn and Harris \(1951\)](#page-44-4); [Au](#page-43-3) and Beck  $(2001)$ ] to efficiently sample points in X.

▶ Sequentially estimate a sequence of decreasing quantile sets

$$
\Gamma_0(f) \supset \Gamma_1(f) \supset \ldots \supset \Gamma_K(f) = \Gamma(f),
$$

using a QSI-SUR criterion.

 $\triangleright$  Such sets can be defined by setting

$$
\Gamma_k(f) = \{x \in \mathbb{X} : \mathbb{P}(f(x, S) \in C_k) \leq \alpha_k\},\
$$

with  $\alpha_k > \alpha_{k+1}$  and  $C_k \subset C_{k+1}$ .



```
We now assume C = (-\infty, T].
```
We propose a **SMC-based** algorithm inspired by **BSS** [\[Li \(2012\)](#page-44-5); [Bect](#page-43-4) [et al. \(2017\)](#page-43-4)]

It alternates two distinct phases:

#### ▶ Estimation phase

- $\blacktriangleright$  Define a new intermediary quantile set to estimate.
- $\triangleright$  Sample points  $(X_n, S_n)$  using a QSI-SUR criterion.

#### ▶ Move phase

 $\triangleright$  Concentrate the particles towards the previously estimated set.



```
We now assume C = (-\infty, T].
```
We propose a **SMC-based** algorithm inspired by **BSS** [\[Li \(2012\)](#page-44-5); [Bect](#page-43-4) [et al. \(2017\)](#page-43-4)]

It alternates two distinct phases:

#### ▶ Estimation phase

- $\blacktriangleright$  Define a new intermediary quantile set to estimate.
- $\blacktriangleright$  Sample points  $(X_n, S_n)$  using a QSI-SUR criterion.

#### ▶ Move phase

 $\triangleright$  Concentrate the particles towards the previously estimated set.

[The QSI problem](#page-1-0) [Bayesian strategies for QSI](#page-8-0) **[Estimation of small quantile sets](#page-20-0)** [Numerical experiments](#page-33-0) [Conclusion](#page-39-0)<br>1900 0000000 0000000 0000000 0000000 000

Let  $q_{n,k}$  a density targeting  $\Gamma_k(f) = \{x \in \mathbb{X} : \mathbb{P}(f(x, S) \in C_k) \leq \alpha_k\}$  at step n.

### Estimation phase:

**►** Set  $C_{k+1}$  and  $\alpha_{k+1}$  such that

$$
\text{ESS}\left(\frac{q_{n,k+1}}{q_{n,k}}(x)\right)\approx 30\%.
$$

 $\triangleright$  Sample points

 $(X_n, S_n) \in \text{argmin} J_n(x, s)$ ,

with  $J_n$  a QSI-SUR criterion targeting  $\Gamma_{k+1}(f)$ .

Figure: Temporary quantile set (blue line), final quantile set (green line), particles (blue dots). -  $n = 0$ .



[The QSI problem](#page-1-0) [Bayesian strategies for QSI](#page-8-0) **[Estimation of small quantile sets](#page-20-0)** [Numerical experiments](#page-33-0) [Conclusion](#page-39-0)<br>1900 0000000 0000000 0000000 0000000 000

Let  $q_{n,k}$  a density targeting  $\Gamma_k(f) = \{x \in \mathbb{X} : \mathbb{P}(f(x, S) \in C_k) \leq \alpha_k\}$  at step n.

#### Estimation phase:

**►** Set  $C_{k+1}$  and  $\alpha_{k+1}$  such that

$$
\text{ESS}\left(\frac{q_{n,k+1}}{q_{n,k}}(x)\right)\approx 30\%.
$$

 $\blacktriangleright$  Sample points

 $(X_n, S_n) \in \text{argmin } J_n(x, s)$ ,

with  $J_n$  a QSI-SUR criterion targeting  $\Gamma_{k+1}(f)$ .



Figure: Temporary quantile set (blue line), final quantile set (green line), particles (blue dots) and projection of the sequential design (red dots).  $n = 4$ .

Let  $q_{n,k}$  a density targeting  $\Gamma_k(f) = \{x \in \mathbb{X} : \mathbb{P}(f(x, S) \in C_k) \leq \alpha_k\}$  at step n.

#### Move phase:

When stopping condition is met:

- $\blacktriangleright$  Residual resampling.
- $\blacktriangleright$  Move particles to  $\Gamma_{k+1}(f)$ using MHRW with target density  $q_{n,k+1}$ .
- ▶ Adapt walk's variance to target acceptation rate 25%.



Figure: Temporary quantile set (blue line), final quantile set (green line), particles (blue dots) and projection of the sequential design (red dots).  $n = 5$ .



#### Choice of the target densities:

Natural idea (in the spirit of [\[Dubourg et al. \(2013\)](#page-44-6); [Bect et al. \(2017\)](#page-43-4)]):

$$
q_{n,k}(x) \propto \pi_n^k(x) = \mathbb{P}_n(x \in \Gamma_k(\xi))
$$

▶ Does not admit a closed-form expression.

 $\blacktriangleright$  Expensive to estimate.

**Idea:** Replace  $\pi_n^k(x)$  by  $\mathbb{1}(x \in \Gamma_{n,k}^+)$ . How to define  $\Gamma_{n,k}^+$ ?

Given  $x_0 \in X$ ,  $\mu_n$  and  $\sigma_n$  the posterior mean and standard deviation of  $\xi$ and  $\beta \sim 1$ , consider the **quantile function**:

$$
\xi_n^+(x_0,\cdot) = \mu_n(x_0,\cdot) + \Phi^{-1}(\beta)\sigma_n(x_0,\cdot),
$$



#### Choice of the target densities:

Natural idea (in the spirit of [\[Dubourg et al. \(2013\)](#page-44-6); [Bect et al. \(2017\)](#page-43-4)]):

$$
q_{n,k}(x) \propto \pi_n^k(x) = \mathbb{P}_n(x \in \Gamma_k(\xi))
$$

▶ Does not admit a closed-form expression.

 $\blacktriangleright$  Expensive to estimate.

**Idea:** Replace  $\pi_n^k(x)$  by  $\mathbb{1}(x \in \Gamma_{n,k}^+)$ . How to define  $\Gamma_{n,k}^+$ ?

Given  $x_0 \in X$ ,  $\mu_n$  and  $\sigma_n$  the posterior mean and standard deviation of  $\xi$ and  $\beta \sim 1$ , consider the quantile function:

$$
\xi_n^+(x_0,\cdot) = \mu_n(x_0,\cdot) + \Phi^{-1}(\beta)\sigma_n(x_0,\cdot),
$$

### $C = (-\infty, T]$  and  $\xi(x_0, \cdot)$  is a high quantile

▶  $\mathbb{P}(\xi_n^+(x_0, S) \in C_k)$  is an optimistic estimation of the probability of failure at point  $x_0$ .



Figure: Example of quantile function  $\xi^+_n(x_0,\cdot)$ , with a fixed  $x_0$ . Setting  $\Gamma^+_{n,k} = \Gamma_k(\xi^+_n)$  eliminates  $x_0$  if  $\{x_0 \in \Gamma_k(\xi)\}$  is very improbable. We define the target densities as

$$
q_{n,k}(x) \propto \mathbb{1}(x \in \Gamma_k(\xi_n^+))
$$

**NB:** The MHRW step becomes a constrained random walk.

### $C = (-\infty, T]$  and  $\xi(x_0, \cdot)$  is a high quantile

▶  $\mathbb{P}(\xi_n^+(x_0, S) \in C_k)$  is an optimistic estimation of the probability of failure at point  $x_0$ .



Figure: Example of quantile function  $\xi^+_n(x_0,\cdot)$ , with a fixed  $x_0$ . Setting  $\Gamma^+_{n,k} = \Gamma_k(\xi^+_n)$  eliminates  $x_0$  if  $\{x_0 \in \Gamma_k(\xi)\}$  is very improbable.

We define the target densities as

$$
q_{n,k}(x) \propto \mathbb{1}(x \in \Gamma_k(\xi_n^+))
$$

NB: The MHRW step becomes a constrained random walk.

### $C = (-\infty, T]$  and  $\xi(x_0, \cdot)$  is a high quantile

▶  $\mathbb{P}(\xi_n^+(x_0, S) \in C_k)$  is an optimistic estimation of the probability of failure at point  $x_0$ .



Figure: Example of quantile function  $\xi^+_n(x_0,\cdot)$ , with a fixed  $x_0$ . Setting  $\Gamma^+_{n,k} = \Gamma_k(\xi^+_n)$  eliminates  $x_0$  if  $\{x_0 \in \Gamma_k(\xi)\}$  is very improbable. We define the target densities as

$$
q_{n,k}(x) \propto \mathbb{1}(x \in \Gamma_k(\xi_n^+))
$$

NB: The MHRW step becomes a constrained random walk.

## <span id="page-33-0"></span>Table of Contents

[The quantile set inversion problem](#page-1-0)

[Bayesian strategies for QSI](#page-8-0)

[Estimation of small quantile sets](#page-20-0)

[Numerical experiments](#page-33-0)

[Conclusion](#page-39-0)



For illustration purposes, we take interest in two examples functions of the form



Figure: Representation of  $\Gamma(f_1)$  (left - green curve) and  $\Gamma(f_2)$  (right - green curve).

Relative size of the quantile sets:  $\lambda$ <sub>X</sub>(Γ(f<sub>1</sub>)) = 0.0035 and  $\lambda$ <sub>X</sub>(Γ(f<sub>2</sub>)) = 0.0039. We can first observe that the strategy indeed concentrates the particles and sample relevant points.



Figure: Temporary quantile set (blue line), final quantile set (green line), particles (blue dots), projections of the initial design (black dots) and sequential design (red dots).  $- n = 2, 10, 20$ .



Figure: Temporary quantile set (blue line), final quantile set (green line), particles (blue dots), projections of the initial design (black dots) and sequential design (red dots).  $- n = 2, 15, 35$ .

[The QSI problem](#page-1-0) [Bayesian strategies for QSI](#page-8-0) [Estimation of small quantile sets](#page-20-0) [Numerical experiments](#page-33-0) [Conclusion](#page-39-0)

We compare the accuracy of the estimation obtained by our method against BSS, which focus on the estimation of the joint excursion set

$$
\gamma(f) = \{(x, s) \in \mathbb{X} \times \mathbb{S} : f(x, s) \notin C\}
$$



Figure: Median of the proportion of misclassified points vs. number of evaluations (initial design excluded).

[The QSI problem](#page-1-0) [Bayesian strategies for QSI](#page-8-0) [Estimation of small quantile sets](#page-20-0) **[Numerical experiments](#page-33-0)** [Conclusion](#page-39-0)<br>
COOO COOO COOOO COOOOOO COOOOOO COOOOO COOOOO COOOOO

The results obtained are at least similar to BSS.

In some difficult cases, the necessity of estimating several intermediary quantile sets before focusing on  $\Gamma(f)$  leads to slow convergence.



Figure: Median of the proportion of misclassified points vs. number of evaluations on two other test functions  $f_3$  and  $f_4$ , with  $\lambda_X(\Gamma(f_3)) = 0.0058$ and  $\lambda_X(\Gamma(f_4)) = 0.007$  (initial design excluded).

## <span id="page-39-0"></span>Table of Contents

[The quantile set inversion problem](#page-1-0)

[Bayesian strategies for QSI](#page-8-0)

[Estimation of small quantile sets](#page-20-0)

[Numerical experiments](#page-33-0)

[Conclusion](#page-39-0)

#### Conclusion:

- $\blacktriangleright$  The proposed method allows to accurately estimate small quantile sets.
- ▶ The target densities chosen, although simple, concentrate efficiently the particles in  $X$  towards regions of interest.
- ▶ Batch sequential designs can also be obtained by adapting the criterion.
- $\blacktriangleright$  However, this strategy remains computationally complex.
- **►** For now, the QSI-SUR criterion is not adapted to threshold  $\alpha \sim 0$ .

#### Conclusion:

- $\blacktriangleright$  The proposed method allows to accurately estimate small quantile sets.
- ▶ The target densities chosen, although simple, concentrate efficiently the particles in  $X$  towards regions of interest.
- ▶ Batch sequential designs can also be obtained by adapting the criterion.
- $\blacktriangleright$  However, this strategy remains computationally complex.
- $\blacktriangleright$  For now, the QSI-SUR criterion is not adapted to threshold  $\alpha \sim 0$ .

[The QSI problem](#page-1-0) [Bayesian strategies for QSI](#page-8-0) [Estimation of small quantile sets](#page-20-0) [Numerical experiments](#page-33-0) [Conclusion](#page-39-0)

# Thank you for your attention!

This work has been funded by the French National Research Agency (ANR) in the context of the project SAMOURAI (ANR-20-CE46-0013).

### References

- <span id="page-43-2"></span>Ait Abdelmalek-Lomenech, R., Bect, J., Chabridon, V., and Vazquez, E. (2023). Bayesian sequential design of computer experiments for quantile set inversion. arXiv preprint arXiv:2021.01008v3, submitted to Technometrics (in review).
- <span id="page-43-3"></span>Au, S. and Beck, J. L. (2001). Estimation of small failure probabilities in high dimensions by subset simulation. Probabilistic Engineering Mechanics, 16:263–277.
- <span id="page-43-5"></span>Azzimonti, D., Bect, J., Chevalier, C., and Ginsbourger, D. (2016). Quantifying uncertainties on excursion sets under a gaussian random field prior. SIAM/ASA Journal on Uncertainty Quantification, 4(1):850–874.
- <span id="page-43-1"></span>Bect, J., Ginsbourger, D., Li, L., Picheny, V., and Vazquez, E. (2012). Sequential design of computer experiments for the estimation of a probability of failure. Statistics and Computing, 22:773–793.
- <span id="page-43-4"></span>Bect, J., Li, L., and Vazquez, E. (2017). Bayesian Subset Simulations. SIAM/ASA Journal on Uncertainty Quantification, 5:762–786.
- <span id="page-43-6"></span>Bect, J., Vazquez, E., et al. (2022). STK: a Small (Matlab/Octave) Toolbox for Kriging. Release 2.7.0.
- <span id="page-43-7"></span>Branin, F. H. and Hoo, S. K. (1972). A method for finding multiple extrema of a function of n variables. In Lootsma, F. A., editor, Numerical methods of Nonlinear Optimization, pages 231–237. Academic Press.
- <span id="page-43-0"></span>Bryan, B., Nichol, R. C., Genovese, C. R., Schneider, J., Miller, C. J., and Wasserman, L. (2005). Active learning for identifying function threshold boundaries. In Weiss, Y., Schölkopf, B., and Platt, J., editors, Advances in Neural Information Processing Systems, volume 18. MIT Press.

### References (cont.)

- <span id="page-44-1"></span>Chevalier, C., Bect, J., Ginsbourger, D., Vazquez, E., Picheny, V., and Richet, Y. (2014). Fast parallel kriging-based stepwise uncertainty reduction with application to the identification of an excursion set. Technometrics, 56(4):455–465.
- <span id="page-44-8"></span>Dixon, L. and Szegö, G. P. (1978). The global optimization problem: an introduction. In Dixon, L. C. W. and Szegö, G. P., editors, *Towards Global Optimization 2*. North Holland.
- <span id="page-44-6"></span>Dubourg, V., Sudret, B., and Deheeger, F. (2013). Metamodel-based importance sampling for structural reliability analysis. Probabilistic Engineering Mechanics, 33:47–57.
- <span id="page-44-0"></span>Echard, B., Gayton, N., and Lemaire, M. (2011). AK-MCS: An active learning reliability method combining Kriging and Monte Carlo Simulation. Structural Safety, 33(2):145–154.
- <span id="page-44-7"></span>Feliot, P. (2017). Une approche Bayésienne pour l'optimisation multi-objectif sous contraintes. Theses, Université Paris Saclay (COmUE).
- <span id="page-44-4"></span>Kahn, H. and Harris, T. E. (1951). Estimation of particle transmission by random sampling. National Bureau of Standards applied mathematics series, 12:27–30.
- <span id="page-44-5"></span>Li, L. (2012). Sequential Design of Experiments to Estimate a Probability of Failure. PhD thesis.
- <span id="page-44-3"></span>Marques, A., Lam, R., and Willcox, K. (2018). Contour location via entropy reduction leveraging multiple information sources. In Advances in Neural Information Processing Systems 31 (NeurIPS 2018), pages 1–11.
- <span id="page-44-2"></span>Picheny, V., Ginsbourger, D., Roustant, O., Haftka, R. T., and Kim, N.-H. (2010). Adaptive designs of experiments for accurate approximation of a target region. Journal of Mechanical Design, 132(7):071008.

### References (cont.)

- <span id="page-45-1"></span>Picheny, V., Wagner, T., and Ginsbourger, D. (2013). A benchmark of kriging-based infill criteria for noisy optimization. Structural and Multidisciplinary Optimization, 48(3):607–626.
- <span id="page-45-0"></span>Ranjan, P., Bingham, D., and Michailidis, G. (2008). Sequential experiment design for contour estimation from complex computer codes. Technometrics, 50(4):527–541.

#### Approximated QSI-SUR criterion:

To reduce the cost, we define  $J_n^k(x, s)$  as the SUR criterion based on

$$
\mathcal{Q}_n^k = \int_{\mathbb{X}} \min(\pi_n^k(x), 1 - \pi_n^k(x)) \, \mathrm{d}x,
$$

where  $\pi_h^k (x) = \mathbb{P}_n \left( x \in \Gamma_k (\tilde{\xi} ) \right)$  and, given a subset of simulation points  $\Theta_{\text{sim}} \subset X \times S$ .

$$
\tilde{\xi}(x,s)=\mathbb{E}_n[\xi(x,s)\,|\,\xi(\Theta_{sim})].
$$

NB: a close idea is exploited in [\[Azzimonti et al. \(2016\)](#page-43-5)].

#### **Extension to batch designs:** (inspired by [\[Feliot \(2017\)](#page-44-7)])

Given a batch size parameter r, for  $1 \leq j \leq r$ :

- $\blacktriangleright$  Select  $(X_{n+j}, S_{n+j})$  according to QSI-SUR criterion.
- ▶ Sample a random realization  $z_j$  of  $\xi(X_{n+j}, S_{n+j})$  according to  $\mathbb{P}_{n+i-1}$ .
- ▶ Consider  $z_j$  as value of  $f(X_{n+j}, S_{n+j})$  until  $j = r$ .

When 
$$
j = r
$$
: evaluate  $f$  at  $\{(X_{n+j}, S_{n+j}), 1 \le j \le b\}$ .

NB: This procedure produces 'approximated' batchs. The exact batchs

$$
\{(X_{n+j}, S_{n+j}), j = 1, ..., r\} \in \operatorname*{argmin}_{(x_j, s_j) \in X \times S} \mathbb{E}_n(Q_{n+r} | (X_{n+j}, S_{n+j}) = (x_j, s_j), j = 1, ..., r)
$$

being to computationally expensive (see, e.g [\[Chevalier et al. \(2014\)](#page-44-1)]).

#### Complementary details on numerical experiments

GP prior  $\xi$  trained on an initial design of size  $10 * dim(X \times S)$ .

Parameters are fitted using reML with:

- $\blacktriangleright$  Constant mean function  $\mu$ .
- $\blacktriangleright$  Matérn covariance function k, with regularity parameter *ν* ∈ {1*/*2*,* 3*/*2*,* 5*/*2*,* ∞}

All experiments are conducted in Matlab using the STK toolbox [\[Bect](#page-43-6)] [et al. \(2022\)](#page-43-6)].

#### **Function**  $f_1$ :

- $\blacktriangleright$  X = [0, 10]  $\times$  [0, 15], S = [0, 15].
- $\blacktriangleright$   $P_s$  rescaled Beta(7.5, 1.9)
- $\triangleright$  *C* = [15, +∞),  $\alpha = 0.05$
- $\triangleright$   $g_1$  is the Branin-Hoo function [\[Branin and Hoo \(1972\)](#page-43-7)].

#### **Function**  $f_2$ :

- $\blacktriangleright$  **X** = [-2, 2]<sup>2</sup>, **S** = [-1, 1].
- $\blacktriangleright$   $\mathbb{P}_S$  Gaussian  $\mathcal{N}(1,1)$  truncated on S.

$$
\blacktriangleright \ \mathcal{C} = [9.5, +\infty), \ \alpha = 0.1
$$

▶  $g_2$  is the Camel Back function [Dixon and Szegö (1978)].

#### **Function**  $f_3$ :

- ►  $X = [-1, 1]^2$ ,  $S = [-1, 1]^2$ .
- $\blacktriangleright$   $\mathbb{P}_S$  uniform on S.
- $\triangleright$  *C* = (−∞, 1.065],  $\alpha = 0.5$
- $\blacktriangleright$   $f_3$  is the Hartmann4 function [\[Picheny et al. \(2013\)](#page-45-1)].

#### **Function**  $f_4$ :

$$
\quad \blacktriangleright \ \mathbb{X} = [-2,2]^2, \, \mathbb{S} = [-1,1]^2.
$$

- $\blacktriangleright$   $\mathbb{P}_5$  uniform on S.
- $\triangleright$  *C* = (−∞, 1.4],  $\alpha = 0.1$

 $\blacktriangleright$   $f_4$  is a mean of Camel Back functions

$$
f_4(x,s) = \frac{1}{2}(g_2(x_1,s_1) + g_2(x_2,s_2))
$$

#### Bayesian Subset Simulation - general idea:

Given a function  $f : U \mapsto \mathbb{R}$  and a critical region  $C = (-\infty, T]$ , the BSS [\[Bect et al. \(2017\)](#page-43-4)] algorithm aims at estimating the excursion set

$$
\gamma(f)=\{u\in U\,:\,f(x)\notin C\}.
$$

The algorithm sequentially estimates a sequence of decreasing sets

$$
\gamma_1(f) \supset \ldots \supset \gamma_K(f) = \gamma(f)
$$

using the 'joint-SUR' criterion combined with SMC based on the target densities

$$
q_{n,k}(u)=\mathbb{P}_n(u\in\gamma_k(\xi))
$$

#### Heuristic: When does QSI-SUR outperforms methods focusing on  $\gamma(f)$ ?

Empirically, it appears that the QSI problem must respect two conditions:

$$
\blacktriangleright
$$
 f is not 'too linear'.

▶ Setting

$$
\gamma_{\text{restrict}}(f) = \{ (x, s) \in \mathbb{X} \times \mathbb{S} : f(x, s) \notin C \text{ and } x \in \Gamma(f) \},
$$

the ratio  $\frac{\lambda_{\text{X} \times \text{S}}(\gamma_{\text{restrict}}(f))}{\lambda_{\text{X} \times \text{S}}(\gamma(f))}$  is small.

Complementary results on QSI-SUR (from [\[Ait Abdelmalek-Lomenech](#page-43-2) [et al. \(2023\)](#page-43-2)]) - 1/2.



Figure: Median of the proportion of misclassified points vs. number of steps. (100 runs)

Complementary results on QSI-SUR (from [\[Ait Abdelmalek-Lomenech](#page-43-2) [et al. \(2023\)](#page-43-2)]) - 2/2.



Figure: Median of the proportion of misclassified points vs. number of steps. (100 runs)