Obliquely Reflected Backward Stochastic Differential Equations

J-F Chassagneux (Université Paris Diderot) joint work with A. Richou (Université de Bordeaux)

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Results in the Markovian case Existence Uniqueness

Extension and concluding remarks

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Introduction

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BSDEs

Backward Stochastic Differential Equation (Y, Z)

$$Y_t = \xi + \int_t^T F(t, Y_t, Z_t) \mathrm{d}t - \int_t^T (Z_t)' \mathrm{d}W_t$$

with $\xi \in L^2$ and F possibly random function.

• Markovian Setting: Forward-Backward SDEs for (b, σ, f, g) Lipschitz (say):

$$\begin{cases} X_t = X_0 + \int_0^t b(X_u) \mathrm{d}u + \int_0^t \sigma(X_u) \mathrm{d}W_u \\ Y_t = g(X_T) + \int_t^T f(X_t, Y_t, Z_t) \mathrm{d}t - \int_t^T (Z_t)' \mathrm{d}W_t \end{cases}$$

▶ Representation result: $Y_t = u(t, X_t)$ and $Z_t = \sigma(X_t)\partial_x u(t, X_t)$ with u solution to

$$\partial_t u + b(x)\partial_x u + \frac{1}{2}\operatorname{Tr}[\partial_{xx}^2 u\sigma\sigma'(x)] + f(x, u, \partial_x u\sigma) = 0 \text{ and } u(T, x) = g(x).$$

Motivation: Control Problem, Pricing formula in non linear markets, Numerical probabilistic methods for PDEs, etc.

Reflected BSDEs Motivation: around switching problems

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Reflected BSDEs

• One dimensional, 'Simply' reflected BSDEs on the boundary I(X): (Y, Z, K)

$$Y_{t} = g(X_{T}) + \int_{t}^{T} f(X_{t}, Y_{t}, Z_{t}) dt - \int_{t}^{T} (Z_{t})' dW_{t} + \int_{t}^{T} dK_{t}$$

(C1) $Y_{t} \ge I(X_{t})$ (constrained value process)
(C2) $\int_{0}^{T} (Y_{t} - I(X_{t})) dK_{t} = 0$ ("optimality" of K)

K increasing & continuous.

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K increasing & continuous.

Linked to optimal stopping (pricing of US options)

$$Y_t = \mathrm{ess}\sup_{\tau \in \mathcal{T}_{[0,T]}} \mathbb{E} \bigg[g(X_\tau) + \int_t^\tau f(X_t, Y_t, Z_t) \mathrm{d}t | \mathcal{F}_t \bigg]$$

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Doubly reflected BSDEs: upper boundary (Dynkin games)

Reflected BSDEs Motivation: around switching problems

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Multidimensional case

• Let $\mathcal{D} \subset \mathbb{R}^d$ be an open convex domain: (Y, Z, K)

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▶ Direction of Reflection? n(y) denotes the (set of) outward normal for $y \in \partial D$

- 1. Normal reflection: $dK_t = -\Phi_t dt$, $\Phi_t \in n(Y_t)$ increasing
- 2. Oblique reflection: $dK_t = -H(X_t, Y_t, Z_t)\Phi_t dt$, *H* matrix valued s.t. $\nu(X_t, Y_t, Z_t) = H_t n(Y_t)$ is the oblique outward direction.

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- Minimality condition: $\int_0^T |\Phi_t| \mathbf{1}_{\{Y_t \notin \partial \mathcal{D}\}} dt = 0.$
- ▶ Key point: start from v to build H symmetric → this follows Lions & Sznitman (84)
- Note: we require $\langle \frac{\nu}{\|\nu\|}, \frac{n}{\|n\|} \rangle \geq \epsilon > 0$.

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Starting and Stopping problem (1)

Hamadene and Jeanblanc (01) - Carmona and Ludkovski (10):

- Consider e.g. a power station producing electricity whose price is given by a diffusion process X: dX_t = b(X_t)dt + σ(X_t)dW_t
- Management decide to produce electricity only when it is profitable enough.
- ► The management strategy is (θ_j, α_j) : θ_j is a sequence of stopping times representing switching times from mode α_{j-1} to α_j.

 $(a_t)_{0 \le t \le T}$ is the state process (the management strategy).

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Starting and Stopping problem (2)

Following a strategy a from t up to T, gives

$$J(a,t) = \int_t^T f^{a_s}(X_s) \mathrm{d}s - \sum_{j \ge 0} c \mathbf{1}_{\{t \le heta_j \le T\}}$$

• The optimisation problem is then (at t = 0, for $\alpha_0 = 1$)

$$Y_0^1 := \sup_a \mathbb{E}[J(a,0)]$$

At any date $t \in [0, T]$ in state $i \in \{1, 2\}$, the value function is Y_t^i .

Y is solution of a coupled optimal stopping problem

$$\begin{aligned} \mathbf{Y}_{t}^{1} &= \mathrm{ess}\sup_{t \leq \tau \leq T} \mathbb{E}\left[\int_{t}^{\tau} f(1, X_{s}) \mathrm{d}s + (\mathbf{Y}_{\tau}^{2} - c) \mathbf{1}_{\{\tau < T\}} \mid \mathcal{F}_{t}\right] \\ \mathbf{Y}_{t}^{2} &= \mathrm{ess}\sup_{t \leq \tau \leq T} \mathbb{E}\left[\int_{t}^{\tau} f(2, X_{s}) \mathrm{d}s + (\mathbf{Y}_{\tau}^{1} - c) \mathbf{1}_{\{\tau < T\}} \mid \mathcal{F}_{t}\right] \end{aligned}$$

Reflected BSDEs Motivation: around switching problems

Oblique RBSDE

• Y is the solution of the following system of reflected BSDEs:

$$Y_{t}^{i} = \int_{t}^{T} f^{i}(X_{s}, Y_{s}, Z_{s}) ds - \int_{t}^{T} (Z_{s}^{i})' dW_{s} + \int_{t}^{T} dK_{s}^{i}, i \in \{1, 2\},$$
(C1) $Y_{t}^{1} \ge Y_{t}^{2} - c$ and $Y_{t}^{2} \ge Y_{t}^{1} - c$ (constraint - coupling)
(C2) $\int_{0}^{T} (Y_{s}^{1} - (Y_{s}^{2} - c)) dK_{s}^{1} = 0$ and $\int_{0}^{T} (Y_{s}^{2} - (Y_{s}^{1} - c)) dK_{s}^{2} = 0$





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More generally, d modes, the convex set is

$$\mathcal{D}=\set{y\in \mathbb{R}^d|y^i\geq \max_j(y_j-c) \ , \ 1\leq i\leq d}$$

► d=2:



Reflected BSDEs Motivation: around switching problems

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Randomised switching

▶ $d \ge 3$ modes, (ξ_n) homogeneous Markov Chain on $\{1, \ldots, d\}$ s.t. $\mathbb{P}(\xi_n = j | \xi_{n-1} = i) = p_{ij}$ and $p_{ii} = 0$.

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- The agent decides when to switch (τ_n) but the state is randomly chosen according to (ξ_n). The agent knows the (p_{ij}).

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- The agent decides when to switch (τ_n) but the state is randomly chosen according to (ξ_n). The agent knows the (p_{ij}).
- $Y_0 = \sup_a \mathbb{E}[J(a, 0)]$, J reward following strategy a.

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- The agent decides when to switch (τ_n) but the state is randomly chosen according to (ξ_n). The agent knows the (p_{ij}).
- $Y_0 = \sup_a \mathbb{E}[J(a, 0)]$, J reward following strategy a.
- The solution is given by an obliquely reflected BSDEs with domain

$$\mathcal{D} := \{ y \in \mathbb{R}^d \mid y^j > \sum_i p_{ji} y^i - c \}$$

The reflection is along the axis.

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Known results

 Normal Reflection: Existence and uniqueness in classical L², Lipschitz setting for a fixed domain (Gegout-Petit & Pardoux 95), some extension to random domain (Ma & Yong 99)

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Known results

- Normal Reflection: Existence and uniqueness in classical L², Lipschitz setting for a fixed domain (Gegout-Petit & Pardoux 95), some extension to random domain (Ma & Yong 99)
- Oblique Reflection:
 - 1. Reflection in an orthant: Ramasubramanian (02), f := f(Y).
 - Switching problem: fⁱ(Y, Z) = fⁱ(Y, Zⁱ) (do not cover non-zero sum game) contributions by several authors: Hu & Tang (08), Hamadene & Zhang (09), C., Elie & Kharroubi (11)
 - 3. Attempt to general case: existence of a (weak) solution when f = f(Y) and H = H(t, Y) is Lipschitz in the Markovian setting. By Gassous, Rascanu & Rotenstein (15)

Existence Uniqueness

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Existence Uniqueness

Penalised BSDEs

▶ Let $y \mapsto \varphi_n(y) = nd^2(y, D)$, $\nabla \varphi_n(y) = 2n(y - P(y))$, P normal projection:

$$Y_t^n = g(X_T) + \int_t^T f(Y_s^n, Z_s^n) \mathrm{d}s - \int_t^T Z_s^n \mathrm{d}W_s - \int_t^T H(Y_s^n, Z_s^n) \nabla \varphi_n(Y_s^n) \mathrm{d}s$$

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Existence Uniqueness

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▶ A priori estimates yields $(Y, Z) \in S^2 \times H^2$ with norms uniform in *n* and

$$\sup_{t} \mathbb{E}\left[nd^{2}(Y_{t}^{n}, \mathcal{D}) + \int_{t}^{T} |\nabla \varphi_{n}(Y_{s}^{n})|^{2} \mathrm{d}s\right] \leq C$$

 \hookrightarrow At the limit $n \to \infty$ the process Y^n is in \mathcal{D} !

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- Is there a limit and does it satisfy an oblique RBSDE?
- Show that uⁿ(t, x) where uⁿ(t, X_t) = Yⁿ_t is a Cauchy sequence. → Need σ non degenerated, use weak convergence: idea from Hamadene, Lepeltier, Peng (97) in the red book...

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Methods

- 1. Linking (Y, Z, K) to a control problem e.g. (randomised) switching.
- 2. Trying a stability approach: compare two solutions of the RBSDEs...

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Stability approach: $H^{-1} = H^{-1}(t, y)$ and \mathcal{D} are smooth and \mathcal{D} or g is bounded by Λ .

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Stability approach: $H^{-1} = H^{-1}(t, y)$ and \mathcal{D} are smooth and \mathcal{D} or g is bounded by Λ .

• Apply Ito's formula to $||Y_t - Y'_t||^2$... works well in the normal case, thanks to

$$\langle y'-y,y-\mathcal{P}(y)
angle \leq 0 \ , \ y\in \mathbb{R}^d, y'\in ar{\mathcal{D}}$$

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Stability approach: $H^{-1} = H^{-1}(t, y)$ and \mathcal{D} are smooth and \mathcal{D} or g is bounded by Λ .

• Apply Ito's formula to $||Y_t - Y'_t||^2$... works well in the normal case, thanks to

$$\langle y'-y,y-\mathcal{P}(y)
angle \leq 0 \ , \ y\in \mathbb{R}^d, y'\in ar{\mathcal{D}}$$

Apply Ito's formula to (Y_t − Y'_t)^TH(t, Y_t)⁻¹(Y_t − Y'_t): extra terms appear coming from covariation terms and reflections.

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Existence Uniqueness

Methods

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- Apply Ito's formula to (Y_t − Y'_t)^TH(t, Y_t)⁻¹(Y_t − Y'_t): extra terms appear coming from covariation terms and reflections.
- ► Apply Ito's formula to $\Gamma_t(\alpha,\beta)(Y_t Y'_t)^\top H(t,Y_t)^{-1}(Y_t Y'_t)$ where

$$\Gamma_t = e^{\alpha t + \beta \int_0^t \left(|\Phi_s| + |\Phi'_s| + |Z_s|^2 \right) \mathrm{d}s}$$

Stability result

Small time result

- ▶ Main question: Is Γ integrable? \rightarrow In fact the most difficult part is: $e^{\beta \int_0^t |Z_s|^2 ds}$ integrable?
- We rely on BMO techniques and we are able to get that integrability holds for all $\delta \leq c(\beta, \Lambda)$ (specially does not depend on the Lipschitz constant of g).
- This leads to

$$\sup_{t \leq \delta} \mathbb{E} \Big[\left\| \delta Y_t \right\|^2 \Big] \leq C \mathbb{E} \Big[\left| g(X_T) - \xi' \right|^4 \Big]^{\frac{1}{2}}$$

 \Rightarrow uniqueness in small time

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Arbitrary time result

Divide interval [0, T] in small interval and apply stability result using Backward induction: Importantly c(β, Λ) is fixed in this procedure.

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Outline

ntroduction Reflected BSDEs Motivation: around switching problems

Results in the Markovian case Existence Uniqueness

Extension and concluding remarks

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Non markovian case:

- ► Use the stability approach to obtain that Yⁿ is a Cauchy sequence (smooth setting for H and D)
- Existence for bounded terminal condition, *f* Lipschitz and sublinear in *z*.
- Existence and uniqueness in the path dependent case UC assumption.

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- Existence for bounded terminal condition, *f* Lipschitz and sublinear in *z*.
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Various application to switching problem: RBSDEs for randomised switching is well posed,

For d = 2 and RBSDEs for switching problem, existence and uniqueness for full dependence in Z for f.

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