



Urban-scale quantitative visual analysis

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WHAT MAKES PARIS LOOK LIKE PARIS?



[Doersch, Singh, Gupta, Sivic, Efros SIGGRAPH'12]

On Raiset hveser is afnohif Paris

...this is Paris



Raise your hand if ...



Humans are good but what about machine?

Can machine recognize visual elements
characterizing an urban area?



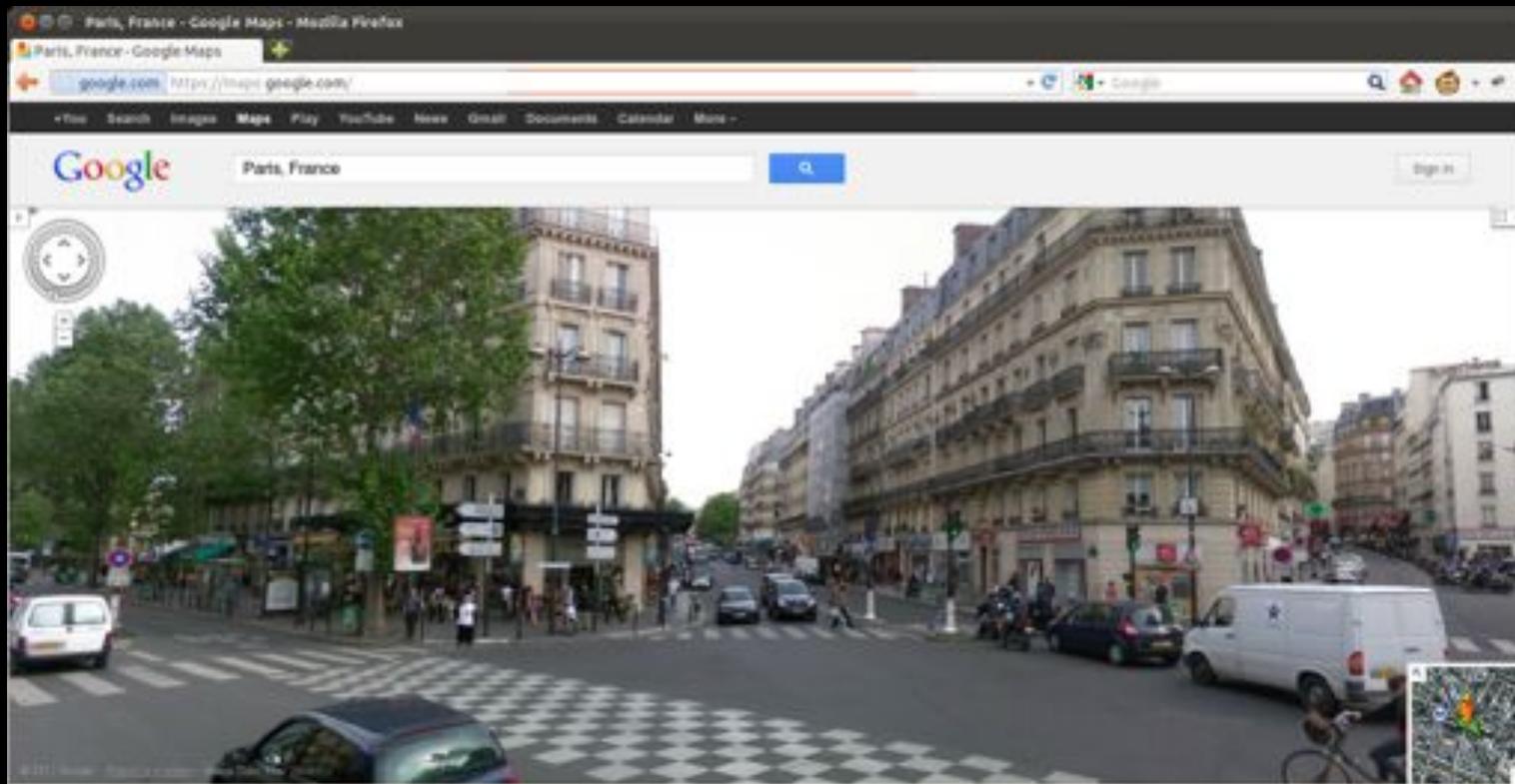
Our Goal:

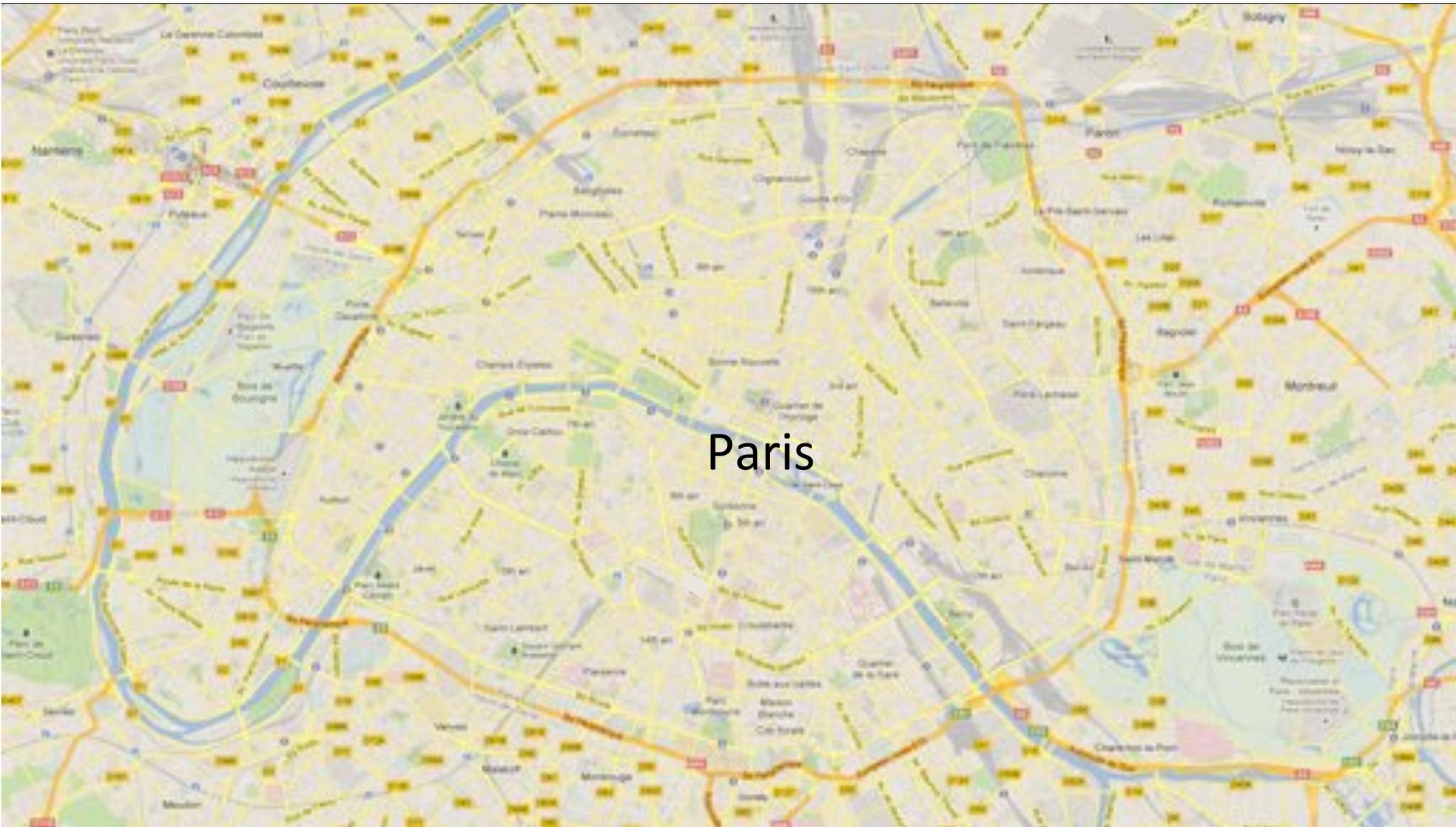
*Given a large geo-tagged image dataset,
we automatically discover **visual elements**
that characterize a geographic location*

Our Hypothesis

- The visual elements that capture Paris:
 - Frequent: Occur often in Paris
 - Discriminative: Are not found outside Paris

Map based imagery provides a comprehensive visual record of a city





Paris





Hundreds of Millions of Patches



Scientific challenges

1. **Difficult learning problem:** How do you represent and automatically learn vocabulary of architectural elements characteristic for a city?



2. **Efficiency:** need to search through large amount of visual data (hundreds of millions of data points)



Problem formulation

Weakly supervised machine learning: [Bach and Harchaoui'08, Xu et al.'04]

Given a set of inputs x_i and supervisory meta-data y_i , $i=1,\dots,N$
learn **vocabulary** $\hat{z}_i = f(x_i)$ by solving

$$\min_{f,z} \underbrace{\sum_{i=1}^N \ell(z_i, f(x_i))}_{\text{Discriminative loss on data}} + \underbrace{\Omega(f)}_{\text{Regularization}}$$

$$\text{s.t. } \underbrace{g(z) = y}_{\text{Supervision from available meta-data}}$$

Supervision from available meta-data

Input $\{x_i\}$: Millions of image patches extracted from street-view images from different cities
Supervisory meta-data $\{y_i\}$: geo-tags for each image

Our Approach



Our Approach

I. Use geo-supervision

— Paris
— Not Paris



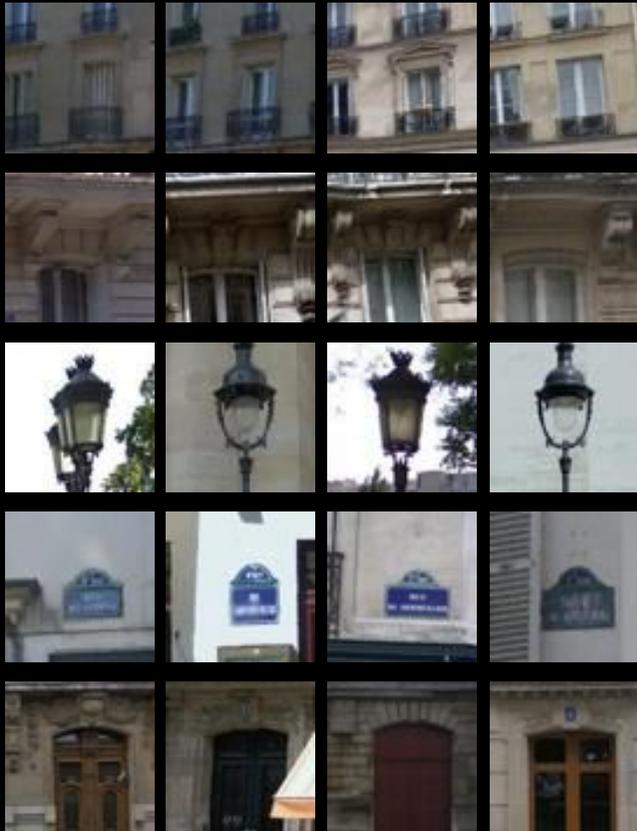
Our Approach

- I. Use geo-supervision
- II. Find groups that discriminate positive from negative data

— Paris
— Not Paris



Paris: A Few Top Elements





Elements from Prague



Elements from London



Elements from Barcelona





Google earth



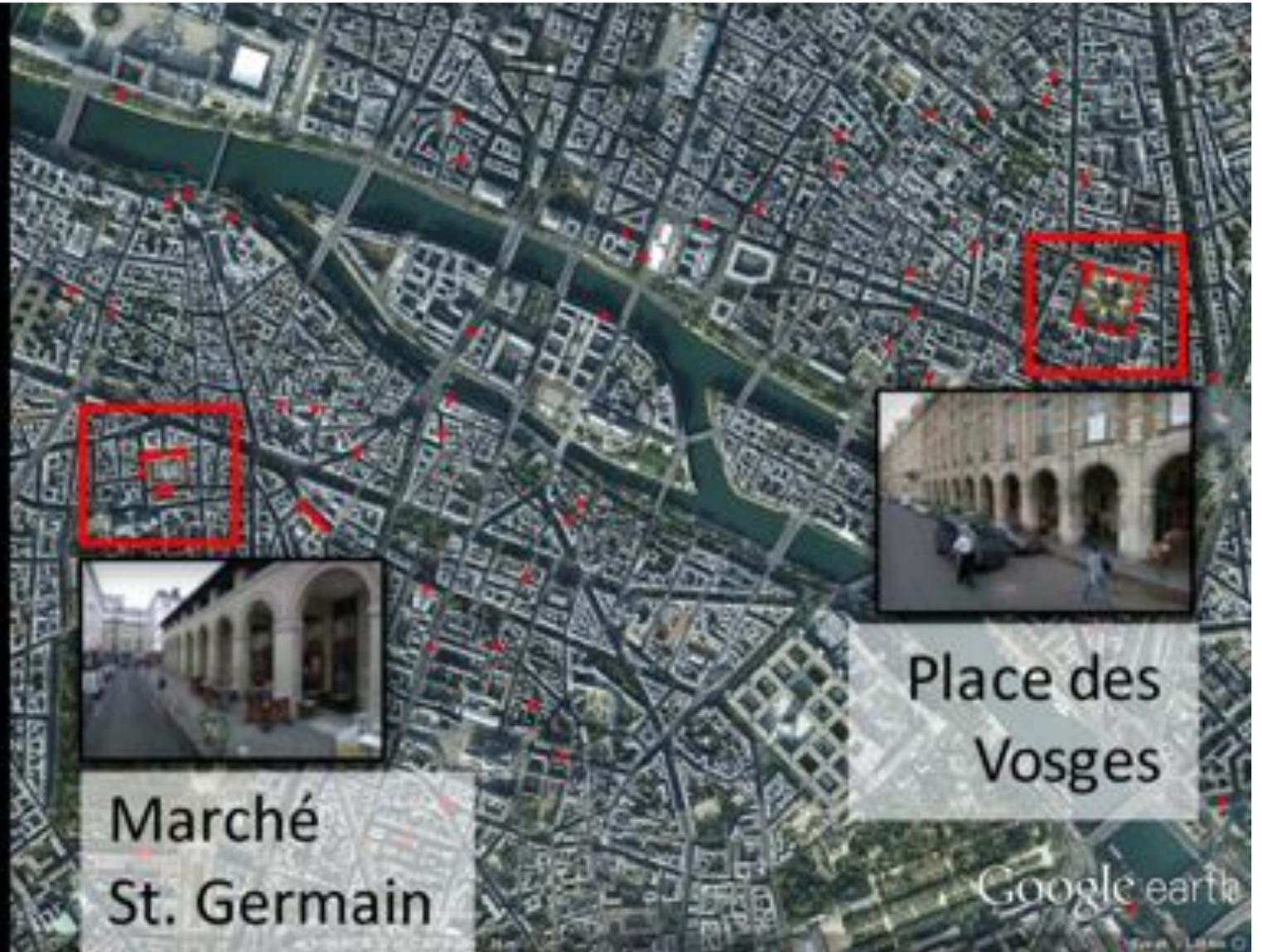






Place des Vosges

Google earth



Marché
St. Germain



Place des
Vosges

Google earth





London

Prague

Paris

Milan

Barcelona

Google earth

Images © 2012 TerraMetrics
Data SRTM, NOAA, U.S. Navy, NGA, GEBCO
Map © 2012 Google
© 2012 Google Earth
48°27'14.47" N, 1°12'28.47" E, elev. 388 m

Fransky Date: 8/14/2014

Eye alt: 2000.01 km

London

Prague

Paris

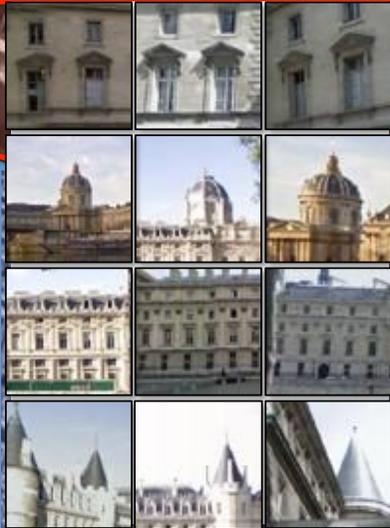
Milan

Barcelona



Images © 2012 TomTom
Data © 2012 NOAA, U.S. Navy, NGA, GEBCO
Image © 2012 GeoEye
© 2012 GeoEye
48°27'14.47" N, 1°12'28.47" E, elev. 388 m

Google earth



Louvre /Opera



Marais



Latin Quarter

Google earth

Analyze architecture style over time

Geo-located Google street-view images



Cadastral maps



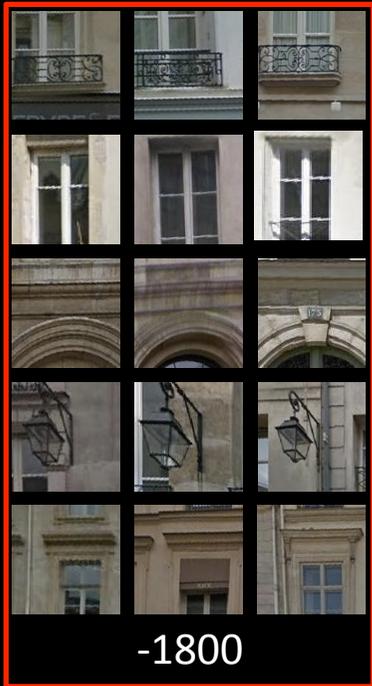
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[Lee, Maissonneuve, Efros, Sivic, 2014]

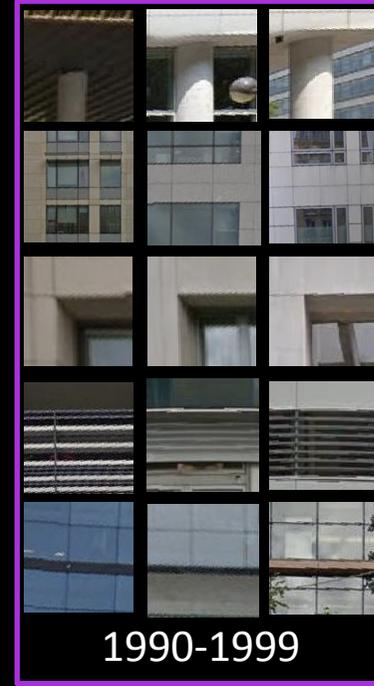
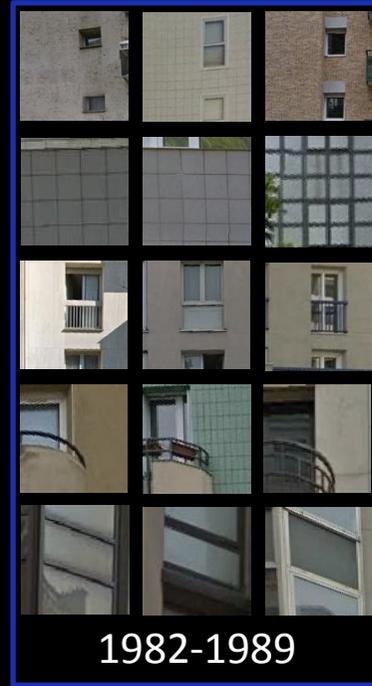
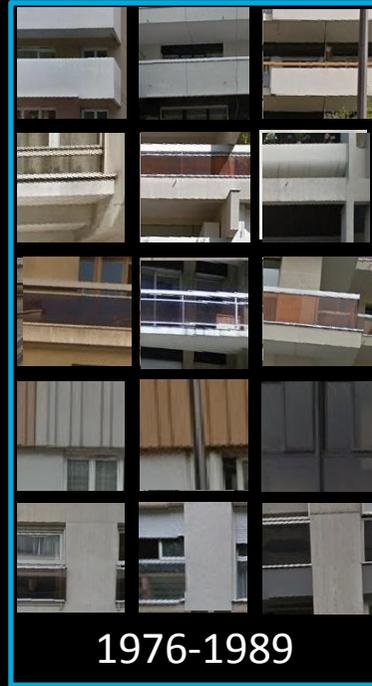
Cadastral map of Paris: 128k buildings with meta-data



Visual elements specific for a time-period



Visual elements specific for a time-period



On Relating Visual Elements to City Statistics

Sean M. Arietta*
University of California, Berkeley

Maneesh Agrawala†
University of California, Berkeley

Ravi Ramamoorthi‡
University of California, Berkeley



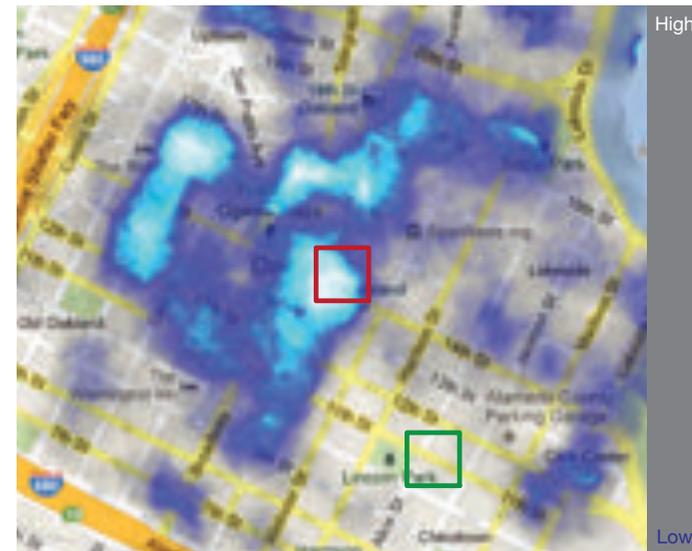
(a) Predicted High Theft Location in Oakland



(b) Predicted Low Theft Location in Oakland



(c) Visual Elements for Thefts in San Francisco



(d) Predicted Theft Rate in Oakland

What next?

I. **Historical** urban visual record



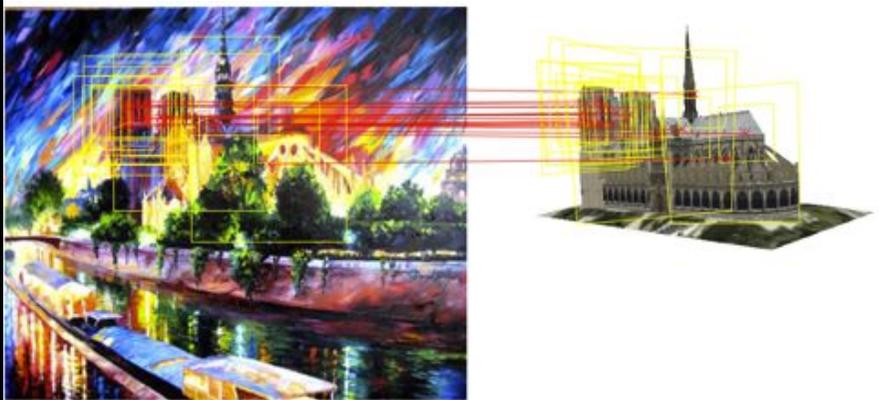
II. **3D** urban visual record



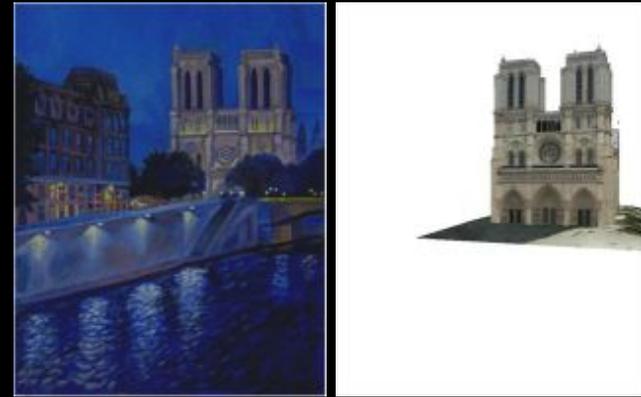
III. **Dynamic** urban visual record



Example: painting to 3D model alignment



Painting



Painting



Historical photograph



Sketch



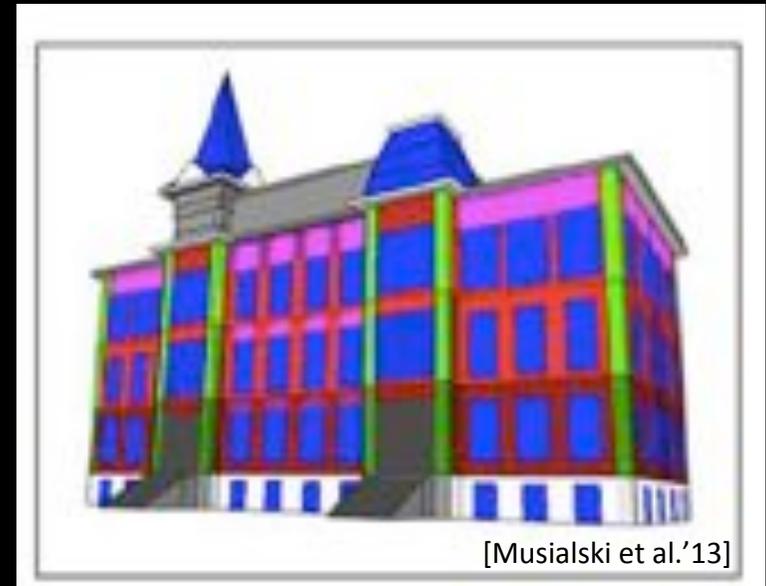


II. 3D urban visual record



Goal: detailed **semantic 3D reconstruction** for simulation of urban environments (e.g. noise, pollution, energy consumption).
[ANR project SEMAPOLIS, 2013-2016]

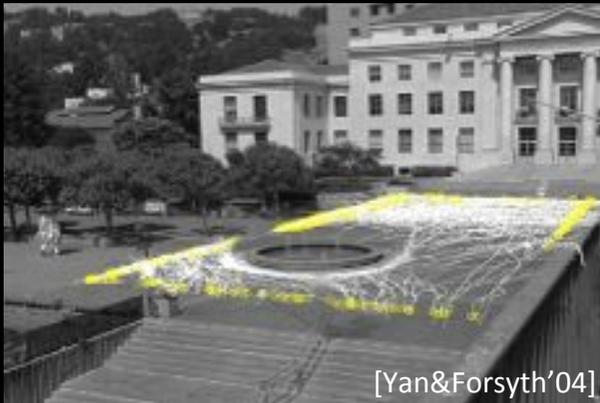
Towards semantic 3D reconstruction



Goal: detailed **semantic 3D reconstruction** for simulation of urban environments (e.g. noise, pollution, energy consumption).
[ANR project SEMAPOLIS, 2013-2016]

III. Dynamic urban visual record

Cameras around us



Public space cameras



Car cameras



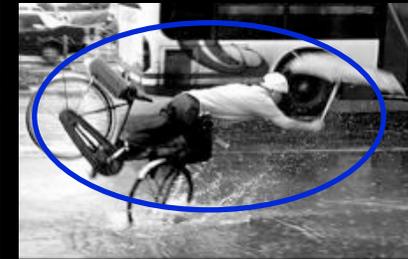
Citizen cameras

Towards large-scale temporal analysis

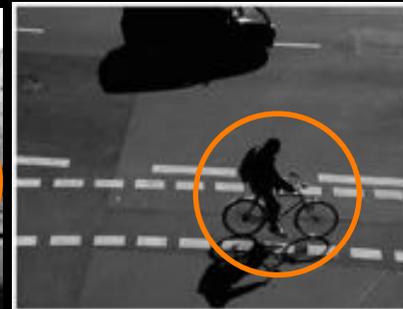
Extract statistics of **human behaviors** across a city over time



crossing street



"bicycle accident"

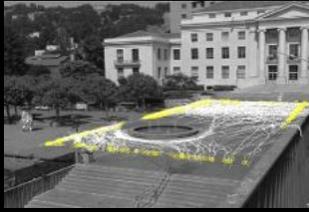


riding bicycle

Applications: new ways to optimize road safety, urban planning or commerce in cities

Summary

- Multiple data sources and archives provide a **comprehensive visual record** of cities.



- Goal: develop **visual quantitative analysis** tools to:
 - understand, simulate and optimize urban environments