

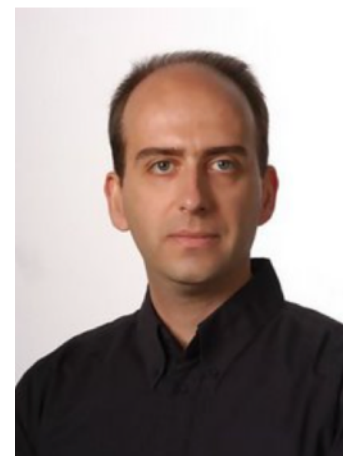
Regular Model Checking Revisited

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[Joint with Philipp Rümmer]

Acknowledgment



Outline of the talk

- RMC background and some history
- Reformulation of RMC in terms regular synthesis problem
- Brief overview of automata learning for regular synthesis

Parameterized Systems

Definition: An infinite family of finite-state systems

$\mathcal{F} := \{\text{Distributed Protocol with } n \text{ finite processes} : n \in \mathbb{N}\}$

Plethora of examples from distributed computing, e.g., Dining Philosopher protocol, Bakery Protocol, etc.

Undecidability for simple safety properties (Apt & Kozen'86)

Lots of work on parameterized systems dating back to 1990s by Emerson, Pnueli, and others

Regular Model Checking

A symbolic framework for verifying parameterized systems

Symbolic model checking with rich assertional languages

Y Resten, O Maler, M Marcus, A Pnueli... - ... Conference on Computer

... In this section we demonstrate the use of the class of regular **languages**. As a running example, we ... Going back to the use of FSAs **language**, we observe that if A is an automaton characterizing a set of s

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Regular model checking

A Bouajjani, B Jonsson, M Nilsson, T Touili - International Conference on ..., 2000 - Springer

... We present **regular model checking**, a framework for algorithmic verification of infinite- systems with, ... States are represented by strings over a finite alphabet and the transition relation by a **regular** length-... We introduce the program **model** used in **regular model cl**

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Verifying systems with infinite but regular state spaces

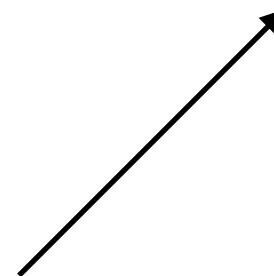
P Wolper, B Boigelot - ... Conference on Computer Aided Verification, 1998 - Springer

... to consider a larger class of **systems**, but to be satisfied with a ... of closed **systems** wr **infinite state space** originates from the ... The focus on closed **systems** is typical of many

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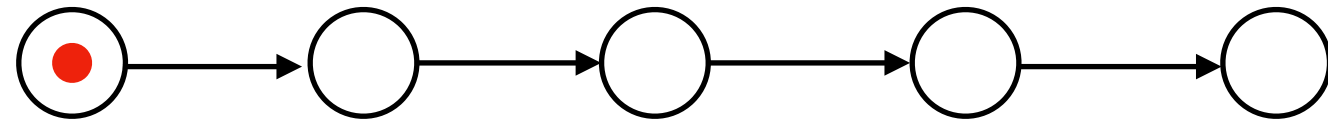
Crux:

1. Model configuration as a string
2. Represent an infinite set of strings using **regular languages**
3. Model transition relation by a **length-preserving transducer R**



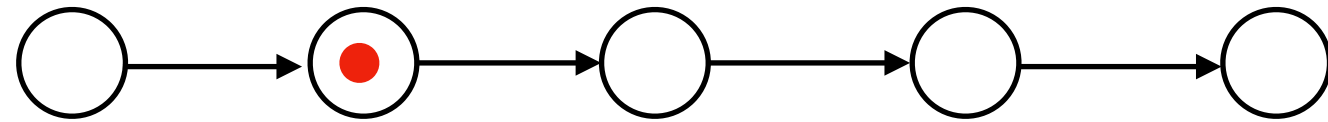
other notions of transducers (e.g. over trees, ω -words) are possible, but we restrict to this for simplicity

Token Passing Protocol



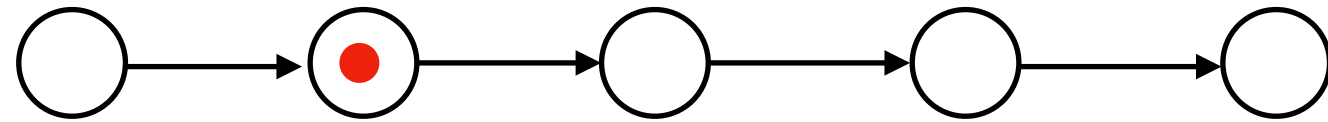
$t = 1$

Token Passing Protocol



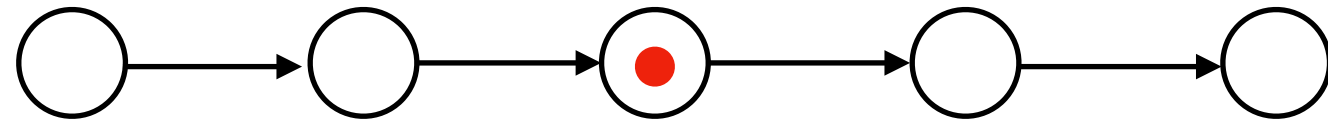
$t = 2$

Token Passing Protocol



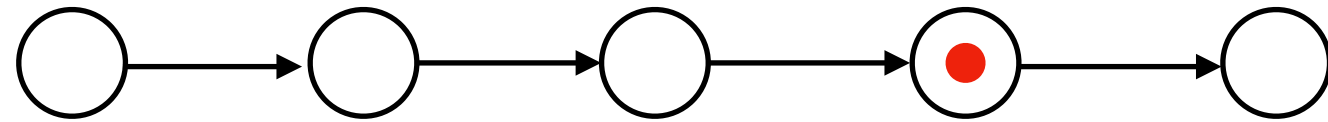
$t = 3$

Token Passing Protocol



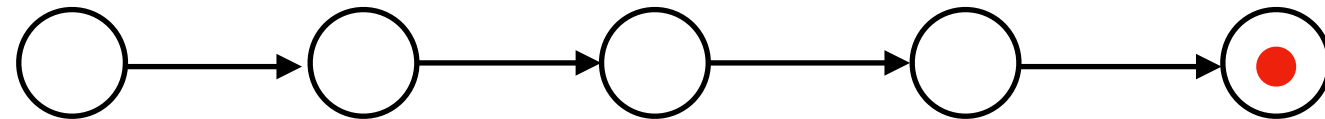
$t = 4$

Token Passing Protocol



$t = 5$

Token Passing Protocol

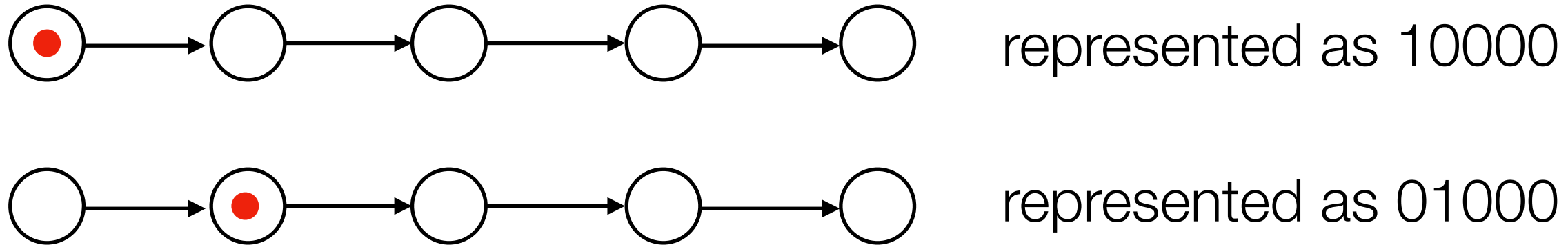


$t = 6$

Safety: prove that the token never disappears

Liveness: prove that the token always reaches the last process (under some fairness assumption)

Model in RMC



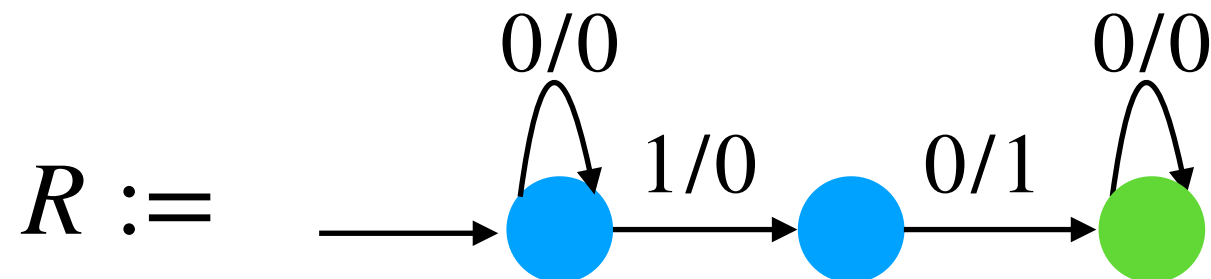
The set *Init* of initial configurations is a regular language:

$$Init = 10^*$$

The set *Bad* of bad configurations is a regular language:

$$Init = 0^*$$

The transition relation (over strings) can be represented as transducer:

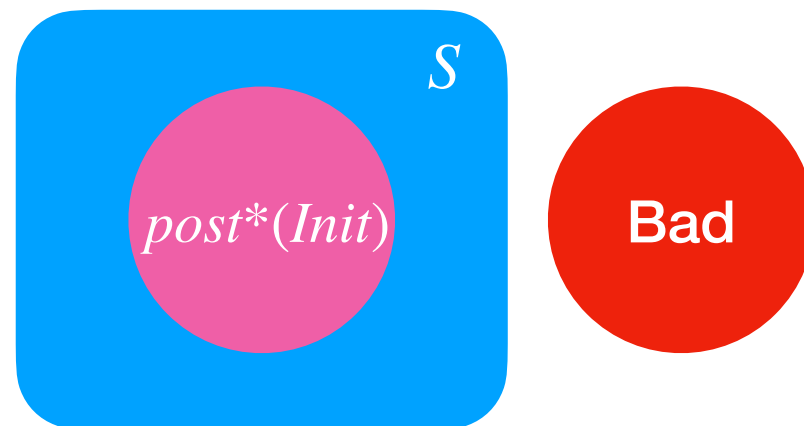


Computing Closures

Reachability Set

Compute a regular language representing $post_R^*(Init)$ or its overapproximation

Useful for safety: $S \supseteq post_R^*(Init) \wedge S \cap Bad = \emptyset \longrightarrow$ safe



For our simple token-passing example:

$$Init = 10^*$$

$$Bad = 0^*$$

$$\text{So: } post^*(Init) = 0^*10^*$$


$$\text{We could also take } S = (0 + 1)^*1(0 + 1)^*$$

Problem and Solutions

Problem with computing closures:

1. Non-regularity
2. Non-termination
3. Regular but extremely large states

General solutions:

1. Acceleration (Abdulla, Jonsson, Nilsson, Orso; Boigelot et al.)
2. Widening (Bouajjani and Touili; Boigelot, Legay, and Wolper; Yu, Alkhalaf, Bultan, and Ibarra)
3. Abstraction (Bouajjani, Habermehl, Vojnar)
4. **Automata learning**  **inspired our new framework**
(pre 2010: Vardhan et al.; Habermehl and Vojnar)
(post 2010: Neider and Jansen; Chen, Hong, Lengal, L., Majumdar, Markgraf, Neider, Rümmer, Stan)

RMC Beyond Safety

So far, **only automata learning** enjoys some success:

Liveness of Randomized Distributed Protocols (L. & Rümmer, Lengal, L., Majumdar, and Rümmer)

Solving Safety Games (Neider and Topcu; Markgraf, Hong, L., Najib and Neider)

Probabilistic Bisimulation and Anonymity Protocols (Hong, L., Majumdar, Rümmer)

Knowledge Reasoning in Multi-Agent Systems (Stan and L.)

Symmetry Detection in RMC (L., Nguyen, Rümmer, and Sun)

RMC as a Regular Synthesis Problem

Deductive Verification

Commonly used in program verification (among others)

```
x = 0
while true:
  x = x + 2
  if x % 2 == 1:
    print "error"
```

Prove "error" is never printed

Safety as "Invariant checking" in some decidable theory:

Init(x) := $x = 0$ Bad(x) := $x \equiv_2 1$

Want to synthesize formula Inv(x) s.t.

$\forall x(\text{Init}(x) \rightarrow \text{Inv}(x))$

$\forall x(\text{Inv}(x) \rightarrow \neg \text{Bad}(x))$

$\forall x(\text{Inv}(x) \rightarrow \text{Inv}(x + 2))$

Satisfied by $\text{Inv}(x) := x \equiv_2 0$

Proposition: Given Presburger Inv, invariant checking is decidable

Decidable Theory for RMC

Which decidable theory of regular languages and transducers is suitable for deductive verification in RMC?

Our answer: universal automatic structure (Blumensath&Grädel'00)

$$\mathfrak{S}_u = \langle \Sigma^* : \preceq, eql, \{L\}_{L \in REG} \rangle$$

Domain is the set of all words over Σ

\preceq is the prefix-of relation: $v \preceq w$ iff v is a prefix of w

eql is the equal-length relation: $eql(v, w)$ iff $|v| = |w|$

L is any regular language: $L(x)$ iff $x \in L$

Theorem (BG'00): FO theory over \mathfrak{S}_u is decidable

Regular relations

r -ary relation over Σ^* definable by a synchronous automaton A

A synchronous automaton is simply an automaton over the alphabet $(\Sigma_{\perp})^r$

where $\Sigma_{\perp} := \Sigma \cup \{ \perp \}$

How A defines a relation?

given a tuple $\bar{v} = (w_1, \dots, w_r)$, write it down as a matrix $M_{\bar{v}}$ with each w_i being the i th row (pad shorter string with \perp)

Example:

$$\bar{v} := (aaa, cb, a) \qquad M_{\bar{v}} := \begin{pmatrix} a & a & a \\ b & c & \perp \\ a & \perp & \perp \end{pmatrix}$$

Regular relations

r -ary relation over Σ^* definable by a synchronous automaton A

A synchronous automaton is simply an automaton over the alphabet $(\Sigma_{\perp})^r$

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How A defines a relation?

Run A on $M_{\bar{v}}$ column-by-column

$$\bar{v} := (aaa, cb, a)$$

$$M_{\bar{v}} := \begin{pmatrix} a & a & a \\ b & c & \perp \\ a & \perp & \perp \end{pmatrix}$$

A

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A

Define: $Rel(A) := \{ \bar{v} : M_{\bar{v}} \in L(A) \}$

Regular Relations in \mathfrak{S}_u

A relation $R \subseteq (\Sigma^*)^r$ is **definable** in \mathfrak{S}_u iff there is an FO formula $\varphi(x_1, \dots, x_r)$ s.t.

$$R = \{(w_1, \dots, w_r) : \mathfrak{S}_u \models \varphi(w_1, \dots, w_r)\}$$

Theorem (BG'00): Regular relations coincide precisely with relations definable in \mathfrak{S}_u

RMC as a Regular Synthesis Problem

Existential Second-Order (ESO) formulas over \mathfrak{S}_u

$$\Phi := \exists R_1, \dots, R_n \varphi$$

where

(1) R_i is a second-order variable of arity r_i

(2) φ is an FO formula over $\mathfrak{S}_u \cup \{R_1, \dots, R_n\}$

ESO model checking over \mathfrak{S}_u :

given an ESO formula Φ over \mathfrak{S}_u , decide if $\mathfrak{S}_u \models \Phi$

Regular Synthesis for RMC:

given an ESO formula Φ over \mathfrak{S}_u , decide if there exist r_i -ary regular relations R_i such that $\mathfrak{S}_u \models \varphi$

Empirically: Regular proofs suffice in practice

Safety as Regular Synthesis

Inputs: (1) regular languages $Init, Bad$,
(2) length-preserving regular relation R

Verification Condition:

$$\exists Inv (Init \subseteq Inv \wedge Inv \cap Bad = \emptyset \wedge post_R(Inv) \subseteq Inv)$$

$\forall x (Init(x) \rightarrow Inv(x))$

$\forall x (Inv(x) \rightarrow \neg Bad(x))$

$\forall x, y (Inv(x) \wedge R(x, y) \rightarrow Inv(y))$

Our simple token-passing example:

$$Init = 10^*$$

$$Bad = 0^*$$

Can take $Inv_1 = 0^*10^*$

or $Inv_2 = (0 + 1)^*1(0 + 1)^*$

Termination as Regular Synthesis

Termination: no infinite runs exist

- Inputs:** (1) regular languages $Init$,
(2) length-preserving regular relation R

Verification Condition:

$\exists Inv \subseteq \Sigma^*, Rank \subseteq \Sigma^* \times \Sigma^*:$

- (1) $Init \subseteq Inv$,
- (2) Inv is inductive
- (3) $Rank$ covers reachable transitions: $R \cap (Inv \times Inv) \subseteq Rank$
- (4) $Rank$ is transitive and irreflexive

Verification Condition:

$\exists Inv \subseteq \Sigma^*, Rank \subseteq \Sigma^* \times \Sigma^*:$

(1) $Init \subseteq Inv,$

(2) Inv is inductive

(3) $Rank$ covers reachable transitions: $R \cap Inv \times Inv \subseteq Rank$

(4) $Rank$ is transitive and irreflexive

Example

Consider a length-preserving regular relation over $\Sigma = \{0,1\}$ that nondeterministically rewrites 10 to 01

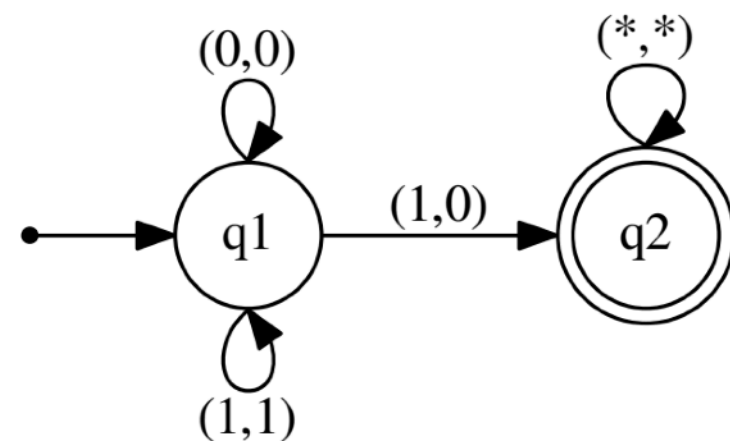
$1010 \rightarrow 0110 \rightarrow 0101 \rightarrow 0011$

$Init = 0\Sigma^*1$

$R := ((0,0) + (1,1))^*(1,0)(0,1)((0,0) + (1,1))^*$

$Inv = \Sigma^*$

$Rank =$



Lexicographic order

Reachability Games as Regular Synthesis

Inputs: (1) regular languages $Init, F$

(2) length-preserving regular relations R_1, R_2 with

$$post_{R_i}^*(\Sigma^*) \cap pre_{R_i}^*(\Sigma^*) = \emptyset \text{ [i.e. strictly alternating.]}$$

Goal: Player 2 (resp. 1) tries to reach (resp. avoid) F from $Init$

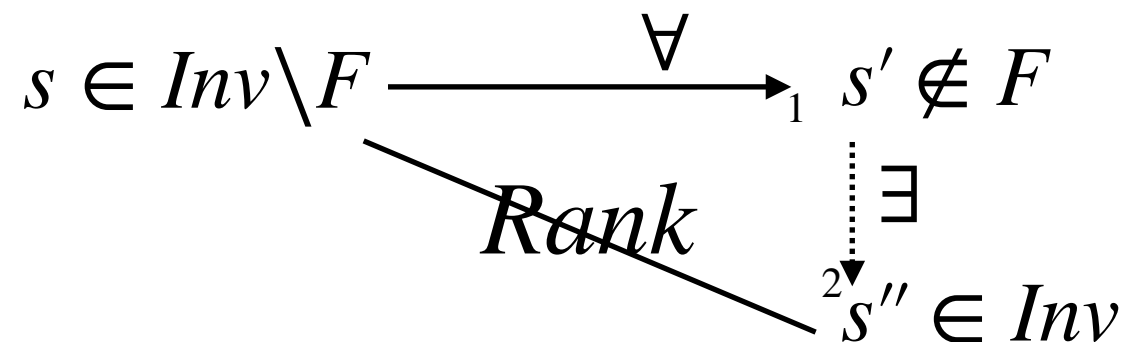
Verification Condition:

$\exists Inv \subseteq \Sigma^*, Rank \subseteq \Sigma^* \times \Sigma^*:$

(1) $Init \subseteq Inv$,

(2) $Rank$ is transitive and irreflexive

(3) Player 0 can force the game to progress according to $Rank$



Example: Take-Away Game

There are n coins on the table



At each turn, a player can take 1,2, or 3 coins

Player who is to move when no coins are left loses

Initially, Player 1 moves

The game strictly alternates

Example: Take-Away Game

Regular modelling:

$$Dom = (p_1 + p_2)1^*0^*$$

e.g. $p_1 111000$ represents Player 1's turn on



Say we want to prove that, starting with $4k$ coins, Player 2 has a winning strategy

$$Init = p_1(1111)^*0^*$$

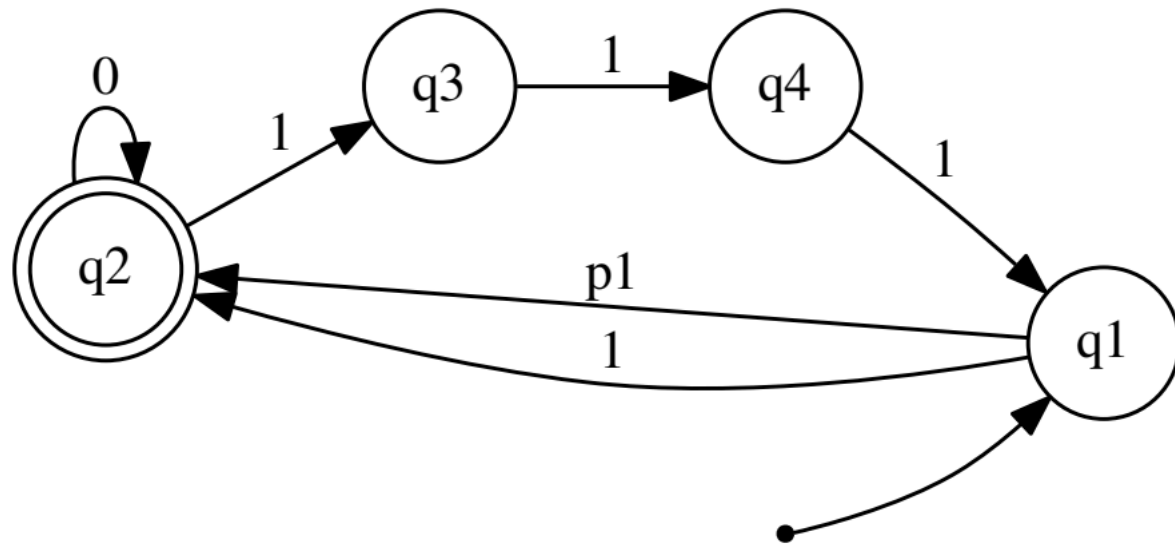
$$F = p_10^*$$

Transitions:

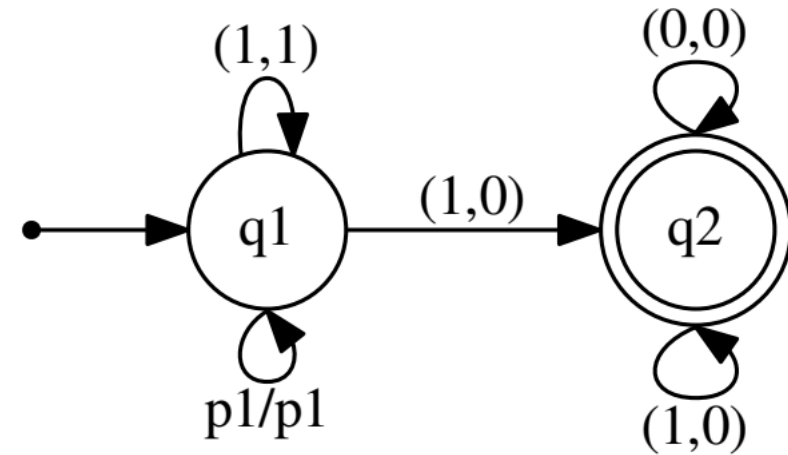
$$R_1 = (p_1, p_2)(1,1)^*((1,0) + (11,00) + (111,000))(0,0)^*$$

$$R_2 = (p_2, p_1)(1,1)^*((1,0) + (11,00) + (111,000))(0,0)^*$$

Regular Proofs



Inv



Rank

Liveness of Randomized Parameterized Systems

Similar regular encoding as in 2-player reachability games is possible

Lots of examples:

1. Lehmann-Rabin dining philosopher protocol
2. Israeli-Jalfon self-stabilizing protocol
3. Herman self-stabilizing protocol
4. ...

**Regular synthesis
algorithms via automata
learning: Brief Overview**

The Gist of Automata Learning (a la Angluin)



Learner tries to learn L_T from Teacher

Typical queries:

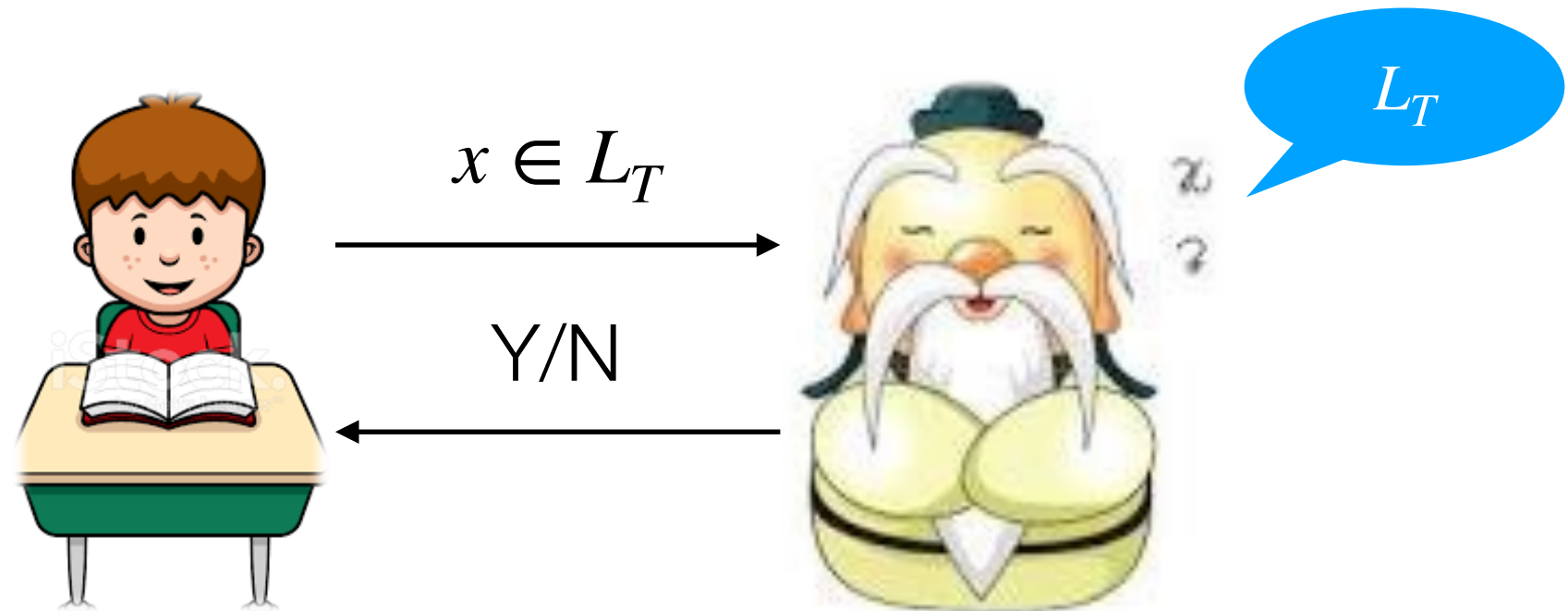
(ME) Membership query: $x \in L_T$

(EQ) Equivalence query: $L = L_T$

Two common variations
in RMC:

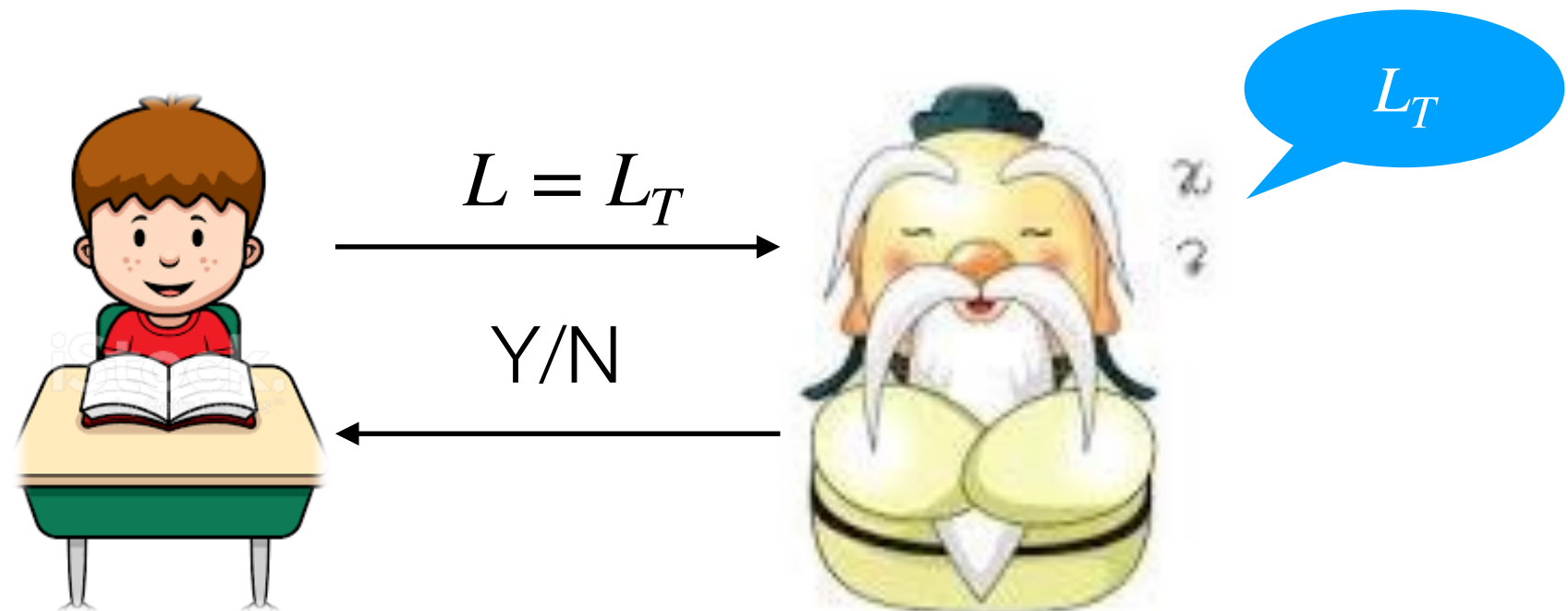
1. EQ only
2. ME+EQ

Membership



Learner tries to learn L_T from Teacher

Equivalence



Learner tries to learn L_T from Teacher

Counterexample: $w \in (L_T \setminus L) \cup (L \setminus L_T)$

Theorem (Angluin): there is a polynomial-time algorithm for inferring an unknown DFA from a teacher with ME+EQ

Problem with Membership

In general, difficult to implement a teacher for membership

Example: to learn a $post_R^*(Init)$, checking whether $w \in post_R^*(Init)$ is typically undecidable

In restricted cases, solutions are available (we will see later)

In general case, it seems a good idea to *dispense with memberships*

Automata Learning with Equivalence (and SAT-solver)

(Heule and Verwer'10)



Learner: keeps a Boolean formula φ representing a set S_φ of DFAs with n states (n is incremented as needed)

Main loop:

1. Learner guesses $A_\varphi \in S_\varphi$ [using SAT-solver]
2. If $L(A_\varphi) \neq L_T$ with cex $w \in \Sigma^*$, incorporate w into φ as a “blocking clause” and goto (1)

Non-Uniqueness of Target Automata

Safety: $\exists Inv(Init \underset{(1)}{\subseteq} Inv \wedge Inv \cap Bad \underset{(2)}{=} \emptyset \wedge post_R(Inv) \underset{(3)}{\subseteq} Inv)$

Inv is not unique in general!

Solution: Teacher *returns a boolean formula as a blocking clause*

For L_T violating (1)-(2), teacher can reply a +/- cex

For L_T violating (3), teacher replies an implication cex

$$v \in L_T \rightarrow w \in L_T$$

Sometimes Membership can be implemented

Membership query: $x \in L_T$

Using finite-state model checker to check if

$$\{y \in \text{Init} : |y| = |x|\} \rightarrow^* x$$

Possible because of
length-preserving assumption

Empirical observation:

when learning with ME+EQ can be applied, it's faster than
SAT-based learning

Experimental Results

| The safety property | | | | | | | | Learning | | | SAT | | | T(O)RMC | | | ARMC |
|---------------------|-----|-------------------|-------------------|-------------------|-------------------|------------------|------------------|----------|------------------|------------------|------|------------------|------------------|---------|------------------|------------------|------|
| Name | #L | S _{init} | T _{init} | S _{tran} | T _{tran} | S _{bad} | T _{bad} | Time | S _{inv} | T _{inv} | Time | S _{inv} | T _{inv} | Time | S _{inv} | T _{inv} | Time |
| Bakery | 3 | 3 | 3 | 5 | 19 | 3 | 9 | 0.0s | 6 | 18 | 0.5s | 2 | 5 | 0.0s | 6 | 11 | 0.0s |
| Burns | 12 | 3 | 3 | 10 | 125 | 3 | 36 | 0.2s | 8 | 96 | 1.1s | 2 | 10 | 0.1s | 7 | 38 | 0.6s |
| Szymanski | 11 | 9 | 9 | 123 | 469 | 13 | 40 | 0.6s | 48 | 528 | t.o. | – | – | 0.9s | 51 | 102 | t.o. |
| German | 581 | 3 | 3 | 17 | 9.5k | 4 | 2112 | 4.8s | 14 | 8134 | t.o. | – | – | t.o. | – | – | 2.3s |
| Dijkstra, linear | 42 | 1 | 1 | 13 | 827 | 3 | 126 | 0.1s | 9 | 378 | 1.7s | 2 | 24 | 6.1s | 8 | 83 | t.o. |
| Dijkstra, ring | 12 | 3 | 3 | 13 | 199 | 3 | 36 | 1.4s | 22 | 264 | 0.9s | 2 | 14 | t.o. | – | – | t.o. |
| Dining Crypt. | 14 | 10 | 30 | 17 | 70 | 12 | 70 | 0.1s | 32 | 448 | t.o. | – | – | 0.2s | 37 | 164 | 1.3s |
| Coffee Can | 6 | 8 | 18 | 13 | 34 | 5 | 8 | 0.0s | 3 | 18 | 0.2s | 2 | 7 | 0.1s | 6 | 13 | 0.0s |
| Herman, linear | 2 | 2 | 4 | 4 | 10 | 1 | 1 | 0.0s | 2 | 4 | 0.2s | 2 | 4 | 0.0s | 2 | 4 | 0.0s |
| Herman, ring | 2 | 2 | 4 | 9 | 22 | 1 | 1 | 0.0s | 2 | 4 | 0.4s | 2 | 4 | 0.0s | 2 | 4 | 0.0s |
| Israeli-Jalfon | 2 | 3 | 6 | 24 | 62 | 1 | 1 | 0.0s | 4 | 8 | 0.1s | 2 | 4 | 0.0s | 4 | 8 | 0.0s |
| Lehmann-Rabin | 6 | 4 | 4 | 14 | 96 | 3 | 13 | 0.1s | 8 | 48 | 0.5s | 2 | 11 | 0.8s | 19 | 105 | 0.0s |
| LR Dining Phil. | 4 | 4 | 4 | 3 | 10 | 3 | 4 | 0.0s | 4 | 16 | 0.2s | 2 | 6 | 0.1s | 7 | 18 | 0.0s |
| Mux Array | 6 | 3 | 3 | 4 | 31 | 3 | 18 | 0.0s | 5 | 30 | 0.4s | 2 | 7 | 0.2s | 4 | 14 | 0.1s |
| Res. Allocator | 3 | 3 | 3 | 7 | 25 | 4 | 11 | 0.0s | 5 | 15 | 0.0s | 3 | 7 | 0.0s | 4 | 9 | 0.0s |
| Kanban | 3 | 25 | 48 | 98 | 250 | 37 | 68 | t.o. | – | – | t.o. | – | – | t.o. | – | – | t.o. |
| Water Jugs | 11 | 5 | 6 | 23 | 132 | 5 | 12 | 0.1s | 24 | 264 | t.o. | – | – | t.o. | – | – | t.o. |

Conclusion

Summary

- RMC can be in general formulated as a regular synthesis problem
- Future work:
 - (1) more general and faster synthesis algorithm for regular synthesis
 - (2) Extension to non-length-preserving RMC and ω -RMC (proof rules are more complicated requiring Ramsey quantifiers)

ANNEX



Strict but Generous Teacher

(FMCAD'17)

Since there could be multiple Inv, we implement a teacher that is:

1. strict: provides hints consistent with minimal invariant $L_T = post^*(Init)$
2. generous: accepts *any* invariant

How to answer membership query $x \in L_T$

$$x \in L_T \text{ IFF } \{y \in \text{Init} : |y| = |x|\} \rightarrow^* x$$

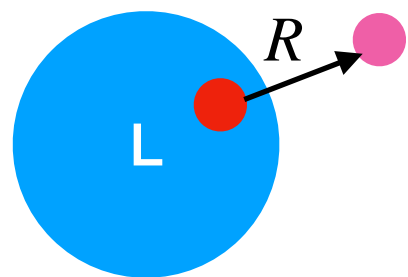
use finite-state model checker

How to answer equivalence query $L = L_T$

$$\text{Init} \subseteq L \wedge L \cap \text{Bad} = \emptyset \wedge R(L) \subseteq L$$

use automata algorithm

Counterexample for $R(L) \subseteq L$



- is NOT reachable (or ● \in Bad) \Rightarrow remove ● from L
- is reachable \Rightarrow add ● to L