

# Functional data analysis : modelling curves variations

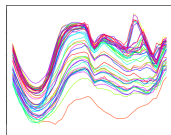
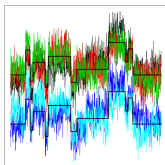
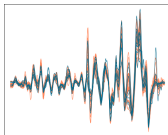
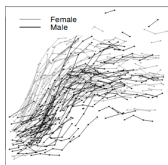
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Journées sur les données temporelles  
INRIA Rennes - 25 mars 2019

- 1 Introduction : functional data
- 2 Nonparametric functional regression
- 3 Modelling individual variability
  - Functional Mixed-Effects model
  - Estimation issue
  - Model-based clustering
  - Deformation models
- 4 Conclusion and Perspectives

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- More and more research fields collect **curve-like data**
  - ▷ Growth curves, spectrometry data, genomic data, weather data...



- The term **functional data** gathers different types of data
  - Measured along time or space or any continuum
  - Sparse data
  - Dense data (high throughput)
  - With a common or not time grid

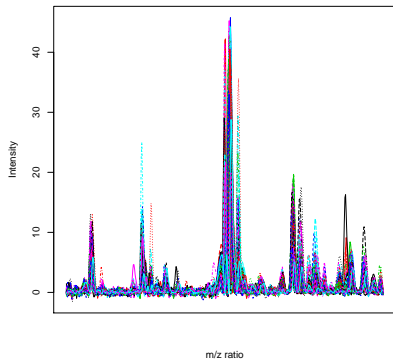
- Historically, functional data appears around the 90's
- Their development has been caught between
  - Time series analysis
  - Longitudinal data analysis
- As for time series and longitudinal data, they consist of observations  $(y_1^{(i)}, \dots, y_T^{(i)})$  ordered along time for the  $i$ th individual
- Fundamental particularity :
  - the ideal unit of observations are curves**
  - ▷ Consider the whole curve as a single entity
  - ▷ To consider functional quantities such as smoothness

# Ovarian cancer data

Petricoin et al, 2002

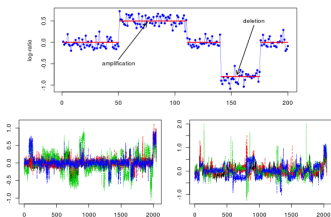
## Mass spectrometry data

- Related to the study of the proteome
- ▷ To investigate biological processes involved in the development of a pathology
- Proteomic spectra generated by mass spectrometry (MALDI-TOF technology)
- Samples from 253 women under 2 conditions
  - Unaffected (91)
  - Affected by ovarian cancer (162)
- Each spectra contains 15154 ionised peptides defined by a  $m/z$  ratio.



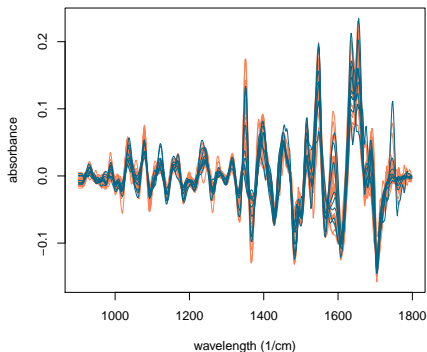
## Microarray CGH data

- Related to the study of the genome
- ▶ To detect possible chromosomal aberrations
- Represent genomic profiles of breast cancer tumor cells (compared to healthy cells)
- Samples from 66 women affected
- Each spectra contains 2044 ratios of copy number measurements
- Individual spectra are piecewise constant



## Mid-infrared spectrometry data

- Fast and non-invasive method to obtain the molecular composition of a biological fluid
- Ascites : abnormal presence of fluid in the abdomen
- Samples from 219 patients under 2 conditions
  - Infected liquid (46) : bad prognosis (50% mortality after 2 years)
  - Non-infected liquid (173)
- Each spectra is measured at 641 equally-spaced wavelength





Such data are :

- Complex
- Structured
- Possibly dependent
- Intrinsically infinite dimensional

But most of the statistical questions are standard :

- Uncovering homogeneous subgroup of responses   ▷ Clustering
- Recover a mean pattern   ▷ Estimation/Smoothing
- Quantify variations across individuals   ▷ Mixed-effects models
- Predict a response variable   ▷ Supervised learning

And some others specific to the functional nature of data :

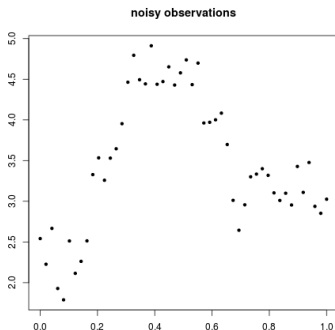
- Alignment on individual curves   ▷ Deformation models
- Identify discriminative portion of a signal   ▷ Domain selection
- and many others...

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# Functional model (Ramsay et Silverman, 1997)

The first step is to go from a discrete to a continuous representation

- ▷ Referred as smoothing in the literature
- ▷ May be included in a more complex procedure

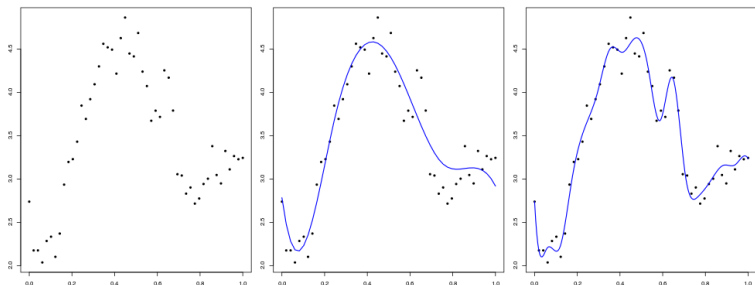


# Functional model (Ramsay et Silverman, 1997)

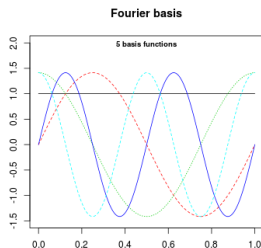
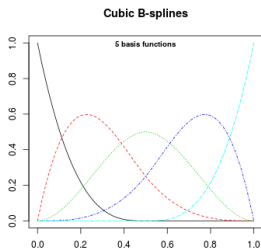
Data are seen as curves sampled on a fine grid  $(t_1, \dots, t_M)$  and corrupted by noise, such that :

$$Y(t_m) = \mu(t_m) + E(t_m), \quad E(t_m) \sim \mathcal{N}(0, \sigma_E^2)$$

▷ Goal : Recover function  $\mu$  from noisy observations



- In a nonparametric framework, no specified forms for involved functions
  - ▷ The problem lie in infinite dimensional framework
- Popular approach
  - Projection on an adapted functional basis
    - ▷ Set of pre-specified basis functions  $\{\phi_k, k \in \mathbb{N}\}$
- Examples
  - ▷ Fourier basis
  - ▷ Splines basis
  - ▷ Wavelets basis



- B-splines : the most popular functional basis
  - Polynomial functions
  - Adapted to smooth data : estimation based on roughness penalty
- Fourier basis
  - Sine and cosine functions
  - Adapted to periodic data : good localisation in frequency

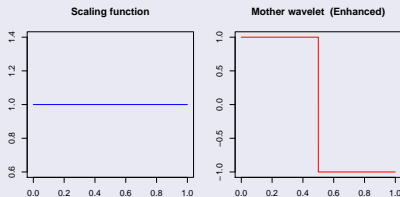
# Wavelets basis

Orthonormal basis of  $L^2(\mathbb{R})$  generated by dilatations and translations of a scaling function  $\phi$  and a mother wavelet  $\psi$  such that :

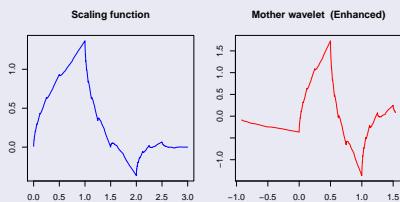
$$\{ \phi_{j_0 k}(t), k = 0, \dots, 2^{j_0} - 1; \psi_{jk}(t), j \geq j_0, k = 0, \dots, 2^j - 1 \}$$

with  $\phi_{jk}(t) = 2^{\frac{j}{2}} \phi(2^j t - k)$  and  $\psi_{jk}(t) = 2^{\frac{j}{2}} \psi(2^j t - k)$

## Haar basis



## Daubechies extremal phase wavelets (2 vanishing moments)



- Decomposition in the basis

Any function  $f \in L^2(\mathbb{R})$  is then expressed in the wavelet basis :

$$f(t) = \sum_{k=0}^{2^{j_0}-1} c_{j_0 k}^* \phi_{j_0 k}(t) + \sum_{j \geq j_0} \sum_{k=0}^{2^j-1} d_{j k}^* \psi_{j k}(t)$$

where  $c_{j_0 k}^* = \langle f, \phi_{j_0 k} \rangle$  and  $d_{j k}^* = \langle f, \psi_{j k} \rangle$  are theoretical scaling and wavelets coefficients



- Strength of wavelets
  - ▷ Fine modelling of curves with irregularities
  - ▷ Strong connexion with Besov spaces
  - ▷ Localisation in time and frequency
  - ▷ Decorrelating properties
  - ▷ Computational efficiency
  - ▷ Sparse representation of regular signals
  
- Drawbacks
  - ▷ Designed for equally spaced design
  - ▷ Common time grid for all individuals
  - ▷ Dyadic number of points

# Discrete Wavelet Transform (DWT)

- With discretely sampled signals  $\mathbf{Y} = (Y(t_1), \dots, Y(t_M))$ , we use the Discrete Wavelet Transform (Mallat, 1989) :

$$\underset{[M \times M]}{\mathbf{W}} \underset{[M \times 1]}{\mathbf{Y}} = \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix}$$

where  $\mathbf{W}$  is an orthogonal matrix of filters (wavelet specific)

- $(\mathbf{c}, \mathbf{d})$  are empirical wavelet coefficients such that :

$$\begin{aligned} \mathbf{c} &\simeq \sqrt{M} \times \mathbf{c}^* \\ \mathbf{d} &\simeq \sqrt{M} \times \mathbf{d}^* \end{aligned}$$

- Functional nonparametric model

In the coefficient domain, the model is written as

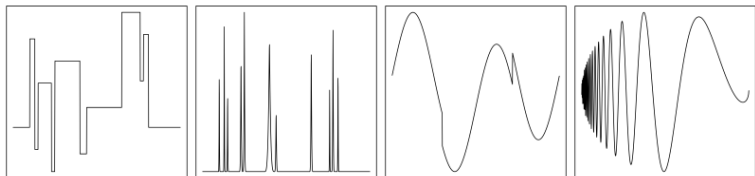
$$\begin{aligned} W\mathbf{Y} &= W\mu + W\mathbf{E} \\ \Leftrightarrow \begin{bmatrix} \mathbf{c} \\ \mathbf{d} \end{bmatrix} &= \begin{bmatrix} \boldsymbol{\alpha} \\ \boldsymbol{\beta} \end{bmatrix} + \boldsymbol{\varepsilon} \end{aligned}$$

where  $\boldsymbol{\varepsilon} \sim \mathcal{N}(0, \sigma^2 \mathbf{I})$

## Objective

From the linear representation in the wavelet domain, we want to find estimates of  $(\boldsymbol{\alpha}, \boldsymbol{\beta})$

- Our goal is to reconstruct **spatially inhomogeneous** functions



**General idea** : to look at the irregularities at finer scales and stay on coarser scales for smooth parts

- ▷ Requires **non-linear estimates** for optimal reconstruction
- Done with **thresholding** estimators (Donoho and Johnstone, 1994)
  - ▷ Shrink, kill or keep coefficients depending on a given threshold  $\lambda$  to produce sparse estimates of wavelet coefficients

**General idea :** Shrink, kill or keep coefficients depending on a given threshold  $\lambda$

- Hard thresholding (Keep or kill rule)  $d_{jk} \mathbb{1}_{\{|d_{jk}| < \lambda\}}$
- Soft thresholding (Shrink or kill rule)  $\text{sign}(d_{jk})(|d_{jk}| - \lambda)_+$
- Universal threshold :  $\lambda = \sigma \sqrt{2 \log M}$
- Robust estimate of  $\sigma$  based on the MAD of the coefficients at the finest resolution
- These estimators achieve a near-minimax rate of convergence (minimax within a logarithmic factor)
- Many existing variants depending on the characteristics of data

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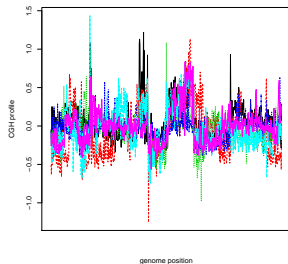
# Multisample data

We now consider individual replicates, *i.e.* we observe  $n$  individual curves

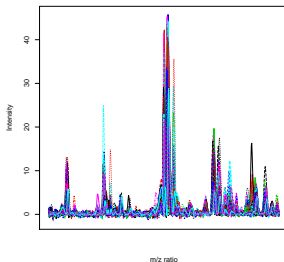
## Basic nonparametric model

- Poor modelling for multisample data that can present strong individual heterogeneity

CGH data



Mass Spectrometry data



More appropriate framework : **Mixed-effects models**

- Modelling individuals variations around a main pattern by adding individual functional random effects

$$Y_i(t_m) = \mu(t_m) + U_i(t_m) + E_i(t_m)$$

where  $U_i \sim \mathcal{N}(0, K(s, t))$  is a centered Gaussian process independant of  $E_i$ .

Wavelet representation of the model

$$\begin{bmatrix} \mathbf{c}_i \\ \mathbf{d}_i \end{bmatrix} = \begin{bmatrix} \boldsymbol{\alpha} \\ \boldsymbol{\beta} \end{bmatrix} + \begin{bmatrix} \boldsymbol{\nu}_i \\ \boldsymbol{\theta}_i \end{bmatrix} + \boldsymbol{\varepsilon}_i$$

where  $\boldsymbol{\varepsilon}_i \sim \mathcal{N}(0, \sigma_\varepsilon^2 \mathbf{I})$  and  $(\boldsymbol{\nu}_i, \boldsymbol{\theta}_i) \sim \mathcal{N}(0, \boldsymbol{\Gamma})$

▷ Resumes to a linear mixed effects model on wavelet coefficients



# Modelling the covariance of the random effects

- A wide litterature on functional mixed effects models
- Common essential point : modelling the matrix  $\Gamma$

We want to specify the covariance of the process  $U_i(t)$  to :

- ▷ have a model with a "simple" structure
- ▷ make fixed and random effects lie in the same functional space (Antoniadis and Sapatinas, 2007)
  - Modelling choice justified by real data applications

Natural idea : To propose a model for  $K(s, t)$  and infer conditions on matrix  $\Gamma$ . This leads in general to difficulties :

- ▷ to control the total number of parameters
- ▷ to control trajectories regularity

# Assumptions on matrix $\Gamma$

We prefer to specify  $\Gamma$  in the wavelet domain

**First assumption**  $\Gamma$  is assumed to be diagonal

▷ justified by the decorrelating property of wavelets (see Johnstone and Silverman, 1997 for discussion)

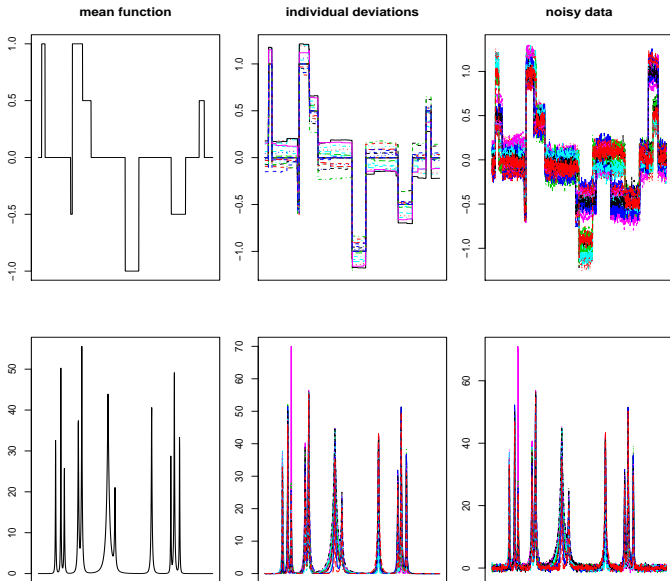
**Second assumption** Diagonal terms of  $\Gamma$  decrease exponentially with the scale  $j$

$$[\Gamma_{\theta}]_{jk} = 2^{-j\eta} \gamma^2$$

▷ Ensure that both fixed and random effects lie in the same functional space (see theorem of Abramovich et al, 1998)

Note that  $\gamma^2$  may depend on the level of decomposition and location  $(j, k)$  as  $\gamma_{jk}^2$

# Synthetic data



## Model reinterpretation

$$\begin{bmatrix} \mathbf{c}_i \\ \mathbf{d}_i \end{bmatrix} = \begin{bmatrix} \boldsymbol{\alpha} \\ \boldsymbol{\beta} \end{bmatrix} + \tilde{\boldsymbol{\varepsilon}}_i \quad \tilde{\varepsilon}_{i,jk} \sim \mathcal{N}(0, \gamma_{jk}^2 2^{-j\eta} + \sigma_\epsilon^2)$$

individual variability + noise

▷ Nonparametric regression problem in a heteroscedastic framework with replicates

- Extension of the universal threshold to an heteroscedastic setting  $\lambda = \sigma_{jk} \sqrt{2 \log M}$  (position dependant threshold)
- Estimates of parameters  $\sigma_{jk}$  are given by empirical estimates thanks to the  $N$  individual replicates
- The heteroscedastic thresholding enjoys a near-optimal convergence rate in the multisample setting, *i.e.* optimal within a logarithmic factor in signal size  $M$  (G., Lambert-Lacroix, Picard, 2017)

# Simulation results

- $N = 100, M = 512$
- Control of the level of noise and individual deviations
- Competed procedures
  - Usual homoscedastic thresholding with the universal threshold [Ho]
  - Heteroscedastic thresholding with the universal threshold [He]
- Reconstruction error criteria : Mean Integrated Square Error (MISE)

## Results on 200 repetitions : homoscedastic case

	SNR = 1		SNR= 5	
	Ho	He	Ho	He
Blocks	0.189 (0.016)	0.168 (0.017)	1.44e-3 (2.5e-4)	1.43e-3 (2.5e-4)
Bumps	0.736 (0.024)	0.726 (0.024)	0.045 (1.25e-3)	0.040 (1.25e-3)
Heavisine ( $\times 10^{-2}$ )	1.203 (0.097)	1.204 (0.104)	0.079 (0.006)	0.078 (0.006)
Doppler ( $\times 10^{-4}$ )	5.658 (0.246)	5.622 (0.274)	0.201 (0.011)	0.188 (0.011)

# Results on 200 repetitions : heteroscedastic case

	SNR= 5			
	$\tau = 0.1$		$\tau = 1$	
	Ho	He	Ho	He
Blocks	0.186 (0.054)	0.001 (2e-4)	0.011 (0.006)	0.001 (2e-4)
Bumps	0.220 (0.029)	0.040 (0.001)	0.0573 (0.002)	0.040 (0.001)
Heavisine ( $\times 10^{-2}$ )	0.530 (0.016)	0.079 (0.006)	0.129 (0.008)	0.079 (0.006)
Doppler ( $\times 10^{-4}$ )	1.387 (0.136)	0.187 (0.117)	0.304 (0.015)	0.188 (0.010)

# Curve clustering model

Natural extension : in a clustering framework, the  $N$  individuals are spread among  $L$  unknown clusters such as

$$Y_i(t_m) | \{\zeta_{i\ell} = 1\} = \mu_\ell(t_m) + U_i(t) + E_i(t_m) \quad E(t_m) \sim \mathcal{N}(0, \sigma_E^2)$$

where  $\zeta_{i\ell} = 1$  if individual  $i$  is in class  $\ell$

Wavelet representation of the model

- Given that  $\zeta_{i\ell} = 1$ ,

$$\begin{bmatrix} \mathbf{c}^i \\ \mathbf{d}^i \end{bmatrix} \Big| \{\zeta_{i\ell} = 1\} = \begin{bmatrix} \boldsymbol{\alpha}^\ell \\ \boldsymbol{\beta}^\ell \end{bmatrix} + \begin{bmatrix} \boldsymbol{\nu}_i \\ \boldsymbol{\theta}_i \end{bmatrix} + \boldsymbol{\varepsilon}^i; \quad \begin{aligned} \boldsymbol{\varepsilon}^i &\sim \mathcal{N}(0, \sigma^2 \mathbf{I}) \\ (\boldsymbol{\nu}_i, \boldsymbol{\theta}_i)^T &\sim \mathcal{N}(0, \boldsymbol{\Gamma}) \end{aligned}$$

- Translate into a Gaussian Mixture Model in the wavelet domain

▷ Goal : To recover individual labels  $(\zeta_{i\ell})_{i=1, \dots, N}^{\ell=1, \dots, L}$

- Maximum Likelihood estimation is performed via the EM algorithm with the following unobserved variables
    - ▷ Label variables  $\zeta$
    - ▷ Random effects  $(\nu, \theta)^T$
  - Dimension reduction step based on thresholding and aggregation estimators
  - Model selection done via a BIC criterion
- ▷ Individual labels are then deduced by a *Maximum A Posteriori* (MAP) rule



# Results on Mass spectrometry data

- Need important pre-treatment step (matrix effects, peaks alignment), computationally expensive (Antoniadis et. al, 2007)
- Results on a range of  $M = 8192$  positions (to discard effects of matrix)

Method	FCM	FCMM	FCMM.gr	FCMM.jk
<b>EER - global alignment</b>	38%	24%	24%	23%
<b>EER - group alignment</b>	20%	21%	22%	0.4%

## Conclusions

- Random effects consideration improves results for a global alignment
- Huge effect of peaks alignment
- One mismatch when variances depend on positions  
⇒ Suggest a sparse configuration of the random effects ?

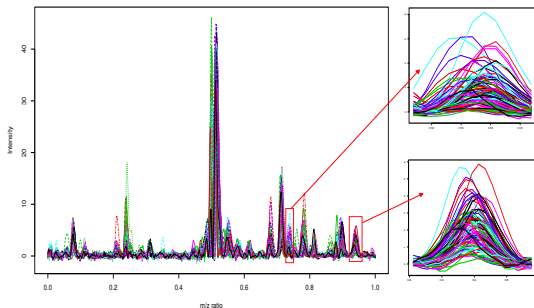
- Existing approaches based on hierarchical clustering of segmentation results (van Wieringen & van de Wiel (2008))
- Inter individual variability has never been quantified on CGH data
- On this dataset : existing clustering linked to survival data

## Main conclusions

- We find more subgroups than the original study (5 vs 3)
- We retrieve the cluster associated with the best outcome (one mismatch)
- Posterior estimation of SNR and  $\tau_U$  shows high level of noise and individual variability ( $\approx 10^{-4}$ )
  - ⇒ Find cluster with biological significance will require much more individuals

# Back on mass spectrometry data

Among the objectives : Identifying typical main profiles associated to affected patients to enable early stage detection of a pathology.



- Irregular data
- Variations in amplitude
- Phase variations
- Error noise (electrical perturbations)

- Difference in timing can have a high impact on statistical results
- Alignment as pre-treatment step neglect its variability

## Functional warped mixed model

- Individual phase deviations modeled by adding nonlinear individuals random warping functions

$$Y_i(t_{ij}) = \mu(w_i(t_{ij})) + U_i(w_i(t_{ij})) + E_{ij}, \quad E_{ij} \sim \mathcal{N}(0, \sigma^2)$$

- $w_i(\cdot) = w(\cdot, \theta_i)$  are parametrized by individual random variables  $\theta_i$

## Modelling of the warping functions $w_i$

- Monotonicity constraint : the functions  $w_i$  are nondecreasing diffeomorphisms
- [Gervini and Carter (2014)] Using Hermite splines that offer a direct link between knots and features
- [Bigot (2013)] Using Ordinary Differential Equation based on a reference function parametrized by cubic B-splines

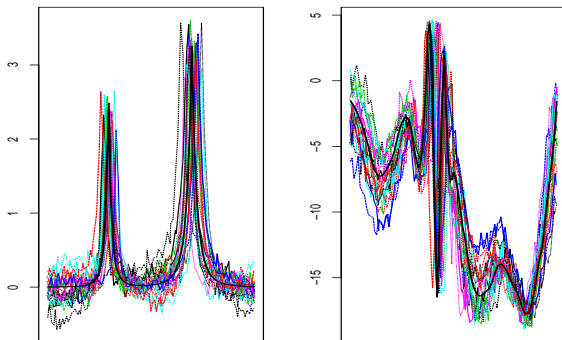
- The model fits in the [Non Linear Mixed Effects Models](#) (NLMEM) setting (Lindstrom & Bates (1990))
  - Nonobserved random effects (amplitude and phase deviations parameters) considered as hidden data
  - We use [EM algorithm](#) for Maximum Likelihood estimation of the parameters
- 
- Computation of the E-step
    - ▷ Untractable because of the nonlinearity of warping functions
  - Several existing approaches to either
    - approximate the likelihood function (Lindstrom & Bates (1990))
    - stochastically approximate the expectations of interest (Kuhn & Lavielle (2005))
  - We first focus on MCEM algorithm based on Monte-Carlo approximations of the desired expectations

# Applications on simulated data

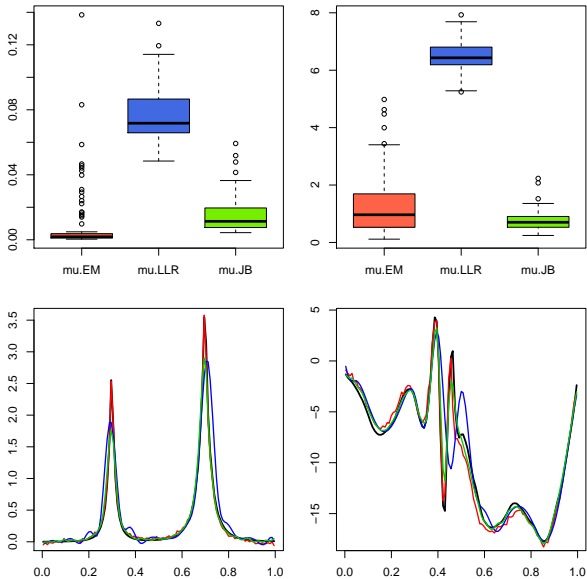
We compare three procedures

- [Bigot13]
- [Raket14]
- Wavelet-based warped mixed model

Compared w.r.t the MISE criteria (Mean Integrated Square Error) on the functional fixed effect.



# MISEs results - High deviations in phase and amplitude



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## Conclusions

- Flexible functional modelling for irregular curves with diverse sources of variability
- Related to standard models in the coefficient domain

## Remaining questions

- Supervised learning (PhD Marie Morvan in co-supervision)
- Sparse estimation of functional random effects
- Clustering in deformation models

-  Antoniadis, A. and Sapatinas, T. (2007), *Estimation and inference in functional mixed-effects models*. CSDA, 51 (10), p4793-4813.
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